# Package 'castor' 

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lions of tips. Functions include pruning, rerooting, calculation of most-recent common ances-tors, calculating distances from the tree root and calculating pairwise distances. Calcula-tion of phylogenetic signal and mean trait depth (trait conservatism), ancestral state reconstruc-tion and hidden character prediction of discrete characters, simulating and fitting mod-els of trait evolution, fitting and simulating diversification models, dating trees, compar-ing trees, and reading/writing trees in Newick format. Citation: Louca, Stilianos and Doe-beli, Michael (2017) [doi:10.1093/bioinformatics/btx701](doi:10.1093/bioinformatics/btx701).
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castor-package Efficient computations on large phylogenetic trees.

## Description

This package provides efficient tree manipulation functions including pruning, rerooting, calculation of most-recent common ancestors, calculating distances from the tree root and calculating pairwise distance matrices. Calculation of phylogenetic signal and mean trait depth (trait conservatism). Efficient ancestral state reconstruction and hidden character prediction of discrete characters on phylogenetic trees, using Maximum Likelihood and Maximum Parsimony methods. Simulating models of trait evolution, and generating random trees.

## Details

The most important data unit is a phylogenetic tree of class "phylo", with the tree topology encoded in the member variable tree. edge. See the ape package manual for details on the "phylo" format. The castor package was designed to be efficient for large phylogenetic trees ( $>10,000 \mathrm{tips}$ ), and scales well to trees with millions of tips. Most functions have asymptotically linear time complexity $\mathrm{O}(\mathrm{N})$ in the number of edges N . This efficiency is achived via temporary auxiliary data structures, use of dynamic programing, heavy use of C++, and integer-based indexing instead of name-based indexing of arrays. All functions support trees that include monofurcations (nodes with a single child) as well as multifurcations (nodes with more than 2 children). See the associated paper by Louca et al. for a comparison with other packages.

Throughout this manual, "Ntips" refers to the number of tips, "Nnodes" to the number of nodes and "Nedges" to the number of edges in a tree. In the context of discrete trait evolution/reconstruction, "Nstates" refers to the number of possible states of the trait. In the context of multivariate trait evolution, "Ntraits" refers to the number of traits.

## Author(s)

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## References

S. Louca and M. Doebeli (2017). Efficient comparative phylogenetics on large trees. Bioinformatics. DOI:10.1093/bioinformatics/btx701

```
asr_empirical_probabilities
    Empirical ancestral state probabilities.
```


## Description

Given a rooted phylogenetic tree and the states of a discrete trait for each tip, calculate the empirical state frequencies/probabilities for each node in the tree, i.e. the frequencies/probabilities of states across all tips descending from that node. This may be used as a very crude estimate of ancestral state probabilities.

## Usage

asr_empirical_probabilities(tree, tip_states, Nstates=NULL, probabilities=TRUE, check_input=TRUE)

## Arguments

tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
tip_states An integer vector of size Ntips, specifying the state of each tip in the tree as an integer from 1 to Nstates, where Nstates is the possible number of states (see below).
Nstates Either NULL, or an integer specifying the number of possible states of the trait. If NULL, then it will be computed based on the maximum value encountered in tip_states
probabilities Logical, specifying whether empirical frequencies should be normalized to represent probabilities. If FALSE, then the raw occurrence counts are returned.
check_input Logical, specifying whether to perform some basic checks on the validity of the input data. If you are certain that your input data are valid, you can set this to FALSE to reduce computation.

## Details

For this function, the trait's states must be represented by integers within $1, .$, ,Nstates, where Nstates is the total number of possible states. If the states are originally in some other format (e.g., characters or factors), you should map them to a set of integers $1, .$. ,Nstates. You can easily map any set of discrete states to integers using the function map_to_state_space.
The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child). The function has asymptotic time complexity O (Nedges x Nstates).
Tips must be represented in tip_states in the same order as in tree\$tip.label. The vector tip_states need not include names; if it does, however, they are checked for consistency (if check_input==TRUE).

## Value

A list with the following elements:

```
ancestral_likelihoods
```

A 2D integer (if probabilities==FALSE) or numeric (if probabilities==TRUE) matrix, listing the frequency or probability of each state for each node. This matrix will have size Nnodes x Nstates, where Nstates was either explicitly provided as an argument or inferred from tip_states. The rows in this matrix will be in the order in which nodes are indexed in the tree, i.e. the [ $\mathrm{n}, \mathrm{s}$ ]-th entry will be the frequency or probability of the s-th state for the $n$-th node. Note that the name was chosen for compatibility with other ASR functions.

## Author(s)

Stilianos Louca

## See Also

```
asr_max_parsimony, asr_squared_change_parsimony asr_mk_model, map_to_state_space
```


## Examples

```
## Not run:
# generate a random tree
Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)$tree
# create a random transition matrix
Nstates = 3
Q = get_random_mk_transition_matrix(Nstates, rate_model="ER", max_rate=0.01)
cat(sprintf("Simulated ER transition rate=%g\n",Q[1,2]))
# simulate the trait's evolution
simulation = simulate_mk_model(tree, Q)
tip_states = simulation$tip_states
# calculate empirical probabilities of tip states
```

    asr_empirical_probabilities(tree, tip_states=tip_states, Nstates=Nstates)
    \#\# End(Not run)
    asr_independent_contrasts

Ancestral state reconstruction via phylogenetic independent contrasts.

## Description

Reconstruct ancestral states for a continuous (numeric) trait using phylogenetic independent contrasts (PIC; Felsenstein, 1985).

## Usage

asr_independent_contrasts(tree,
tip_states,
weighted = TRUE,
include_CI = FALSE,
check_input = TRUE)

## Arguments

tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
tip_states A numeric vector of size Ntips, specifying the known state of each tip in the tree.
weighted Logical, specifying whether to weight tips and nodes by the inverse length of their incoming edge, as in the original method by Felsenstein (1985). If FALSE, edge lengths are treated as if they were 1.
include_CI Logical, specifying whether to also calculate standard errors and confidence intervals for the reconstructed states under a Brownian motion model, as described by Garland et al (1999).
check_input Logical, specifying whether to perform some basic checks on the validity of the input data. If you are certain that your input data are valid, you can set this to FALSE to reduce computation.

## Details

The function traverses the tree in postorder (tips->root) and estimates the state of each node as a convex combination of the estimated states of its chilren. These estimates are the intermediate "X" variables introduced by Felsenstein (1985) in his phylogenetic independent contrasts method. For the root, this yields the same globally parsimonious state as the squared-changes parsimony algorithm implemented in asr_squared_change_parsimony (Maddison 1991). For any other node, PIC only yields locally parsimonious reconstructions, i.e. reconstructed states only depend on the subtree descending from the node (see discussion by Maddison 1991).

If weighted==TRUE, then this function yields the same ancestral state reconstructions as
ape: :ace(phy=tree, x=tip_states, type="continuous", method="pic", model="BM", CI=FALSE)
in the ape package (v. 0.5-64). Note that in contrast to the CI95 returned by ape: : ace, the confidence intervals calculated here have the same units as the trait and depend both on the tree topology as well as the tip states.
If tree\$edge. length is missing, each edge in the tree is assumed to have length 1 . This is the same as setting weighted=FALSE. The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as mono-furcations (i.e. nodes with only one child). Edges with length 0 will be adjusted internally to some tiny length if needed (if weighted==TRUE).

Tips must be represented in tip_states in the same order as in tree\$tip.label. The vector tip_states need not include item names; if it does, however, they are checked for consistency (if check_input==TRUE). All tip states must be non-NA; otherwise, consider using one of the functions for hidden-state-prediction (e.g., hsp_independent_contrasts).
The function has asymptotic time complexity O (Nedges).

## Value

A list with the following elements:

```
ancestral_states
```

A numeric vector of size Nnodes, listing the reconstructed state of each node. The entries in this vector will be in the order in which nodes are indexed in the tree.
standard_errors
Numeric vector of size Nnodes, listing the phylogenetically estimated standard error for the state in each node, under a Brownian motion model. The standard errors have the same units as the trait and depend both on the tree topology as well as the tip states. Calculated as described by Garland et al. (1999, page 377). Only included if include_CI==TRUE.

CI95 Numeric vector of size Nnodes, listing the radius (half width) of the $95 \%$ confidence interval of the state in each node. Confidence intervals have same units as the trait and depend both on the tree topology as well as the tip states. For each node, the confidence interval is calculated according to the Student's tdistribution with Npics degrees of freedom, where Npics is the number of internally calculated independent contrasts descending from the node [Garland et al, 1999]. Only included if include_CI==TRUE.

## Author(s)

Stilianos Louca

## References

J. Felsenstein (1985). Phylogenies and the Comparative Method. The American Naturalist. 125:115.
W. P. Maddison (1991). Squared-change parsimony reconstructions of ancestral states for continuousvalued characters on a phylogenetic tree. Systematic Zoology. 40:304-314.
T. Garland Jr., P. E. Midford, A. R. Ives (1999). An introduction to phylogenetically based statistical methods, with a new method for confidence intervals on ancestral values. American Zoologist. 39:374-388.

## See Also

asr_squared_change_parsimony, asr_max_parsimony, asr_mk_model

## Examples

```
# generate random tree
Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)$tree
# simulate a continuous trait
tip_states = simulate_ou_model(tree, stationary_mean=0, spread=1, decay_rate=0.001)$tip_states
# reconstruct node states via weighted PIC
asr = asr_independent_contrasts(tree, tip_states, weighted=TRUE, include_CI=TRUE)
node_states = asr$ancestral_states
# get lower bounds of 95% CIs
lower_bounds = node_states - asr$CI95
```

asr_max_parsimony Maximum-parsimony ancestral state reconstruction.

## Description

Reconstruct ancestral states for a discrete trait using maximum parsimony. Transition costs can vary between transitions, and can optionally be weighted by edge length.

## Usage

asr_max_parsimony(tree, tip_states, Nstates=NULL, transition_costs="all_equal", edge_exponent=0, weight_by_scenarios=TRUE, check_input=TRUE)

## Arguments

tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
tip_states An integer vector of size Ntips, specifying the state of each tip in the tree as an integer from 1 to Nstates, where Nstates is the possible number of states (see below).

Nstates Either NULL, or an integer specifying the number of possible states of the trait. If NULL, then Nstates will be computed based on the maximum value encountered in tip_states

Either "all_equal","sequential", "proportional", "exponential", or a quadratic non-negatively valued matrix of size Nstates x Nstates, specifying the transition costs between all possible states (which can include 0 as well as Inf). The [r,c]th entry of the matrix is the cost of transitioning from state $r$ to state $c$. The option "all_equal" specifies that all transitions are permitted and are equally costly. "sequential" means that only transitions between adjacent states are permitted from a node to its children, and all permitted transitions are equally costly. "proportional" means that all transitions are permitted, but the cost increases proportional to the distance between states. "exponential" means that all transitions are permitted, but the cost increases exponentially with the distance between states. The options "sequential" and "proportional" only make sense if states exhibit an order relation (as reflected in their integer representation).
edge_exponent Non-negative real-valued number. Optional exponent for weighting transition costs by the inverse length of edge lengths. If 0 , edge lengths do not influence the ancestral state reconstruction (this is the conventional max-parsimony). If $>0$, then at each edge the transition costs are multiplied by $1 / L^{e}$, where $L$ is the edge length and $e$ is the edge exponent. This parameter is mostly experimental; modify at your own discretion.
weight_by_scenarios
Logical, indicating whether to weight each optimal state of a node by the number of optimal maximum-parsimony scenarios in which the node is in that state. If FALSE, then all optimal states of a node are weighted equally (i.e. are assigned equal probabilities).
check_input Logical, specifying whether to perform some basic checks on the validity of the input data. If you are certain that your input data are valid, you can set this to FALSE to reduce computation.

## Details

For this function, the trait's states must be represented by integers within 1,..,Nstates, where Nstates is the total number of possible states. If the states are originally in some other format (e.g. characters or factors), you should map them to a set of integers $1, . .$, Nstates. The order of states (if relevant) should be reflected in their integer representation. For example, if your original states are "small", "medium" and "large" and transition_costs=="sequential", it is advised to represent these states as integers $1,2,3$. You can easily map any set of discrete states to integers using the function map_to_state_space.
This function utilizes Sankoff's (1975) dynamic programming algorithm for determining the smallest number (or least costly if transition costs are uneven) of state changes along edges needed to reproduce the observed tip states. The function has asymptotic time complexity O (Ntips+Nnodes x Nstates).
If tree\$edge. length is missing, each edge in the tree is assumed to have length 1 . If edge_exponent is 0 , then edge lengths do not influence the result. If edge_exponent $!=0$, then all edges must have non-zero length. The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as mono-furcations (i.e. nodes with only one child).

Tips must be represented in tip_states in the same order as in tree\$tip.label. None of the input vectors or matrixes need include row or column names; if they do, however, they are checked for consistency (if check_input==TRUE).

This function is meant for reconstructing ancestral states in all nodes of a tree, when the state of each tip is known. If some of the tips have unknown state, consider either pruning the tree to keep only tips with known states, or using the function hsp_max_parsimony.
Not all datasets are consistent with all possible transition cost models, i.e., it could happen that for some peculiar datasets some rather constrained models (e.g. "sequential") cannot possibly produce the data. In this case, castor will most likely return non-sensical ancestral state estimates and total_cost=Inf, although this has not thoroughly been tested.

## Value

A list with the following elements:
success Boolean, indicating whether ASR was successful. If FALSE, the remaining returned elements may be undefined.
ancestral_likelihoods
A 2D numeric matrix, listing the probability of each node being in each state. This matrix will have size Nnodes x Nstates, where Nstates was either explicitly provided as an argument or inferred from tip_states. The rows in this matrix will be in the order in which nodes are indexed in the tree, i.e. the [ $\mathrm{n}, \mathrm{s}$ ]-th entry will be the probability of the s-th state for the n-th node. These probabilities are calculated based on scenario_counts (see below), assuming that every maximum parsimony scenario is equally likely. Note that the name was chosen for compatibility with other ASR functions.
scenario_counts
A 2D numeric matrix of size Nnodes x Nstates, listing for each node and each state the number of maximum parsimony scenarios in which the node was in the specific state. If only a single maximum parsimony scenario exists for the whole tree, then the sum of entries in each row will be one.
total_cost Real number, specifying the total transition cost across the tree for the most parsimonious scenario. In the classical case where transition_costs="all_equal", the total_cost equals the total number of state changes in the tree under the most parsimonious scenario. Under some constrained transition models (e.g., "sequential"), total_cost may sometimes be Inf, which basically means that the data violates the model.

## Author(s)

Stilianos Louca

## References

D. Sankoff (1975). Minimal mutation trees of sequences. SIAM Journal of Applied Mathematics. 28:35-42.
J. Felsenstein (2004). Inferring Phylogenies. Sinauer Associates, Sunderland, Massachusetts.

## See Also

hsp_max_parsimony, asr_squared_change_parsimony asr_mk_model, hsp_mk_model, map_to_state_space

## Examples

```
## Not run:
# generate random tree
Ntips = 10
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)$tree
# simulate a discrete trait
Nstates = 5
Q = get_random_mk_transition_matrix(Nstates, rate_model="ER")
tip_states = simulate_mk_model(tree, Q)$tip_states
# reconstruct node states via MPR
results = asr_max_parsimony(tree, tip_states, Nstates)
node_states = max.col(results$ancestral_likelihoods)
# print reconstructed node states
print(node_states)
## End(Not run)
```

asr_mk_model

Ancestral state reconstruction with Mk models and rerooting

## Description

Ancestral state reconstruction of a discrete trait using a fixed-rates continuous-time Markov model (a.k.a. "Mk model"). This function can estimate the (instantaneous) transition matrix using maximum likelihood, or take a specified transition matrix. The function can optionally calculate marginal ancestral state likelihoods for each node in the tree, using the rerooting method by Yang et al. (1995).

## Usage

## Arguments

tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
tip_states An integer vector of size Ntips, specifying the state of each tip in the tree in terms of an integer from 1 to Nstates, where Ntips is the number of tips and Nstates is the number of possible states (see below). Can also be NULL. If tip_states==NULL, then tip_priors must not be NULL (see below).
Nstates Either NULL, or an integer specifying the number of possible states of the trait. If Nstates==NULL, then it will be computed based on the maximum value encountered in tip_states or based on the number of columns in tip_priors (whichever is non-NULL).
tip_priors A 2D numeric matrix of size Ntips x Nstates, where Nstates is the possible number of states for the character modelled. Hence, tip_priors $[i, s]$ is the likelihood of the observed state of tip i, if the tip's true state was in state s. For example, if you know for certain that a tip is in state $k$, then set tip_priors $[i, s]=1$ for $s=k$ and tip_priors $[i, s]=0$ for all other $s$.
rate_model Rate model to be used for fitting the transition rate matrix. Can be "ER" (all rates equal), "SYM" (transition rate $\mathrm{i} \rightarrow \mathrm{j}$ is equal to transition rate $\mathrm{j}->\mathrm{i}$ ), "ARD" (all rates can be different), "SUEDE" (only stepwise transitions $i \rightarrow i+1$ and $i-$ $>i-1$ allowed, all 'up' transitions are equal, all 'down' transitions are equal) or "SRD" (only stepwise transitions $\mathrm{i}->\mathrm{i}+1$ and $\mathrm{i}->\mathrm{i}-1$ allowed, and each rate can be different). Can also be an index matrix that maps entries of the transition matrix to the corresponding independent rate parameter to be fitted. Diagonal entries should map to 0 , since diagonal entries are not treated as independent rate parameters but are calculated from the remaining entries in the transition matrix. All other entries that map to 0 represent a transition rate of zero. The format of this index matrix is similar to the format used by the ace function in the ape package. rate_model is only relevant if transition_matrix==NULL.
transition_matrix
Either a numeric quadratic matrix of size Nstates $x$ Nstates containing fixed transition rates, or NULL. The [r,c]-th entry in this matrix should store the transition rate from state $r$ to state $c$. Each row in this matrix must have sum zero. If NULL, then the transition rates will be estimated using maximum likelihood, based on the rate_model specified.
root_prior Prior probability distribution of the root's states, used to calculate the model's overall likelihood from the root's marginal ancestral state likelihoods. Can be "flat" (all states equal), "empirical" (empirical probability distribution of states across the tree's tips), "stationary" (stationary probability distribution of the transition matrix), "likelihoods" (use the root's state likelihoods as prior) or "max_likelihood" (put all weight onto the state with maximum likelihood). If "stationary" and transition_matrix==NULL, then a transition matrix is first fitted using a flat root prior, and then used to calculate the stationary distribution. root_prior can also be a non-negative numeric vector of size Nstates and with total sum equal to 1 .
include_ancestral_likelihoods
Include the marginal ancestral likelihoods for each node (conditional scaled state likelihoods) in the return values. Note that this may increase the com-

```
putation time and memory needed, so you may set this to FALSE if you don't need marginal ancestral states.
reroot Reroot tree at each node when computing marginal ancestral likelihoods, according to Yang et al. (1995). This is the default and recommended behavior, but leads to increased computation time. If FALSE, ancestral likelihoods at each node are computed solely based on the subtree descending from that node, without rerooting. Caution: Rerooting is strictly speaking only valid if the Mk model is time-reversible (for example, if the transition matrix is symmetric). Do not use the rerooting method if rate_model="ARD".
Ntrials Number of trials (starting points) for fitting the transition matrix. Only relevant if transition_matrix=NULL. A higher number may reduce the risk of landing in a local non-global optimum of the likelihood function, but will increase computation time during fitting.
```

```
optim_algorithm
```

optim_algorithm
Either "optim" or "nlminb", specifying which optimization algorithm to use for maximum-likelihood estimation of the transition matrix. Only relevant if transition_matrix==NULL.
optim_max_iterations
Maximum number of iterations (per fitting trial) allowed for optimizing the likelihood function.
optim_rel_tol Relative tolerance (stop criterion) for optimizing the likelihood function. store_exponentials
Logical, specifying whether to pre-calculate and store exponentials of the transition matrix during calculation of ancestral likelihoods. This may reduce computation time because each exponential is only calculated once, but requires more memory since all exponentials are stored.
Only relevant if include_ancestral_likelihoods==TRUE, otherwise exponentials are never stored.
check_input Logical, specifying whether to perform some basic checks on the validity of the input data. If you are certain that your input data are valid, you can set this to FALSE to reduce computation.
Nthreads Number of parallel threads to use for running multiple fitting trials simultaneously. This only makes sense if your computer has multiple cores/CPUs and if Ntrials>1, and is only relevant if transition_matrix==NULL. This option is ignored on Windows, because Windows does not support forking.

```

\section*{Details}

For this function, the trait's states must be represented by integers within 1,..,Nstates, where Nstates is the total number of possible states. If the states are originally in some other format (e.g. characters or factors), you should map them to a set of integers \(1, . .\), Nstates. The order of states (if relevant) should be reflected in their integer representation. For example, if your original states are "small", "medium" and "large" and rate_model=="SUEDE", it is advised to represent these states as integers \(1,2,3\). You can easily map any set of discrete states to integers using the function map_to_state_space.
This function allows the specification of the precise tip states (if these are known) using the vector tip_states. Alternatively, if some tip states are only known in terms of a probability distribution,
you can pass these probability distributions using the matrix tip_priors. Note that exactly one of the two arguments, tip_states or tip_priors, must be non-NULL.
Tips must be represented in tip_states or tip_priors in the same order as in tree\$tip.label. None of the input vectors or matrixes need include row or column names; if they do, however, they are checked for consistency (if check_input==TRUE).

The tree is either assumed to be complete (i.e. include all possible species), or to represent a random subset of species chosen independently of their states. The rerooting method by Yang et al (1995) is used to calculate the marginal ancestral state likelihoods for each node by treating the node as a root and calculating its conditional scaled likelihoods. Note that the re-rooting algorithm is strictly speaking only valid for reversible Mk models, that is, satisfying the criterion
\[
\pi_{i} Q_{i j}=\pi_{j} Q_{j i}, \quad \forall i, j
\]
where \(Q\) is the transition rate matrix and \(\pi\) is the stationary distribution of the model. The rate models "ER", 'SYM", "SUEDE" and "SRD" are reversible. For example, for "SUEDE" or "SRD" choose \(\pi_{i+1}=\pi_{i} Q_{i, i+1} / Q_{i+1, i}\). In contrast, "ARD" models are generally not reversible.
If tree\$edge.length is missing, each edge in the tree is assumed to have length 1 . The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as mono-furcations (i.e. nodes with only one child). This function is similar to rerootingMethod in the phytools package (v0.5-64) and similar to ape: :ace (v4.1) with options method="ML", type="discrete" and marginal=FALSE, but tends to be much faster than rerootingMethod and ace for large trees.
Internally, this function uses fit_mk to estimate the transition matrix if the latter is not provided. If you only care about estimating the transition matrix but not the ancestral states, consider using the more versatile function fit_mk.

\section*{Value}

A list with the following elements:
success Logical, indicating whether ASR was successful. If FALSE, all other return values may be NULL.
Nstates Integer, specifying the number of modeled trait states.
transition_matrix
A numeric quadratic matrix of size Nstates x Nstates, containing the transition rates of the Markov model. The [r,c]-th entry is the transition rate from state \(r\) to state c . Will be the same as the input transition_matrix, if the latter was not NULL.
loglikelihood Log-likelihood of the observed tip states under the fitted (or provided) Mk model. If transition_matrix was NULL in the input, then this will be the log-likelihood maximized during fitting.
AIC Numeric, the Akaike Information Criterion for the fitted Mk model (if applicable), defined as \(2 k-2 \log (L)\), where \(k\) is the number of independent fitted parameters and \(L\) is the maximized likelihood. If the transition matrix was provided as input, then no fitting was performed and hence AIC will be NULL.
ancestral_likelihoods
Optional, only returned if include_ancestral_likelihoods was TRUE. A 2D numeric matrix, listing the likelihood of each state at each node (marginal ancestral likelihoods). This matrix will have size Nnodes x Nstates, where Nstates
was either explicitly provided as an argument, or inferred from tip_states or tip_priors (whichever was non-NULL). The rows in this matrix will be in the order in which nodes are indexed in the tree, i.e. the [ \(\mathrm{n}, \mathrm{s}\) ]-th entry will be the likelihood of the s-th state at the n-th node. For example, likelihoods[1, 3] will store the likelihood of observing the tree's tip states (if reroot=TRUE) or the descending subtree's tip states (if reroot=FALSE), if the first node was in state 3. Note that likelihoods are rescaled (normalized) to sum to 1 for convenience and numerical stability. The marginal likelihoods at a node should not, however, be interpreted as a probability distribution among states.

\section*{Author(s)}

Stilianos Louca

\section*{References}
Z. Yang, S. Kumar and M. Nei (1995). A new method for inference of ancestral nucleotide and amino acid sequences. Genetics. 141:1641-1650.

\section*{See Also}
```

hsp_mk_model, asr_max_parsimony, asr_squared_change_parsimony, hsp_max_parsimony, map_to_state_space,
fit_mk

```

\section*{Examples}
```


## Not run:

# generate random tree

Ntips = 1000
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# create random transition matrix

Nstates = 5
Q = get_random_mk_transition_matrix(Nstates, rate_model="ER", max_rate=0.01)
cat(sprintf("Simulated ER transition rate=%g\n",Q[1,2]))

# simulate the trait's evolution

simulation = simulate_mk_model(tree, Q)
tip_states = simulation$tip_states
cat(sprintf("Simulated states for last 20 nodes:\n"))
print(tail(simulation$node_states,20))

# reconstruct node states from simulated tip states

# at each node, pick state with highest marginal likelihood

results = asr_mk_model(tree, tip_states, Nstates, rate_model="ER", Ntrials=2)
node_states = max.col(results\$ancestral_likelihoods)

