# Package 'SpatialTools' 

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coincident Determine coincident coordinates

## Description

coincident takes the coordinate matrices coords1 and coords2 and returns the indices of the coincident coordinates of the two matrices.

## Usage

coincident(coords1, coords2)

## Arguments

coords1 An $n 1 \times 2$ numeric matrix of coordinates.
coords $2 \quad$ An $n 2 \times 2$ numeric matrix of coordinates.

## Details

This function calls a compiled C++ program created using the Rcpp package. This (may) result in a significant speedup over pure R code since the search algorithm involves loops. We assume that there are no duplicate coordinates in coords1 and coords2, respectively. In other words, each row of coords 1 is unique and each row of coords 2 is unique. There is at most 1 row of coords 1 that will match with a row in coords2.

## Value

Returns a matrix with the indices of the coincident locations. Specifically, an $r \times 2$ matrix will be returned, with $r$ being the number of coordinates in coords1 coinciding with coordinates in coords2. If row $i$ of the matrix is $c(2,5)$, then the $i$ th set of coincident locations is between the 2 nd row of coords 1 and the 5 th row of coords2. If there are no coincident locations, then a matrix of size $0 \times 2$ is returned.

## Author(s)

Joshua French

## Examples

```
#Generate two sets of coordinates
loc1 <- as.matrix(expand.grid(seq(0, 1, len = 25), seq(0, 1, len = 25)))
loc2 <- as.matrix(expand.grid(seq(0, 1, len = 101), seq(0, 1, len = 101)))
coincident(loc1, loc2)
```

```
cov.sp
```

Calculates spatial covariance

## Description

Calculates spatial covariance matrix of the observed responses, and possibly, the responses to be predicted. If pcoords is not provided, then only V , the covariance matrix of the observed responses will be returned. If pcoords is provided, then $V p$ and $V o p$ (the covariance matrix for predicted responses and between observed and predicted responses, respectively) will also be returned.

## Usage

cov.sp(coords, sp.type = "exponential", sp.par = stop("specify sp.par argument"), error.var $=0$, smoothness $=0.5$, finescale.var $=0$, pcoords $=$ NULL, $D=$ NULL, $D p=$ NULL, Dop $=$ NULL)

## Arguments

coords A numeric matrix of size $n \times d$ containing the observed data locations.
sp.type A character vector specifying the spatial covariance type. Valid types are currently exponential, gaussian, matern, matern2, and spherical.
sp.par A vector of length 2 specifying the scale and strength of dependence of the covariance function. The first element is the variance of the underlying spatial process (also known as the hidden or latent spatial process). This value is also called the partial sill. The second element is the strength of dependence between responses.
error.var A non-negative number indicating the variance of the error term.
smoothness A positive number indicating the variance of the error term.
finescale.var A non-negative positive number indicating the finescale variability. The is also called the microscale variance
pcoords A numeric matrix of size $n p \times d$ containing the locations of the responses to be predicted.
D The Euclidean distance matrix for the coords matrix. Must be of size $n \times n$.
Dp The Eucliean distance matrix for the pcoords matrix. Must be of size $n p \times n p$.
Dop The Euclidean intersite distance matrix between the locations in coords and the locations in pcoords. Must be of size $n \times n p$.

## Details

The spatial covariance functions are parameterized in a manner consistent with the cov. spatial function in the geoR package. The matern2 covariance function is an alternative covariance function suggested by Handcock and Wallis (1994). The benefit of this parameterization is that the range parameter is that it allows the effective range to be less dependent on the smoothness parameter.

The $D$, $D p$, and Dop arguments are supplied to decrease the number of necessary computations needed when performing repetitive analysis or simulations. It is probably in the user's interest to not supply these arguments unless the duration of analysis is an important consideration. Note that these arguments override the information given in coords and pcoords, i.e., if dist1(coords) $!=\mathrm{D}$, then D is used in subsequent calculations, etc. This could create problems.

## Value

Returns a list with the following elements:
$V \quad$ The covariance matrix for the observed responses. Will be of size $n \times n$.
Vp The covariance matrix for the predicted responses. Only returned if pcoords is supplied. Will be of size $n p \times n p$.

Vp The covariance matrix between the observed responses and the predicted responses. Only returned if pcoords is supplied. Will be of size $n \times n p$.

## Author(s)

Joshua French

## References

M.S. Handcock, J.R. Wallis. An approach to statistical spatial-temporal modeling of meteorological fields (with discussion). Journal of the American Statistical Association, 89 (1994), pp. 368-390.

## See Also

```
simple.cov.sp
```


## Examples

```
    coords <- matrix(rnorm(30), ncol = 3)
    cov.sp(coords = coords, sp.type = "exponential", sp.par = c(2, 1),
            error.var = 1)
```


## Description

Calculates spatial covariance matrix of the observed responses, and possibly, the responses to be predicted. If pcoords is not provided, then only V , the covariance matrix of the observed responses will be returned. If pcoords is provided, then $V p$ and Vop (the covariance matrix for predicted responses and between observed and predicted responses, respectively) will also be returned.

