Package 'BLSM'

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Title Bayesian Latent Space Model

Version 0.1.0 **Date** 2018-04-25

Description Provides a Bayesian latent space

model for complex networks, either weighted or unweighted.

Given an observed input graph, the estimates for the latent coordinates

of the nodes are obtained through a Bayesian MCMC algorithm.

The overall likelihood of the graph depends on a fundamental probability

equation, which is defined so that ties are more likely to exist

between nodes whose latent space coordinates are close.

The package is mainly based on the model by Hoff, Raftery and Handcock (2002)

<doi:10.1198/016214502388618906> and contains some extra features

(e.g., removal of the Procrustean step, weights implemented as

coefficients of the latent distances, 3D plots).

The original code related to the above model was retrieved from

 $< https://www.stat.washington.edu/people/pdhoff/Code/hoff_raftery_handcock_2002_jasa/>.$

Users can inspect the MCMC simulation, create and customize insightful graphical representations or apply clustering techniques.

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LinkingTo Rcpp, RcppEigen

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Description

Accept/reject the proposal for the α model variable

Usage

```
alpha_up(Y, lpz, W, alpha, adelta, a_a, a_b)
```

Arguments

Υ	Adjacency matrix of the observed network
lpz	Matrix containing the negative square root of the Euclidean distances between latent positions
W	BLSM Weights matrix of the observed network
alpha	Model variable α
adelta	The uniform proposal for α is defined on the $[-adelta, +adelta]$ interval
a_a	Shape parameter of the Gamma prior distribution for α . The value is usually set to 1, so the prior is actually an exponential distribution.
a_b	Rate parameter of the Gamma prior distribution for α .

Value

Updated value of the α variable

Bayesian Latent Space Model

BLSM

Description

R package allowing the computation of a Bayesian Latent Space Model for complex networks.

Latent Space Models are characterized by the presence of unobservable variables (latent coordinates) that are used to compute the likelihood of the observed networks. Their goal is to map the observed network in the latent space by meeting specific probabilistic requirements, so that the estimated latent coordinates can then be used to describe and characterize the original graph.

In the BSLM package framework, given a network characterized by its adjacency Y matrix, the model assigns a binary random variable to each tie: $Y_i j$ is related to the tie between nodes i and j and its value is 1 if the tie exists, 0 otherwise.

The model assumes the independence of $Y_i j | x_i, x_j, \alpha$, where x_i and x_j are the coordinates of the nodes in the multidimensional latent space and α is an additional parameter such that $logit(P(Y_i j = 1)) = \alpha - ||x_i - x_j||$.

The latent space coordinates are estimated by following a MCMC procedure that is based on the overall likelihood induced by the above equation.

Due to the symmetry of the distance, the model leads to more intuitive outputs for undirected networks, but the functions can also deal with directed graphs.

If the network is weighted, i.e. to each tie is associated a positive coefficient, the model's probability equation becomes $logit(P(Y_ij=1)) = \alpha - W_ij||x_i - x_j||$, where W_ij denotes the weight related to link existing between x_i and x_j . This means that even non existing links should have a weight, therefore the matrix used in the computation isn't the original weights matrix but actually a specific "BLSM weights" matrix that contains positive coefficients for all the possible pairs of nodes. When dealing with weighted networks, please be careful to pass a "BLSM weights" matrix as input #' (please refer to example_weights_matrix for more detailed information and a valid example).

The output of the model allows the user to inspect the MCMC simulation, create insightful graphical representations or apply clustering techniques to better describe the latent space. See estimate_latent_positions or plot_latent_positions for further information.

References

P. D. Hoff, A. E. Raftery, M. S. Handcock, Latent Space Approaches to Social Network Analysis, Journal of the American Statistical Association, Vol. 97, No. 460, (2002), pp. 1090-1098.

A. Donizetti, A Latent Space Model Approach for Clustering Complex Network Data, Master's Thesis, Politecnico di Milano, (2017).

dst

Geodesic distance

Description

Evaluate geodesic distance (shortest path) between all pairs of nodes in the network.

Usage

dst(M)

Arguments

Μ

Input adjacency matrix

Value

Matrix containing all the pairwise geodesic distances

Examples

```
dst(example_adjacency_matrix)
```

```
estimate_latent_positions
```

BLSM simulation

Description

Core function of the BLSM package: run a simulation to obtain the positions of the network nodes in the latent space for each sampled iteration.