# print Mk model fitting summary

cat(sprintf("Mk model: log-likelihood=%g\n",results$loglikelihood))
cat(sprintf("Fitted ER transition rate=%g\n",results$transition_matrix[1,2]))

```
\# print reconstructed node states for last 20 nodes
print(tail(node_states,20))
\#\# End(Not run)
asr_squared_change_parsimony
Squared-change parsimony ancestral state reconstruction.

\section*{Description}

Reconstruct ancestral states for a continuous (numeric) trait using squared-change maximum parsimony (Maddison, 1991). Transition costs can optionally be weighted by the inverse edge lengths ("weighted squared-change parsimony" by Maddison).

\section*{Usage}
asr_squared_change_parsimony(tree, tip_states, weighted=TRUE, check_input=TRUE)

\section*{Arguments}
\begin{tabular}{ll} 
tree & \begin{tabular}{l} 
A rooted tree of class "phylo". The root is assumed to be the unique node with \\
no incoming edge.
\end{tabular} \\
tip_states & \begin{tabular}{l} 
A numeric vector of size Ntips, specifying the known state of each tip in the \\
tree.
\end{tabular} \\
weighted & \begin{tabular}{l} 
Logical, specifying whether to weight transition costs by the inverted edge lengths. \\
This corresponds to the "weighted squared-change parsimony" reconstruction \\
by Maddison (1991) for a Brownian motion model of trait evolution.
\end{tabular} \\
check_input \(\quad\)\begin{tabular}{l} 
Logical, specifying whether to perform some basic checks on the validity of the \\
input data. If you are certain that your input data are valid, you can set this to \\
FALSE to reduce computation.
\end{tabular}
\end{tabular}

\section*{Details}

The function traverses the tree in postorder (tips->root) to calculate the quadratic parameters described by Maddison (1991) and obtain the globally parsimonious squared-change parsimony state for the root. The function then reroots at each node, updates all affected quadratic parameters in the tree and calculates the node's globally parsimonious squared-change parsimony state. The function has asymptotic time complexity O (Nedges).
If tree\$edge. length is missing, each edge in the tree is assumed to have length 1 . This is the same as setting weighted=FALSE. The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as mono-furcations (i.e. nodes with only one child). Edges with length 0 will be adjusted internally to some tiny length if needed (if weighted==TRUE).

Tips must be represented in tip_states in the same order as in tree\$tip.label. The vector tip_states need not include item names; if it does, however, they are checked for consistency (if check_input==TRUE).

If weighted==FALSE, then this function yields the same ancestral state reconstructions as
```

ape::ace(tip_states, tree,type="continuous",method="ML",model="BM",CI=FALSE)

```
in the ape package ( \(\mathrm{v} .0 .5-64\) ), assuming the tree as unit edge lengths. If weighted==TRUE, then this function yields the same ancestral state reconstructions as the maximum likelihood estimates under a Brownian motion model, as implemented by the Rphylopars package (v. 0.2.10):
```

Rphylopars::anc.recon(tip_states,tree,vars=FALSE,CI=FALSE).

```

\section*{Value}

A list with the following elements:
ancestral_states
A numeric vector of size Nnodes, listing the reconstructed state of each node. The entries in this vector will be in the order in which nodes are indexed in the tree.
total_sum_of_squared_changes
The total sum of squared changes, minimized by the (optionally weighted) squaredchange parsimony algorithm. This is equation 7 in (Maddison, 1991).

\section*{Author(s)}

Stilianos Louca

\section*{References}
W. P. Maddison (1991). Squared-change parsimony reconstructions of ancestral states for continuousvalued characters on a phylogenetic tree. Systematic Zoology. 40:304-314.

\section*{See Also}
asr_independent_contrasts asr_max_parsimony, asr_mk_model

\section*{Examples}
```


# generate random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# simulate a continuous trait

tip_states = simulate_ou_model(tree, stationary_mean=0, spread=1, decay_rate=0.001)\$tip_states

# reconstruct node states based on simulated tip states

node_states = asr_squared_change_parsimony(tree, tip_states, weighted=TRUE)\$ancestral_states

```
asr_subtree_averaging Ancestral state reconstruction via subtree averaging.

\section*{Description}

Reconstruct ancestral states in a phylogenetic tree for a continuous (numeric) trait by averaging trait values over descending subtrees. That is, for each node the reconstructed state is set to the arithmetic average state of all tips descending from that node.

\section*{Usage}
asr_subtree_averaging(tree, tip_states, check_input=TRUE)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
tip_states A numeric vector of size Ntips, specifying the known state of each tip in the tree.
check_input Logical, specifying whether to perform some basic checks on the validity of the input data. If you are certain that your input data are valid, you can set this to FALSE to reduce computation.

\section*{Details}

The function returns the estimated ancestral states (=averages) as well as the corresponding standard deviations. Note that reconstructed states are local estimates, i.e. they only take into account the tips descending from the reconstructed node.
The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child). Edge lengths and distances between tips and nodes are not taken into account. All tip states are assumed to be known, and NA or NaN are not allowed in tip_states.
Tips must be represented in tip_states in the same order as in tree\$tip.label. The vector tip_states need not include item names; if it does, however, they are checked for consistency (if check_input==TRUE).

\section*{Value}

A list with the following elements:
success Logical, indicating whether ASR was sucessful. If all input data are valid then this will always be TRUE, but it is provided for consistency with other ASR functions.
ancestral_states
A numeric vector of size Nnodes, listing the reconstructed state (=average over descending tips) for each node. The entries in this vector will be in the order in which nodes are indexed in the tree.
ancestral_stds A numeric vector of size Nnodes, listing the standard deviations corresponding to ancestral_stds.
ancestral_counts
A numeric vector of size Nnodes, listing the number of (descending) tips used to reconstruct the state of each node.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
asr_independent_contrasts, asr_squared_change_parsimony

\section*{Examples}
```


# generate random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# simulate a continuous trait

tip_states = simulate_ou_model(tree, stationary_mean=0, spread=1, decay_rate=0.001)\$tip_states

# reconstruct node states by averaging simulated tip states

node_states = asr_subtree_averaging(tree, tip_states)\$ancestral_states

```
```

collapse_monofurcations

```

\section*{Remove monofurcations from a tree.}

\section*{Description}

Eliminate monofurcations (nodes with only a single child) from a phylogenetic tree, by connecting their incoming and outgoing edge.

\section*{Usage}
collapse_monofurcations(tree, force_keep_root=TRUE, as_edge_counts=FALSE)

\section*{Arguments}
tree A rooted tree of class "phylo".
force_keep_root
Logical, indicating whether the root node should always be kept (i.e., even if it only has a single child).
as_edge_counts Logical, indicating whether all edges should be assumed to have length 1. If TRUE, the outcome is the same as if the tree had no edges.

\section*{Details}

All tips in the input tree retain their original indices, however the returned tree may include fewer nodes and edges. Edge and node indices may change.

If tree\$edge. length is missing, then all edges in the input tree are assumed to have length 1.

\section*{Value}

A list with the following elements:
tree A new tree of class "phylo", containing only bifurcations (and multifurcations, if these existed in the input tree). The number of nodes in this tree, Nnodes_new, may be lower than of the input tree.
new2old_node Integer vector of length Nnodes_new, mapping node indices in the new tree to node indices in the old tree.

Nnodes_removed Integer. Number of nodes (monofurcations) removed from the tree.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
multifurcations_to_bifurcations

\section*{Examples}
```


# generate a random tree

Ntips = 1000
tree = generate_random_tree(list(birth_rate_intercept=1), max_tips=Ntips)\$tree

# prune the tree to generate random monofurcations

random_tips = sample.int(n=Ntips, size=0.5 * Ntips, replace=FALSE)
tree = get_subtree_with_tips(tree, only_tips=random_tips, collapse_monofurcations=FALSE)\$subtree

# collapse monofurcations

new_tree = collapse_monofurcations(tree)\$tree

# print summary of old and new tree

cat(sprintf("Old tree has %d nodes\n",tree$Nnode))
cat(sprintf("New tree has %d nodes\n",new_tree$Nnode))

```
```

collapse_tree_at_resolution

```

Collapse nodes of a tree at a phylogenetic resolution.

\section*{Description}

Given a rooted tree and a phylogenetic resolution threshold, collapse all nodes whose distance to all descending tips does not exceed the threshold (or whose sum of descending edge lengths does not exceed the threshold), into new tips. This function can be used to obtain a "coarser" version of the tree, or to cluster closely related tips into a single tip.

\section*{Usage}
collapse_tree_at_resolution(tree,
\[
\text { resolution } \quad=0
\]
\[
\text { by_edge_count } \quad=\text { FALSE }
\]
\[
\text { shorten } \quad=\text { TRUE, }
\]
rename_collapsed_nodes = FALSE,
\[
\text { criterion } \quad=\text { 'max_tip_depth') }
\]

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
resolution Numeric, specifying the phylogenetic resolution at which to collapse the tree. This is the maximum distance a descending tip can have from a node, such that the node is collapsed into a new tip. If set to 0 (default), then only nodes whose descending tips are identical to the node will be collapsed.
by_edge_count Logical. Instead of considering edge lengths, consider edge counts as phylogenetic distance between nodes and tips. This is the same as if all edges had length equal to 1 .
shorten Logical, indicating whether collapsed nodes should be turned into tips at the same location (thus potentially shortening the tree). If FALSE, then the incoming edge of each collapsed node is extended by some length \(L\), where \(L\) is the distance of the node to its farthest descending tip (thus maintaining the height of the tree).
rename_collapsed_nodes
Logical, indicating whether collapsed nodes should be renamed using a representative tip name (the farthest descending tip). See details below.
criterion Character, specifying the criterion to use for collapsing (i.e. how to interpret resolution). 'max_tip_depth': Collapse nodes based on their maximum distance to any descending tip. 'sum_tip_paths': Collapse nodes based on the sum of descending edges (each edge counted once). 'max_tip_pair_dist': Collapse nodes based on the maximum distance between any pair of descending tips.

\section*{Details}

The tree is traversed from root to tips and nodes are collapsed into tips as soon as the criterion equals or falls below the resolution threshold.
The input tree may include multi-furcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child). Tip labels and uncollapsed node labels of the collapsed tree are inheritted from the original tree. If rename_collapsed_nodes==FALSE, then labels of collapsed nodes will be the node labels from the original tree (in this case the original tree should include node labels). If rename_collapsed_nodes==TRUE, each collapsed node is given the label of its farthest descending tip. If shorten==TRUE, then edge lengths are the same as in the original tree. If shorten==FALSE, then edges leading into collapsed nodes may be longer than before.

\section*{Value}

A list with the following elements:
```

tree A new rooted tree of class "phylo", containing the collapsed tree.
root_shift Numeric, indicating the phylogenetic distance between the old and the new root.
Will always be non-negative.
collapsed_nodes
Integer vector, listing indices of collapsed nodes in the original tree (subset of
1,..,Nnodes).
farthest_tips Integer vector of the same length as collapsed_nodes, listing indices of the
farthest tips for each collapsed node. Hence, farthest_tips[n] will be the in-
dex of a tip in the original tree that descended from node collapsed_nodes[n]
and had the greatest distance from that node among all descending tips.
new2old_clade Integer vector of length equal to the number of tips+nodes in the collapsed tree,
with values in 1,..,Ntips+Nnodes, mapping tip/node indices of the collapsed tree
to tip/node indices in the original tree.
new2old_edge Integer vector of length equal to the number of edges in the collapsed tree, with
values in 1,..,Nedges, mapping edge indices of the collapsed tree to edge indices
in the original tree.

```

\section*{Author(s)}

Stilianos Louca

\section*{Examples}
```


# generate a random tree

tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=1000)\$tree

# print number of nodes

cat(sprintf("Simulated tree has %d nodes\n",tree\$Nnode))

# collapse any nodes with tip-distances < 20

collapsed = collapse_tree_at_resolution(tree, resolution=20)\$tree

# print number of nodes

cat(sprintf("Collapsed tree has %d nodes\n",collapsed\$Nnode))

```
```

congruent_divergence_times

```

Extract dating anchors for a target tree, using a dated reference tree

\section*{Description}

Given a reference tree and a target tree, this function maps target nodes to concordant reference nodes when possible, and extracts divergence times of the mapped reference nodes from the reference tree. This function can be used to define secondary dating constraints for a larger target tree, based on a time-calibrated smaller reference tree (Eastman et al. 2013). This only makes sense if the reference tree is time-calibrated. A provided mapping specifies which and how tips in the target tree correspond to tips in the reference tree.

\section*{Usage}
congruent_divergence_times(reference_tree, target_tree, mapping)

\section*{Arguments}
reference_tree A rooted tree object of class "phylo". Usually this tree will be time-calibrated (i.e. edge lengths represent time intervals).
target_tree A rooted tree object of class "phylo".
mapping A table mapping a subset of target tips to a subset of reference tips, as described by Eastman et al (2013). Multiple target tips may map to the same reference tip, but not vice versa (i.e. every target tip can appear at most once in the mapping). In general, a tip mapped to in the reference tree is assumed to represent a monophyletic group of tips in the target tree, although this assumption may be violated in practice (Eastman et al. 2013).
The mapping must be in one of the following formats:
Option 1: A 2D integer array of size NM x 2 (with NM being the number of mapped target tips), listing target tip indices mapped to reference tip indices (mapping \([\mathrm{m}, 1]\) (target tip) \(\rightarrow\) mapping \([\mathrm{m}, 2]\) (reference tip)).
Option 2: A 2D character array of size NM x 2, listing target tip labels mapped to reference tip labels.
Option 3: A data frame of size NM x 1, whose row names are target tip labels and whose entries are either integers (reference tip indices) or characters (reference tip labels). This is the format used by geiger : :congruify.phylo (v.206).

Option 4: A vector of size NM, whose names are target tip labels and whose entries are either integers (reference tip indices) or characters (reference tip labels).

\section*{Details}

Both the reference and target tree may include monofurcations and/or multifurcations. In principle, neither of the two trees needs to be ultrametric, although in most applications reference_tree will be ultrametric.

In special cases each reference tip may be found in the target tree, i.e. the reference tree is a subtree of the target tree. This may occur e.g. if a smaller subtree of the target tree has been extracted and dated, and subsequently the larger target tree is to be dated using secondary constraints inferred from the dated subtree.

The function returns a table that maps a subset of target nodes to an equally sized subset of concordant reference nodes. Ages (divergence times) of the mapped reference nodes are extracted and associated with the concordant target nodes.

For bifurcating trees the average time complexity of this function is O (TNtips \(\times \log\) (RNtips) \(\times \mathrm{NM}\) ), where TNtips and RNtips are the number of tips in the target and reference tree, respectively. This function is similar to geiger : : congruify.phylo (v.206). For large trees, this function tends to be much faster than geiger: : congruify. phylo.

\section*{Value}

A named list with the following elements:
Rnodes Integer vector of length NC (where NC is the number of concordant node pairs found) and with values in \(1, . .\), RNnodes, listing indices of reference nodes that could be matched with (i.e. were concordant to) a target node. Entries in Rnodes will correspond to entries in Tnodes and ages.

Tnodes Integer vector of length NC and with values in \(1, . .\), TNnodes, listing indices of target nodes that could be matched with (i.e. were concordant to) a reference node. Entries in Tnodes will correspond to entries in Rnodes and ages.
ages \(\quad\) Numeric vector of length NC, listing divergence times (ages) of the reference nodes listed in Rnodes. These ages can be used as fixed anchors for timecalibrating the target tree using a separate program (such as PATHd8).

\section*{Author(s)}

Stilianos Louca

\section*{References}
J. M. Eastman, L. J. Harmon, D. C. Tank (2013). Congruification: support for time scaling large phylogenetic trees. Methods in Ecology and Evolution. 4:688-691.

\section*{See Also}

\section*{Examples}
```


# generate random tree (target tree)

Ntips = 10000
tree = castor::generate_random_tree(parameters=list(birth_rate_intercept=1), max_tips=Ntips)\$tree

# extract random subtree (reference tree)

Nsubtips = 10
subtips = sample.int(n=Ntips,size=Nsubtips,replace=FALSE)
subtreeing = castor::get_subtree_with_tips(tree, only_tips=subtips)
subtree = subtreeing\$subtree

# map subset of target tips to reference tips

mapping = matrix(c(subtreeing\$new2old_tip,(1:Nsubtips)),ncol=2,byrow=FALSE)

# extract divergence times by congruification

congruification = congruent_divergence_times(subtree, tree, mapping)
cat("Concordant target nodes:\n")
print(congruification$target_nodes)
cat("Ages of concordant nodes:\n")
print(congruification$ages)

```
congruent_hbds_model Generate a congruent homogenous-birth-death-sampling model.

\section*{Description}

Given a homogenous birth-death-sampling (HBDS) model (or abstract congruence class), obtain the congruent model (or member of the congruence class) with a specific speciation rate \(\lambda\), or extinction rate \(\mu\), or sampling rate \(\psi\), or effective reproduction ratio \(R_{e}\) or removal rate \(\mu+\psi\) (aka. "become uninfectious"" rate). All input and output time-profiles are specified as piecewise polynomial curves (splines), defined on a discrete grid of ages. This function allows exploration of a model's congruence class, by obtaining various members of the congruence class depending on the specified \(\lambda, \mu, \psi, R_{e}\) or removal rate. For more details on HBDS models and congruence classes see the documentation of simulate_deterministic_hbds.

\section*{Usage}
```

congruent_hbds_model(age_grid,
PSR,
PDR,
lambda_psi,
lambda = NULL,
mu = NULL,
psi = NULL,
Reff = NULL,
removal_rate = NULL,

```
\begin{tabular}{ll} 
lambda0 & \(=\) NULL, \\
CSA_ages & \(=\) NULL, \\
CSA_pulled_probs & \(=\) NULL, \\
CSA_PSRs & \(=\) NULL, \\
splines_degree & \(=1\), \\
ODE_relative_dt & \(=0.001\), \\
ODE_relative_dy & \(=1 e-4)\)
\end{tabular}

\section*{Arguments}
age_gri

PSR Numeric vector, of the same size as age grid, specifying the pulled speciation rate (PSR) (in units 1/time) at the ages listed in age_grid. The PSR is assumed to vary polynomially between grid points (see argument splines_degree). Can also be a single number, in which case PSR is assumed to be time-independent.
PDR
Numeric vector, listing discrete ages (time before present) on which the various model variables (e.g., \(\lambda, \mu\) etc) are specified. Listed ages must be strictly increasing, and must include the present-day (i.e. age 0 ).

Numeric vector, of the same size as age_grid, specifying the pulled diversification rate (PDR) (in units 1/time) at the ages listed in age_grid. The PDR is assumed to vary polynomially between grid points (see argument splines_degree). The PDR of a HBDS model is defined as \(P D R=\lambda-\mu-\psi+(1 / \lambda) d \lambda / d t\) (where \(t\) denotes age). Can also be a single number, in which case PDR is assumed to be time-independent.
lambda_psi
lambda
mu
psi
mu
pis
路
-
meric vector, of the same size as age_grid, specifying the extinction rate ( \(\mu\), in units \(1 /\) time) at the ages listed in age_grid. The extinction rate is assumed to vary polynomially between grid points (see argument splines_degree). Can also be a single number, in which case \(\mu\) is assumed to be time-independent. In an epidemiological context, \(\mu\) typically corresponds to the recovery rate plus the death rate of infected individuals. By providing \(\mu\) (together with lambda0, see below), one can select a specific model from the congruence class. Note that exactly one of lambda, mu, psi, Reff or removal_rate must be provided.
Numeric vector, of the same size as age_grid, specifying the (Poissonian) sampling rate ( \(\psi\), in units \(1 /\) time) at the ages listed in age_grid. The sampling rate is assumed to vary polynomially between grid points (see argument splines_degree). Can also be a single number, in which case \(\psi\) is assumed to be time-independent. By providing \(\psi\), one can select a specific model from the congruence class. Note that exactly one of lambda, mu, psi, Reff or removal_rate must be provided.
\begin{tabular}{|c|c|}
\hline Reff & Numeric vector, of the same size as age_grid, specifying the effective reproduction ratio ( \(R_{e}\), unitless) at the ages listed in age_grid. The \(R_{e}\) is assumed to vary polynomially between grid points (see argument splines_degree). Can also be a single number, in which case \(R_{e}\) is assumed to be time-independent. By providing \(R_{e}\) (together with lambda0, see below), one can select a specific model from the congruence class. Note that exactly one of lambda, mu, psi, Reff or removal_rate must be provided. \\
\hline removal_rate & Numeric vector, of the same size as age_grid, specifying the removal rate ( \(\mu+\) \(\psi\), in units \(1 /\) time) at the ages listed in age_grid. IN an epidemiological context this is also known as "become uninfectious" rate. The removal rate is assumed to vary polynomially between grid points (see argument splines_degree). Can also be a single number, in which case the removal rate is assumed to be timeindependent. By providing \(\mu+\psi\) (together with lambda0, see below), one can select a specific model from the congruence class. Note that exactly one of lambda, mu, psi, Reff or removal_rate must be provided. \\
\hline lambda0 & Numeric, specifying the speciation rate at the present-day (i.e., at age 0 ). Must be provided if and only if one of mu, Reff or removal_rate is provided. \\
\hline CSA_ages & Optional numeric vector, listing the ages of concentrated sampling attempts, in ascending order. Concentrated sampling is assumed to occur in addition to any continuous (Poissonian) sampling specified by psi. \\
\hline \multicolumn{2}{|l|}{CSA_pulled_probs} \\
\hline & Optional numeric vector of the same size as CSA_ages, listing pulled sampling probabilities at each concentrated sampling attempt (CSA). Note that in contrast to the sampling rates psi, the CSA_pulled_probs are interpreted as probabilities and must thus be between 0 and 1 . CSA_pulled_probs must be provided if and only if CSA_ages is provided. \\
\hline CSA_PSRs & Optional numeric vector of the same size as CSA_ages, specifying the pulled sampling rate (PSR) during each concentrated sampling attempt. While in principle the PSR is already provided by the argument PSR, the PSR may be noncontinuous at CSAs, which makes a representation as piecewise polynomial function difficult; hence, you must explicitly provide the correct PSR at each CSA. CSA_PSRs must be provided if and only if CSA_ages is provided. \\
\hline splines_degree & Integer, either \(0,1,2\) or 3 , specifying the polynomial degree of the provided time-dependent variables between grid points in age_grid. For example, if splines_degree \(==1\), then the provided PDR, PSR and so on are interpreted as piecewise-linear curves; if splines_degree==2 they are interpreted as quadratic splines; if splines_degree==3 they are interpreted as cubic splines. The splines_degree influences the analytical properties of the curve, e.g. splines_degree==1 guarantees a continuous curve, splines_degree==2 guarantees a continuous curve and continuous derivative, and so on. \\
\hline \multicolumn{2}{|l|}{ODE_relative_dt} \\
\hline & Positive unitless number, specifying the default relative time step for internally used ordinary differential equation solvers. Typical values are 0.01-0.001. \\
\hline \multicolumn{2}{|l|}{ODE_relative_dy} \\
\hline & Positive unitless number, specifying the relative difference between subsequent simulated and interpolated values, in internally used ODE solvers. Typical val- \\
\hline
\end{tabular}
ues are 1e-2 to 1e-5. A smaller ODE_relative_dy increases interpolation accuracy, but also increases memory requirements and adds runtime.

\section*{Details}

The PDR, PSR and the product \(\lambda \psi\) are variables that are invariant across the entire congruence class of an HBDS model, i.e. any two congruent models have the same PSR, PDR and product \(\lambda \psi\). Reciprocally, any HBDS congruence class is fully determined by its PDR, PSR and \(\lambda \psi\). This function thus allows "collapsing" a congruence class down to a single member (a specific HBDS model) by specifying one or more additional variables over time (such as \(\lambda\), or \(\psi\), or \(\mu\) and \(\lambda_{0}\) ). Alternatively, this function may be used to obtain alternative models that are congruent to some reference model, for example to explore the robustness of specific epidemiological quantities of interest. The function returns a specific HBDS model in terms of the time profiles of various variables (such as \(\lambda, \mu\) and \(\psi\) ).
In the current implementation it is assumed that any sampled lineages are immediately removed from the pool, that is, this function cannot accommodate models with a non-zero retention probability upon sampling. This is a common assumption in molecular epidemiology. Note that in this function age always refers to time before present, i.e., present day age is 0 , and age increases towards the root.

\section*{Value}

A named list with the following elements:
\begin{tabular}{|c|c|}
\hline success & Logical, indicating whether the calculation was successful. If FALSE, then the returned list includes an additional 'error' element (character) providing a description of the error; all other return variables may be undefined. \\
\hline valid & Logical, indicating whether the returned model appears to be biologically valid (for example, does not have negative \(\lambda, \mu\) or \(\psi\) ). In principle, a congruence class may include biologically invalid models, which might be returned depending on the input to congruent_hbds_model. Note that only biologically valid models can be subsequently simulated using simulate_deterministic_hbds. \\
\hline ages & Numeric vector of size NG, specifying the discrete ages (time before present) on which all returned time-curves are specified. Will always be equal to age_grid. \\
\hline lambda & Numeric vector of size NG, listing the speciation rates \(\lambda\) of the returned model at the ages given in ages[]. \\
\hline mu & Numeric vector of size NG, listing the extinction rates \(\mu\) of the returned model at the ages given in ages[]. \\
\hline psi & Numeric vector of size NG, listing the (Poissonian) sampling rates \(\psi\) of the returned model at the ages given in ages[]. \\
\hline lambda_psi & Numeric vector of size NG , listing the product \(\lambda \psi\) at the ages given in ages[]. \\
\hline Reff & Numeric vector of size NG, listing the effective reproduction ratio \(R_{e}\) of the returned model at the ages given in ages[]. \\
\hline removal_rate & Numeric vector of size NG, listing the removal rate \((\mu+\psi\), aka. "become uninfectious" rate) of the returned model at the ages given in ages[]. \\
\hline Pmissing & Numeric vector of size NG, listing the probability that a past lineage extant during ages[] will be missing from a tree generated by the model. \\
\hline
\end{tabular}

CSA_probs Numeric vector of the same size as CSA_ages, listing the sampling probabilities at each of the CSAs.
CSA_Pmissings Numeric vector of the same size as CSA_ages, listing the probability that a past lineage extant during each of CSA_ages[] will be missing from a tree generated by the model.

\section*{Author(s)}

Stilianos Louca

\section*{References}
T. Stadler, D. Kuehnert, S. Bonhoeffer, A. J. Drummond (2013). Birth-death skyline plot reveals temporal changes of epidemic spread in HIV and hepatitis C virus (HCV). PNAS. 110:228-233.
A. MacPherson, S. Louca, A. McLaughlin, J. B. Joy, M. W. Pennell (in review as of 2020). A general birth-death-sampling model for epidemiology and macroevolution. DOI:10.1101/2020.10.10.334383

\section*{See Also}
generate_tree_hbds, fit_hbds_model_parametric, simulate_deterministic_hbds

\section*{Examples}
```


# define an HBDS model with exponentially decreasing speciation/extinction rates

# and constant Poissonian sampling rate psi

oldest_age= 10
age_grid = seq(from=0,to=oldest_age,by=0.1) \# choose a sufficiently fine age grid
lambda = 1*exp(0.01*age_grid) \# define lambda on the age grid
mu = 0.2*lambda \# assume similarly shaped but smaller mu

# simulate deterministic HBD model

# scale LTT such that it is 100 at age 1

sim = simulate_deterministic_hbds(age_grid = age_grid,
lambda = lambda,
mu = mu,
psi = 0.1,
age0 = 1,
LTT0 = 100)

```
```


# calculate a congruent HBDS model with an alternative sampling rate

# use the previously simulated variables to define the congruence class

new_psi = 0.1*exp(-0.01*sim$ages) # consider a psi decreasing with age
congruent = congruent_hbds_model(age_grid = sim$ages,
PSR = sim$PSR,
    PDR = sim$PDR,
lambda_psi = sim\$lambda_psi,
psi = new_psi)

```
\# compare the deterministic LTT of the two models
\# to confirm that the models are indeed congruent
if(!congruent\$valid)\{
```

    cat("WARNING: Congruent model is not biologically valid\n")
    }else{
    # simulate the congruent model to get the LTT
    csim = simulate_deterministic_hbds(age_grid = congruent$ages,
                                    lambda = congruent$lambda,
    mu = congruent$mu,
    psi = congruent$psi,
    age0 = 1,
    LTT0 = 100)
    # plot deterministic LTT of the original and congruent model
    plot( x = sim$ages, y = sim$LTT, type='l',
        main='dLTT', xlab='age', ylab='lineages',
        xlim=c(oldest_age,0), col='red')
    lines(x= csim$ages, y=csim$LTT,
        type='p', pch=21, col='blue')
    }
    ```
consentrait_depth Calculate phylogenetic depth of a binary trait using the consenTRAIT metric.