## Usage

```
cov.st(coords, time, sp.type = "exponential",
sp.par = stop("specify sp.par argument"),
    error.var = 0, smoothness = 0.5, finescale.var = 0,
    t.type = "ar1", t.par = .5,
    pcoords = NULL, ptime = NULL,
    D = NULL, Dp = NULL, Dop = NULL,
    T = NULL, Tp = NULL, Top = NULL)
```


## Arguments

coords A numeric matrix of size $n \times d$ containing the observed data locations.
time A numeric matrix of size $n \times 1$ containing the times at which the data was observed.
sp.type A character vector specifying the spatial covariance type. Valid types are currently exponential, gaussian, matern, and spherical.
sp.par A vector of length 2 specifying the scale and dependence of the covariance function. The first element refers to the variance of the hidden process (sometimes this is called the partial sill) while the second elements determines the strength of dependence between locations.
error.var A non-negative number indicating the variance of the error term.
smoothness A positive number indicating the variance of the error term.
finescale.var A non-negative positive number indicating the finescale variability. The is also called the microscale variance
$t$.type A character vector indicating the temporal dependance structure. Currently, only "ar1" is implemented.
t.par A numeric vector of length 1 indicating the strength of temporal dependence.
pcoords A numeric matrix of size $n p \times d$ containing the locations of the responses to be predicted
ptime A numeric matrix of size $n p \times 1$ containing the times at which the responses are to be predicted.

D

| Dp | The Eucliean distance matrix for the pcoords matrix. Must be of size $n p \times n p$. |
| :--- | :--- |
| Dop | The Eucliean intersite distance matrix between the locations in coords and the |
| locations in pcoords. Must be of size $n \times n p$. |  |
| T | The Euclidean distance matrix for the time matrix. Must be of size $n \times n$. |
| Tp | The Eucliean distance matrix for the ptime matrix. Must be of size $n p \times n p$. |
| Top | The Eucliean intertime distance matrix between the times in time and ptime. <br> Must be of size $n \times n p$. |

## Details

At this point, this function only implements a separable spatio-temporal covariance funcation. If $h$ is the distance between two sites, and $t$ is the temporal lag between the times when the associated responses were observed, then the covariance function $C(h, t)=C s(h) \times C t(t)$ where $C s$ is a spatial covariance function corresponding to the exponential, matern, gaussian, or spherical and $C t$ is the temporal covariance function corresponding to an ar1 process with $C t(t)=\phi^{t}$.
The D, Dp, Dop, T, Tp, Top arguments are supplied to decrease the number of necessary computations needed when performing repetitive analysis or simulations. It is probably in the user's interest to not supply these arguments unless the duration of analysis is an important consideration. Note that these arguments override the information given in coords, pcoords, time, and prime, i.e., if dist 1 (coords) $!=\mathrm{D}$, then D is used in subsequent calculations, etc. This could create problems.

## Value

Returns a list with the following elements:
V The covariance matrix for the observed responses.
Vp The covariance matrix for the predicted responses. Only returned if pcoords is supplied.
Vp The covariance matrix between the observed responses and the predicted responses. Only returned if pcoords is supplied. Will be of size $n \times n p$

## Author(s)

Joshua French

## See Also

simple.cov.sp

## Examples

```
coords <- matrix(rnorm(30), ncol = 3)
pcoords <- matrix(rnorm(90), ncol = 3)
time <- 1:10
ptime <- 1:30
cov.st(coords = coords, time = time, sp.type = "exponential",
    sp.par = c(2, 1), error.var = 1, t.type = "ar1", t.par = .5,
    pcoords = pcoords, ptime = ptime)
```

decomp.cov Calculates decomposition of covariance matrix

## Description

Calculates a decomposition of the provided covariance matrix, $\vee$, using the chosen method.

## Usage

decomp.cov(V, method = "eigen")

## Arguments

$V$ A (symmetric, positive-definite) covariance matrix.
method A character vector specifying the method used to decompose V. Options are "eigen", "chol", or "svd" (Eigen decomposition, Cholesky decomposition, or Singular value decomposition, respectively).

## Details

The matrix $V$ is assumed to be symmetric and positive definite. Symmetry is checked, but the positive definiteness of the matrix is not. Returns a decomposition matrix U such that $\mathrm{V}=\mathrm{U} \% * \%$ $t(U)$.

## Value

Returns a decomposition matrix $U$ such that $V=U \% * \% t(U)$.

## Author(s)

Joshua French

## See Also

cov.sp

## Examples

```
data(toydata)
U <- decomp.cov(toydata$V, method = "chol")
#range(toydata$V - U %*% t(U))
```


## Description

dist1 takes a matrix of coordinates and returns the Euclidean distance matrix of the coordinates. It does this using a compiled C program, so it is faster than the builtin R dist function.

## Usage

dist1 (coords)

## Arguments

coords An $n r \times n c$ numeric matrix of coordinates.

## Value

An $n r \times n r$ matrix of Euclidean distances.

## Author(s)

Joshua French

## See Also

dist, dist2

## Examples

```
x <- matrix(rnorm(30), ncol = 3)
dist1(x)
```

dist2 Calculate Euclidean distance matrix between coordinates of two matrices

## Description

dist2 takes the matrices of coordinates coords1 and coords2 and returns the inter-Euclidean distances between coordinates.