The positions are simulated accordingly to the model assumptions, please refer to BLSM for further information. The output of the function can be used to retrieve and compare specific iterations, observe their evolution or simply compute the average positions (more details in the descriptions and examples below).

Usage

```
estimate_latent_positions(Y, W, procrustean = TRUE, k = 2, alpha = 2,
  nscan = 8 * 10^5, burn_in = 5 * 10^5, odens = 10^3, zdelta = 1,
  z_norm_prior_mu = 0, z_norm_prior_sd = 10, adelta = 0.3,
  a_exp_prior_a = 1, a_exp_prior_b = 1, dynamic_plot = FALSE,
  dynamic_circles = FALSE, ...)
```

Arguments

Y Adjacency matrix of the network

W (Optional) BLSM Weight matrix of the network

procrustean Boolean to include/exclude (TRUE/FALSE) the Procrustean Transform step in the

algorithm. Set TRUE by default.

k Space dimensionality

alpha Starting value of the α variable

nscan Number of iterations

burn_in Burn-in value (starting iterations to be discarded)

odens Thinning: only 1 iteration every odens will be sampled and stored in the output

zdelta Standard deviation of the Gaussian proposal for latent positions

z_norm_prior_mu

Mean of the Gaussian prior distribution for latent positions

z_norm_prior_sd

Standard deviation of the Gaussian prior distribution for latent positions

adelta The uniform proposal for α is defined on the [-adelta, +adelta] interval

a_exp_prior_a Shape parameter of the Gamma prior distribution for α . As the value is usually

set to 1 the prior is an exponential distribution.

a_exp_prior_b Rate parameter of the Gamma prior distribution for α .

dynamic_plot Boolean to plot dynamically the simulated positions (one update every odens

iterations)

dynamic_circles

Boolean to add circles of radius α to the dynamic plots

... Additional parameters that can be passed to plot_latent_positions

Value

Returns a "BLSM object" (blsm_obj), i.e. a list containing:

- Alpha α values from the sampled iterations
- Likelihood Log-likelihood values from the sampled iterations
- Iterations Latent space coordinates from the sampled iterations. Latent positions are stored in a 3D array whose dimensions are given by (1: number of nodes, 2: space dimensionality, 3: number of iterations). In the non-Procrustean framework the latent distances are given instead of the positions: another 3D array is returned, whose dimensions are given by (1: number of nodes, 2: number of nodes, 3: number of iterations). The command needed in order to get the average values over the iterations for either the positions or the distances is rowMeans(blsm_obj\$Iterations, dims=2) (see example below).
- StartingPositions Latent space coordinates right after the initialization step. In the non-Procrustean framework starting distances are given instead.
- Matrix Original matrices of the network (adjacency and BLSM weights)
- Parameters List of parameters specified during the call to estimate_latent_positions

Examples

```
## Not run:
  # Procrustean version followed by clustering
  blsm_obj = estimate_latent_positions(example_adjacency_matrix,
                           burn_in = 3*10^4, nscan = 10^5, dynamic_plot = TRUE)
  avg_latent_positions = rowMeans(blsm_obj$Iterations, dims=2)
  h_cl = hclust(dist(avg_latent_positions), method="complete")
  n = 3
  latent_space_clusters = cutree(h_cl, k=n)
  print(latent_space_clusters)
  plot(avg_latent_positions, col=rainbow(n)[latent_space_clusters], pch=20)
  # Non-Procrustean version followed by clustering
  blsm_obj_2 = estimate_latent_positions(example_adjacency_matrix, procrustean=FALSE,
                           burn_in = 3*10^4, nscan = 10^5)
  avg_latent_distances = rowMeans(blsm_obj_2$Iterations, dims=2)
  h_cl = hclust(as.dist(avg_latent_distances), method="complete")
  n = 3
  latent_space_clusters_2 = cutree(h_cl, k=n)
  print(latent_space_clusters_2)
  # Weighted network
  blsm_obj_3 = estimate_latent_positions(example_adjacency_matrix, example_weights_matrix,
                           burn_in = 10^5, nscan = 2*10^5, dynamic_plot = TRUE)
 ## End(Not run)
example_adjacency_matrix
                         Example Adjacency Matrix
```

Description

Adjacency matrix of a 10 nodes random network for testing purposes

Usage

```
example_adjacency_matrix
```

Format

A binary adjacency matrix representing links between nodes.