\section*{Description}

Given a rooted phylogenetic tree and presences/absences of a binary trait for each tip, calculate the mean phylogenetic depth at which the trait is conserved across clades, in terms of the consenTRAIT metric introduced by Martiny et al (2013). This is the mean depth of clades that are positive in the trait (i.e. in which a sufficient fraction of tips exhibits the trait).

\section*{Usage}
\[
\begin{aligned}
& \text { consentrait_depth } \\
& \begin{aligned}
& \text { tree, } \\
& \text { tip_states, } \\
& \text { min_fraction } \\
& \text { count_singletons }=0.9, \\
&=\text { TRUE, } \\
& \text { singleton_resolution }=0, \\
& \text { weighted } \\
&=\text { FALSE, } \\
& \text { Npermutations }=0)
\end{aligned}
\end{aligned}
\]

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
tip_states A numeric vector of size Ntips indicating absence (value \(<=0\) ) or presence (value \(>0\) ) of a particular trait at each tip of the tree. Note that tip_states[i] (where i is an integer index) must correspond to the i-th tip in the tree.
min_fraction Minimum fraction of tips in a clade exhibiting the trait, for the clade to be considered "positive" in the trait. In the original paper by Martiny et al (2013), this was 0.9.
```

count_singletons

```

Logical, specifying whether to include singletons in the statistics (tips positive in the trait, but not part of a larger positive clade). The phylogenetic depth of singletons is taken to be half the length of their incoming edge, as proposed by Martiny et al (2013). If FALSE, singletons are ignored.
singleton_resolution
Numeric, specifying the phylogenetic resolution at which to resolve singletons. Any clade found to be positive in a trait will be considered a singleton if the distance of the clade's root to all descending tips is below this threshold.
weighted Whether to weight positive clades by their number of positive tips. If FALSE, each positive clades is weighted equally, as proposed by Martiny et al (2013).
Npermutations Number of random permutations for estimating the statistical significance of the mean trait depth. If zero (default), the statistical significance is not calculated.

\section*{Details}

This function calculates the "consenTRAIT" metric (or variants thereof) proposed by Martiny et al. (2013) for measuring the mean phylogenetic depth at which a binary trait (e.g. presence/absence of a particular metabolic function) is conserved across clades. A greater mean depth means that the trait tends to be conserved in deeper-rooting clades. In their original paper, Martiny et al. proposed to consider a trait as conserved in a clade (i.e. marking a clade as "positive" in the trait) if at least \(90 \%\) of the clade's tips exhibit the trait (i.e. are "positive" in the trait). This fraction can be controlled using the min_fraction parameter. The depth of a clade is taken as the average distance of its tips to the clade's root.
Note that the consenTRAIT metric does not treat "presence" and "absence" equally, i.e., if one were to reverse all presences and absences then the consenTRAIT metric will generally have a different value. This is because the focus is on the presence of the trait (e.g., presence of a metabolic function, or presence of a morphological feature).
The default parameters of this function reflect the original choices made by Martiny et al. (2013), however in some cases it may be sensible to adjust them. For example, if you suspect a high risk of false positives in the detection of a trait, it may be worth setting count_singletons to FALSE to avoid skewing the distribution of conservation depths towards shallower depths due to false positives.
The statistical significance of the calculated mean depth, i.e. the probability of encountering such a mean dept or higher by chance, is estimated based on a null model in which each tip is re-assigned a presence or absence of the trait by randomly reshuffling the original tip_states.
The tree may include multi-furcations as well as mono-furcations (i.e. nodes with only one child). If tree\$edge. length is missing, then every edge is assumed to have length 1.

\section*{Value}

A list with the following elements:
mean_depth Mean phylogenetic depth of clades that are positive in the trait.
var_depth Variance of phylogenetic depths of clades that are positive in the trait.
min_depth Minimum phylogenetic depth of clades that are positive in the trait.
max_depth Maximum phylogenetic depth of clades that are positive in the trait.

Npositives Number of clades that are positive in the trait.
P Statistical significance ( P -value) of mean_depth, under a null model of random trait presences/absences (see details above). This is the probability that, under the null model, the mean_depth would be at least as high as observed in the data.
mean_random_depth
Mean random mean_depth, under a null model of random trait presences/absences (see details above).
positive_clades
Integer vector, listing indices of tips and nodes (from 1 to Ntips+Nnodes) that were found to be positive in the trait and counted towards the statistic.
positives_per_clade
Integer vector of size Ntips+Nnodes, listing the number of descending tips per clade (tip or node) that were positive in the trait.
mean_depth_per_clade
Numeric vector of size Ntips+Nnodes, listing the mean phylogenetic depth of each clade (tip or node), i.e. the average distance to all its descending tips.

\section*{Author(s)}

Stilianos Louca

\section*{References}
A. C. Martiny, K. Treseder and G. Pusch (2013). Phylogenetic trait conservatism of functional traits in microorganisms. ISME Journal. 7:830-838.

\section*{See Also}
```

get_trait_acf, discrete_trait_depth

```

\section*{Examples}
```


## Not run:

# generate a random tree

tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=1000)\$tree

# simulate binary trait evolution on the tree

Q = get_random_mk_transition_matrix(Nstates=2, rate_model="ARD", max_rate=0.1)
tip_states = simulate_mk_model(tree, Q)\$tip_states

# change states from 1/2 to 0/1 (presence/absence)

tip_states = tip_states - 1

# calculate phylogenetic conservatism of trait

results = consentrait_depth(tree, tip_states, count_singletons=FALSE, weighted=TRUE)
cat(sprintf("Mean depth = %g, std = %g\n",results$mean_depth,sqrt(results$var_depth)))

## End(Not run)

```
```

count_lineages_through_time

```

Count number of lineages through time (LTT).

\section*{Description}

Given a rooted timetree (i.e., a tree whose edge lengths represent time intervals), calculate the number of lineages represented in the tree at various time points, otherwise known as "lineages through time"" (LTT) curve. The root is interpreted as time 0 , and the distance of any node or tip from the root is interpreted as time elapsed since the root. Optionally, the slopes and relative slopes of the LTT curve are also returned.

\section*{Usage}
\[
\begin{array}{rll}
\text { count_lineages_through_time( } & \\
& \text { tree, } & \\
\text { Ntimes } & =\text { NULL, } \\
& \text { min_time } & =\text { NULL, } \\
\text { max_time } & =N U L L, \\
& \text { times } & =\text { NULL, } \\
& \text { include_slopes } & =\text { FALSE, } \\
& \text { ultrametric } & =\text { FALSE, } \\
\text { degree } & =1, \\
\text { regular_grid } & =\text { TRUE })
\end{array}
\]

\section*{Arguments}
\begin{tabular}{ll} 
tree & \begin{tabular}{l} 
A rooted tree of class "phylo", where edge lengths represent time intervals (or \\
similar).
\end{tabular} \\
Ntimes & \begin{tabular}{l} 
Integer, number of equidistant time points at which to count lineages. Can also \\
be NULL, in which case times must be provided. \\
Minimum time (distance from root) to consider. If NULL, this will be set to the \\
minimum possible (i.e. 0). Only relevant if times==NULL. \\
min_time \\
Maximum time (distance from root) to consider. If NULL, this will be set to the \\
maximum possible. Only relevant if times==NULL.
\end{tabular} \\
max_time & \begin{tabular}{l} 
Integer vector, listing time points (in ascending order) at which to count lineages. \\
Can also be NULL, in which case Ntimes must be provided.
\end{tabular} \\
include_slopes & \begin{tabular}{l} 
Logical, specifying whether the slope and the relative slope of the returned \\
clades-per-time-point curve should also be returned.
\end{tabular} \\
ultrametric & \begin{tabular}{l} 
Logical, specifying whether the input tree is guaranteed to be ultrametric, even \\
in the presence of some numerical inaccuracies causing some tips not have ex- \\
actly the same distance from the root. If you know the tree is ultrametric, then \\
this option helps the function choose a better time grid for the LTT.
\end{tabular} \\
degree & \begin{tabular}{l} 
Integer, specifying the "degree" of the LTT curve: LTT(t) will be the number \\
of lineages in the tree at time t that have at least n descending tips in the tree.
\end{tabular} \\
Typically order=1, which corresponds to the classical LTT curve.
\end{tabular}
regular_grid Logical, specifying whether the automatically generated time grid should be regular (equal distances between grid points). This option only matters if times==NULL. If regular_grid==FALSE and times==NULL, the time grid will be irregular, with grid point density being roughly proportional to the square root of the number of lineages at any particular time (i.e., the grid becomes finer towards the tips).

\section*{Details}

Given a sequence of time points between a tree's root and tips, this function essentially counts how many edges "cross" each time point (if degree==1). The slopes and relative slopes are calculated from this curve using finite differences.
Note that the classical LTT curve (degree=1) is non-decreasing over time, whereas higher-degree LTT's may be decreasing as well as increasing over time.
If tree\$edge. length is missing, then every edge in the tree is assumed to be of length 1 . The tree may include multifurcations as well as monofurcations (i.e. nodes with only one child). The tree need not be ultrametric, although in general this function only makes sense for dated trees (e.g., where edge lengths are time intervals or similar).
Either Ntimes or times must be non-NULL, but not both. If times!=NULL, then min_time and max_time must be NULL.

\section*{Value}

A list with the following elements:
Ntimes Integer, indicating the number of returned time points. Equal to the provided Ntimes if applicable.
times Numeric vector of size Ntimes, listing the time points at which the LTT was calculated. If times was provided as an argument to the function, then this will be the same as provided.
lineages Integer vector of size Ntimes, listing the number of lineages represented in the tree at each time point that have at least degree descending tips, i.e. the LTT curve.
slopes Numeric vector of size Ntimes, listing the slopes (finite-difference approximation of 1st derivative) of the LTT curve.
relative_slopes
Numeric vector of size Ntimes, listing the relative slopes of the LTT curve, i.e. slopes divided by a sliding-window average of lineages.

\section*{Author(s)}

Stilianos Louca

\section*{Examples}
```


# generate a random tree

tree = generate_random_tree(list(birth_rate_intercept=1), max_tips=1000)\$tree

```
```


# calculate classical LTT curve

results = count_lineages_through_time(tree, Ntimes=100)

# plot classical LTT curve

plot(results$times, results$lineages, type="l", xlab="time", ylab="\# clades")

```
```

count_tips_per_node Count descending tips.

```

\section*{Description}

Given a rooted phylogenetic tree, count the number of tips descending (directy or indirectly) from each node.

\section*{Usage}
count_tips_per_node(tree)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.

\section*{Details}

The asymptotic time complexity of this function is O (Nedges), where Nedges is the number of edges.

\section*{Value}

An integer vector of size Nnodes, with the i-th entry being the number of tips descending (directly or indirectly) from the i-th node.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

    get_subtree_at_node
    ```

\section*{Examples}
```


# generate a tree using a simple speciation model

tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=1000)\$tree

# count number of tips descending from each node

tips_per_node = count_tips_per_node(tree);

# plot histogram of tips-per-node

barplot(table(tips_per_node[tips_per_node<10]), xlab="\# tips", ylab="\# nodes")

```
count_transitions_between_clades

Count the number of state transitions between tips or nodes.

\section*{Description}

Given a rooted phylogenetic tree, one or more pairs of tips and/or nodes, and the state of some discrete trait at each tip and node, calculate the number of state transitions along the shortest path between each pair of tips/nodes.

\section*{Usage}
count_transitions_between_clades(tree, A, B, states, check_input=TRUE)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.

A
An integer vector or character vector of size Npairs, specifying the first of the two members of each pair of tips/nodes. If an integer vector, it must list indices of tips (from 1 to Ntips) and/or nodes (from Ntips+1 to Ntips+Nnodes). If a character vector, it must list tip and/or node names.

B
states Integer vector of length Ntips+Nnodes, listing the discrete state of each tip and node in the tree. The order of entries must match the order of tips and nodes in the tree; this requirement is only verified if states has names and check_input==TRUE.
check_input Logical, whether to perform basic validations of the input data. If you know for certain that your input is valid, you can set this to FALSE to reduce computation time.

\section*{Details}

The discrete state must be represented by integers (both negatives and positives are allowed); characters and other data types are not allowed. If tip/node states are originally encoded as characters rather than integers, you can use map_to_state_space to convert these to integers (for example "male" \& "female" may be represented as \(1 \& 2\) ). Also note that a state must be provided for each tip and ancestral node, not just for the tips. If you only know the states of tips, you can use an ancestral state reconstruction tool to estimate ancestral states first.
The tree may include multi-furcations as well as mono-furcations (i.e. nodes with only one child). If \(A\) and/or \(B\) is a character vector, then tree\$tip. label must exist. If node names are included in \(A\) and/or \(B\), then tree\$node. label must also exist.

\section*{Value}

An integer vector of size Npairs, with the i-th element being the number of state transitions between tips/nodes A[i] and B[i] (along their shortest connecting path).

\section*{Author(s)}

Stilianos Louca

\section*{Examples}
\# generate a random tree
Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),Ntips)\$tree
\# pick 3 random pairs of tips or nodes
Npairs = 3
A = sample.int(n=(Ntips+tree\$Nnode), size=Npairs, replace=FALSE)
\(B=\) sample.int( \(n=(N t i p s+t r e e \$ N n o d e)\), size=Npairs, replace=FALSE)
\# assign a random state to each tip \& node in the tree
\# consider a binary trait
states = sample.int( \(n=2\), size=Ntips+tree\$Nnode, replace=TRUE)
\# calculate number of transitions for each tip pair
Ntransitions = count_transitions_between_clades(tree, A, B, states=states)
```

date_tree_red Date a tree based on relative evolutionary divergences.

```

\section*{Description}

Given a rooted phylogenetic tree and a single node ('anchor') of known age (distance from the present), rescale all edge lengths so that the tree becomes ultrametric and edge lengths correspond to time intervals. The function is based on relative evolutionary divergences (RED), which measure the relative position of each node between the root and its descending tips (Parks et al. 2018). If no anchor node is provided, the root is simply assumed to have age 1 . This function provides a heuristic quick-and-dirty way to date a phylogenetic tree.

\section*{Usage}
date_tree_red(tree, anchor_node = NULL, anchor_age = 1)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
anchor_node Integer, ranging between 1 and Nnodes. Index of the node to be used as dating anchor. If NULL, the tree's root is used as anchor.
anchor_age Positive numeric. Age of the anchor node.

\section*{Details}

The RED of a node measures its relative placement between the root and the node's descending tips (Parks et al. 2018). The root's RED is set to 0 . Traversing from root to tips (preorder traversal), for each node the RED is set to \(P+(a /(a+b)) \cdot(1-P)\), where \(P\) is the RED of the node's parent, \(a\) is the edge length connecting the node to its parent, and \(b\) is the average distance from the node to its descending tips. The RED of all tips is set to 1 .
For each edge, the RED difference between child \& parent is used to set the new length of that edge, multiplied by some common scaling factor to translate RED units into time units. The scaling factor is chosen such that the new distance of the anchor node from its descending tips equals anchor_age. All tips will have age 0 . The topology of the dated tree, as well as tip/node/edge indices, remain unchanged.
This function provides a heuristic approach to making a tree ultrametric, and has not been derived from a specific evolutionary model. In particular, its statistical properties are unknown to the author.
The time complexity of this function is O (Nedges). The input tree may include multi-furcations (i.e. nodes with more than 2 children) as well as mono-furcations (i.e. nodes with only one child). If tree\$edge. length is NULL, then all edges in the input tree are assumed to have length 1.

\section*{Value}

A list with the following elements:
success Logical, indicating whether the dating was successful. If FALSE, all other return values (except for error) may be undefined.
tree A new rooted tree of class "phylo", representing the dated tree.
REDs Numeric vector of size Nnodes, listing the RED of each node in the input tree.
error Character, listing any error message if success==FALSE.

\section*{Author(s)}

Stilianos Louca

\section*{References}
D. H. Parks, M. Chuvochina et al. (2018). A proposal for a standardized bacterial taxonomy based on genome phylogeny. bioRxiv 256800. DOI:10.1101/256800

\section*{See Also}
congruent_divergence_times

\section*{Examples}
\# generate a random non-ultrametric tree
params = list(birth_rate_intercept=1, death_rate_intercept=0.8)
tree \(=\) generate_random_tree(params, max_time=1000, coalescent=FALSE)\$tree
\# make ultrametric, by setting the root to 2 million years
dated_tree = date_tree_red(tree, anchor_age=2e6)
discrete_trait_depth Calculate phylogenetic depth of a discrete trait.

\section*{Description}

Given a rooted phylogenetic tree and the state of a discrete trait at each tip, calculate the mean phylogenetic depth at which the trait is conserved across clades, using a modification of the consenTRAIT metric introduced by Martiny et al (2013). This is the mean depth of clades that are "maximally uniform" in the trait (see below for details).

\section*{Usage}
discrete_trait_depth(tree,
tip_states,
min_fraction \(=0.9\),
count_singletons = TRUE
singleton_resolution \(=0\),
weighted \(=\) FALSE ,
Npermutations \(=0\) )

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
tip_states A vector of size Ntips specifying the state at each tip. Note that tip_states[i] (where i is an integer index) must correspond to the i -th tip in the tree. This vector may be of any base data type, although character or integer are the most typical types.
min_fraction Minimum fraction of tips in a clade that must have the dominant state, for the clade to be considered "uniform" in the trait.
count_singletons
Logical, specifying whether to consider singleton clades in the statistics (e.g., tips not part of a larger uniform clade). The phylogenetic depth of singletons is taken to be half the length of their incoming edge, as proposed by Martiny et al (2013). If FALSE, singletons are ignored. If you suspect a high risk of false
positives in the detection of a trait, it may be worth setting count_singletons to FALSE to avoid skewing the distribution of conservation depths towards shallower depths due to false positives.
```

singleton_resolution

```

Numeric, specifying the phylogenetic resolution at which to resolve singletons. A clade will be considered a singleton if the distance of the clade's root to all descending tips is below this threshold.
weighted Whether to weight uniform clades by their number of tips in the dominant state. If FALSE, each uniform clades is weighted equally.
Npermutations Number of random permutations for estimating the statistical significance of the mean trait depth. If zero (default), the statistical significance is not calculated.

\section*{Details}

The depth of a clade is defined as the average distance of its tips to the clade's root. The "dominant" state of a clade is defined as the most frequent state among all of the clade's tips. A clade is considered "uniform" in the trait if the frequency of its dominant state is equal to or greater than min_fraction. The clade is "maximally uniform" if it is uniform and not descending from another uniform clade. The mean depth of the trait is defined as the average phylogenetic depth of all considered maximal uniform clades (whether a maximally uniform clade is considered in this statistic depends on count_singletons and singleton_resolution). A greater mean depth means that the trait tends to be conserved in deeper-rooting clades.

This function implements a modification of the "consenTRAIT" metric proposed by Martiny et al. (2013) for measuring the mean phylogenetic depth at which a binary trait is conserved across clades. Note that the original consenTRAIT metric by Martiny et al. (2013) does not treat the two states of a binary trait ("presence" and "absence") equally, whereas the function discrete_trait_depth does. If you want the original consenTRAIT metric for a binary trait, see the function consentrait_depth.
The statistical significance of the calculated mean depth, i.e. the probability of encountering such a mean dept or higher by chance, is estimated based on a null model in which each tip is re-assigned a state by randomly reshuffling the original tip_states. A low P value indicates that the trait exhibits a phylogenetic signal, whereas a high \(P\) value means that there is insufficient evidence in the data to suggest a phylogenetic signal (i.e., the trait's phylogenetic conservatism is indistinguishable from the null model of zero conservatism).
The tree may include multi-furcations as well as mono-furcations (i.e. nodes with only one child). If tree\$edge. length is missing, then every edge is assumed to have length 1.

\section*{Value}

A list with the following elements:
unique_states Vector of the same type as tip_states and of length Nstates, listing the unique possible states of the trait.
mean_depth Numeric, specifying the mean phylogenetic depth of the trait, i.e., the mean depth of considered maximally uniform clades.
var_depth Numeric, specifying the variance of phylogenetic depths of considered maximally uniform clades.
```

min_depth Numeric, specifying the minimum phylogenetic depth of considered maximally
uniform clades.
max_depth Numeric, specifying the maximum phylogenetic depth of considered maximally
uniform clades.
Nmax_uniform Number of considered maximal uniform clades.
mean_depth_per_state
Numeric vector of size Nstates. Mean depth of considered maximally uni-
form clades, separately for each state and in the same order as unique_states.
Hence, mean_depth_per_state[s] lists the mean depth of considered maxi-
mally uniform clades whose dominant state is unique_states[s].
var_depth_per_state
Numeric vector of size Nstates. Variance of depths of considered maximally uni-
form clades, separately for each state and in the same order as unique_states
min_depth_per_state
Numeric vector of size Nstates. Minimum phylogenetic depth of considered
maximally uniform clades, separately for each state and in the same order as
unique_states
max_depth_per_state
Numeric vector of size Nstates. Maximum phylogenetic depth of considered
maximally uniform clades, separately for each state and in the same order as
unique_states
Nmax_uniform_per_state
Integer vector of size Nstates. Number of considered maximally uniform clades,
seperately for each state and in the same order as unique_states
P Statistical significance (P-value) of mean_depth, under a null model of random
tip states (see details above). This is the probability that, under the null model,
the mean_depth would be at least as high as observed in the data.
mean_random_depth
Mean random mean_depth, under the null model of random tip states (see details
above).

```

\section*{Author(s)}

Stilianos Louca

\section*{References}
A. C. Martiny, K. Treseder and G. Pusch (2013). Phylogenetic trait conservatism of functional traits in microorganisms. ISME Journal. 7:830-838.

\section*{See Also}
```

get_trait_acf, consentrait_depth

```

\section*{Examples}
```


## Not run:

# generate a random tree

tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=1000)\$tree

# simulate discrete trait evolution on the tree

# consider a trait with 3 discrete states

Q = get_random_mk_transition_matrix(Nstates=3, rate_model="ARD", max_rate=0.1)
tip_states = simulate_mk_model(tree, Q)\$tip_states

# calculate phylogenetic conservatism of trait

results = discrete_trait_depth(tree, tip_states, count_singletons=FALSE, weighted=TRUE)
cat(sprintf("Mean depth = %g, std = %g\n",results$mean_depth,sqrt(results$var_depth)))

## End(Not run)

```
evaluate_spline Evaluate a scalar spline at arbitrary locations.

\section*{Description}

Given a natural spline function \(Y: \mathrm{R} \rightarrow \mathrm{R}\), defined as a series of Y values on a discrete X grid, evaluate its values (or derivative) at arbitrary X points. Supported splines degrees are 0 ( Y is piecewise constant), 1 (piecewise linear), 2 (piecewise quadratic) and 3 (piecewise cubic).

\section*{Usage}
```

evaluate_spline(Xgrid,
Ygrid,
splines_degree,
Xtarget,
extrapolate = "const",
derivative = 0)

```

\section*{Arguments}

Xgrid Numeric vector, listing x-values in ascending order.
Ygrid Numeric vector of the same length as Xgrid, listing the values of Y on Xgrid.
splines_degree Integer, either \(0,1,2\) or 3 , specifying the polynomial degree of the spline curve Y between grid points. For example, 0 means Y is piecewise constant, 1 means Y is piecewise linear and so on.
Xtarget Numeric vector, listing arbitrary X values on which to evaluate Y.
extrapolate Character, specifying how to extrapolate \(Y\) beyond Xgrid if needed. Available options are "const" (i.e. use the value of Y on the nearest Xgrid point) or "splines" (i.e. use the polynomial coefficients from the nearest grid point).
derivative Integer, specifying which derivative to return. To return the spline's value, set derivative \(=0\). Currently only the options \(0,1,2\) are supported.

\section*{Details}

Spline functions are returned by some of castor's fitting routines, so evaluate_spline is meant to aid with the evaluation and plotting of such functions. A spline function of degree \(D \geq 1\) has continuous derivatives up to degree \(D-1\). The function evaluate_spline is much more efficient if Xtarget is monotonically increasing or decreasing.
This function is used to evaluate the spline's values at arbitrary points. To obtain the spline's polynomial coefficients, use spline_coefficients.

\section*{Value}

A numeric vector of the same length as \(X\) target, listing the values (or derivatives, if derivative>0) of Y on Xtarget.