## Usage

dist2(coords1, coords2)

## Arguments

| coords1 | An $n r 1 \times n c 1$ numeric matrix of coordinates. |
| :--- | :--- |
| coords2 | An $n r 2 \times n c 2$ numeric matrix of coordinates. |

## Value

An $n r 1 \times n r 2$ matrix of Euclidean distances.

## Author(s)

Joshua French

## See Also

dist, dist1

## Examples

```
x1 <- matrix(rnorm(30), ncol = 3)
x2 <- matrix(rnorm(60), ncol = 3)
dist2(x1, x2)
```


## get. contours Extracts coordinates from contourLines function

## Description

Takes contours of contourLines function and extracts the associated coordinates.

## Usage

get. contours ( $x$ )

## Arguments

x
A list returned by the contourLines function.

## Value

Returns a 2-column matrix containing the coordinates making up the contours in contours.list.

## Author(s)

Joshua French

## See Also

contourLines, contour

## Examples

```
data(volcano)
x <- 10*1:nrow(volcano)
y <- 10*1:ncol(volcano)
cL <- contourLines(x, y, volcano)
out <- get.contours(cL)
```

krige.ok Performs Ordinary Kriging

## Description

Performs Ordinary Kriging using y, the $n \times 1$ matrix of observed responses, V, the (positive definite) covariance matrix of the observed responses, Vp , the $n p \times n p$ covariance matrix of the responses to be predicted, and Vop, the $n \times n p$ matrix of covariances between the observed responses and the responses to be predicted.

## Usage

krige.ok(y, V, Vp, Vop, nsim = 0, Ve.diag = NULL, method = "eigen")

## Arguments

y
$\vee \quad$ The covariance matrix of the observed responses. The size is $n \times n$.
Vp The covariance matrix of the responses to be predicted. The size is $n p \times n p$.
Vop The cross-covariance between the observed responses and the responses to be predicted. The size is $n \times n p$
nsim The number of simulated data sets to sample from the conditional predictive distribution.
Ve.diag A vector of length $n$ specifying the measure error variances of the observed data. Only needed if nsim $>0$.
method The method for decomposing V in conditional simulation. Default is "eigen", for the Eigen decomposition. Alternatives are "chol" (Cholesky) and "svd" (Singular Value Decomposition).

## Details

It is assumed that there are $n$ observed data values and that we wish to make predictions at $n p$ locations.

If doing conditional simulation, the Cholesky decomposition should not work when there are coincident locations between the observed data locations and the predicted data locations. Both the Eigen and Singular Value Decompositions should work.

If user specifies nsim to be a positive integer, then nsim conditional realizations of the predictive distribution will be generated. If this is less than 1 , then no conditional simulation is done. If nsim is a positive integer, then Ve.diag must also be supplied. Ve.diag is should be a vector of length $n$ specifying the measurement error variances of the observed data. This information is only used for conditional simulation, so this argument is only needed when nsim $>0$. When conditional simulation is desired, then the argument method can be to specify the method used to decompose V . Options are "eigen", "chol", or "svd" (Eigen decomposition, Cholesky decomposition, or Singular value decomposition, respectively). This information is only used for conditional simulation, so this argument is only applicable when nsim $>0$.

## Value

The function returns a list containing the following objects:

| pred | A vector of length $n p$ containing the predicted responses. |
| :--- | :--- |
| mspe | A vector of length $n p$ containing the mean-square prediction error of the pre- <br> dicted responses. |
| coeff | A vector of length $k$ containing the estimated regression coefficients. |
| vcov.coeff | A $k \times k$ matrix containing the (estimated) covariance matrix of estimated the <br> regression coefficients. |
| simulations | An $n \times n s i m$ matrix containing the nsim realizations of the conditional real- <br> izations. Each column of the matrix represents a realization of the conditional <br> normal distribution. |

If nsim $>0$, this list has class "krigeConditionalSample".

## Author(s)

Joshua French

## References

Statistical Methods for Spatial Data Analysis, Schabenberger and Gotway (2003). See p. 226-228.

## Examples

```
# create observed and predicted coordinates
ocoords <- matrix(runif(100), ncol = 2)
pcoords <- matrix(runif(200), ncol = 2)
# include some observed locations in the predicted coordinates
acoords <- rbind(ocoords, pcoords)
# create covariance matrix
C3 <- cov.sp(coords = ocoords, sp.type = "matern", sp.par = c(2, 1), smoothness = 1,
finescale = 0, error = 0.5, pcoords = acoords)
# generate data with error
y <- rmvnorm(nsim = 1, mu = rep(2, 50), V = C3$V) + rnorm(50, sd = sqrt(.5))
```

```
# use universal kriging to make predictions. Do not do conditional simulation
krige.obj <- krige.ok(as.vector(y), V = C3$V, Vp = C3$Vp, Vop = C3$Vop,
nsim = 0)
#Do conditional simulation
krige.obj2 <- krige.ok(as.vector(y), V = C3$V, Vp = C3$Vp, Vop = C3$Vop,
nsim = 100, Ve.diag = rep(.5, 50), method = "eigen")
```

krige.sk Performs simple kriging

## Description

Performs simple kriging using y , a vector of length $n, \mathrm{~V}$, the (positive definite) covariance matrix of the observed responses, Vp , the $n p \times n p$ covariance matrix of the responses to be predicted, Vop, the $n \times n p$ matrix of covariances between the observed responses and the responses to be predicted, and m , a numeric vector of length 1 identifying the value of the mean for each response.