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example_blsm_obj

Example BLSM object

Description

BLSM object obtained by applying the Procrustean version of the latent space model to the unweighted network whose adjacency matrix is example_adjacency_matrix. Further details concerning the simulation are contained in the BLSM object itself.

Usage

example_blsm_obj

Format

BLSM object (blsm_obj), i.e. a list containing:

- Alpha α values from the sampled iterations
- Likelihood Log-likelihood values from the sampled iterations
- Iterations Latent space coordinates from the sampled iterations. Latent positions are stored in a 3D array whose dimensions are given by (1: number of nodes, 2: space dimensionality, 3: number of iterations). In the non-Procrustean framework the latent distances are given instead of the positions: another 3D array is returned, whose dimensions are given by (1: number of nodes, 2: number of nodes, 3: number of iterations). The command needed in order to get the average values over the iterations for either the positions or the distances is rowMeans(blsm_obj\$Iterations, dims=2) (see example below).
- StartingPositions Latent space coordinates right after the initialization step. In the non-Procrustean framework starting distances are given instead.
- Matrix Original matrices of the network (adjacency and BLSM weights)
- Parameters List of parameters specified during the call to estimate_latent_positions

example_weights_matrix

Example Weights Matrix

Description

"BLSM weights" matrix of a 10 nodes random network for testing purposes

Usage

example_weights_matrix

lpY

Format

A matrix containing positive weights for all pairs of nodes.

Given a couple of nodes, a weight expresses the importance of the distance between the coordinates associated to the two nodes in the latent space in terms of the overall likelihood of the graph. For this reason, even missing links must have a coefficient, otherwise the relative positioning of disconnected nodes would have no effect at all on the graph likelihood.

The exact probability equation is described in BLSM, as well as the notation used.

A few examples:

- for unweighted networks, the "BLSM weights" matrix has all the values set to 1.
- if two nodes share a strong connection, then the weight coefficient should be greater than 1 so that their positions in the latent space will be closer than they would be in an unweighted framework.
- if two nodes share a weak connection, a coefficient smaller than 1 will allow the latent coordinates to be pretty far from each other even though the nodes are connected.

lpY Network log-likelihood

Description

Compute the log-likelihood of the whole observed network based on the latent positions estimates and the model assumptions. See BLSM for more information.

Usage

```
lpY(Y, lpz, alpha, W)
```

Arguments

Υ	Adjacency matrix of the observed network
lpz	Matrix containing the negative square root of the Euclidean distances between latent positions (output of lpz_dist)
alpha	Model variable α
W	BLSM Weights matrix of the observed network

Value

Log-likelihood of the observed network

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1pYNODE Network log-likelihood for individual updates	
---	--

Description

Compute the log-likelihood of the whole observed network based on the latent positions estimates and the model assumptions. The function follows almost the same approach as lpY, but it is more suitable for the individual updates occurring during the simulation.

Usage

```
lpYNODE(Y, Z, alpha, node, diag, W)
```

Arguments

Υ	Adjacency matrix of the observed network
Z	Latent positions matrix
alpha	Model variable α
node	Specific node in the network corresponding to the latent coordinate which will be used as reference
diag	Diagonal from t(Z)%*%Z matrix, passed to speed up the process.
W	BLSM Weights matrix of the observed network

Value

Log-likelihood of the observed network

lpz_dist	Distance between latent positions	

Description

Compute the square root of the Euclidean distances between latent positions and return them with a negative sign.

Usage

```
lpz_dist(Z)
```

Arguments

Z Latent positions matrix. The matrix size must be (n,k), where n and k denote respectively the number of nodes in the network and the latent space dimensionality.

mlpY

Value

Matrix containing the negative square root of the Euclidean distances between latent positions

Examples

```
pos = matrix(rnorm(20), ncol=2)
lpz_dist(pos)
```

lpz_distNODE

lpz_dist optimized for individual updates

Description

Compute the square root of the Euclidean distances between a specific coordinate in the latent space and all the others. The function follows almost the same approach as lpz_dist, but it is more suitable for the individual updates occurring during the simulation.