\section*{Author(s)}

Stilianos Louca

\section*{See Also \\ spline_coefficients}

\section*{Examples}
```


# specify Y on a coarse X grid

Xgrid = seq(from=0,to=10, length.out=10)
Ygrid = sin(Xgrid)

# define a fine grid of target X values

Xtarget = seq(from=0,to=10,length.out=1000)

# evaluate Y on Xtarget, either as piecewise linear or piecewise cubic function

Ytarget_lin = evaluate_spline(Xgrid,Ygrid,splines_degree=1,Xtarget=Xtarget)
Ytarget_cub = evaluate_spline(Xgrid,Ygrid,splines_degree=3,Xtarget=Xtarget)

# plot both the piecewise linear and piecewise cubic curves

plot(x=Xtarget, y=Ytarget_cub, type='l', col='red', xlab='X', ylab='Y')
lines(x=Xtarget, y=Ytarget_lin, type='l', col='blue', xlab='X', ylab='Y')

```

\section*{Description}

Calculate the exponential \(\exp (T \cdot A)\) of some quadratic real-valued matrix A for one or more scalar scaling factors T .

\section*{Usage}
```

exponentiate_matrix(A, scalings=1, max_absolute_error=1e-3,
min_polynomials=1, max_polynomials=1000)

```

\section*{Arguments}

A
scalings

A real-valued quadratic matrix of size \(\mathrm{N} x \mathrm{~N}\).
Vector of real-valued scalar scaling factors T , for each of which the exponential \(\exp (T \cdot A)\) should be calculated.
max_absolute_error
Maximum allowed absolute error for the returned approximations. A smaller allowed error implies a greater computational cost as more matrix polynomials need to be included (see below). The returned approximations may have a greater error if the parameter max_polynomials is set too low.
min_polynomials
Minimum number of polynomials to include in the approximations (see equation below), even if max_absolute_error may be satisfied with fewer polynomials. If you don't know how to choose this, in most cases the default is fine. Note that regardless of min_polynomials and max_absolute_error, the number of polynomials used will not exceed max_polynomials.
max_polynomials
Maximum allowed number of polynomials to include in the approximations (see equation below). Meant to provide a safety limit for the amount of memory and the computation time required. For example, a value of 1000 means that up to 1000 matrices (powers of A) of size \(\mathrm{N} \times \mathrm{N}\) may be computed and stored temporarily in memory. Note that if max_polynomials is too low, the requested accuracy (via max_absolute_error) may not be achieved. That said, for large trees more memory may be required to store the actual result rather than the intermediate polynomials, i.e. for purposes of saving RAM it doesn't make much sense to choose max_polynomials much smaller than the length of scalings.

\section*{Details}

Discrete character evolution Markov models often involve repeated exponentiations of the same transition matrix along each edge of the tree (i.e. with the scaling T being the edge length). Matrix exponentiation can become a serious computational bottleneck for larger trees or large matrices (i.e. spanning multiple discrete states). This function pre-calculates polynomials \(A^{p} / p\) ! of the matrix, and then uses linear combinations of the same polynomials for each requested T :
\[
\exp (T \cdot A)=\sum_{p=0}^{P} T^{p} \frac{A^{p}}{p!}+\ldots
\]

This function thus becomes very efficient when the number of scaling factors is large (e.g. \(>10,000\) ). The number of polynomials included is determined based on the specified max_absolute_error, and based on the largest (by magnitude) scaling factor requested. The function utilizes the balancing algorithm proposed by James et al (2014, Algorithm 3) and the scaling \& squaring method (Moler and Van Loan, 2003) to improve the conditioning of the matrix prior to exponentiation.

\section*{Value}

A 3D numeric matrix of size \(\mathrm{N} \times \mathrm{N} \times \mathrm{S}\), where N is the number of rows \& column of the input matrix \(A\) and \(S\) is the length of scalings. The [r,c,s]-th element of this matrix is the entry in the r-th row and c-th column of \(\exp (\) scalings \([s] \cdot A)\).

\section*{Author(s)}

Stilianos Louca

\section*{References}
R. James, J. Langou and B. R. Lowery (2014). On matrix balancing and eigenvector computation. arXiv:1401.5766
C. Moler and C. Van Loan (2003). Nineteen dubious ways to compute the exponential of a matrix, twenty-five years later. SIAM Review. 45:3-49.

\section*{Examples}
```


# create a random 5 x 5 matrix

A = get_random_mk_transition_matrix(Nstates=5, rate_model="ER")

# calculate exponentials exp(0.1*A) and exp(10*A)

exponentials = exponentiate_matrix(A, scalings=c(0.1,10))

# print 1st exponential: exp(0.1*A)

print(exponentials[,,1])

# print 2nd exponential: exp(10*A)

print(exponentials[,,2])

```
extend_tree_to_height Extend a rooted tree up to a specific height.

\section*{Description}

Given a rooted phylogenetic tree and a specific distance from the root ("new height"), elongate terminal edges (i.e. leading into tips) as needed so that all tips have a distance from the root equal to the new height. If a tip already extends beyond the specified new height, its incoming edge remains unchanged.

\section*{Usage}
```

    extend_tree_to_height(tree, new_height=NULL)
    ```

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
new_height Numeric, specifying the phylogenetic distance from the root to which tips are to be extended. If NULL or negative, then it is set to the maximum distance of any tip from the root.

\section*{Details}

The input tree may include multi-furcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child). All tip, edge and node indices remain unchanged. This function provides a quick-and-dirty way to make a tree ultrametric, or to correct small numerical inaccuracies in supposed-to-be ultrametric trees.

\section*{Value}

A list with the following elements:
tree A new rooted tree of class "phylo", representing the extended tree.
max_extension Numeric. The largest elongation added to a terminal edge.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
trim_tree_at_height

\section*{Examples}
```


# generate a random non-ultrametric tree

tree = generate_random_tree(list(birth_rate_intercept=1,death_rate_intercept=0.5),
max_time=1000,
coalescent=FALSE)\$tree

# print min \& max distance from root

span = get_tree_span(tree)
cat(sprintf("Min \& max tip height = %g \& %g\n",span$min_distance,span$max_distance))

# make tree ultrametric by extending terminal edges

extended = extend_tree_to_height(tree)\$tree

# print new min \& max distance from root

span = get_tree_span(extended)
cat(sprintf("Min \& max tip height = %g \& %g\n",span$min_distance,span$max_distance))

```
```

extract_fasttree_constraints
Extract tree constraints in FastTree alignment format.

```

\section*{Description}

Given a rooted phylogenetic tree, extract binary constraints in FastTree alignment format. Every internal bifurcating node with more than 2 descending tips will constitute an separate constraint.

\section*{Usage}
extract_fasttree_constraints(tree)

\section*{Arguments}
tree A rooted tree of class "phylo".

\section*{Details}

This function can be used to define constraints based on a backbone subtree, to be used to generate a larger tree using FastTree (as of v2.1.11). Only bifurcating nodes with at least 3 descending tips are used as constraints.

The constraints are returned as a 2D matrix; the actual fasta file with the constraint alignments can be written easily from this matrix. For more details on FastTree constraints see the original FastTree documentation.

\section*{Value}

A list with the following elements:
Nconstraints Integer, specifying the number of constraints extracted.
constraints 2D character matrix of size Ntips x Nconstraints, with values '0', ' 1 ' or '-', specifying which side ("left" or "right") of a constraint (node) each tip is found on.
constraint2node
Integer vector of size Nconstraints, with values in 1,..,Nnodes, specifying the original node index used to define each constraint.

\section*{Author(s)}

Stilianos Louca

\section*{Examples}
```

    # generate a simple rooted tree, with tip names tip.1, tip.2, ...
    Ntips = 10
    tree = generate_random_tree(list(birth_rate_intercept=1),
                        max_tips=Ntips,
        tip_basename="tip.")$tree
    # extract constraints
    constraints = castor::extract_fasttree_constraints(tree)$constraints
    # print constraints to screen in fasta format
    cat(paste(sapply(1:Ntips,
        FUN=function(tip) sprintf(">%s\n%s\n",tree$tip.label[tip],
        paste(as.character(constraints[tip,]),collapse=""))),collapse=""))
    ```
find_farthest_tips Find farthest tip to each tip \& node of a tree.

\section*{Description}

Given a rooted phylogenetic tree and a subset of potential target tips, for each tip and node in the tree find the farthest target tip. The set of target tips can also be taken as the whole set of tips in the tree.

\section*{Usage}
find_farthest_tips( tree, only_descending_tips = FALSE, target_tips = NULL, as_edge_counts = FALSE, check_input = TRUE)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
only_descending_tips
A logical indicating whether the farthest tip to a node or tip should be chosen from its descending tips only. If FALSE, then the whole set of possible target tips is considered.
target_tips Optional integer vector or character vector listing the subset of target tips to restrict the search to. If an integer vector, this should list tip indices (values in \(1, . ., N\) Ntips). If a character vector, it should list tip names (in this case tree\$tip. label must exist). If target_tips is NULL, then all tips of the tree are considered as target tips.
as_edge_counts Logical, specifying whether to count phylogenetic distance in terms of edge counts instead of cumulative edge lengths. This is the same as setting all edge lengths to 1 .

\begin{abstract}
check_input Logical, whether to perform basic validations of the input data. If you know for certain that your input is valid, you can set this to FALSE to reduce computation time.
\end{abstract}

\section*{Details}

If only_descending_tips is TRUE, then only descending target tips are considered when searching for the farthest target tip of a node/tip. In that case, if a node/tip has no descending target tip, its farthest target tip is set to NA. If tree\$edge. length is missing or NULL, then each edge is assumed to have length 1 . The tree may include multi-furcations as well as mono-furcations (i.e. nodes with only one child).
The asymptotic time complexity of this function is O (Nedges), where Nedges is the number of edges in the tree.

\section*{Value}

A list with the following elements:
farthest_tip_per_tip
An integer vector of size Ntips, listing the farthest target tip for each tip in the tree. Hence, farthest_tip_per_tip[i] is the index of the farthest tip (from the set of target tips), with respect to tip i (where \(\mathrm{i}=1, . ., \mathrm{Ntips})\). Some values may appear multiple times in this vector, if multiple tips share the same farthest target tip.
farthest_tip_per_node
An integer vector of size Nnodes, listing the index of the farthest target tip for each node in the tree. Hence, farthest_tip_per_node[i] is the index of the farthest tip (from the set of target tips), with respect to node i (where \(\mathrm{i}=1, . .\), Nnodes). Some values may appear multiple times in this vector, if multiple nodes share the same farthest target tip.
farthest_distance_per_tip
Integer vector of size Ntips. Phylogenetic ("patristic") distance of each tip in the tree to its farthest target tip. If only_descending_tips was set to TRUE, then farthest_distance_per_tip[i] will be set to infinity for any tip ithat is not a target tip.
farthest_distance_per_node
Integer vector of size Nnodes. Phylogenetic ("patristic") distance of each node in the tree to its farthest target tip. If only_descending_tips was set to TRUE, then farthest_distance_per_node[i] will be set to infinity for any node i that has no descending target tips.

\section*{Author(s)}

Stilianos Louca

\section*{References}
M. G. I. Langille, J. Zaneveld, J. G. Caporaso et al (2013). Predictive functional profiling of microbial communities using 16S rRNA marker gene sequences. Nature Biotechnology. 31:814-821.

\section*{See Also}

> find_nearest_tips

\section*{Examples}
```


# generate a random tree

Ntips = 1000
parameters = list(birth_rate_intercept=1,death_rate_intercept=0.9)
tree = generate_random_tree(parameters,Ntips,coalescent=FALSE)\$tree

# pick a random set of "target" tips

target_tips = sample.int(n=Ntips, size=5, replace=FALSE)

# find farthest target tip to each tip \& node in the tree

results = find_farthest_tips(tree, target_tips=target_tips)

# plot histogram of distances to target tips (across all tips of the tree)

distances = results\$farthest_distance_per_tip
hist(distances, breaks=10, xlab="farthest distance", ylab="number of tips", prob=FALSE);

```
find_farthest_tip_pair

Find the two most distant tips in a tree.

\section*{Description}

Given a phylogenetic tree, find the two most phylogenetically distant tips (to each other) in the tree.

\section*{Usage}
find_farthest_tip_pair(tree, as_edge_counts = FALSE)

\section*{Arguments}
tree A rooted tree of class "phylo". While the tree must be rooted for technical reasons, the outcome does not actually depend on the rooting.
as_edge_counts Logical, specifying whether to count phylogenetic distance in terms of edge counts instead of cumulative edge lengths. This is the same as setting all edge lengths to 1 .

\section*{Details}

If tree\$edge. length is missing or NULL, then each edge is assumed to have length 1 . The tree may include multi-furcations as well as mono-furcations (i.e. nodes with only one child).
The asymptotic time complexity of this function is O (Nedges), where Nedges is the number of edges in the tree.

\section*{Value}

A named list with the following elements:
tip1 An integer between 1 and Ntips, specifying the first of the two most distant tips.
tip2 An integer between 1 and Ntips, specifying the second of the two most distant tips.
distance \(\quad\) Numeric, specifying the phylogenetic (patristic) distance between the farthest_tip1 and farthest_tip2.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
find_nearest_tips, find_farthest_tips

\section*{Examples}
```


# generate a random tree

Ntips = 1000
parameters = list(birth_rate_intercept=1,death_rate_intercept=0.9)
tree = generate_random_tree(parameters,Ntips,coalescent=FALSE)\$tree

# find farthest pair of tips

results = find_farthest_tip_pair(tree)

# print results

cat(sprintf("Tip %d and %d have distance %g\n",
results$tip1,results$tip2,results\$distance))

```
find_nearest_tips Find nearest tip to each tip \& node of a tree.

\section*{Description}

Given a rooted phylogenetic tree and a subset of potential target tips, for each tip and node in the tree find the nearest target tip. The set of target tips can also be taken as the whole set of tips in the tree.

\section*{Usage}
```

find_nearest_tips(tree,
only_descending_tips = FALSE,
target_tips = NULL,
as_edge_counts = FALSE,
check_input = TRUE)

```

\section*{Arguments}
\[
\begin{array}{ll}
\text { tree } & \begin{array}{l}
\text { A rooted tree of class "phylo". The root is assumed to be the unique node with } \\
\text { no incoming edge. }
\end{array} \\
\text { only_descending_tips } \\
\text { A logical indicating whether the nearest tip to a node or tip should be chosen } \\
\text { from its descending tips only. If FALSE, then the whole set of possible target } \\
\text { tips is considered. }
\end{array}
\]

\section*{Details}

Langille et al. (2013) introduced the Nearest Sequenced Taxon Index (NSTI) as a measure for how well a set of microbial operational taxonomic units (OTUs) is represented by a set of sequenced genomes of related organisms. Specifically, the NSTI of a microbial community is the average phylogenetic distance of any OTU in the community, to the closest relative with an available sequenced genome ("target tips"). In analogy to the NSTI, the function find_nearest_tips provides a means to find the nearest tip (from a subset of target tips) to each tip and node in a phylogenetic tree, together with the corresponding phylogenetic ("patristic") distance.

If only_descending_tips is TRUE, then only descending target tips are considered when searching for the nearest target tip of a node/tip. In that case, if a node/tip has no descending target tip, its nearest target tip is set to NA. If tree\$edge. length is missing or NULL, then each edge is assumed to have length 1. The tree may include multi-furcations as well as mono-furcations (i.e. nodes with only one child).

The asymptotic time complexity of this function is O (Nedges), where Nedges is the number of edges in the tree.

\section*{Value}

A list with the following elements:

\footnotetext{
nearest_tip_per_tip
An integer vector of size Ntips, listing the nearest target tip for each tip in the tree. Hence, nearest_tip_per_tip[i] is the index of the nearest tip (from the set of target tips), with respect to tip i (where \(\mathrm{i}=1, . . \mathrm{Ntips}\) ). Some values may appear multiple times in this vector, if multiple tips share the same nearest target tip.
}
nearest_tip_per_node
An integer vector of size Nnodes, listing the index of the nearest target tip for each node in the tree. Hence, nearest_tip_per_node[i] is the index of the nearest tip (from the set of target tips), with respect to node i (where \(\mathrm{i}=1, . .\), Nnodes). Some values may appear multiple times in this vector, if multiple nodes share the same nearest target tip.
nearest_distance_per_tip
Integer vector of size Ntips. Phylogenetic ("patristic") distance of each tip in the tree to its nearest target tip. If only_descending_tips was set to TRUE, then nearest_distance_per_tip[i] will be set to infinity for any tip ithat is not a target tip.
nearest_distance_per_node
Integer vector of size Nnodes. Phylogenetic ("patristic") distance of each node in the tree to its nearest target tip. If only_descending_tips was set to TRUE, then nearest_distance_per_node[i] will be set to infinity for any node i that has no descending target tips.

\section*{Author(s)}

Stilianos Louca

\section*{References}
M. G. I. Langille, J. Zaneveld, J. G. Caporaso et al (2013). Predictive functional profiling of microbial communities using 16S rRNA marker gene sequences. Nature Biotechnology. 31:814-821.

\section*{See Also}
find_farthest_tips

\section*{Examples}
```


# generate a random tree

Ntips = 1000
tree = generate_random_tree(list(birth_rate_intercept=1),Ntips)\$tree

# pick a random set of "target" tips

target_tips = sample.int(n=Ntips, size=as.integer(Ntips/10), replace=FALSE)

# find nearest target tip to each tip \& node in the tree

results = find_nearest_tips(tree, target_tips=target_tips)

# plot histogram of distances to target tips (across all tips of the tree)

distances = results\$nearest_distance_per_tip
hist(distances, breaks=10, xlab="nearest distance", ylab="number of tips", prob=FALSE);

```

\section*{Description}

Find the root of a phylogenetic tree. The root is defined as the unique node with no parent.

\section*{Usage}
find_root(tree)

\section*{Arguments}
tree A tree of class "phylo". If the tree is not rooted, the function will return NA.

\section*{Details}

By convention, the root of a "phylo" tree is typically the first node (i.e. with index Ntips+1), however this is not always guaranteed. This function finds the root of a tree by searching for the node with no parent. If no such node exists, \(N A\) is returned. If multiple such nodes exist, \(N A\) is returned. If any node has more than 1 parent, NA is returned. Hence, this function can be used to test if a tree is rooted purely based on the edge structure, assuming that the tree is connected (i.e. not a forest).
The asymptotic time complexity of this function is O (Nedges), where Nedges is the number of edges in the tree.

\section*{Value}

Index of the tree's root, as listed in tree\$edge. An integer ranging from Ntips+1 to Ntips+Nnodes, where Ntips and Nnodes is the number of tips and nodes in the tree, respectively. By convention, the root will typically be Ntips+1 but this is not guaranteed.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
find_root_of_monophyletic_tips, root_at_node, root_at_midpoint

\section*{Examples}
```


# generate a random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),Ntips)\$tree

# reroot the tree at the 20-th node

new_root_node = 20
tree = root_at_node(tree, new_root_node, update_indices=FALSE)

```
```


# find new root index and compare with expectation

cat(sprintf("New root is %d, expected at %d\n",find_root(tree),new_root_node+Ntips))

```
find_root_of_monophyletic_tips
Find the node or tip that, as root, would make a set of target tips monophyletic.

\section*{Description}

Given a tree (rooted or unrooted) and a specific set of target tips, this function finds the tip or node that, if turned into root, would make a set of target tips a monophyletic group that either descends from a single child of the new root (if as_MRCA==FALSE) or whose MRCA is the new root (if as_MRCA==TRUE).

\section*{Usage}
find_root_of_monophyletic_tips(tree, monophyletic_tips, as_MRCA=TRUE, is_rooted=FALSE)

\section*{Arguments}
tree A tree object of class "phylo". Can be unrooted or rooted.
monophyletic_tips
Character or integer vector, specifying the names or indices, respectively, of the target tips that should be turned monophyletic. If an integer vector, its elements must be between 1 and Ntips. If a character vector, its elements must be elements in tree\$tip. label.
as_MRCA Logical, specifying whether the new root should become the MRCA of the target tips. If FALSE, the new root is chosen such that the MRCA of the target tips is the child of the new root.
is_rooted Logical, specifying whether the input tree can be assumed to be rooted. If you are sure that the input tree is rooted, set this to TRUE for computational efficiency, otherwise to be on the safe side set this to FALSE.

\section*{Details}

The input tree may include an arbitrary number of incoming and outgoing edges per node (but only one edge per tip), and the direction of these edges can be arbitrary. Of course, the undirected graph defined by all edges must still be a valid tree (i.e. a connected acyclic graph). Note that this function does not change the tree, it just determines which tip or node should be made root for the target tips to be a monophyletic group.
The asymptotic time complexity of this function is O (Nedges).

\section*{Value}

A single integer between 1 and (Ntips+Nnodes), specifying the index of the tip or node that, if made root, would make the target tips monophyletic. If this was not possible, NA is returned.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
find_root

\section*{Examples}
```


# generate a random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# pick a random node and find all descending tips

MRCA = sample.int(tree$Nnode,size=1)
monophyletic_tips = get_subtree_at_node(tree, MRCA)$new2old_tip

# change root of tree (change edge directions)

tree = root_at_node(tree, new_root_node=10, update_indices=FALSE)

# determine root that would make target tips monophyletic

new_root = find_root_of_monophyletic_tips(tree, monophyletic_tips, as_MRCA=TRUE, is_rooted=FALSE)

# compare expectation with result

cat(sprintf("MRCA = %d, new root node=%d\n",MRCA, new_root-Ntips))

```
```

fit_and_compare_bm_models

```

Fit and compare Brownian Motion models for multivariate trait evolution between two data sets.

\section*{Description}

Given two rooted phylogenetic trees and states of one or more continuous (numeric) traits on the trees' tips, fit a multivariate Brownian motion model of correlated evolution to each data set and compare the fitted models. This function estimates the diffusivity matrix for each data set (i.e., each tree/tip-states set) via maximum-likelihood and assesses whether the log-difference between the two fitted diffusivity matrixes is statistically significant, under the null hypothesis that the two data sets exhibit the same diffusivity. Optionally, multiple trees can be used as input for each data set, under the assumption that the trait evolved on each tree according to the same BM model. For more details on how BM is fitted to each data set see the function fit_bm_model.

\section*{Usage}
```

fit_and_compare_bm_models( trees1,
tip_states1,
trees2,
tip_states2,

```
```

Nbootstraps = 0,
Nsignificance = 0,
check_input = TRUE,
verbose = FALSE,
verbose_prefix = "")

```

\section*{Arguments}
trees1 Either a single rooted tree or a list of rooted trees, of class "phylo", corresponding to the first data set on which a BM model is to be fitted. Edge lengths are assumed to represent time intervals or a similarly interpretable phylogenetic distance.
tip_states1 Numeric state of each trait at each tip in each tree in the first data set. If trees1 is a single tree, then tip_states 1 must either be a numeric vector of size Ntips or a 2D numeric matrix of size Ntips x Ntraits, listing the trait states for each tip in the tree. If trees 1 is a list of Ntrees trees, then tip_states 1 must be a list of length Ntrees, each element of which lists the trait states for the corresponding tree (as a vector or 2D matrix, similarly to the single-tree case).
trees2 Either a single rooted tree or a list of rooted trees, of class "phylo", corresponding to the second data set on which a BM model is to be fitted. Edge lengths are assumed to represent time intervals or a similarly interpretable phylogenetic distance.
tip_states2 Numeric state of each trait at each tip in each tree in the second data set, similarly to tip_states1.
Nbootstraps Integer, specifying the number of parametric bootstraps to perform for calculating the confidence intervals of BM diffusivities fitted to each data set. If \(<=0\), no bootstrapping is performed.
Nsignificance Integer, specifying the number of simulations to perform for assessing the statistical significance of the log-transformed difference between the diffusivities fitted to the two data sets, i.e. of \(\left|\log \left(D_{1}\right)-\log \left(D_{2}\right)\right|\). Set to 0 to not calculate the statistical significance. See below for additional details.
check_input Logical, specifying whether to perform some basic checks on the validity of the input data. If you are certain that your input data are valid, you can set this to FALSE to reduce computation.
verbose Logical, specifying whether to print progress report messages to the screen.
verbose_prefix Character, specifying a prefix to include in front of progress report messages on each line. Only relevant if verbose==TRUE.

\section*{Details}

For details on the Brownian Motion model see fit_bm_model and simulate_bm_model. This function separately fits a single-variate or multi-variate BM model with constant diffusivity (diffusivity matrix, in the multivariate case) to each data set; internally, this function applies fit_bm_model to each data set.

If Nsignificance>0, the statistical significance of the log-transformed difference of the two fitted diffusivity matrixes, \(\left|\log \left(D_{1}\right)-\log \left(D_{2}\right)\right|\), is assessed, under the null hypothesis that both data sets
were generated by the same common BM model. The diffusivity of this common BM model is estimated by fitting to both datasets at once, i.e. after merging the two datasets into a single dataset of trees and tip states (see return variable fit_common below). For each of the Nsignificance random simulations of the common BM model on the two tree sets, the diffusivities are again separately fitted on the two simulated sets and the resulting log-difference is compared to the one of the original data sets. The returned significance is the probability that the diffusivities would have a log-difference larger than the observed one, if the two data sets had been generated under the common BM model.

If tree\$edge. length is missing, each edge in the tree is assumed to have length 1 . The tree may include multifurcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child). Note that multifurcations are internally expanded to bifurcations, prior to model fitting.

\section*{Value}

A list with the following elements:
success Logical, indicating whether the fitting was successful for both data sets. If FALSE, then an additional return variable, error, will contain a description of the error; in that case all other return variables may be undefined.
fit1 A named list containing the fitting results for the first data set, in the same format as returned by fit_bm_model. In particular, the diffusivity fitted to the first data set will be stored in fit1\$diffusivity.
fit2 A named list containing the fitting results for the second data set, in the same format as returned by fit_bm_model. In particular, the diffusivity fitted to the second data set will be stored in fit2\$diffusivity.
\(\log\) _difference The absolute difference between the log-transformed diffusivities, i.e. \(\mid \log \left(D_{1}\right)\) \(\log \left(D_{2}\right) \mid\). In the multivariate case, this will be a matrix of size Ntraits x Ntraits.
significance Numeric, statistical significance of the observed log-difference under the null hypothesis that the two data sets were generated by a common BM model. Only returned if Nsignificance>0.
fit_common A named list containing the fitting results for the two data sets combined, in the same format as returned by fit_bm_model. The common diffusivity, fit_common\$diffusivity is used for the random simulations when assessing the statistical significance of the log-difference of the separately fitted diffusivities. Only returned if Nsignificance>0.