## Usage

krige.sk(y, V, Vp, Vop, m = 0, nsim = 0, Ve.diag = NULL, method = "eigen")

## Arguments

y

V
Vp
Vop
m
nsim

Ve.diag A vector of length $n$ specifying the measure error variances of the observed data. Only needed if nsim $>0$.
method The method for decomposing $V$ in conditional simulation. Default is "eigen", for the Eigen decomposition. Alternatives are "chol" (Cholesky) and "svd" (Singular Value Decomposition).

## Details

It is assumed that there are $n$ observed data values and that we wish to make predictions at $n p$ locations. The mean is subtracted from each value of y before determining the kriging weights, and then the mean is added onto the predicted response.
If doing conditional simulation, the Cholesky decomposition should not work when there are coincident locations between the observed data locations and the predicted data locations. Both the Eigen and Singular Value Decompositions should work.

If user specifies nsim to be a positive integer, then nsim conditional realizations of the predictive distribution will be generated. If this is less than 1, then no conditional simulation is done. If nsim is a positive integer, then Ve.diag must also be supplied. Ve.diag is should be a vector of length $n$ specifying the measurement error variances of the observed data. This information is only used for conditional simulation, so this argument is only needed when nsim $>0$. When conditional simulation is desired, then the argument method can be to specify the method used to decompose V . Options are "eigen", "chol", or "svd" (Eigen decomposition, Cholesky decomposition, or Singular value decomposition, respectively). This information is only used for conditional simulation, so this argument is only applicable when nsim $>0$.

## Value

The function returns a list containing the following objects:

$$
\begin{array}{ll}
\text { pred } \\
\text { mspe }
\end{array} \quad \begin{aligned}
& \text { A vector of length } n p \text { containing the predicted responses. } \\
& \text { A vector of length } n p \text { containing the mean-square prediction error of the pre- } \\
& \text { dicted responses. }
\end{aligned}
$$

## Author(s)

Joshua French

## References

Statistical Methods for Spatial Data Analysis, Schabenberger and Gotway (2003). See p. 226-228.

## Examples

```
data(toydata)
y <- as.vector(toydata$y)
V <- toydata$V
Vp <- toydata$Vp
Vop <- toydata$Vop
krige.sk(y, V, Vp, Vop, m = 2)
```

krige.uk Performs universal kriging

## Description

Performs universal kriging using X , the $n \times k$ design matrix for the regression coefficients of the observed data, y , the $n \times 1$ matrix of observed responses, V , the (positive definite) covariance matrix of the observed responses, Xp , the $n p \times k$ design matrix of the responses to be predicted, Vp , the $n p \times n p$ covariance matrix of the responses to be predicted, and Vop, the $n \times n p$ matrix of covariances between the observed responses and the responses to be predicted. If user specifies nsim to be a positive integer, then nsim conditional realizations of the predictive distribution will be generated.

## Usage

krige.uk(y, V, Vp, Vop, X, Xp, nsim = 0, Ve.diag = NULL, method = "eigen")

## Arguments

y
$\checkmark \quad$ The covariance matrix of the observed responses. The size is $n \times n$.
Vp The covariance matrix of the responses to be predicted. The size is $n p \times n p$
Vop The cross-covariance between the observed responses and the responses to be predicted. The size is $n \times n p$
$\mathrm{X} \quad$ The design matrix of the observed data. The size is $n \times k$
$\mathrm{Xp} \quad$ The design matrix of the responses to be predicted. The size is $n p \times k$.
nsim The number of simulated data sets to sample from the conditional predictive distribution.
Ve.diag A vector of length $n$ specifying the measure error variances of the observed data.
method The method for decomposing $V$ in conditional simulation. Default is "eigen", for the Eigen decomposition. Alternatives are "chol" (Cholesky) and "svd" (Singular Value Decomposition).

## Details

It is assumed that there are $n$ observed data values and that we wish to make predictions at $n p$ locations. We assume that there are $k$ regression coefficients (including the intercept). Both X and Xp should contain a column of 1's if an intercept is desired.
If doing conditional simulation, the Cholesky decomposition should not work when there are coincident locations between the observed data locations and the predicted data locations. Both the Eigen and Singular Value Decompositions should work.

If user specifies nsim to be a positive integer, then nsim conditional realizations of the predictive distribution will be generated. If this is less than 1 , then no conditional simulation is done. If nsim is a positive integer, then Ve.diag must also be supplied. Ve.diag is should be a vector of
length $n$ specifying the measurement error variances of the observed data. This information is only used for conditional simulation, so this argument is only needed when nsim $>0$. When conditional simulation is desired, then the argument method can be to specify the method used to decompose V . Options are "eigen", "chol", or "svd" (Eigen decomposition, Cholesky decomposition, or Singular value decomposition, respectively). This information is only used for conditional simulation, so this argument is only applicable when nsim $>0$.