Usage

```
lpz_distNODE(Z, node, diag)
```

Arguments

Z Latent positions matrix

node Specific node in the network corresponding to the latent coordinate which will

be used as reference

diag Diagonal from t(Z)%*%Z matrix, passed to speed up the process.

Value

Vector containing the negative square root of the Euclidean distances between latent positions

mlpY

Network (positive) log-likelihood

Description

Compute the (positive) log-likelihood of the whole observed network based on the latent positions estimates and the model assumptions. The inputs are slightly different from those of lpY, so the function basically applies some preprocessing before calling lpY and returning its value with the opposite sign.

Usage

```
mlpY(avZ, Y, W)
```

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Arguments

avZ Vector containing the α value and the latent positions	avZ	Vector containing the α value and the latent positions
---	-----	---

Y Adjacency matrix of the observed network

W BLSM Weights matrix of the observed network

Value

Log-likelihood of the observed network

```
plot_latent_positions Base BLSM plot function
```

Description

Plot latent positions from a Procrustean simulation.

Usage

```
plot_latent_positions(blsm_obj, colors, points_size = 0.1,
    labels_point_size = 5, labels_point_color = "yellow",
    labels_text_size = 1, labels_text_color = "blue", circles_2D = FALSE)
```

Arguments

blsm_obj BLSM object obtained through estimate_latent_positions

colors (Optional) Colors of the simulated coordinate points in the latent space. Internal

default colors are used if the argument is missing.

points_size Size of the coordinate points

labels_point_size

Size of the label points

labels_point_color

Color of the label points

labels_text_size

Text size in the label points

labels_text_color

Text color in the label points

circles_2D Plot circles of radius α (see the model's main variables) centered around the

label points

Examples

```
plot_latent_positions(example_blsm_obj, labels_point_color = "black", labels_text_color = "black")
plot_latent_positions(example_blsm_obj, circles_2D = TRUE)
```

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```
plot_traceplots_acf BLSM traceplots and ACF
```

Description

Traceplots and autocorrelation functions for the α variable and a selected node (or pair of nodes in the non-Procrustean framework).

Usage

```
plot_traceplots_acf(blsm_obj, chosen_node = 1, coordinate = 1,
  chosen_pair = c(1, 2))
```

Arguments

blsm_obj BLSM object obtained through estimate_latent_positions

chosen_node Specified node for traceplot and autocorrelation function (Procrustean frame-

work)

coordinate Specified coordinate dimension from the n-dimensional latent space

chosen_pair Specified pair of nodes for traceplot and autocorrelation function (non-Procrustean

framework)

Examples

proc_crr

Procrustean corresponding positions

Description

Given a set of starting coordinates, the function returns the Procrustean Transform of the initial points that minimizes the sum of squared positional difference from a set of reference coordinates. The (Euclidean) distances between a candidate configuration and the reference are evaluated by considering the couples of corresponding points.

The reference configuration must be centered at the origin.

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Usage

```
proc_crr(Z, Z0)
```

Arguments

Z set of initial coordinates to be transformed

zo set of reference coordinates centered at the origin

Value

Set of coordinates minimizing the distance between the initial configuration and the reference one

Examples

```
# Create configuration and center it at the origin
pos_ref = matrix(runif(20), ncol=2)
pos_ref = t(t(pos_ref)-colMeans(pos_ref))

# Create a new configuration by adding a perturbation to the previous one
pos = pos_ref + matrix(rnorm(20, mean=1, sd=0.1), ncol=2)

# Compute the Procrustean Transform and inspect the results
proc_pos = proc_crr(pos, pos_ref)
plot(pos_ref, col="blue", pch=20, xlim=c(-1,3), ylim=c(-1,3))
points(pos, col="red", pch=20)
points(proc_pos, col="purple", pch=20)
```

Z_up

Update step for the latent positions

Description

Accept/reject the proposals for the latent positions

Usage

```
Z_up(Y, Z, W, alpha, zdelta, mu_z, sd_z)
```

Arguments

Υ	Adjacency matrix of the observed network
Z	Latent positions matrix
W	BLSM Weights matrix of the observed network
alpha	Model variable α
zdelta	Standard deviation of the Gaussian proposal for latent positions
mu_z	Mean of the Gaussian prior distribution for latent positions
sd_z	Standard deviation of the Gaussian prior distribution for latent positions

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Value

Updated latent positions matrix

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