\section*{Author(s)}

Stilianos Louca

\section*{References}
J. Felsenstein (1985). Phylogenies and the Comparative Method. The American Naturalist. 125:115.

\section*{See Also}
```

simulate_bm_model, fit_bm_model, get_independent_contrasts

```

\section*{Examples}
```


# simulate distinct BM models on two random trees

D1 = 1
D2 = 2
tree1 = generate_random_tree(list(birth_rate_factor=1),max_tips=100)$tree
tree2 = generate_random_tree(list(birth_rate_factor=1),max_tips=100)$tree
tip_states1 = simulate_bm_model(tree1, diffusivity = D1)$tip_states
tip_states2 = simulate_bm_model(tree2, diffusivity = D2)$tip_states

# fit and compare BM models between the two data sets

fit = fit_and_compare_bm_models(trees1 = tree1,
tip_states1 = tip_states1,
trees2 = tree2,
tip_states2 = tip_states2,
Nbootstraps = 100,
Nsignificance = 100)

# print summary of results

cat(sprintf("Fitted D1 = %g, D2 = %g, significance of log-diff. = %g\n",
fit$fit1$diffusivity, fit$fit2$diffusivity, fit\$significance))

```
fit_and_compare_sbm_const

Fit and compare Spherical Brownian Motion models for diffusive geographic dispersal between two data sets.

\section*{Description}

Given two rooted phylogenetic trees and geographic coordinates of the trees' tips, fit a Spherical Brownian Motion (SBM) model of diffusive geographic dispersal with constant diffusivity to each tree and compare the fitted models. This function estimates the diffusivity \((D)\) for each data set (i.e., each set of trees + tip-coordinates) via maximum-likelihood and assesses whether the logdifference between the two fitted diffusivities is statistically significant, under the null hypothesis that the two data sets exhibit the same diffusivity. Optionally, multiple trees can be used as input for each data set, under the assumption that dispersal occurred according to the same diffusivity in each tree of that dataset. For more details on how SBM is fitted to each data set see the function fit_sbm_const.

\section*{Usage}
```

fit_and_compare_sbm_const( trees1,
tip_latitudes1,
tip_longitudes1,
trees2,
tip_latitudes2,
tip_longitudes2,
radius,
planar_approximation = FALSE,

```
```

only_basal_tip_pairs = FALSE,
only_distant_tip_pairs = FALSE,
min_MRCA_time = 0,
max_MRCA_age = Inf,
max_phylodistance = Inf,
min_diffusivity = NULL,
max_diffusivity = NULL,
Nbootstraps = 0,
Nsignificance = 0,
SBM_PD_functor = NULL,
verbose = FALSE,
verbose_prefix = "")

```

\section*{Arguments}
trees1 Either a single rooted tree or a list of rooted trees, of class "phylo", corresponding to the first data set on which an SBM model is to be fitted. Edge lengths are assumed to represent time intervals or a similarly interpretable phylogenetic distance.
tip_latitudes1 Numeric vector listing the latitude (in decimal degrees) of each tip in each tree in the first data set. If trees 1 is a single tree, then tip_latitudes 1 must be a numeric vector of size Ntips, listing the latitudes for each tip in the tree. If trees 1 is a list of Ntrees trees, then tip_latitudes 1 must be a list of length Ntrees, each element of which lists the latitudes for the corresponding tree (as a vector, similarly to the single-tree case).
tip_longitudes1
Similar to tip_latitudes1, but listing longitudes (in decimal degrees) of each tip in each tree in the first data set.
trees2 Either a single rooted tree or a list of rooted trees, of class "phylo", corresponding to the second data set on which an SBM model is to be fitted. Edge lengths are assumed to represent time intervals or a similarly interpretable phylogenetic distance.
tip_latitudes2 Numeric vector listing the latitude (in decimal degrees) of each tip in each tree in the second data set, similarly to tip_latitudes1.
tip_longitudes2
Numeric vector listing the longitude (in decimal degrees) of each tip in each tree in the second data set, similarly to tip_longitudes1.
radius Strictly positive numeric, specifying the radius of the sphere. For Earth, the mean radius is 6371 km .
planar_approximation
Logical, specifying whether to estimate the diffusivity based on a planar approximation of the SBM model, i.e. by assuming that geographic distances between tips are as if tips are distributed on a 2D cartesian plane. This approximation is only accurate if geographical distances between tips are small compared to the sphere's radius.
only_basal_tip_pairs
Logical, specifying whether to only compare immediate sister tips, i.e., tips connected through a single parental node.
```

only_distant_tip_pairs
Logical, specifying whether to only compare tips at distinct geographic loca-
tions.
min_MRCA_time Numeric, specifying the minimum allowed time (distance from root) of the most
recent common ancestor (MRCA) of sister tips considered in the fitting. In other
words, an independent contrast is only considered if the two sister tips' MRCA
has at least this distance from the root. Set min_MRCA_time<=0 to disable this
filter.
max_MRCA_age Numeric, specifying the maximum allowed age (distance from youngest tip) of
the MRCA of sister tips considered in the fitting. In other words, an independent
contrast is only considered if the two sister tips' MRCA has at most this age
(time to present). Set max_MRCA_age=Inf to disable this filter.
max_phylodistance
Numeric, maximum allowed geodistance for an independent contrast to be included in the SBM fitting. Set max_phylodistance=Inf to disable this filter.
min_diffusivity
Non-negative numeric, specifying the minimum possible diffusivity. If NULL, this is automatically chosen.
max_diffusivity
Non-negative numeric, specifying the maximum possible diffusivity. If NULL, this is automatically chosen.
Nbootstraps Integer, specifying the number of parametric bootstraps to perform for calculating the confidence intervals of SBM diffusivities fitted to each data set. If $<=0$, no bootstrapping is performed.
Nsignificance Integer, specifying the number of simulations to perform for assessing the statistical significance of the linear difference and log-transformed difference between the diffusivities fitted to the two data sets, i.e. of $\left|D_{1}-D_{2}\right|$ and of $\left|\log \left(D_{1}\right)-\log \left(D_{2}\right)\right|$. Set to 0 to not calculate statistical significances. See below for additional details.
SBM_PD_functor SBM probability density functor object. Used internally and for debugging purposes. Unless you know what you're doing, you should keep this NULL.
verbose Logical, specifying whether to print progress report messages to the screen.
verbose_prefix Character, specifying a prefix to include in front of progress report messages on each line. Only relevant if verbose==TRUE.

```

\section*{Details}

For details on the Spherical Brownian Motion model see fit_sbm_const and simulate_sbm. This function separately fits an SBM model with constant diffusivity to each of two data sets; internally, this function applies fit_sbm_const to each data set.
If Nsignificance>0, the statistical significance of the linear difference \(\left(\left|D_{1}-D_{2}\right|\right)\) and \(\log\) transformed difference \(\left(\left|\log \left(D_{1}\right)-\log \left(D_{2}\right)\right|\right)\) of the two fitted diffusivities is assessed under the null hypothesis that both data sets were generated by the same common SBM model. The diffusivity of this common SBM model is estimated by fitting to both datasets at once, i.e. after merging the two datasets into a single dataset of trees and tip coordinates (see return variable fit_common below). For each of the Nsignificance random simulations of the common SBM model on the two tree
sets, the diffusivities are again separately fitted on the two simulated sets and the resulting difference and log-difference is compared to those of the original data sets. The returned lin_significance (or log_significance) is the probability that the diffusivities would have a difference (or logdifference) larger than the observed one, if the two data sets had been generated under the common SBM model.

If edge. length is missing from one of the input trees, each edge in the tree is assumed to have length 1. Trees may include multifurcations as well as monofurcations, however multifurcations are internally expanded into bifurcations by adding dummy nodes.

\section*{Value}

A list with the following elements:
success Logical, indicating whether the fitting was successful for both data sets. If FALSE, then an additional return variable, error, will contain a description of the error; in that case all other return variables may be undefined.
fit1 A named list containing the fitting results for the first data set, in the same format as returned by fit_sbm_const. In particular, the diffusivity fitted to the first data set will be stored in fit1\$diffusivity.
fit2 A named list containing the fitting results for the second data set, in the same format as returned by fit_sbm_const. In particular, the diffusivity fitted to the second data set will be stored in fit2\$diffusivity.
lin_difference The absolute difference between the two diffusivities, i.e. \(\left|D_{1}-D_{2}\right|\).
\(\log\) _difference The absolute difference between the two log-transformed diffusivities, i.e. \(\mid \log \left(D_{1}\right)-\) \(\log \left(D_{2}\right) \mid\).
lin_significance
Numeric, statistical significance of the observed lin-difference under the null hypothesis that the two data sets were generated by a common SBM model. Only returned if Nsignificance>0.
log_significance
Numeric, statistical significance of the observed log-difference under the null hypothesis that the two data sets were generated by a common SBM model. Only returned if Nsignificance>0.
fit_common A named list containing the fitting results for the two data sets combined, in the same format as returned by fit_sbm_const. The common diffusivity, fit_common\$diffusivity is used for the random simulations when assessing the statistical significance of the lin-difference and log-difference of the separately fitted diffusivities. Only returned if Nsignificance>0.

\section*{Author(s)}

Stilianos Louca

\section*{References}
S. Louca (in review as of 2020). Phylogeographic estimation and simulation of global diffusive dispersal. Systematic Biology.

\section*{See Also}
```

simulate_sbm, fit_sbm_const, fit_sbm_linear, fit_sbm_parametric

```

\section*{Examples}
```


## Not run:

# simulate distinct SBM models on two random trees

radius = 6371 \# Earth's radius
D1 = 1 \# diffusivity on 1st tree
D2 = 3 \# diffusivity on 2nd tree
tree1 = generate_random_tree(list(birth_rate_factor=1),max_tips=100)$tree
tree2 = generate_random_tree(list(birth_rate_factor=1),max_tips=100)$tree
sim1 = simulate_sbm(tree=tree1, radius=radius, diffusivity=D1)
sim2 = simulate_sbm(tree=tree2, radius=radius, diffusivity=D2)
tip_latitudes1 = sim1$tip_latitudes
tip_longitudes1 = sim1$tip_longitudes
tip_latitudes2 = sim2$tip_latitudes
tip_longitudes2 = sim2$tip_longitudes

# fit and compare SBM models between the two hypothetical data sets

fit = fit_and_compare_sbm_const(trees1 = tree1,
tip_latitudes1 = tip_latitudes1,
tip_longitudes1 = tip_longitudes1,
trees2 = tree2,
tip_latitudes2 = tip_latitudes2,
tip_longitudes2 = tip_longitudes2,
radius = radius,
Nbootstraps = 0,
Nsignificance = 100)

# print summary of results

cat(sprintf("Fitted D1 = %g, D2 = %g, significance of log-diff. = %g\n",
fit$fit1$diffusivity, fit$fit2$diffusivity, fit\$log_significance))

## End(Not run)

```
fit_bm_model Fit a Brownian Motion model for multivariate trait evolution.

\section*{Description}

Given a rooted phylogenetic tree and states of one or more continuous (numeric) traits on the tree's tips, fit a multivariate Brownian motion model of correlated co-evolution of these traits. This estimates a single diffusivity matrix, which describes the variance-covariance structure of each trait's random walk. The model assumes a fixed diffusivity matrix on the entire tree. Optionally, multiple trees can be used as input, under the assumption that the trait evolved on each tree according to the same BM model.

\section*{Usage}
\[
\begin{aligned}
\text { fit_bm_model }( & \text { trees, } \\
& \text { tip_states, } \\
& \text { isotropic }=\text { FALSE, } \\
& \text { Nbootstraps }=0, \\
& \text { check_input }=\text { TRUE })
\end{aligned}
\]

\section*{Arguments}
trees Either a single rooted tree or a list of rooted trees, of class "phylo". The root of each tree is assumed to be the unique node with no incoming edge. Edge lengths are assumed to represent time intervals or a similarly interpretable phylogenetic distance.
tip_states Numeric state of each trait at each tip in each tree. If trees was a single tree, then tip_states must either be a numeric vector of size Ntips or a 2D numeric matrix of size Ntips x Ntraits, listing the trait states for each tip in the tree. If trees is a list of Ntrees trees, then tip_states must be a list of length Ntrees, each element of which lists the trait states for the corresponding tree (as a vector or 2D matrix, similarly to the single-tree case).
isotropic Logical, specifying whether diffusion should be assumed to be isotropic (i.e., independent of the direction). Hence, if isotropic=TRUE, then the diffusivity matrix is forced to be diagonal, with all entries being equal. If isotropic=FALSE, an arbitrary diffusivity matrix is fitted (i.e., the diffusivity matrix is only constrained to be symmetric and non-negative definite).
Nbootstraps Integer, specifying the number of parametric bootstraps to perform for calculating the confidence intervals. If \(<=0\), no bootstrapping is performed.
check_input Logical, specifying whether to perform some basic checks on the validity of the input data. If you are certain that your input data are valid, you can set this to FALSE to reduce computation.

\section*{Details}

The BM model is defined by the stochastic differential equation
\[
d X=\sigma \cdot d W
\]
where \(W\) is a multidimensional Wiener process with Ndegrees independent components and \(\sigma\) is a matrix of size Ntraits x Ndegrees. Alternatively, the same model can be defined as a Fokker-Planck equation for the probability density \(\rho\) :
\[
\frac{\partial \rho}{\partial t}=\sum_{i, j} D_{i j} \frac{\partial^{2} \rho}{\partial x_{i} \partial x_{j}}
\]

The matrix \(D\) is referred to as the diffusivity matrix (or diffusion tensor), and \(2 D=\sigma \cdot \sigma^{T}\). Note that \(\sigma\) can be obtained from \(D\) by means of a Cholesky decomposition.
The function uses phylogenetic independent contrasts (Felsenstein, 1985) to retrieve independent increments of the multivariate random walk. The diffusivity matrix \(D\) is then fitted using maximumlikelihood on the intrinsic geometry of positive-definite matrices. If multiple trees are provided as
input, then independent contrasts are extracted from all trees and combined into a single set of independent contrasts (i.e., as if they had been extracted from a single tree).

If tree\$edge. length is missing, each edge in the tree is assumed to have length 1 . The tree may include multifurcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child). Note that multifurcations are internally expanded to bifurcations, prior to model fitting.

\section*{Value}

A list with the following elements:
success Logical, indicating whether the fitting was successful. If FALSE, then an additional return variable, error, will contain a description of the error; in that case all other return variables may be undefined.
diffusivity Either a single non-negative number (if tip_states was a vector) or a 2D quadratic non-negative-definite matrix (if tip_states was a 2 D matrix). The fitted diffusivity matrix of the multivariate Brownian motion model.
loglikelihood The log-likelihood of the fitted model, given the provided tip states data.
Ncontrasts Integer, number of independent contrasts used to estimate the diffusivity. This corresponds to the number of independent data points used.
standard_errors
Either a single numeric or a 2D numeric matrix of size Ntraits x Ntraits, listing the estimated standard errors of the estimated diffusivity, based on parametric bootstrapping. Only returned if Nbootstraps>0.
CI50lower Either a single numeric or a 2D numeric matrix of size Ntraits x Ntraits, listing the lower bounds of the \(50 \%\) confidence interval for the estimated diffusivity ( \(25-75 \%\) percentile), based on parametric bootstrapping. Only returned if Nbootstraps>0.

CI50upper Either a single numeric or a 2D numeric matrix of size Ntraits x Ntraits, listing the upper bound of the \(50 \%\) confidence interval for the estimated diffusivity, based on parametric bootstrapping. Only returned if Nbootstraps>0.

CI95lower Either a single numeric or a 2D numeric matrix of size Ntraits x Ntraits, listing the lower bound of the \(95 \%\) confidence interval for the estimated diffusivity (2.5-97.5\% percentile), based on parametric bootstrapping. Only returned if Nbootstraps>0.
CI95upper \(\quad\) Either a single numeric or a 2D numeric matrix of size Ntraits x Ntraits, listing the upper bound of the \(95 \%\) confidence interval for the estimated diffusivity, based on parametric bootstrapping. Only returned if Nbootstraps \(>0\).
consistency Numeric between 0 and 1 , estimated consistency of the data with the fitted model. If \(L\) denotes the loglikelihood of new data generated by the fitted model (under the same model) and \(M\) denotes the expectation of \(L\), then consistency is the probability that \(|L-M|\) will be greater or equal to \(|X-M|\), where \(X\) is the loglikelihood of the original data under the fitted model. Only returned if Nbootstraps>0. A low consistency (e.g., <0.05) indicates that the fitted model is a poor description of the data. See Lindholm et al. (2019) for background.

\section*{Author(s)}

Stilianos Louca

\section*{References}
J. Felsenstein (1985). Phylogenies and the Comparative Method. The American Naturalist. 125:115.
A. Lindholm, D. Zachariah, P. Stoica, T. B. Schoen (2019). Data consistency approach to model validation. IEEE Access. 7:59788-59796.

\section*{See Also}
simulate_bm_model, get_independent_contrasts

\section*{Examples}
```


# generate a random tree

tree = generate_random_tree(list(birth_rate_intercept=1), 10000)\$tree

# Example 1: Scalar case

# - - - - - - - - - - - - - -

# simulate scalar continuous trait on the tree

D = 1
tip_states = simulate_bm_model(tree, diffusivity=D)\$tip_states

# estimate original diffusivity from the generated data

fit = fit_bm_model(tree, tip_states)
cat(sprintf("True D=%g, fitted D=%g\n",D,fit\$diffusivity))

# Example 2: Multivariate case

# - - - - - - - - - - - - - - -

# simulate vector-valued continuous trait on the tree

D = get_random_diffusivity_matrix(Ntraits=5)
tip_states = simulate_bm_model(tree, diffusivity=D)\$tip_states

# estimate original diffusivity matrix from the generated data

fit = fit_bm_model(tree, tip_states)

# compare true and fitted diffusivity matrices

cat("True D:\n"); print(D)
cat("Fitted D:\n"); print(fit\$diffusivity)

```
```

fit_hbds_model_on_grid

```

\section*{Description}

Given a timetree (potentially sampled through time and not necessarily ultrametric), fit a homogenous birth-death-sampling (HBDS) model in which speciation, extinction and lineage sampling occurs at some continuous (Poissonian) rates \(\lambda, \mu\) and \(\psi\), which are defined on a fixed grid of discrete time points and assumed to vary polynomially between grid points. Sampled lineages are kept in the pool of extant lineages at some "retention probability" \(\kappa\), which may also depend on time. In addition, this model can include concentrated sampling attempts (CSAs) at a finite set of discrete time points \(t_{1}, . ., t_{m}\). "Homogenous" refers to the assumption that, at any given moment in time, all lineages exhibit the same speciation/extinction/sampling rates. Every HBDS model is thus defined based on the values that \(\lambda, \mu, \psi\) and \(\kappa\) take over time, as well as the sampling probabilities \(\rho_{1}, . ., \rho_{m}\) and retention probabilities \(\kappa_{1}, . ., \kappa_{m}\) during the concentrated sampling attempts. This function estimates the values of \(\lambda, \mu, \psi\) and \(\kappa\) on each grid point, as well as the \(\rho_{1}, . ., \rho_{m}\) and \(\kappa_{1}, . ., \kappa_{m}\), by maximizing the corresponding likelihood of the timetree. Special cases of this model (when rates are piecewise constant through time) are sometimes known as "birth-death-skyline plots" in the literature (Stadler 2013). In epidemiology, these models are often used to describe the phylogenies of viral strains sampled over the course of the epidemic.

\section*{Usage}
\begin{tabular}{|c|c|c|}
\hline & tree, root_age & \(=\) NULL, \\
\hline & oldest_age & = NULL, \\
\hline & age_grid & = NULL, \\
\hline & CSA_ages & = NULL, \\
\hline & min_lambda & \(=0\), \\
\hline & max_lambda & \(=+\) Inf, \\
\hline & min_mu & \(=0\), \\
\hline & max_mu & \(=+I n f\), \\
\hline & min_psi & \(=0\), \\
\hline & max_psi & = +Inf, \\
\hline & min_kappa & \(=0\), \\
\hline & max_kappa & \(=1\), \\
\hline & min_CSA_probs & \(=0\), \\
\hline & max_CSA_probs & \(=1\), \\
\hline & min_CSA_kappas & \(=0\), \\
\hline & max_CSA_kappas & \(=1\), \\
\hline & guess_lambda & = NULL, \\
\hline & guess_mu & = NULL, \\
\hline & guess_psi & = NULL, \\
\hline & guess_kappa & = NULL, \\
\hline & guess_CSA_probs & = NULL, \\
\hline & guess_CSA_kappas & = NULL, \\
\hline & fixed_lambda & = NULL, \\
\hline & fixed_mu & = NULL, \\
\hline & fixed_psi & = NULL, \\
\hline & fixed_kappa & = NULL, \\
\hline & fixed_CSA_probs & = NULL, \\
\hline & fixed_CSA_kappas & = NULL, \\
\hline
\end{tabular}
\begin{tabular}{|c|c|}
\hline fixed_age_grid & = NULL, \\
\hline const_lambda & = FALSE, \\
\hline const_mu & = FALSE, \\
\hline const_psi & = FALSE, \\
\hline const_kappa & = FALSE, \\
\hline const_CSA_probs & = FALSE, \\
\hline const_CSA_kappas & = FALSE, \\
\hline splines_degree & \(=1\), \\
\hline condition & = "auto", \\
\hline ODE_relative_dt & = 0.001, \\
\hline ODE_relative_dy & \(=1 \mathrm{e}-3\), \\
\hline CSA_age_epsilon & = NULL, \\
\hline Ntrials & \(=1\), \\
\hline max_start_attempts & \(=1\), \\
\hline Nthreads & \(=1\), \\
\hline max_model_runtime & = NULL, \\
\hline Nbootstraps & \(=0\), \\
\hline Ntrials_per_bootstrap & = NULL, \\
\hline fit_control & \(=1 \mathrm{ist}()\), \\
\hline focal_param_values & = NULL, \\
\hline verbose & = FALSE, \\
\hline diagnostics & = FALSE, \\
\hline verbose_prefix & = "") \\
\hline
\end{tabular}