## Value

The function returns a list containing the following objects:
pred A vector of length $n p$ containing the predicted responses.
mspe A vector of length $n p$ containing the mean-square prediction error of the predicted responses.
coeff A vector of length $k$ containing the estimated regression coefficients.
vcov.coeff A $k \times k$ matrix containing the (estimated) covariance matrix of estimated the regression coefficients.
sim An $n \times n$ sim matrix containing the nsim realizations of the conditional realizations. Each column of the matrix represents a realization of the conditional normal distribution.

If nsim $>0$, this list has class "krigeConditionalSample".

## Author(s)

Joshua French

## References

Statistical Methods for Spatial Data Analysis, Schabenberger and Gotway (2003). See p. 241-243.

## Examples

```
# create observed and predicted coordinates
ocoords <- matrix(runif(100), ncol = 2)
pcoords <- matrix(runif(200), ncol = 2)
# include some observed locations in the predicted coordinates
acoords <- rbind(ocoords, pcoords)
# create design matrices
X <- as.matrix(cbind(1, ocoords))
Xa <- as.matrix(cbind(1, acoords))
# create covariance matrix
C3 <- cov.sp(coords = ocoords, sp.type = "matern", sp.par = c(2, 1), smoothness = 1,
finescale = 0, error = 0.5, pcoords = acoords)
# set values of regression coefficients
coeff <- matrix(c(1, 2, 3), nrow = 1)
```

```
# generate data with error
y <- rmvnorm(nsim = 1, mu = tcrossprod(X, coeff), V = C3$V) + rnorm(50, sd = sqrt(.5))
# use universal kriging to make predictions. Do not do
# conditional simulation
krige.obj <- krige.uk(as.vector(y), V = C3$V, Vp = C3$Vp, Vop = C3$Vop,
X = X, Xp = Xa, nsim = 0)
#Do kriging with conditional simulation
krige.obj2 <- krige.uk(as.vector(y), V = C3$V, Vp = C3$Vp, Vop = C3$Vop,
X = X, Xp = Xa, nsim = 100,
Ve.diag = rep(.5, 50), method = "eigen")
```

maxlik.cov.sp Determines maximum likelihood estimates of covariance parameters

## Description

Estimates covariance parameters of spatial covariance functions using maximum likelihood or restricted maximum likelihood. See cov. sp for more details of covariance functions to be estimated.

## Usage

```
maxlik.cov.sp(X, y, coords, sp.type = "exponential",
        range.par = stop("specify range.par argument"),
        error.ratio = stop("specify error.ratio argument"),
        smoothness = 0.5,
        D = NULL, reml = TRUE, lower = NULL, upper = NULL,
        control = list(trace = TRUE), optimizer="nlminb")
```


## Arguments

| X | A numeric matrix of size $n \times k$ containing the design matrix of the data locations. |
| :--- | :--- |
| y | A vector of length $n$ containing the observed responses. |
| coords | A numeric matrix of size $n \times d$ containing the locations of the observed re- <br> sponses. |
| sp. type | A character vector specifying the spatial covariance type. Valid types are cur- <br> rently exponential, gaussian, matern, and spherical. |
| range.par | An initial guess for the spatial dependence parameter. |
| error.ratio | A value non-negative value indicating the ratio error. var/sp. par[1]. |
| smoothness | A positive number indicating the smoothness of the matern covariance function, <br> if applicable. |
| D | The Euclidean distance matrix for the coords matrix. Must be of size $n \times n$. |
| reml | A boolean value indicating whether restricted maximum likelihood estimation <br> should be used. Defaults to TRUE. |

$\begin{array}{ll}\text { lower } & \begin{array}{l}\text { A vector giving lower bounds for the covariance parameters sp.par[2], error.ratio, } \\ \text { and smoothness (when the model is matern). Order matters! If not given de- } \\ \text { faults to an upper bound of Inf for sp.par[2], 1 for error. ratio, and } 10 \text { for } \\ \text { smoothness. }\end{array} \\ \text { upper } & \begin{array}{l}\text { A vector giving upper bounds for the covariance parameters sp.par[2], error. ratio, } \\ \text { and smoothness (when the model is matern). Order matters! If not given de- } \\ \text { faults to an upper bound of Inf for sp.par[2], 1 for error.ratio, and } 10 \text { for } \\ \text { smoothness. }\end{array} \\ \text { control } & \begin{array}{l}\text { A list giving tuning parameters for the nlminb function. See nlminb for more } \\ \text { details. }\end{array} \\ \text { optimizer } & \begin{array}{l}\text { A vector describing the optimization function to use for the optimization. Cur- } \\ \text { rently, only nlminb is an acceptable value. }\end{array}\end{array}$

## Details

When doing the numerical optimizaiton, the covariance function is reparameterized slightly to speedup computation. Specifically, the variance parameter for the process of interest,sp.par[1], is profiled out, and the error.var parameter is parameterized as sp.par[1] * error.ratio, where error.ratio = error.var/sp.par[1].