\section*{Arguments}
tree A timetree of class "phylo", representing the time-calibrated reconstructed phylogeny of a set of extant and/or extinct species. Tips of the tree are interpreted as terminally sampled lineages, while monofurcating nodes are interpreted as non-terminally sampled lineages, i.e., lineages sampled at some past time point and with subsequently sampled descendants.
root_age Positive numeric, specifying the age of the tree's root. Can be used to define a time offset, e.g. if the last tip was not actually sampled at the present. If NULL, this will be calculated from the tree and it will be assumed that the last tip was sampled at the present.
oldest_age Strictly positive numeric, specifying the oldest time before present ("age") to consider when calculating the likelihood. If this is equal to or greater than the root age, then oldest_age is interpreted as the stem age. If oldest_age is less than the root age, the tree is split into multiple subtrees at that age by treating every edge crossing that age as the stem of a subtree, and each subtree is considered an independent realization of the HBDS model stemming at that age. This can be useful for avoiding points in the tree close to the root, where estimation uncertainty is generally higher. If oldest_age==NULL, it is automatically set to the root age.
age_grid Numeric vector, listing ages in ascending order, on which \(\lambda, \mu, \psi\) and \(\kappa\) are fitted and allowed to vary independently. This grid must cover at least the age range from the present (age 0) to oldest_age. If NULL or of length \(<=1\) (regardless of value), then \(\lambda, \mu, \psi\) and \(\kappa\) are assumed to be time-independent.
\begin{tabular}{|c|c|}
\hline CSA_ages & Optional numeric vector, listing ages (in ascending order) at which concentrated sampling attempts (CSAs) occurred. If NULL, it is assumed that no concentrated sampling attempts took place and that all tips were sampled according to the continuous sampling rate psi. \\
\hline min_lambda & Numeric vector of length Ngrid (=max (1, length(age_grid))), or a single numeric, specifying lower bounds for the fitted speciation rate \(\lambda\) at each point in the age grid. If a single numeric, the same lower bound applies at all ages. \\
\hline max_lambda & Numeric vector of length Ngrid, or a single numeric, specifying upper bounds for the fitted speciation rate \(\lambda\) at each point in the age grid. If a single numeric, the same upper bound applies at all ages. Use +Inf to omit upper bounds. \\
\hline min_mu & Numeric vector of length Ngrid, or a single numeric, specifying lower bounds for the fitted extinction rate \(\mu\) at each point in the age grid. If a single numeric, the same lower bound applies at all ages. \\
\hline max_mu & Numeric vector of length Ngrid, or a single numeric, specifying upper bounds for the fitted extinction rate \(\mu\) at each point in the age grid. If a single numeric, the same upper bound applies at all ages. Use +Inf to omit upper bounds. \\
\hline min_psi & Numeric vector of length Ngrid, or a single numeric, specifying lower bounds for the fitted Poissonian sampling rate \(\psi\) at each point in the age grid. If a single numeric, the same lower bound applies at all ages. \\
\hline max_psi & Numeric vector of length Ngrid, or a single numeric, specifying upper bounds for the fitted Poissonian sampling rate \(\psi\) at each point in the age grid. If a single numeric, the same upper bound applies at all ages. Use +Inf to omit upper bounds. \\
\hline min_kappa & Numeric vector of length Ngrid, or a single numeric, specifying lower bounds for the fitted retention probability \(\kappa\) at each point in the age grid. If a single numeric, the same lower bound applies at all ages. \\
\hline max_kappa & Numeric vector of length Ngrid, or a single numeric, specifying upper bounds for the fitted retention probability \(\kappa\) at each point in the age grid. If a single numeric, the same upper bound applies at all ages. Use +Inf to omit upper bounds. \\
\hline min_CSA_probs & Numeric vector of length NCSA (=length(CSA_ages)), or a single numeric, specifying lower bounds for the fitted sampling probabilities \(\rho_{1}, . ., \rho_{m}\) at each concentrated sampling attempt. If a single numeric, the same lower bound applies at all CSAs. Note that, since \(\rho_{1}, \rho_{2}, \ldots\) are probabilities, min_CSA_probs should not be negative. \\
\hline max_CSA_probs & Numeric vector of length NCSA, or a single numeric, specifying upper bounds for the fitted sampling probabilities \(\rho_{1}, \rho_{2}, \ldots\) at each concentrated sampling attempt. If a single numeric, the same upper bound applies at all CSAs. Note that, since \(\rho_{1}, \rho_{2}, \ldots\) are probabilities, max_CSA_probs should not be greater than 1. \\
\hline min_CSA_kappas & Numeric vector of length NCSA, or a single numeric, specifying lower bounds for the fitted retention probabilities \(\kappa_{1}, \kappa_{2}, \ldots\) at each concentrated sampling attempt. If a single numeric, the same lower bound applies at all CSAs. Note that, since \(\kappa_{1}, \kappa_{2}, \ldots\) are probabilities, min_CSA_kappas should not be negative. \\
\hline
\end{tabular}
max_CSA_kappas Numeric vector of length NCSA, or a single numeric, specifying upper bounds for the fitted sampling probabilities \(\kappa_{1}, \kappa_{2}, \ldots\) at each concentrated sampling attempt. If a single numeric, the same upper bound applies at all CSAs. Note that, since \(\kappa_{1}, \kappa_{2}\),.. are probabilities, max_CSA_kappas should not be greater than 1.
guess_lambda Initial guess for \(\lambda\) at each age-grid point. Either NULL (an initial guess will be computed automatically), or a single numeric (guessing the same \(\lambda\) at all ages) or a numeric vector of size Ngrid specifying a separate guess for \(\lambda\) at each age-grid point. To omit an initial guess for some but not all age-grid points, set their guess values to NA. Guess values are ignored for non-fitted (i.e., fixed) parameters.
guess_mu Initial guess for \(\mu\) at each age-grid point. Either NULL (an initial guess will be computed automatically), or a single numeric (guessing the same \(\mu\) at all ages) or a numeric vector of size Ngrid specifying a separate guess for \(\mu\) at each age-grid point. To omit an initial guess for some but not all age-grid points, set their guess values to NA. Guess values are ignored for non-fitted (i.e., fixed) parameters.
guess_psi Initial guess for \(\psi\) at each age-grid point. Either NULL (an initial guess will be computed automatically), or a single numeric (guessing the same \(\psi\) at all ages) or a numeric vector of size Ngrid specifying a separate guess for \(\psi\) at each age-grid point. To omit an initial guess for some but not all age-grid points, set their guess values to NA. Guess values are ignored for non-fitted (i.e., fixed) parameters.
guess_kappa Initial guess for \(\kappa\) at each age-grid point. Either NULL (an initial guess will be computed automatically), or a single numeric (guessing the same \(\kappa\) at all ages) or a numeric vector of size Ngrid specifying a separate guess for \(\kappa\) at each age-grid point. To omit an initial guess for some but not all age-grid points, set their guess values to NA. Guess values are ignored for non-fitted (i.e., fixed) parameters.
guess_CSA_probs
Initial guess for the \(\rho_{1}, \rho_{2}, \ldots\) at each concentrated sampling attempt. Either NULL (an initial guess will be computed automatically), or a single numeric (guessing the same value at every CSA) or a numeric vector of size NCSA specifying a separate guess at each CSA. To omit an initial guess for some but not all CSAs, set their guess values to NA. Guess values are ignored for non-fitted (i.e., fixed) parameters.
guess_CSA_kappas
Initial guess for the \(\kappa_{1}, \kappa_{2}, \ldots\) at each concentrated sampling attempt. Either NULL (an initial guess will be computed automatically), or a single numeric (guessing the same value at every CSA) or a numeric vector of size NCSA specifying a separate guess at each CSA. To omit an initial guess for some but not all CSAs, set their guess values to NA. Guess values are ignored for non-fitted (i.e., fixed) parameters.
fixed_lambda Optional fixed (i.e. non-fitted) \(\lambda\) values on one or more age-grid points. Either \(\operatorname{NULL}\) ( \(\lambda\) is not fixed anywhere), or a single numeric ( \(\lambda\) fixed to the same value at all grid points) or a numeric vector of size Ngrid (if fixed_age_grid=NULL; \(\lambda\) fixed on one or more age-grid points, use NA for non-fixed values) or a numeric vector of the same size as fixed_age_grid (if fixed_age_grid!=NULL, in which case all entries in fixed_lambda must be finite numbers).
\begin{tabular}{|c|c|}
\hline fixed_mu & Optional fixed (i.e. non-fitted) \(\mu\) values on one or more age-grid points. Either NULL ( \(\mu\) is not fixed anywhere), or a single numeric ( \(\mu\) fixed to the same value at all grid points) or a numeric vector of size Ngrid (if fixed_age_grid=NULL; \(\mu\) fixed on one or more age-grid points, use NA for non-fixed values) or a numeric vector of the same size as fixed_age_grid (if fixed_age_grid!=NULL, in which case all entries in fixed_mu must be finite numbers). \\
\hline fixed_psi & Optional fixed (i.e. non-fitted) \(\psi\) values on one or more age-grid points. Either NULL ( \(\psi\) is not fixed anywhere), or a single numeric ( \(\psi\) fixed to the same value at all grid points) or a numeric vector of size Ngrid (if fixed_age_grid=NULL; \(\psi\) fixed on one or more age-grid points, use NA for non-fixed values) or a numeric vector of the same size as fixed_age_grid (if fixed_age_grid!=NULL, in which case all entries in fixed_psi must be finite numbers). \\
\hline fixed_kappa & Optional fixed (i.e. non-fitted) \(\kappa\) values on one or more age-grid points. Either NULL ( \(\kappa\) is not fixed anywhere), or a single numeric ( \(\kappa\) fixed to the same value at all grid points) or a numeric vector of size Ngrid (if fixed_age_grid=NULL; \(\kappa\) fixed on one or more age-grid points, use NA for non-fixed values) or a numeric vector of the same size as fixed_age_grid (if fixed_age_grid!=NULL, in which case all entries in fixed_kappa must be finite numbers). \\
\hline \multicolumn{2}{|l|}{fixed_CSA_probs} \\
\hline & Optional fixed (i.e. non-fitted) \(\rho_{1}, \rho_{2}, \ldots\) values on one or more age-grid points. Either NULL (none of the \(\rho_{1}, \rho_{2}, \ldots\) are fixed), or a single numeric ( \(\rho_{1}, \rho_{2}, \ldots\) are fixed to the same value at all CSAs) or a numeric vector of size NCSA (one or more of the \(\rho_{1}, \rho_{2}, \ldots\) are fixed, use NA for non-fixed values). \\
\hline \multicolumn{2}{|l|}{fixed_CSA_kappas} \\
\hline & Optional fixed (i.e. non-fitted) \(\kappa_{1}, \kappa_{2}, \ldots\) values on one or more age-grid points. Either NULL (none of the \(\kappa_{1}, \kappa_{2}, \ldots\) are fixed), or a single numeric ( \(\kappa_{1}, \kappa_{2}, \ldots\) are fixed to the same value at all CSAs) or a numeric vector of size NCSA (one or more of the \(\kappa_{1}, \kappa_{2}, \ldots\) are fixed, use NA for non-fixed values). \\
\hline fixed_age_grid & \begin{tabular}{l}
Optional numeric vector, specifying an age grid on which fixed_lambda, fixed_mu, fixed_psi and fixed_kappa (whichever is provided) are defined instead of on the age_grid. If fixed_age_grid is provided, then each of fixed_lambda, fixed_mu, fixed_psi and fixed_kappa must be defined (i.e. have a finite nonnegative value) on every point in fixed_age_grid. Entries in fixed_age_grid must be in ascending order and must cover at least the ages 0 to oldest_age. \\
This option may be useful if you want to fit some parameters on a coarse grid, but want to specify (fix) some other parameters on a much finer grid. Also note that if fixed_age_grid is used, all parameters lambda, mu, psi and kappa are internally re-interpolated onto fixed_age_grid when evaluating the likelihood; hence, in general fixed_age_grid should be much finer than age_grid. In most situations you would probably want to keep the default fixed_age_grid=NULL
\end{tabular} \\
\hline const_lambda & Logical, specifying whether \(\lambda\) should be assumed constant across the grid, i.e. time-independent. Setting const_lambda=TRUE reduces the number of free (i.e., independently fitted) parameters. If \(\lambda\) is fixed on some grid points (i.e. via fixed_lambda), then only the non-fixed lambdas are assumed to be identical to one another. \\
\hline const_mu & Logical, specifying whether \(\mu\) should be assumed constant across the grid, i.e. time-independent. Setting const_mu=TRUE reduces the number of free (i.e., \\
\hline
\end{tabular}
\(\left.\begin{array}{ll} & \begin{array}{l}\text { independently fitted) parameters. If } \mu \text { is fixed on some grid points (i.e. via } \\ \\ \text { fixed_mu), then only the non-fixed mus are assumed to be identical to one an- } \\ \text { other. }\end{array} \\ \text { Logical, specifying whether } \psi \text { should be assumed constant across the grid, i.e. } \\ \text { time-independent. Setting const_psi=TRUE reduces the number of free (i.e., } \\ \text { independently fitted) parameters. If } \psi \text { is fixed on some grid points (i.e. via } \\ \text { fixed_psi), then only the non-fixed psis are assumed to be identical to one } \\ \text { another. } \\ \text { Logical, specifying whether } \kappa \text { should be assumed constant across the grid, i.e. } \\ \text { time-independent. Setting const_kappa=TRUE reduces the number of free (i.e., } \\ \text { independently fitted) parameters. If } \kappa \text { is fixed on some grid points (i.e. via } \\ \text { fixed_kappa), then only the non-fixed kappas are assumed to be identical to }\end{array}\right\}\) one another.

Positive unitless number, specifying the relative difference between subsequent simulated and interpolated values, in internally used ODE solvers. Typical values are \(1 \mathrm{e}-2\) to \(1 \mathrm{e}-5\). A smaller ODE_relative_dy increases interpolation accuracy, but also increases memory requirements and adds runtime (scaling with the tree's age span, not with Ntips).

Non-negative numeric, in units of time, specfying the age radius around a concentrated sampling attempt, within which to assume that sampling events were due to that concentrated sampling attempt. If NULL, this is chosen automatically based on the anticipated scale of numerical rounding errors. Only relevant if concentrated sampling attempts are included.

Ntrials Integer, specifying the number of independent fitting trials to perform, each starting from a random choice of model parameters. Increasing Ntrials reduces the risk of reaching a non-global local maximum in the fitting objective.
```

max_start_attempts

```

Integer, specifying the number of times to attempt finding a valid start point (per trial) before giving up on that trial. Randomly choosen extreme start parameters may occasionally result in Inf/undefined likelihoods, so this option allows the algorithm to keep looking for valid starting points.
Nthreads Integer, specifying the number of parallel threads to use for performing multiple fitting trials simultaneously. This should generally not exceed the number of available CPUs on your machine. Parallel computing is not available on the Windows platform.
max_model_runtime
Optional numeric, specifying the maximum number of seconds to allow for each evaluation of the likelihood function. Use this to abort fitting trials leading to parameter regions where the likelihood takes a long time to evaluate (these are often unlikely parameter regions).

Nbootstraps Integer, specifying the number of parametric bootstraps to perform for estimating standard errors and confidence intervals of estimated parameters. Set to 0 for no bootstrapping.
Ntrials_per_bootstrap
Integer, specifying the number of fitting trials to perform for each bootstrap sampling. If NULL, this is set equal to max (1,Ntrials). Decreasing Ntrials_per_bootstrap will reduce computation time, at the expense of potentially inflating the estimated confidence intervals; in some cases (e.g., for very large trees) this may be useful if fitting takes a long time and confidence intervals are very narrow anyway. Only relevant if Nbootstraps>0.
fit_control Named list containing options for the nlminb optimization routine, such as iter.max, eval.max or rel.tol. For a complete list of options and default values see the documentation of nlminb in the stats package.
focal_param_values
Optional list, listing combinations of parameter values of particular interest and for which the log-likelihoods should be returned. Every element of this list should itself be a named list, containing the elements lambda, mu, psi and kappa (each being a numeric vector of size NG) as well as the elements CSA_probs and CSA_kappas (each being a numeric vector of size NCSA). This may be used e.g. for diagnostic purposes, e.g. to examine the shape of the likelihood function.
verbose Logical, specifying whether to print progress reports and warnings to the screen. Note that errors always cause a return of the function (see return values success and error).
diagnostics Logical, specifying whether to print detailed information (such as model likelihoods) at every iteration of the fitting routine. For debugging purposes mainly.
verbose_prefix Character, specifying the line prefix for printing progress reports to the screen.

\section*{Details}

Warning: In the absence of concentrated sampling attempts (NCSA=0), and without well-justified a priori constraints on either \(\lambda, \mu, \psi\) and/or \(\kappa\), it is generally impossible to reliably estimate \(\lambda, \mu, \psi\) and \(\kappa\) from timetrees alone. This routine (and any other software that claims to estimate \(\lambda, \mu, \psi\) and \(\kappa\) solely from timetrees) should thus be treated with great suspicion. Many epidemiological models make the (often reasonable assumption) that \(\kappa=0\); note that even in this case, one generally can't co-estimate \(\lambda, \mu\) and \(\psi\) from the timetree alone.

It is advised to provide as much information to the function fit_hbds_model_on_grid as possible, including reasonable lower and upper bounds (min_lambda, max_lambda, min_mu, max_mu, min_psi, max_psi, min_kappa, max_kappa) and reasonable parameter guesses. It is also important that the age_grid is sufficiently fine to capture the expected major variations of \(\lambda, \mu, \psi\) and \(\kappa\) over time, but keep in mind the serious risk of overfitting when age_grid is too fine and/or the tree is too small. The age_grid does not need to be uniform, i.e., you may want to use a finer grid in regions where there's more data (tips) available. If strong lower and upper bounds are not available and fitting takes a long time to run, consider using the option max_model_runtime to limit how much time the fitting allows for each evaluation of the likelihood.
Note that here "age" refers to time before present, i.e., age increases from tips to root and age 0 is present-day. CSAs are enumerated in the order of increasing age, i.e., from the present to the past. Similarly, the age grid specifies time points from the present towards the past.

\section*{Value}

A list with the following elements:
success Logical, indicating whether model fitting succeeded. If FALSE, the returned list will include an additional "error" element (character) providing a description of the error; in that case all other return variables may be undefined.
objective_value
The maximized fitting objective. Currently, only maximum-likelihood estimation is implemented, and hence this will always be the maximized log-likelihood.
objective_name The name of the objective that was maximized during fitting. Currently, only maximum-likelihood estimation is implemented, and hence this will always be "loglikelihood".
loglikelihood The log-likelihood of the fitted model for the given timetree.
guess_loglikelihood
The log-likelihood of the guessed model for the given timetree.
param_fitted Named list, specifying the fixed and fitted model parameters. This list will contain the elements lambda, mu, psi and kappa (each being a numeric vector of size NG, listing \(\lambda, \mu, \psi\) and \(\kappa\) at each age-grid point) as well as the elements CSA_probs and CSA_kappas (each being a numeric vector of size NCSA).
\begin{tabular}{ll} 
param_guess & \begin{tabular}{l} 
Named list, specifying the guessed model parameters. This list will contain the \\
elements lambda, mu, psi and kappa (each being a numeric vector of size NG) \\
as well as the elements CSA_probs and CSA_kappas (each being a numeric vec- \\
tor of size NCSA). Between grid points \(\lambda\) should be interpreted as a piecewise \\
polynomial function (natural spline) of degree splines_degree; to evaluate this \\
function at arbitrary ages use the castor routine evaluate_spline. The same \\
also applies to \(\mu, \psi\) and \(\kappa\).
\end{tabular} \\
Numeric vector of size NG, the age-grid on which \(\lambda, \mu, \psi\) and \(\kappa\) are defined. \\
This will be the same as the provided age_grid, unless the latter was NULL or \\
of length <=1.
\end{tabular}\(\quad\)\begin{tabular}{l} 
Numeric vector of size NCSA, ting listhe ages at which concentrated sampling \\
attempts occurred. This is the same as provided to the function.
\end{tabular}
\begin{tabular}{ll} 
CI50upper & \begin{tabular}{l} 
Similar to CI50lower, but listing the upper end of the \(50 \%\) confidence inter- \\
val (i.e. the \(75 \%\) quantile) for each parameter. For example, the confidence \\
interval for \(\lambda\) at age age_grid[1] will be between CI50lower \(\$\) lambda[1] and \\
CI50upper \(\$ l a m b d a[1] . ~ O n l y ~ i n c l u d e d ~ i f ~ N b o o t s t r a p s ~\)
\end{tabular} 0 .
\end{tabular}

\section*{Author(s)}

Stilianos Louca

\section*{References}
T. Stadler, D. Kuehnert, S. Bonhoeffer, A. J. Drummond (2013). Birth-death skyline plot reveals temporal changes of epidemic spread in HIV and hepatitis C virus (HCV). PNAS. 110:228-233.
A. Lindholm, D. Zachariah, P. Stoica, T. B. Schoen (2019). Data consistency approach to model validation. IEEE Access. 7:59788-59796.

\section*{See Also}
```

simulate_deterministic_hbds,fit_hbds_model_parametric

```

\section*{Examples}
```


## Not run:

# define lambda \& mu \& psi as functions of time

# Assuming an exponentially varying lambda \& mu, and a constant psi

time2lambda = function(times){ 2*exp(0.1*times) }
time2mu = function(times){ 0.1*exp(0.09*times) }
time2psi = function(times){ rep(0.2, times=length(times)) }

# define concentrated sampling attempts

CSA_times = c(3,4)
CSA_probs =c(0.1, 0.2)

# generate random tree based on lambda, mu \& psi

# assume that all sampled lineages are removed from the pool (i.e. kappa=0)

time_grid = seq(from=0, to=100, by=0.01)
simul = generate_tree_hbds( max_time = 5,
time_grid = time_grid,
lambda = time2lambda(time_grid),

```
```

                mu = time2mu(time_grid),
                psi = time2psi(time_grid),
                    kappa = 0,
                    CSA_times = CSA_times,
                    CSA_probs = CSA_probs,
                    CSA_kappas = 0)
    tree = simul$tree
root_age = simul$root_age
cat(sprintf("Tree has %d tips\n",length(tree\$tip.label)))

# Define an age grid on which lambda_function \& mu_function shall be fitted

fit_age_grid = seq(from=0,to=root_age,length.out=3)

# Fit an HBDS model on a grid

# Assume that psi is known and that sampled lineages are removed from the pool

# Hence, we only fit lambda \& mu \& CSA_probs

cat(sprintf("Fitting model to tree..\n"))
fit = fit_hbds_model_on_grid(tree,
root_age
fixed_psi = time2psi(simul$final_time-fit_age_grid),
    fixed_kappa = 0,
    fixed_CSA_kappas = 0,
    Ntrials = 4,
    Nthreads = 4,
    Nbootstraps = 0,
    verbose = TRUE,
    verbose_prefix = " ")
if(!fit$success){
cat(sprintf("ERROR: Fitting failed: %s\n",fit$error))
}else{
    # compare fitted lambda to true lambda
    plot(x=fit$age_grid,
y=fit$param_fitted$lambda,
type='l',
col='\#000000',
xlim=c(root_age,0),
xlab='age',
ylab='lambda')
lines(x=simul\$final_time-time_grid,
y=time2lambda(time_grid),
type='l',
col='\#0000AA')
}

# compare true and fitted model in terms of their LTTs

LTT = castor::count_lineages_through_time(tree, Ntimes=100, include_slopes=TRUE)
LTT$ages = root_age - LTT$times
cat(sprintf("Simulating deterministic HBDS (true model)..\n"))
age0 = 0.5 \# reference age at which to equate LTTs

```
```

LTT0 = approx(x=LTT$ages, y=LTT$lineages, xout=age0)$y # tree LTT at age0
fsim = simulate_deterministic_hbds( age_grid = fit$age_grid,
lambda = fit$param_fitted$lambda,
mu = fit$param_fitted$mu,
psi = fit$param_fitted$psi,
kappa = fit$param_fitted$kappa,
CSA_ages = fit$CSA_ages,
    CSA_probs = fit$param_fitted$CSA_probs,
    CSA_kappas = fit$param_fitted$CSA_kappas,
    requested_ages = seq(0,root_age,length.out=200),
    age0 = age0,
    LTT0 = LTT0,
    splines_degree = 1)
if(!fsim$success){
cat(sprintf("ERROR: Could not simulate fitted model: %s\n",fsim$error))
    stop()
}
plot(x=LTT$ages, y=LTT$lineages, type='l', col='#0000AA', lwd=2, xlim=c(root_age,0))
lines(x=fsim$ages, y=fsim\$LTT, type='l', col='\#000000', lwd=2)

## End(Not run)

```
fit_hbds_model_parametric

Fit a parametric homogenous birth-death-sampling model to a timetree.

\section*{Description}

Given a timetree (potentially sampled through time and not necessarily ultrametric), fit a homogenous birth-death-sampling (HBDS) model in which speciation, extinction and lineage sampling occurs at some continuous (Poissonian) rates \(\lambda, \mu\) and \(\psi\), which are given as parameterized functions of time before present. Sampled lineages are kept in the pool of extant lineages at some "retention probability" \(\kappa\), which may also depend on time. In addition, this model can include concentrated sampling attempts (CSAs) at a finite set of discrete time points \(t_{1}, . ., t_{m}\). "Homogenous" refers to the assumption that, at any given moment in time, all lineages exhibit the same speciation/extinction/sampling rates. Every HBDS model is thus defined based on the values that \(\lambda, \mu\), \(\psi\) and \(\kappa\) take over time, as well as the sampling probabilities \(\rho_{1}, . ., \rho_{m}\) and retention probabilities \(\kappa_{1}, . ., \kappa_{m}\) during the concentrated sampling attempts; each of these parameters, in turn, is assumed to be determined by a finite set of parameters. This function estimates these parameters by maximizing the corresponding likelihood of the timetree. Special cases of this model are sometimes known as "birth-death-skyline plots" in the literature (Stadler 2013). In epidemiology, these models are often used to describe the phylogenies of viral strains sampled over the course of the epidemic.

\section*{Usage}
fit_hbds_model_parametric(tree,
param_values,
param_guess = NULL,


\section*{Arguments}
\begin{tabular}{ll} 
tree & \begin{tabular}{l} 
A timetree of class "phylo", representing the time-calibrated reconstructed phy- \\
logeny of a set of extant and/or extinct species. Tips of the tree are interpreted \\
as terminally sampled lineages, while monofurcating nodes are interpreted as \\
non-terminally sampled lineages, i.e., lineages sampled at some past time point \\
and with subsequently sampled descendants.
\end{tabular} \\
param_values \(\quad\)\begin{tabular}{l} 
Numeric vector, specifying fixed values for a some or all model parameters. \\
For fitted (i.e., non-fixed) parameters, use NaN or NA. For example, the vector \\
c (1.5, NA, 40) specifies that the 1st and 3rd model parameters are fixed at the \\
values 1.5 and 40, respectively, while the 2nd parameter is to be fitted. The \\
length of this vector defines the total number of model parameters. If entries in \\
this vector are named, the names are taken as parameter names. Names should \\
be included if the functions lambda, mu, psi, kappa, CSA_psi and CSA_kappa \\
query parameter values by name (as opposed to numeric index).
\end{tabular} \\
param_guess \(\quad\)\begin{tabular}{l} 
Numeric vector of size NP, specifying a first guess for the value of each model \\
parameter. For fixed parameters, guess values are ignored. Can be NULL only if \\
all model parameters are fixed.
\end{tabular} \\
param_min & \begin{tabular}{l} 
Optional numeric vector of size NP, specifying lower bounds for model parame-
\end{tabular}
\end{tabular}
ters. If of size 1 , the same lower bound is applied to all parameters. Use -Inf to omit a lower bound for a parameter. If NULL, no lower bounds are applied. For fixed parameters, lower bounds are ignored.
param_max Optional numeric vector of size NP, specifying upper bounds for model parameters. If of size 1 , the same upper bound is applied to all parameters. Use +Inf to omit an upper bound for a parameter. If NULL, no upper bounds are applied. For fixed parameters, upper bounds are ignored.
param_scale Optional numeric vector of size NP, specifying typical scales for model parameters. If of size 1 , the same scale is assumed for all parameters. If NULL, scales are determined automatically. For fixed parameters, scales are ignored. It is strongly advised to provide reasonable scales, as this facilitates the numeric optimization algorithm.
root_age Positive numeric, specifying the age of the tree's root. Can be used to define a time offset, e.g. if the last tip was not actually sampled at the present. If NULL, this will be calculated from the tree and it will be assumed that the last tip was sampled at the present.
oldest_age Strictly positive numeric, specifying the oldest time before present ("age") to consider when calculating the likelihood. If this is equal to or greater than the root age, then oldest_age is interpreted as the stem age. If oldest_age is less than the root age, the tree is split into multiple subtrees at that age by treating every edge crossing that age as the stem of a subtree, and each subtree is considered an independent realization of the HBDS model stemming at that age. This can be useful for avoiding points in the tree close to the root, where estimation uncertainty is generally higher. If oldest_age==NULL, it is automatically set to the root age.
lambda Function specifying the speciation rate at any given age (time before present) and for any given parameter values. This function must take exactly two arguments, the 1 st one being a numeric vector (one or more ages) and the 2 nd one being a numeric vector of size NP (parameter values), and return a numeric vector of the same size as the 1st argument with strictly positive entries. Can also be a single numeric (i.e., lambda is fixed).
Function specifying the extinction rate at any given age and for any given parameter values. This function must take exactly two arguments, the 1 st one being a numeric vector (one or more ages) and the 2 nd one being a numeric vector of size NP (parameter values), and return a numeric vector of the same size as the 1 st argument with non-negative entries. Can also be a single numeric (i.e., mu is fixed).
psi Function specifying the continuous (Poissonian) lineage sampling rate at any given age and for any given parameter values. This function must take exactly two arguments, the 1 st one being a numeric vector (one or more ages) and the 2 nd one being a numeric vector of size NP (parameter values), and return a numeric vector of the same size as the 1 st argument with non-negative entries. Can also be a single numeric (i.e., psi is fixed).
kappa Function specifying the retention probability for continuously sampled lineages, at any given age and for any given parameter values. This function must take exactly two arguments, the 1 st one being a numeric vector (one or more ages)
and the 2 nd one being a numeric vector of size NP (parameter values), and return a numeric vector of the same size as the 1st argument with non-negative entries. The retention probability is the probability of a sampled lineage remaining in the pool of extant lineages. Can also be a single numeric (i.e., kappa is fixed).
age_grid Numeric vector, specifying ages at which the lambda, mu, psi and kappa functionals should be evaluated. This age grid must be fine enough to capture the possible variation in \(\lambda, \mu, \psi\) and \(\kappa\) over time, within the permissible parameter range. Listed ages must be strictly increasing, and must cover at least the full considered age interval (from 0 to oldest_age). Can also be NULL or a vector of size 1 , in which case \(\lambda, \mu, \psi\) and \(\kappa\) are assumed to be time-independent.
CSA_ages Optional numeric vector, listing ages (in ascending order) at which concentrated sampling attempts occurred. If NULL, it is assumed that no concentrated sampling attempts took place and that all tips were sampled according to the continuous sampling rate psi.
CSA_probs Function specifying the sampling probabilities during the various concentrated sampling attempts, depending on parameter values. Hence, for any choice of parameters, CSA_probs must return a numeric vector of the same size as CSA_ages. Can also be a single numeric (i.e., concentrated sampling probability is fixed).
CSA_kappas Function specifying the retention probabilities during the various concentrated sampling attempts, depending on parameter values. Hence, for any choice of parameters, CSA_kappas must return a numeric vector of the same size as CSA_ages. Can also be a single numeric (i.e., retention probability during concentrated samplings is fixed).
condition Character, either "crown", "stem", "none" or "auto", specifying on what to condition the likelihood. If "crown", the likelihood is conditioned on the survival of the two daughter lineages branching off at the root. If "stem", the likelihood is conditioned on the survival of the stem lineage. Note that "crown" really only makes sense when oldest_age is equal to the root age, while "stem" is recommended if oldest_age differs from the root age. "none" is usually not recommended. If "auto", the condition is chosen according to the above recommendations.
ODE_relative_dt
Positive unitless number, specifying the default relative time step for the ordinary differential equation solvers. Typical values are 0.01-0.001.

ODE_relative_dy
Positive unitless number, specifying the relative difference between subsequent simulated and interpolated values, in internally used ODE solvers. Typical values are \(1 \mathrm{e}-2\) to \(1 \mathrm{e}-5\). A smaller ODE_relative_dy increases interpolation accuracy, but also increases memory requirements and adds runtime (scaling with the tree's age span, not with Ntips).
CSA_age_epsilon
Non-negative numeric, in units of time, specfying the age radius around a concentrated sampling attempt, within which to assume that sampling events were due to that concentrated sampling attempt. If NULL, this is chosen automatically based on the anticipated scale of numerical rounding errors. Only relevant if concentrated sampling attempts are included.
Ntrials \begin{tabular}{l} 
Integer, specifying the number of independent fitting trials to perform, each \\
starting from a random choice of model parameters. Increasing Ntrials re- \\
duces the risk of reaching a non-global local maximum in the fitting objective.
\end{tabular}
max_start_attempts
Integer, specifying the number of times to attempt finding a valid start point (per
trial) before giving up on that trial. Randomly chosen extreme start parameters
may occasionally result in Inf/undefined likelihoods, so this option allows the
algorithm to keep looking for valid starting points.
Integer, specifying the number of parallel threads to use for performing multiple
fitting trials simultaneously. This should generally not exceed the number of
available CPUs on your machine. Parallel computing is not available on the
Windows platform.

\section*{Details}

This function is designed to estimate a finite set of scalar parameters ( \(p_{1}, . ., p_{n} \in \mathrm{R}\) ) that determine the speciation rate \(\lambda\), the extinction rate \(\mu\), the sampling rate \(\psi\), the retention rate \(\kappa\), the concentrated sampling probabilities \(\rho_{1}, . ., \rho_{m}\) and the concentrated retention probabilities \(\kappa_{1}, . ., \kappa_{m}\), by
maximizing the likelihood of observing a given timetree under the HBDS model. Note that the ages (times before present) of the concentrated sampling attempts are assumed to be known and are not fitted.
It is generally advised to provide as much information to the function fit_hbds_model_parametric as possible, including reasonable lower and upper bounds (param_min and param_max), a reasonable parameter guess (param_guess) and reasonable parameter scales param_scale. If some model parameters can vary over multiple orders of magnitude, it is advised to transform them so that they vary across fewer orders of magnitude (e.g., via log-transformation). It is also important that the age_grid is sufficiently fine to capture the variation of \(\lambda, \mu, \psi\) and \(\kappa\) over time, since the likelihood is calculated under the assumption that these functions vary linearly between grid points.
Note that in this function age always refers to time before present, i.e., present day age is 0 and age increases from tips to root. The functions lambda, mu, psi and kappa should be functions of age, not forward time. Similarly, concentrated sampling attempts (CSAs) are enumerated in order of increasing age, i.e., starting with the youngest CSA and moving towards older CSAs.

\section*{Value}

A list with the following elements:
success Logical, indicating whether model fitting succeeded. If FALSE, the returned list will include an additional "error" element (character) providing a description of the error; in that case all other return variables may be undefined.
objective_value
The maximized fitting objective. Currently, only maximum-likelihood estimation is implemented, and hence this will always be the maximized log-likelihood.
objective_name The name of the objective that was maximized during fitting. Currently, only maximum-likelihood estimation is implemented, and hence this will always be "loglikelihood".
loglikelihood The log-likelihood of the fitted model for the given timetree.
param_fitted Numeric vector of size NP (number of model parameters), listing all fitted or fixed model parameters in their standard order (see details above). If param_names was provided, elements in fitted_params will be named.
param_guess Numeric vector of size NP, listing guessed or fixed values for all model parameters in their standard order. If param_names was provided, elements in param_guess will be named.
guess_loglikelihood
The loglikelihood of the data for the initial parameter guess (param_guess).
focal_loglikelihoods
A numeric vector of the same size as nrow(focal_param_values), listing loglikelihoods for each of the focal parameter conbinations listed in focal_loglikelihoods.
NFP Integer, number of fitted (i.e., non-fixed) model parameters.
Ndata Number of data points used for fitting, i.e., the number of sampling and branching events that occurred between ages 0 and oldest_age.

AIC The Akaike Information Criterion for the fitted model, defined as \(2 k-2 \log (L)\), where \(k\) is the number of fitted parameters and \(L\) is the maximized likelihood.
\begin{tabular}{|c|c|}
\hline BIC & The Bayesian information criterion for the fitted model, defined as \(\log (n) k-\) \(2 \log (L)\), where \(k\) is the number of fitted parameters, \(n\) is the number of data points (Ndata), and \(L\) is the maximized likelihood. \\
\hline condition & Character, specifying what conditioning was root for the likelihood (e.g. "crown" or "stem"). \\
\hline converged & Logical, specifying whether the maximum likelihood was reached after convergence of the optimization algorithm. Note that in some cases the maximum likelihood may have been achieved by an optimization path that did not yet converge (in which case it's advisable to increase iter.max and/or eval.max). \\
\hline Niterations & Integer, specifying the number of iterations performed during the optimization path that yielded the maximum likelihood. \\
\hline Nevaluations & Integer, specifying the number of likelihood evaluations performed during the optimization path that yielded the maximum likelihood. \\
\hline \multicolumn{2}{|l|}{trial_start_objectives} \\
\hline & Numeric vector of size Ntrials, listing the initial objective values (e.g., loglikelihoods) for each fitting trial, i.e. at the start parameter values. \\
\hline \multicolumn{2}{|l|}{trial_objective_values} \\
\hline & Numeric vector of size Ntrials, listing the final maximized objective values (e.g., loglikelihoods) for each fitting trial. \\
\hline \multicolumn{2}{|l|}{trial_Nstart_attempts} \\
\hline & Integer vector of size Ntrials, listing the number of start attempts for each fitting trial, until a starting point with valid likelihood was found. \\
\hline \multicolumn{2}{|l|}{trial_Niterations} \\
\hline & Integer vector of size Ntrials, listing the number of iterations needed for each fitting trial. \\
\hline \multicolumn{2}{|l|}{trial_Nevaluations} \\
\hline & Integer vector of size Ntrials, listing the number of likelihood evaluations needed for each fitting trial. \\
\hline \multicolumn{2}{|l|}{standard_errors} \\
\hline & Numeric vector of size NP, estimated standard error of the parameters, based on parametric bootstrapping. Only returned if Nbootstraps>0. \\
\hline medians & Numeric vector of size NP, median the estimated parameters across parametric bootstraps. Only returned if Nbootstraps>0. \\
\hline CI50lower & Numeric vector of size NP, lower bound of the \(50 \%\) confidence interval (25\(75 \%\) percentile) for the parameters, based on parametric bootstrapping. Only returned if Nbootstraps>0. \\
\hline CI50upper & Numeric vector of size NP, upper bound of the \(50 \%\) confidence interval for the parameters, based on parametric bootstrapping. Only returned if Nbootstraps>0. \\
\hline CI95lower & Numeric vector of size NP, lower bound of the \(95 \%\) confidence interval (2.5\(97.5 \%\) percentile) for the parameters, based on parametric bootstrapping. Only returned if Nbootstraps>0. \\
\hline CI95upper & Numeric vector of size NP, upper bound of the \(95 \%\) confidence interval for the parameters, based on parametric bootstrapping. Only returned if Nbootstraps>0. \\
\hline consistency & Numeric between 0 and 1, estimated consistency of the data with the fitted model (Lindholm et al. 2019). See the documentation of fit_hbds_model_on_grid for an explanation. \\
\hline
\end{tabular}

\section*{Author(s)}

Stilianos Louca

\section*{References}
T. Stadler, D. Kuehnert, S. Bonhoeffer, A. J. Drummond (2013). Birth-death skyline plot reveals temporal changes of epidemic spread in HIV and hepatitis C virus (HCV). PNAS. 110:228-233.
A. Lindholm, D. Zachariah, P. Stoica, T. B. Schoen (2019). Data consistency approach to model validation. IEEE Access. 7:59788-59796.

\section*{See Also}
```

generate_tree_hbds, simulate_deterministic_hbds

```

\section*{Examples}
```


## Not run:

# Generate a random tree with exponentially varying lambda \& mu and constant psi

# assume that all sampled lineages are removed from the pool (i.e. kappa=0)

time_grid = seq(from=0, to=100, by=0.01)
root_age = 5
tree = generate_tree_hbds(max_time = root_age,
time_grid = time_grid,
lambda = 2*exp(0.1*time_grid),
mu = 0.1*exp(0.09*time_grid),
psi = 0.1,
kappa = 0)$tree
cat(sprintf("Tree has %d tips\n",length(tree$tip.label)))

# Define a parametric HBDS model, with exponentially varying lambda \& mu

# Assume that the sampling rate is constant but unknown

# The model thus has 5 parameters: lambda0, mu0, alpha, beta, psi

lambda_function = function(ages,params){
return(params['lambda0']*exp(-params['alpha']*ages));
}
mu_function = function(ages,params){
return(params['mu0']*exp(-params['beta']*ages));
}
psi_function = function(ages,params){
return(rep(params['psi'],length(ages)))
}

# Define an age grid on which lambda_function \& mu_function shall be evaluated

# Should be sufficiently fine to capture the variation in lambda \& mu

age_grid = seq(from=0,to=root_age,by=0.01)

# Perform fitting

cat(sprintf("Fitting model to tree..\n"))
fit = fit_hbds_model_parametric(tree,
root_age = root_age,

```
```

param_values = c(lambda0=NA, mu0=NA, alpha=NA, beta=NA, psi=NA),
param_guess = c(1,1,0,0,0.5),
param_min =c(0,0,-1,-1,0),
param_max = c(10,10,1,1,10),
param_scale = 1, \# all params are in the order of 1
lambda = lambda_function,
mu = mu_function,
psi = psi_function,
kappa = 0,
age_grid = age_grid,
Ntrials = 4, \# perform 4 fitting trials
Nthreads = 2) \# use 2 CPUs
if(!fit$success){
    cat(sprintf("ERROR: Fitting failed: %s\n",fit$error))
}else{
cat(sprintf("Fitting succeeded:\nLoglikelihood=%g\n",fit$loglikelihood))
    # print fitted parameters
    print(fit$param_fitted)
}

## End(Not run)

```
fit_hbd_model_on_grid Fit a homogenous birth-death model on a discrete time grid.

\section*{Description}

Given an ultrametric timetree, fit a homogenous birth-death (HBD) model in which speciation and extinction rates ( \(\lambda\) and \(m u\) ) are defined on a fixed grid of discrete time points and assumed to vary polynomially between grid points. "Homogenous" refers to the assumption that, at any given moment in time, all lineages exhibit the same speciation/extinction rates (in the literature this is sometimes referred to simply as "birth-death model"). Every HBD model is defined based on the values that \(\lambda\) and \(\mu\) take over time as well as the sampling fraction \(\rho\) (fraction of extant species sampled). This function estimates the values of \(\lambda\) and \(\mu\) at each grid point by maximizing the likelihood (Morlon et al. 2011) of the timetree under the resulting HBD model.

\section*{Usage}
fit_hbd_model_on_grid(tree,
\begin{tabular}{rl} 
oldest_age & \(=\) NULL, \\
age0 & \(=0\), \\
age_grid & \(=\) NULL, \\
min_lambda & \(=0\), \\
max_lambda & \(=+I n f\), \\
min_mu & \(=0\), \\
max_mu & \(=+I n f\), \\
min_rho0 & \(=1 \mathrm{e}-10\), \\
max_rho0 & \\
guess_lambda & \\
& \(=1\),
\end{tabular}
```

guess_mu = NULL,
guess_rho0 = 1,
fixed_lambda = NULL,
fixed_mu = NULL,
fixed_rho0 = NULL,
const_lambda = FALSE,
const_mu = FALSE,
splines_degree = 1,
condition = "auto",
relative_dt = 1e-3,
Ntrials = 1,
Nthreads = 1,
max_model_runtime = NULL,
fit_control = list())

```

\section*{Arguments}
tree
oldest_age

A rooted ultrametric timetree of class "phylo", representing the time-calibrated reconstructed phylogeny of a set of extant sampled species.
Strictly positive numeric, specifying the oldest time before present ("age") to consider when calculating the likelihood. If this is equal to or greater than the root age, then oldest_age is taken as the stem age, and the classical formula by Morlon et al. (2011) is used. If oldest_age is less than the root age, the tree is split into multiple subtrees at that age by treating every edge crossing that age as the stem of a subtree, and each subtree is considered an independent realization of the HBD model stemming at that age. This can be useful for avoiding points in the tree close to the root, where estimation uncertainty is generally higher. If oldest_age==NULL, it is automatically set to the root age.
age0 Non-negative numeric, specifying the youngest age (time before present) to consider for fitting, and with respect to which rho is defined. If age0>0, then rho0 refers to the sampling fraction at age age 0 , i.e. the fraction of lineages extant at age0 that are included in the tree. See below for more details.
age_grid Numeric vector, listing ages in ascending order, on which \(\lambda\) and \(\mu\) are allowed to vary independently. This grid must cover at least the age range from age 0 to oldest_age. If NULL or of length \(<=1\) (regardless of value), then \(\lambda\) and \(\mu\) are assumed to be time-independent.
min_lambda \(\quad\) Numeric vector of length Ngrid (=max (1, length(age_grid)) ), or a single numeric, specifying lower bounds for the fitted \(\lambda\) at each point in the age grid. If a single numeric, the same lower bound applies at all ages.
\(\begin{array}{ll}\text { max_lambda } & \begin{array}{l}\text { Numeric vector of length Ngrid, or a single numeric, specifying upper bounds } \\ \text { for the fitted } \lambda \text { at each point in the age grid. If a single numeric, the same upper } \\ \text { bound applies at all ages. Use +Inf to omit upper bounds. }\end{array} \\ \text { min_mu } & \begin{array}{l}\text { Numeric vector of length Ngrid, or a single numeric, specifying lower bounds } \\ \text { for the fitted } \mu \text { at each point in the age grid. If a single numeric, the same lower } \\ \text { bound applies at all ages. }\end{array} \\ \text { max_mu } & \begin{array}{l}\text { Numeric vector of length Ngrid, or a single numeric, specifying upper bounds } \\ \text { for the fitted } \mu \text { at each point in the age grid. If a single numeric, the same upper }\end{array}\end{array}\)
bound applies at all ages. Use +Inf to omit upper bounds.
min_rho0 Numeric, specifying a lower bound for the fitted sampling fraction \(\rho\) (fraction of extant species included in the tree).
max_rho0 Numeric, specifying an upper bound for the fitted sampling fraction \(\rho\).
guess_lambda Initial guess for \(\lambda\) at each age-grid point. Either NULL (an initial guess will be computed automatically), or a single numeric (guessing the same \(\lambda\) at all ages) or a numeric vector of size Ngrid specifying a separate guess for \(\lambda\) at each age-grid point. To omit an initial guess for some but not all age-grid points, set their guess values to NA. Guess values are ignored for non-fitted (i.e., fixed) parameters.
guess_mu Initial guess for \(\mu\) at each age-grid point. Either NULL (an initial guess will be computed automatically), or a single numeric (guessing the same \(\mu\) at all ages) or a numeric vector of size Ngrid specifying a separate guess for \(\mu\) at each age-grid point. To omit an initial guess for some but not all age-grid points, set their guess values to NA. Guess values are ignored for non-fitted (i.e., fixed) parameters.
guess_rho0 Numeric, specifying an initial guess for the sampling fraction \(\rho\) at age0. Setting this to NULL or NA is the same as setting it to 1 .
fixed_lambda Optional fixed (i.e. non-fitted) \(\lambda\) values on one or more age-grid points. Either NULL ( \(\lambda\) is not fixed anywhere), or a single numeric ( \(\lambda\) fixed to the same value at all grid points) or a numeric vector of size \(\operatorname{Ngrid}\) ( \(\lambda\) fixed on one or more age-grid points, use NA for non-fixed values).
fixed_mu Optional fixed (i.e. non-fitted) \(\mu\) values on one or more age-grid points. Either NULL ( \(\mu\) is not fixed anywhere), or a single numeric ( \(\mu\) fixed to the same value at all grid points) or a numeric vector of size Ngrid ( \(\mu\) fixed on one or more age-grid points, use NA for non-fixed values).
fixed_rho0 Numeric between 0 and 1, optionally specifying a fixed value for the sampling fraction \(\rho\). If NULL or NA, the sampling fraction \(\rho\) is estimated, however note that this may not always be meaningful (Stadler 2009, Stadler 2013).
const_lambda Logical, specifying whether \(\lambda\) should be assumed constant across the grid, i.e. time-independent. Setting const_lambda=TRUE reduces the number of free (i.e., independently fitted) parameters. If \(\lambda\) is fixed on some grid points (i.e. via fixed_lambda), then only the non-fixed lambdas are assumed to be identical to one another.
const_mu Logical, specifying whether \(\mu\) should be assumed constant across the grid, i.e. time-independent. Setting const_mu=TRUE reduces the number of free (i.e., independently fitted) parameters. If \(\mu\) is fixed on some grid points (i.e. via fixed_mu), then only the non-fixed mus are assumed to be identical to one another.
splines_degree Integer between 0 and 3 (inclusive), specifying the polynomial degree of \(\lambda\) and \(\mu\) between age-grid points. If 0 , then \(\lambda\) and \(\mu\) are considered piecewise constant, if 1 then \(\lambda\) and \(\mu\) are considered piecewise linear, if 2 or 3 then \(\lambda\) and \(\mu\) are considered to be splines of degree 2 or 3 , respectively. The splines_degree influences the analytical properties of the curve, e.g. splines_degree==1 guarantees a continuous curve, splines_degree==2 guarantees a continuous curve and continuous derivative, and so on. A degree of 0 is generally not recommended. The case splines_degree=0 is also known as "skyline" model.
\begin{tabular}{ll} 
condition & \begin{tabular}{l} 
Character, either "crown", "stem", "auto", "stemN" or "crownN" (where N is an \\
integer >=2), specifying on what to condition the likelihood. If "crown", the \\
likelihood is conditioned on the survival of the two daughter lineages branching \\
off at the root at that time. If "stem", the likelihood is conditioned on the survival \\
of the stem lineage, with the process having started at oldest_age. Note that \\
"crown" and "crownN"" really only make sense when oldest_age is equal to \\
the root age, while "stem" is recommended if oldest_age differs from the root \\
age. If "stem2", the condition is that the process yielded at least two sampled \\
tips, and similarly for "stem3" etc. If "crown3", the condition is that a splitting \\
occurred at the root age, both child clades survived, and in total yielded at least 3 \\
sampled tips (and similarly for "crown4" etc). If "auto", the condition is chosen \\
according to the recommendations mentioned earlier. "none" is generally not \\
recommended.
\end{tabular} \\
relative_dt \(\quad\)\begin{tabular}{l} 
Strictly positive numeric (unitless), specifying the maximum relative time step \\
allowed for integration over time, when calculating the likelihood. Smaller val- \\
ues increase integration accuracy but increase computation time. Typical values \\
are 0.0001-0.001. The default is usually sufficient.
\end{tabular} \\
Ntrials \(\quad\)\begin{tabular}{l} 
Integer, specifying the number of independent fitting trials to perform, each \\
starting from a random choice of model parameters. Increasing Ntrials re- \\
duces the risk of reaching a non-global local maximum in the fitting objective.
\end{tabular} \\
Nthreads & \begin{tabular}{l} 
Integer, specifying the number of parallel threads to use for performing multiple \\
fitting trials simultaneously. This should generally not exceed the number of
\end{tabular} \\
available CPUs on your machine. Parallel computing is not available on the
\end{tabular}
max_model_runtime

Optional numeric, specifying the maximum number of seconds to allow for each evaluation of the likelihood function. Use this to abort fitting trials leading to parameter regions where the likelihood takes a long time to evaluate (these are often unlikely parameter regions).
fit_control Named list containing options for the nlminb optimization routine, such as iter.max, eval.max or rel.tol. For a complete list of options and default values see the documentation of nlminb in the stats package.

\section*{Details}

Warning: Unless well-justified constraints are imposed on either \(\lambda\) and/or \(\mu\) and \(\rho\), it is generally impossible to reliably estimate \(\lambda\) and \(\mu\) from extant timetrees alone (Louca and Pennell, 2019). This routine (and any other software that claims to estimate \(\lambda\) and \(\mu\) solely from extant timetrees) should thus be used with great suspicion. If your only source of information is an extant timetree, and you have no a priori information on how \(\lambda\) or \(\mu\) might have looked like, you should consider using the more appropriate routines fit_hbd_pdr_on_grid and fit_hbd_psr_on_grid instead.
If age \(0>0\), the input tree is essentially trimmed at age0 (omitting anything younger than age0), and the various variables are fitted to this new (shorter) tree, with time shifted appropriately. For example, the fitted rho0 is thus the sampling fraction at age0, i.e. the fraction of lineages extant at age0 that are represented in the timetree.

It is generally advised to provide as much information to the function fit_hbd_model_on_grid as possible, including reasonable lower and upper bounds (min_lambda, max_lambda, min_mu,
max_mu, min_rho0 and max_rho0) and a reasonable parameter guess (guess_lambda, guess_mu and guess_rho0). It is also important that the age_grid is sufficiently fine to capture the expected major variations of \(\lambda\) and \(\mu\) over time, but keep in mind the serious risk of overfitting when age_grid is too fine and/or the tree is too small.

\section*{Value}

A list with the following elements:
success Logical, indicating whether model fitting succeeded. If FALSE, the returned list will include an additional "error" element (character) providing a description of the error; in that case all other return variables may be undefined.
objective_value
The maximized fitting objective. Currently, only maximum-likelihood estimation is implemented, and hence this will always be the maximized log-likelihood.
objective_name The name of the objective that was maximized during fitting. Currently, only maximum-likelihood estimation is implemented, and hence this will always be "loglikelihood".
loglikelihood The log-likelihood of the fitted model for the given timetree.
fitted_lambda Numeric vector of size Ngrid, listing fitted or fixed speciation rates \(\lambda\) at each age-grid point. Between grid points \(\lambda\) should be interpreted as a piecewise polynomial function (natural spline) of degree splines_degree; to evaluate this function at arbitrary ages use the castor routine evaluate_spline.
fitted_mu Numeric vector of size Ngrid, listing fitted or fixed extinction rates \(\mu\) at each age-grid point. Between grid points \(\mu\) should be interpreted as a piecewise polynomial function (natural spline) of degree splines_degree; to evaluate this function at arbitrary ages use the castor routine evaluate_spline.
fitted_rho Numeric, specifying the fitted or fixed sampling fraction \(\rho\).
guess_lambda Numeric vector of size Ngrid, specifying the initial guess for \(\lambda\) at each age-grid point.
guess_mu \(\quad\) Numeric vector of size Ngrid, specifying the initial guess for \(\mu\) at each age-grid point.
guess_rho0 Numeric, specifying the initial guess for \(\rho\).
age_grid The age-grid on which \(\lambda\) and \(\mu\) are defined. This will be the same as the provided age_grid, unless the latter was NULL or of length \(<=1\).
NFP Integer, number of free (i.e., independently) fitted parameters. If none of the \(\lambda\), \(\mu\) and \(\rho\) were fixed, and const_lambda=FALSE and const_mu=FALSE, then NFP will be equal to \(2 *\) Ngrid +1 .
AIC The Akaike Information Criterion for the fitted model, defined as \(2 k-2 \log (L)\), where \(k\) is the number of fitted parameters and \(L\) is the maximized likelihood.
BIC The Bayesian information criterion for the fitted model, defined as \(\log (n) k-\) \(2 \log (L)\), where \(k\) is the number of fitted parameters, \(n\) is the number of data points (number of branching times), and \(L\) is the maximized likelihood.
condition Character, specifying what conditioning was root for the likelihood (e.g. "crown" or "stem").