## Value

Returns a list with the following elements:

| sp.type | The covariance form used. |
| :--- | :--- |
| sp.par | A vector containing the estimated variance of the hidden process and the spatial <br> dependence. |
| error.var | The estimated error variance. |
| smoothness | The smoothness of the matern covariance function. <br> par |
| The final values of the optimization parameters. Note that these will not neces- <br> sarily match sp. par, error.var, and smoothness because of the reparameter- <br> ization. |  |
| message | Convergence message from nlminb. |
| iterations | Message from nlminb. |
| evaluations | Evaluations from nlminb. |

## Author(s)

Joshua French

## See Also

```
cov.st
```


## Examples

```
#generate 20 random (x, y) coordinates
coords <- matrix(rnorm(20), ncol = 2)
#create design matrix
X <- cbind(1, coords)
#create mean for observed data to be generated
mu <- X %*% c(1, 2, 3)
#generate covariance matrix
V <- exp(-dist1 (coords))
#generate observe data
y <- rmvnorm(mu = mu, V = V)
#find maximum likelihood estimates of covariance parameters
maxlik.cov.sp(X = X, y = y, coords = coords,
    sp.type = "exponential", range.par = 1, error.ratio = 0,
    reml = TRUE)
```

maxlik.cov.st Determines maximum likelihood estimates of covariance parameters

## Description

Estimates covariance parameters of spatio-temporal covariance functions using maximum likelihood or restricted maximum likelihood. See cov.st for more details of covariance functions to be estimated. The covariance function is reparameterized slightly to speedup computation. Specifically, the variance parameter for the hidden process, sp.par[1], is profiled out and the error.var parameter is parameterized as sp.par[1] * error.ratio.

## Usage

```
maxlik.cov.st(X, y, coords, time, sp.type = "exponential",
    range.par = stop("specify range.par argument"),
    error.ratio = stop("specify error.ratio argument"),
    smoothness = 0.5, t.type = "ar1", t.par = .5, D = NULL, T = NULL,
    reml = TRUE, lower = NULL, upper = NULL, control = list(trace = TRUE),
    optimizer="nlminb")
```


## Arguments

$X \quad$ A numeric matrix of size $n \times k$ containing the design matrix of the data locations.
$y \quad$ A vector of length $n$ containing the observed responses.
coords A numeric matrix of size $n \times d$ containing the locations of the observed responses.

| time | A numeric vector of length n containing the time at which the responses were observed. |
| :---: | :---: |
| sp.type | A character vector specifying the spatial covariance type. Valid types are currently exponential, gaussian, matern, and spherical. |
| range.par | An initial guess for the spatial dependence parameter. |
| error.ratio | A value non-negative value indicating the ratio error.var/sp.par[1]. |
| smoothness | A positive number indicating the variance of the error term. |
| t.type | A character vector indicating the spatial covariance type. Only ar1 is currently available. |
| t.par | A value specifying the temporal dependence parameter of the ar1 process. |
| D | The Euclidean distance matrix for the coords matrix. Must be of size $n \times n$. |
| T | The Euclidean distance matrix for the time matrix. Must be of size $n \times n$. |
| reml | A boolean value indicating whether restricted maximum likelihood estimation should be used. Defaults to TRUE. |
| lower | A vector giving lower bounds for the covariance parameters sp.par[2], error.ratio, and smoothness (when the model is matern). Order matters! If not given defaults to a lower bound of .001 for sp.par[2], 0 for error. ratio, and .001 for smoothness. |
| upper | A vector giving upper bounds for the covariance parameters sp. par[2], error.ratio, and smoothness (when the model is matern). Order matters! If not given defaults to an upper bound of $\operatorname{Inf}$ for sp.par[2], 1 for error.ratio, and 10 for smoothness. |
| control | A list giving tuning parameters for the nlminb function. See nlminb for more details. |
| optimizer | A vector describing the optimization function to use for the optimization. Currently, only nlminb is an acceptable value. |

## Details

When doing the numerical optimization, the covariance function is reparameterized slightly to speedup computation. Specifically, the variance parameter for the process of interest,sp.par[1], is profiled out, and the error.var parameter is parameterized as sp.par[1] * error.ratio, where error.ratio $=$ error.var/sp.par[1].

## Value

Returns a list with the following elements:
sp.type The covariance form used.
sp.par A vector containing the estimated variance of the hidden process and the spatial dependence.
error.var The estimated error variance.
smoothness
The smoothness of the matern covariance function.

| par | The final values of the optimization parameters. Note that these will not neces- <br> sarily match sp.par, error.var, and smoothness because of the reparameter- <br> ization. |
| :--- | :--- |
| convergence | Convergence message from nlminb. |
| message | Message from nlminb. |
| iterations | Number of iterations for optimization to converge. |
| evaluations | Evaluations from nlminb. |

## Author(s)

Joshua French

## See Also

> cov.st

## Examples

```
#Generate locations and observed times
coords <- matrix(rnorm(40), ncol = 2)
time <- rep(1:2, each = 10)
#Calculate distance matrix for time vector
T <- dist1(matrix(time))
#create design matrix
X <- cbind(1, coords)
#create mean for observed data to be generated
mu <- X %*% c(1, 2, 3)
#generate covariance matrix for spatio-temporal data
V <- exp(-dist1(coords)) * . 25^`
#generate observe data
y <- rmvnorm(mu = mu, V = V)
maxlik.cov.st(X = X, y = y, coords = coords, time = time,
    sp.type = "exponential", range.par = 1, error.ratio = 0,
    t.type = "ar1", t.par = .5, reml = TRUE)
```

    plot.contourLines Plot contour lines
    
## Description

Plot contour lines from list produced by contourLines function.

## Usage

```
## S3 method for class 'contourLines'
plot(x, begin=1, end = length(x), add = FALSE, ...)
```


## Arguments

x
begin Beginning position in list of contour lines you want to plot.
end Ending position in list of contour lines you want to plot.
add A boolean value indicating whether the contour lines should be added to an existing plot (add $=$ TRUE $)$ or should be plotted on a new plot (add = FALSE).
... Additional arguments that will be passed to the plot or lines function.

## Value

This function does not return anything; it only creates a new plot or modifies an existing plot.

## Author(s)

Joshua French

## Examples

```
data(volcano)
x <- 10*1:nrow(volcano)
y <- 10*1:ncol(volcano)
cL <- contourLines(x, y, volcano)
plot.contourLines(cL)
```

rcondnorm Generate from conditional normal distribution

## Description

Generates realizations from a multivariate normal distribution conditional on observed data vector

## Usage

rcondnorm(nsim = 1, y, mu, mup, V, Vp, Vop, method = "eigen")

## Arguments

nsim An integer indicating the number of realizations from the distribution.
y
mu A vector of length $n$ contained the observed data.
The mean vector of the observed data. Should be a vector of length $n$.
mup $\quad$ The mean vector of the responses to be generated. Should be a vector of length np.

V
The covariance matrix of the observed data. The matrix should be symmetric and positive definite. The size must be ntimesn.
Vp The covariance matrix of the responses to be generated. The matrix should be symmetric and positive definite. The size must be nptimesnp.

Vop The cross-covariance matrix between the observed data and the responses to be generated. The size must be ntimesnp.
method The method for performing a decomposition of the covariance matrix. Possible values are "eigen", "chol", and "svd", Eigen value decomposition, Cholesky decomposition, or Singular Value Decomposoition, respectively.

## Value

An $n p \times n s i m$ matrix containing the nsim realizations of the conditional normal distribution. Each column of the matrix represents a realization of the multivariate normal distribution.

## Author(s)

Joshua French

## See Also

rmvnorm

## Examples

```
n <- 100
np <- 100
mu <- rep(1, 100)
mup <- rep(2, 100)
coords <- matrix(runif(2 * n), ncol = 2)
pcoords <- matrix(runif(2 * np), ncol = 2)
myV <- cov.sp(coords, sp.type = "exponential", c(1, 2), error.var = 1, pcoords = pcoords)
y <- rmvnorm(1, mu = mu, V = myV$V)
rcondnorm(3, y = y, mu = mu, mup = mup, V = myV$V, Vp = myV$Vp, Vop = myV$Vop, method = "chol")
```


## rmvnorm Generates realizations from a multivariate normal distribution

## Description

Generates realizations from a multivariate normal distribution.

## Usage

rmvnorm(nsim $=1$, mu, V, method = "eigen")

## Arguments

nsim
mu A vector of length $n$ containing the mean values of the multivariate normal distribution.

V The covariance matrix of the multivariate normal distribution. The matrix should be symmetric and positive definite. The size must be ntimesn.
method The method for performing a decomposition of the covariance matrix. Possible values are "eigen", "chol", and "svd", Eigen value decomposition, Cholesky decomposition, or Singular Value Decomposoition, respectively.

## Value

An $n \times n$ sim matrix containing the nsim realizations of the multivariate normal distribution. Each column of the matrix represents a realization of the multivariate normal distribution.

## Author(s)

Joshua French

## See Also

rmvnorm

## Examples

```
n <- 20
mu <- 1:n
V <- exp(-dist1(matrix(rnorm(n))))
rmvnorm(nsim = 100, mu = mu, V = V, method = "eigen")
```


## Description

Calculates a spatial covariance using a (Euclidean) distance matrix D. Not intended to be used directly by user (though it may be helpful to some). It is strongly recommended that you use the cov. sp function. No argument or error checking is provided for this function.

## Usage

simple.cov.sp(D, sp.type, sp.par, error.var, smoothness, finescale.var)

## Arguments

D
sp.type A character vector specifying the spatial covariance type. Valid types are currently exponential, gaussian, matern, and spherical.
sp.par A vector of length 2 specifying the scale and dependence of the covariance function. The first element refers to the variance of the hidden process (sometimes this is called the partial sill) while the second elements determines the strength of dependence between locations.
error.var A non-negative number indicating the variance of the error term.
smoothness A positive number indicating the variance of the error term.
finescale.var A non-negative positive number indicating the finescale variability. The is also called the microscale variance

## Value

Returns a covariance matrix.

## Author(s)

Joshua French

## See Also

~ cov.sp

## Examples

```
coords <- matrix(rnorm(30), ncol = 3)
D <- dist1(coords)
simple.cov.sp(D = D, sp.type = "exponential", sp.par = c(2, 1),
error.var = 1, smoothness = 0.5, finescale.var = 0)
```


## Description

Calculates a temporal covariance using a (Euclidean) distance matrix T. Not intended to be used directly by user (though it may be helpful to some). It is used in the covets function. No argument or error checking is provided for this function.

## Usage

simple.cov.time(T, t.type, t.par)

## Arguments

T
t.type
t.par A vector of length 1 specifying the strength of dependence of the covariance function.

## Value

Returns a covariance matrix.

## Author(s)

Joshua French

## See Also

~cov.st

## Examples

```
T <- dist1(matrix(1:10))
simple.cov.time(T = T, t.type = "ar1", t.par = .5)
```

```
spLMPredictJoint
```


## Description

The function spLMPredictJoint collects posterior predictive samples for a set of new locations given a spLM object from the spBayes package.

## Usage

```
spLMPredictJoint(sp.obj, pred.coords, pred.covars, start = 1,
    end = nrow(sp.obj$p.theta.samples), thin = 1, verbose = TRUE, n.report = 100,
    noisy = FALSE, method = "eigen")
```


## Arguments

sp.obj An spLM object returned by the spLM function in the spBayes package.
pred.coords An $n p \times 2$ matrix of $n p$ prediction location coordinates in $R^{2}$ (e.g., easting and northing). The first column is assumed to be easting coordinates and the second column northing coordinates.
pred.covars An $n \times p$ matrix of covariates matrix associated with the new locations.
start Specifies the first sample included in the composition sampling.
end Specifies the last sample included in the composition. The default is to use all posterior samples in sp.obj.
thin A sample thinning factor. The default of 1 considers all samples between start and end. For example, if thin $=10$ then 1 in 10 samples are considered between start and end.
verbose If TRUE, model specification and progress of the sampler is printed to the screen. Otherwise, nothing is printed to the screen.
n.report The interval to report sampling progress.
noisy If TRUE, then the posterior sample for the response is for the signal + error noise. The default, FALSE, assumes the user wants the error-free process.
method Method used to decompose covariance matrix. Options are "chol", "eigen", and "svd" for the Cholesky, Eigen, and singular value decomposition approaches, respectively.

## Details

This function samples from the joint posterior predictive distribution of a Bayesian spatial linear model. Specifically, it is intended to be similar to the spPredict function in the spBayes except that it samples from the joint distribution instead of the marginal distribution. However, it will only work for spLM objects and should have the same limitations as the spLM and spPredict functions. Note that the spRecover function is called internally to recover the posterior samples form the posterior distribution of the spatial model.

## Value

The function returns a $n p \times B$ matrix of posterior predictive samples, where B is the number of posterior samples. The class is jointPredicitveSample.

## Author(s)

Joshua French

## See Also

spLM, spPredict, spRecover

## Examples

```
# Set parameters
n <- 100
np <- 12
n.samples <- 10
burnin.start <- .5 * n.samples + 1
sigmasq <- 1
tausq <- 0.0
phi <- 1
cov.model <- "exponential"
n.report <- 5
# Generate coordinates
coords <- matrix(runif(2 * n), ncol = 2);
pcoords <- as.matrix(expand.grid(seq(0, 1, len = 12), seq(0, 1, len = 12)))
# Construct design matrices
X <- as.matrix(cbind(1, coords))
Xp <- cbind(1, pcoords)
# Specify priors
starting <- list("phi" = phi, "sigma.sq"= sigmasq, "tau.sq" = tausq)
tuning <- list("phi"=0.1, "sigma.sq"=0.1, "tau.sq"=0.1)
priors.1 <- list("beta.Norm"=list(c(1, 2, 1), diag(100, 3)),
                                    "phi.Unif"=c(0.00001, 10), "sigma.sq.IG"=c(1, 1))
# Generate data
B <- rnorm(3, c(1, 2, 1), sd = 10)
phi <- runif(1, 0, 10)
sigmasq <- 1/rgamma(1, 1, 1)
V <- simple.cov.sp(D = dist1(coords), cov.model, c(sigmasq, 1/phi), error.var = tausq,
smoothness = nu, finescale.var = 0)
y <- X %*% B + rmvnorm(1, rep(0, n), V) + rnorm(n, 0, sqrt(tausq))
# Create spLM object
library(spBayes)
m1 <- spBayes::spLM(y ~ X - 1, coords = coords, starting = starting,
tuning = tuning, priors = priors.1, cov.model = cov.model,
n.samples = n.samples, verbose = FALSE, n.report = n.report)
```

```
# Sample from joint posterior predictive distribution
y1 <- spLMPredictJoint(m1, pred.coords = pcoords, pred.covars = Xp,
start = burnin.start, verbose = FALSE, method = "chol")
```

toydata

A toy data set for use in examples.

## Description

A list containing X , a $50 \times 3$ design matrix, y , a vector of length 50 of observed responses, V , a 50 x 50 covariance matrix for the observed data, Xp , a $121 \times 3$ design matrix for the predicted responses, Vp , the $121 \times 121$ covariance matrix of the predicted responses, Vop, the $50 \times 121$ covariance matrix between the observed responses and the predicted responses, coords, a $50 \times 2$ matrix containing the sites of the 50 observed responses, and pcoords, a $121 \times 2$ matrix containing the 121 sites for the predicted responses (a $11 \times 11$ regular grid over the domain $[0,1] \times[0,1]$ ).

## Usage

data(toydata)

## Author(s)

Joshua French

## Examples

data(toydata)

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