\title{
converged Logical, specifying whether the maximum likelihood was reached after convergence of the optimization algorithm. Note that in some cases the maximum likelihood may have been achieved by an optimization path that did not yet converge (in which case it's advisable to increase iter.max and/or eval.max). \\ Niterations Integer, specifying the number of iterations performed during the optimization path that yielded the maximum likelihood. \\ Nevaluations Integer, specifying the number of likelihood evaluations performed during the optimization path that yielded the maximum likelihood.
}

\section*{Author(s)}

Stilianos Louca

\section*{References}
T. Stadler (2009). On incomplete sampling under birth-death models and connections to the samplingbased coalescent. Journal of Theoretical Biology. 261:58-66.
T. Stadler (2013). How can we improve accuracy of macroevolutionary rate estimates? Systematic Biology. 62:321-329.
H. Morlon, T. L. Parsons, J. B. Plotkin (2011). Reconciling molecular phylogenies with the fossil record. Proceedings of the National Academy of Sciences. 108:16327-16332.
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S. Louca and M. W. Pennell (2020). Extant timetrees are consistent with a myriad of diversification histories. Nature. 580:502-505.

\section*{See Also}
```

simulate_deterministic_hbd
loglikelihood_hbd
fit_hbd_model_parametric
fit_hbd_pdr_on_grid
fit_hbd_pdr_parametric
fit_hbd_psr_on_grid

```

\section*{Examples}
```


## Not run:

# Generate a random tree with exponentially varying lambda \& mu

Ntips = 10000
rho = 0.5 \# sampling fraction
time_grid = seq(from=0, to=100, by=0.01)
lambdas = 2*exp(0.1*time_grid)
mus = 1.5*exp(0.09*time_grid)
sim = generate_random_tree( parameters = list(rarefaction=rho),
max_tips = Ntips/rho,
coalescent = TRUE,

```
```

added_rates_times = time_grid,
added_birth_rates_pc = lambdas,
added_death_rates_pc = mus)
tree = sim$tree
root_age = castor::get_tree_span(tree)$max_distance
cat(sprintf("Tree has %d tips, spans %g Myr\n",length(tree\$tip.label),root_age))

# Fit mu on grid

# Assume that lambda \& rho are known

Ngrid = 5
age_grid = seq(from=0,to=root_age,length.out=Ngrid)
fit = fit_hbd_model_on_grid(tree,
age_grid = age_grid,
max_mu = 100,
fixed_lambda= approx(x=time_grid,y=lambdas,xout=sim$final_time-age_grid)$y,
fixed_rho0 = rho,
condition = "crown",
Ntrials = 10,\# perform 10 fitting trials
Nthreads = 2,\# use two CPUs
max_model_runtime = 1) \# limit model evaluation to 1 second
if(!fit$success){
    cat(sprintf("ERROR: Fitting failed: %s\n",fit$error))
}else{
cat(sprintf("Fitting succeeded:\nLoglikelihood=%g\n",fit$loglikelihood))
    # plot fitted & true mu
    plot( x = fit$age_grid,
y = fit$fitted_mu,
            main = 'Fitted & true mu',
            xlab = 'age',
            ylab = 'mu',
            type = 'b',
            col = 'red',
            xlim = c(root_age,0))
    lines(x = sim$final_time-time_grid,
y = mus,
type = 'l',
col = 'blue');
\# get fitted mu as a function of age
mu_fun = approxfun(x=fit$age_grid, y=fit$fitted_mu)
}

## End(Not run)

```
fit_hbd_model_parametric

Fit a parametric homogenous birth-death model to a timetree.

\section*{Description}

Given an ultrametric timetree, fit a homogenous birth-death (HBD) model in which speciation and extinction rates ( \(\lambda\) and \(\mu\) ) are given as parameterized functions of time before present. "Homogenous" refers to the assumption that, at any given moment in time, all lineages exhibit the same speciation/extinction rates (in the literature this is sometimes referred to simply as "birth-death model"). Every HBD model is defined based on the values that \(\lambda\) and \(\mu\) take over time as well as the sampling fraction \(\rho\) (fraction of extant species sampled); in turn, \(\lambda, \mu\) and \(\rho\) can be parameterized by a finite set of parameters. This function estimates these parameters by maximizing the likelihood (Morlon et al. 2011) of the timetree under the resulting HBD model.

\section*{Usage}
fit_hbd_model_parametric( tree,
param_values,
param_guess \(=\) NULL,
param_min \(=-\) Inf,
param_max = +Inf,
param_scale = NULL,
oldest_age = NULL,
age0 \(=0\),
lambda,
mu \(=0\),
rho0 \(=1\),
age_grid = NULL,
condition = "auto",
relative_dt \(=1 \mathrm{e}-3\),
Ntrials = 1,
max_start_attempts = 1,
Nthreads \(=1\),
max_model_runtime \(=\) NULL,
Nbootstraps \(=0\),
Ntrials_per_bootstrap = NULL,
fit_algorithm = "nlminb",
fit_control = list(),
focal_param_values = NULL,
verbose = FALSE,
diagnostics = FALSE,
verbose_prefix = "")

\section*{Arguments}
tree A rooted ultrametric timetree of class "phylo", representing the time-calibrated reconstructed phylogeny of a set of extant sampled species.
param_values Numeric vector, specifying fixed values for a some or all model parameters. For fitted (i.e., non-fixed) parameters, use NaN or NA. For example, the vector \(c(1.5, N A, 40)\) specifies that the 1 st and 3 rd model parameters are fixed at the values 1.5 and 40 , respectively, while the 2 nd parameter is to be fitted. The length of this vector defines the total number of model parameters. If entries in
this vector are named, the names are taken as parameter names. Names should be included if you'd like returned parameter vectors to have named entries, or if the functions lambda, mu or rho query parameter values by name (as opposed to numeric index).
param_guess Numeric vector of size NP, specifying a first guess for the value of each model parameter. For fixed parameters, guess values are ignored. Can be NULL only if all model parameters are fixed.
param_min Optional numeric vector of size NP, specifying lower bounds for model parameters. If of size 1 , the same lower bound is applied to all parameters. Use -Inf to omit a lower bound for a parameter. If NULL, no lower bounds are applied. For fixed parameters, lower bounds are ignored.
param_max Optional numeric vector of size NP, specifying upper bounds for model parameters. If of size 1 , the same upper bound is applied to all parameters. Use +Inf to omit an upper bound for a parameter. If NULL, no upper bounds are applied. For fixed parameters, upper bounds are ignored.
param_scale Optional numeric vector of size NP, specifying typical scales for model parameters. If of size 1 , the same scale is assumed for all parameters. If NULL, scales are determined automatically. For fixed parameters, scales are ignored. It is strongly advised to provide reasonable scales, as this facilitates the numeric optimization algorithm.
oldest_age Strictly positive numeric, specifying the oldest time before present ("age") to consider when calculating the likelihood. If this is equal to or greater than the root age, then oldest_age is taken as the stem age, and the classical formula by Morlon et al. (2011) is used. If oldest_age is less than the root age, the tree is split into multiple subtrees at that age by treating every edge crossing that age as the stem of a subtree, and each subtree is considered an independent realization of the HBD model stemming at that age. This can be useful for avoiding points in the tree close to the root, where estimation uncertainty is generally higher. If oldest_age==NULL, it is automatically set to the root age.
age0 Non-negative numeric, specifying the youngest age (time before present) to consider for fitting, and with respect to which rho is defined. If age0>0, then rho0 refers to the sampling fraction at age age0, i.e. the fraction of lineages extant at age0 that are included in the tree. See below for more details.
lambda Function specifying the speciation rate at any given age (time before present) and for any given parameter values. This function must take exactly two arguments, the 1 st one being a numeric vector (one or more ages) and the 2 nd one being a numeric vector of size NP (parameter values), and return a numeric vector of the same size as the 1 st argument with strictly positive entries. Can also be a single number (i.e., lambda is fixed).
mu
Function specifying the extinction rate at any given age and for any given parameter values. This function must take exactly two arguments, the 1 st one being a numeric vector (one or more ages) and the 2 nd one being a numeric vector of size NP (parameter values), and return a numeric vector of the same size as the 1 st argument with non-negative entries. Can also be a single number (i.e., mu is fixed).
rho0 Function specifying the sampling fraction (fraction of extant species sampled at age0) for any given parameter values. This function must take exactly one argument, a numeric vector of size NP (parameter values), and return a numeric between 0 (exclusive) and 1 (inclusive). Can also be a single number (i.e., rho0 is fixed).
age_grid Numeric vector, specifying ages at which the lambda and mu functionals should be evaluated. This age grid must be fine enough to capture the possible variation in \(\lambda\) and \(\mu\) over time, within the permissible parameter range. If of size 1 , then lambda \& mu are assumed to be time-independent. Listed ages must be strictly increasing, and must cover at least the full considered age interval (from 0 to oldest_age). Can also be NULL or a vector of size 1 , in which case the speciation rate and extinction rate is assumed to be time-independent.
condition Character, either "crown", "stem", "auto", "stemN" or "crownN" (where N is an integer \(>=2\) ), specifying on what to condition the likelihood. If "crown", the likelihood is conditioned on the survival of the two daughter lineages branching off at the root at that time. If "stem", the likelihood is conditioned on the survival of the stem lineage, with the process having started at oldest_age. Note that "crown" and "crownN"" really only make sense when oldest_age is equal to the root age, while "stem" is recommended if oldest_age differs from the root age. If "stem2", the condition is that the process yielded at least two sampled tips, and similarly for "stem3" etc. If "crown3", the condition is that a splitting occurred at the root age, both child clades survived, and in total yielded at least 3 sampled tips (and similarly for "crown4" etc). If "auto", the condition is chosen according to the recommendations mentioned earlier. "none" is generally not recommended.
relative_dt Strictly positive numeric (unitless), specifying the maximum relative time step allowed for integration over time, when calculating the likelihood. Smaller values increase integration accuracy but increase computation time. Typical values are \(0.0001-0.001\). The default is usually sufficient.
Ntrials Integer, specifying the number of independent fitting trials to perform, each starting from a random choice of model parameters. Increasing Ntrials reduces the risk of reaching a non-global local maximum in the fitting objective.
max_start_attempts
Integer, specifying the number of times to attempt finding a valid start point (per trial) before giving up on that trial. Randomly choosen extreme start parameters may occasionally result in Inf/undefined likelihoods, so this option allows the algorithm to keep looking for valid starting points.
Nthreads Integer, specifying the number of parallel threads to use for performing multiple fitting trials simultaneously. This should generally not exceed the number of available CPUs on your machine. Parallel computing is not available on the Windows platform.
max_model_runtime
Optional numeric, specifying the maximum number of seconds to allow for each evaluation of the likelihood function. Use this to abort fitting trials leading to parameter regions where the likelihood takes a long time to evaluate (these are often unlikely parameter regions).
\begin{tabular}{|c|c|}
\hline Nbootstraps & Integer, specifying the number of parametric bootstraps to perform for estimating standard errors and confidence intervals of estimated model parameters. Set to 0 for no bootstrapping. \\
\hline \multicolumn{2}{|l|}{Ntrials_per_bootstrap} \\
\hline & Integer, specifying the number of fitting trials to perform for each bootstrap sampling. If NULL, this is set equal to max (1,Ntrials). Decreasing Ntrials_per_bootstrap will reduce computation time, at the expense of potentially inflating the estimated confidence intervals; in some cases (e.g., for very large trees) this may be useful if fitting takes a long time and confidence intervals are very narrow anyway. Only relevant if Nbootstraps>0. \\
\hline fit_algorithm & Character, specifying which optimization algorithm to use. Either "nlminb" or "subplex" are allowed. \\
\hline fit_control & Named list containing options for the nlminb or subplex optimization routine, depending on the choice of fit_algorithm. For example, for "nlminb" commonly modified options are iter.max, eval.max or rel.tol. For a complete list of options and default values see the documentation of nlminb in the stats package or of nloptr in the nloptr package. \\
\hline \multicolumn{2}{|l|}{focal_param_values} \\
\hline & Optional numeric matrix having NP columns and an arbitrary number of rows, listing combinations of parameter values of particular interest and for which the log-likelihoods should be returned. This may be used for diagnostic purposes, e.g., to examine the shape of the likelihood function. \\
\hline verbose & Logical, specifying whether to print progress reports and warnings to the screen. Note that errors always cause a return of the function (see return values success and error). \\
\hline diagnostics & Logical, specifying whether to print detailed information (such as model likelihoods) at every iteration of the fitting routine. For debugging purposes mainly. \\
\hline verbose_prefix & Character, specifying the line prefix for printing progress reports to the screen. \\
\hline
\end{tabular}

\section*{Details}

This function is designed to estimate a finite set of scalar parameters ( \(p_{1}, . ., p_{n} \in \mathrm{R}\) ) that determine the speciation rate \(\lambda\), the extinction rate \(\mu\) and the sampling fraction \(\rho\), by maximizing the likelihood of observing a given timetree under the HBD model. For example, the investigator may assume that both \(\lambda\) and \(\mu\) vary exponentially over time, i.e. they can be described by \(\lambda(t)=\lambda_{o} \cdot e^{-\alpha t}\) and \(\mu(t)=\mu_{o} \cdot e^{-\beta t}\) (where \(\lambda_{o}, \mu_{o}\) are unknown present-day rates and \(\alpha, \beta\) are unknown factors, and \(t\) is time before present), and that the sampling fraction \(\rho\) is known. In this case the model has 4 free parameters, \(p_{1}=\lambda_{o}, p_{2}=\mu_{o}, p_{3}=\alpha\) and \(p_{4}=\beta\), each of which may be fitted to the tree.

It is generally advised to provide as much information to the function fit_hbd_model_parametric as possible, including reasonable lower and upper bounds (param_min and param_max), a reasonable parameter guess (param_guess) and reasonable parameter scales param_scale. If some model parameters can vary over multiple orders of magnitude, it is advised to transform them so that they vary across fewer orders of magnitude (e.g., via log-transformation). It is also important that the age_grid is sufficiently fine to capture the variation of lambda and mu over time, since the likelihood is calculated under the assumption that both vary linearly between grid points.

\section*{Value}

A list with the following elements:
success Logical, indicating whether model fitting succeeded. If FALSE, the returned list will include an additional "error" element (character) providing a description of the error; in that case all other return variables may be undefined.
objective_value
The maximized fitting objective. Currently, only maximum-likelihood estimation is implemented, and hence this will always be the maximized log-likelihood.
objective_name The name of the objective that was maximized during fitting. Currently, only maximum-likelihood estimation is implemented, and hence this will always be "loglikelihood".
param_fitted Numeric vector of size NP (number of model parameters), listing all fitted or fixed model parameters in their standard order (see details above). If param_names was provided, elements in fitted_params will be named.
param_guess Numeric vector of size NP, listing guessed or fixed values for all model parameters in their standard order. If param_names was provided, elements in param_guess will be named.
loglikelihood The log-likelihood of the fitted model for the given timetree.
NFP Integer, number of fitted (i.e., non-fixed) model parameters.
AIC The Akaike Information Criterion for the fitted model, defined as \(2 k-2 \log (L)\), where \(k\) is the number of fitted parameters and \(L\) is the maximized likelihood.
BIC The Bayesian information criterion for the fitted model, defined as \(\log (n) k-\) \(2 \log (L)\), where \(k\) is the number of fitted parameters, \(n\) is the number of data points (number of branching times), and \(L\) is the maximized likelihood.
condition Character, specifying what conditioning was root for the likelihood (e.g. "crown" or "stem").
converged Logical, specifying whether the maximum likelihood was reached after convergence of the optimization algorithm. Note that in some cases the maximum likelihood may have been achieved by an optimization path that did not yet converge (in which case it's advisable to increase iter.max and/or eval.max).
Niterations Integer, specifying the number of iterations performed during the optimization path that yielded the maximum likelihood.
Nevaluations Integer, specifying the number of likelihood evaluations performed during the optimization path that yielded the maximum likelihood.
trial_start_objectives
Numeric vector of size Ntrials, listing the initial objective values (e.g., loglikelihoods) for each fitting trial, i.e. at the start parameter values.
trial_objective_values
Numeric vector of size Ntrials, listing the final maximized objective values (e.g., loglikelihoods) for each fitting trial.
trial_Nstart_attempts
Integer vector of size Ntrials, listing the number of start attempts for each fitting trial, until a starting point with valid likelihood was found.
trial_Niterations
Integer vector of size Ntrials, listing the number of iterations needed for each fitting trial.
trial_Nevaluations
Integer vector of size Ntrials, listing the number of likelihood evaluations needed for each fitting trial.
standard_errors
Numeric vector of size NP, estimated standard error of the parameters, based on parametric bootstrapping. Only returned if Nbootstraps>0.
medians Numeric vector of size NP, median the estimated parameters across parametric bootstraps. Only returned if Nbootstraps>0.
CI50lower Numeric vector of size NP, lower bound of the \(50 \%\) confidence interval (25\(75 \%\) percentile) for the parameters, based on parametric bootstrapping. Only returned if Nbootstraps>0.
CI50upper Numeric vector of size NP, upper bound of the \(50 \%\) confidence interval for the parameters, based on parametric bootstrapping. Only returned if Nbootstraps \(>0\).
CI95lower \(\quad\) Numeric vector of size NP, lower bound of the \(95 \%\) confidence interval (2.5\(97.5 \%\) percentile) for the parameters, based on parametric bootstrapping. Only returned if Nbootstraps>0.
CI95upper Numeric vector of size NP, upper bound of the \(95 \%\) confidence interval for the parameters, based on parametric bootstrapping. Only returned if Nbootstraps \(>0\).
consistency Numeric between 0 and 1, estimated consistency of the data with the fitted model (Lindholm et al. 2019). See the documentation of fit_hbds_model_on_grid for an explanation.

\section*{Author(s)}

Stilianos Louca

\section*{References}
H. Morlon, T. L. Parsons, J. B. Plotkin (2011). Reconciling molecular phylogenies with the fossil record. Proceedings of the National Academy of Sciences. 108:16327-16332.
S. Louca et al. (2018). Bacterial diversification through geological time. Nature Ecology \& Evolution. 2:1458-1467.
A. Lindholm, D. Zachariah, P. Stoica, T. B. Schoen (2019). Data consistency approach to model validation. IEEE Access. 7:59788-59796.
S. Louca and M. W. Pennell (2020). Extant timetrees are consistent with a myriad of diversification histories. Nature. 580:502-505.

\section*{See Also}
```

simulate_deterministic_hbd
loglikelihood_hbd
fit_hbd_model_on_grid
fit_hbd_pdr_on_grid
fit_hbd_pdr_parametric

```

\section*{Examples}
```


## Not run:

# Generate a random tree with exponentially varying lambda \& mu

Ntips = 10000
rho = 0.5 \# sampling fraction
time_grid = seq(from=0, to=100, by=0.01)
lambdas = 2*exp(0.1*time_grid)
mus = 1.5*exp(0.09*time_grid)
tree = generate_random_tree( parameters = list(rarefaction=rho),
max_tips = Ntips/rho,
coalescent = TRUE,
added_rates_times = time_grid,
added_birth_rates_pc = lambdas,
added_death_rates_pc = mus)$tree
root_age = castor::get_tree_span(tree)$max_distance
cat(sprintf("Tree has %d tips, spans %g Myr\n",length(tree\$tip.label),root_age))

# Define a parametric HBD model, with exponentially varying lambda \& mu

# Assume that the sampling fraction is known

# The model thus has 4 parameters: lambda0, mu0, alpha, beta

lambda_function = function(ages,params){
return(params['lambda0']*exp(-params['alpha']*ages));
}
mu_function = function(ages,params){
return(params['mu0']*exp(-params['beta']*ages));
}
rho_function = function(params){
return(rho) \# rho does not depend on any of the parameters
}

# Define an age grid on which lambda_function \& mu_function shall be evaluated

# Should be sufficiently fine to capture the variation in lambda \& mu

age_grid = seq(from=0,to=100,by=0.01)

# Perform fitting

# Lets suppose extinction rates are already known

cat(sprintf("Fitting model to tree..\n"))
fit = fit_hbd_model_parametric( tree,
param_values = c(lambda0=NA, mu0=3, alpha=NA, beta=-0.09),
param_guess = c(1,1,0,0),
param_min = c(0,0,-1,-1),
param_max = c(10, 10,1,1),
param_scale = 1, \# all params are in the order of 1
lambda = lambda_function,
mu = mu_function,
rho0 = rho_function,
age_grid = age_grid,
Ntrials = 10, \# perform 10 fitting trials
Nthreads = 2, \# use 2 CPUs
max_model_runtime = 1, \# limit model evaluation to 1 second
fit_control = list(rel.tol=1e-6))
if(!fit\$success){

```
```

fit_hbd_pdr_on_best_grid_size

```
```

cat(sprintf("ERROR: Fitting failed: %s\n",fit$error))
}else{
cat(sprintf("Fitting succeeded:\nLoglikelihood=%g\n",fit$loglikelihood))
print(fit)
}

## End(Not run)

```
fit_hbd_pdr_on_best_grid_size

Fit pulled diversification rates of birth-death models on a time grid with optimal size.

\section*{Description}

Given an ultrametric timetree, estimate the pulled diversification rate of homogenous birth-death (HBD) models that best explains the tree via maximum likelihood, automatically determining the optimal time-grid size based on the data. Every HBD model is defined by some speciation and extinction rates ( \(\lambda\) and \(\mu\) ) over time, as well as the sampling fraction \(\rho\) (fraction of extant species sampled). "Homogenous" refers to the assumption that, at any given moment in time, all lineages exhibit the same speciation/extinction rates. For any given HBD model there exists an infinite number of alternative HBD models that predict the same deterministic lineages-through-time curve and yield the same likelihood for any given reconstructed timetree; these "congruent" models cannot be distinguished from one another solely based on the tree.

Each congruence class is uniquely described by the "pulled diversification rate" (PDR; Louca et al 2018), defined as \(P D R=\lambda-\mu+\lambda^{-1} d \lambda / d \tau\) (where \(\tau\) is time before present) as well as the product \(\rho \lambda_{o}\) (where \(\lambda_{o}\) is the present-day speciation rate). That is, two HBD models are congruent if and only if they have the same PDR and the same product \(\rho \lambda_{o}\). This function is designed to estimate the generating congruence class for the tree, by fitting the PDR on a grid of discrete times as well as the product \(\rho \lambda_{o}\). Internally, the function uses fit_hbd_pdr_on_grid to perform the fitting. The "best" grid size is determined based on some optimality criterion, such as AIC.

\section*{Usage}
fit_hbd_pdr_on_best_grid_size(tree,
\begin{tabular}{ll} 
oldest_age & \(=\) NULL, \\
age0 & \(=0\), \\
grid_sizes & \(=c(1,10)\), \\
uniform_grid & \(=\) FALSE, \\
criterion & \(=\) "AIC", \\
exhaustive & \(=\) TRUE, \\
min_PDR & \(=-I n f\), \\
max_PDR & \(=+\) Inf, \\
min_rholambda0 & \(=1 e-10\), \\
max_rholambda0 & \(=+\) Inf, \\
guess_PDR & \(=\) NULL, \\
guess_rholambda0 & \(=\) NULL,,
\end{tabular}
\begin{tabular}{ll} 
fixed_PDR & \(=\) NULL, \\
fixed_rholambda0 & \(=\) NULL, \\
splines_degree & \(=1\), \\
condition & \(=\) "auto", \\
relative_dt & \(=1 \mathrm{e}-3\), \\
Ntrials & \(=1\), \\
Nbootstraps & \(=0\), \\
Ntrials_per_bootstrap & \(=\) NULL, \\
Nthreads & \(=1\), \\
max_model_runtime & \(=\) NULL, \\
fit_control & \(=l i s t()\), \\
verbose & \(=\) FALSE, \\
verbose_prefix & \(=" ")\),
\end{tabular}

\section*{Arguments}
\begin{tabular}{ll} 
tree & \begin{tabular}{l} 
A rooted ultrametric timetree of class "phylo", representing the time-calibrated \\
phylogeny of a set of extant sampled species.
\end{tabular} \\
oldest_age & \begin{tabular}{l} 
Strictly positive numeric, specifying the oldest time before present ("age") to \\
consider when calculating the likelihood. If this is equal to or greater than the \\
root age, then oldest_age is taken as the stem age. If oldest_age is less than \\
the root age, the tree is split into multiple subtrees at that age by treating every \\
edge crossing that age as the stem of a subtree, and each subtree is considered \\
an independent realization of the HBD model stemming at that age. This can be \\
useful for avoiding points in the tree close to the root, where estimation uncer- \\
tainty is generally higher. If oldest_age==NULL, it is automatically set to the \\
root age.
\end{tabular} \\
age0 \\
Non-negative numeric, specifying the youngest age (time before present) to con- \\
sider for fitting. If age0>0, the tree essentially is trimmed at age0, omitting \\
anything younger than age0, and the PDR and \(\rho \lambda_{o}\) are fitted to the trimmed tree \\
while shifting time appropriately.
\end{tabular}
\begin{tabular}{|c|c|}
\hline max_PDR & Numeric vector of length Ngrid, or a single numeric, specifying upper bounds for the fitted PDR at each point in the age grid. If a single numeric, the same upper bound applies at all ages. Use +Inf to omit upper bounds. \\
\hline min_rholambda0 & Strictly positive numeric, specifying the lower bound for the fitted \(\rho \lambda_{o}\) (sampling fraction times present-day extinction rate). \\
\hline max_rholambda0 & Strictly positive numeric, specifying the upper bound for the fitted \(\rho \lambda_{o}\). Set to + Inf to omit this upper bound. \\
\hline guess_PDR & Initial guess for the PDR at each age-grid point. Either NULL (an initial guess will be computed automatically), or a single numeric (guessing a constant PDR at all ages), or a function handle (for generating guesses at each grid point; this function may also return NA at some time points for which a guess shall be computed automatically). \\
\hline \multicolumn{2}{|l|}{guess_rholambda0} \\
\hline & Numeric, specifying an initial guess for the product \(\rho \lambda_{o}\). If NULL, a guess will be computed automatically. \\
\hline fixed_PDR & Optional fixed (i.e. non-fitted) PDR values. Either NULL (none of the PDR values are fixed) or a function handle specifying the PDR for any arbitrary age (PDR will be fixed at any age for which this function returns a finite number). The function fixed_PDR() need not return finite values for all times, in fact doing so would mean that the PDR is not fitted anywhere. \\
\hline \multicolumn{2}{|l|}{fixed_rholambda0} \\
\hline & Numeric, optionally specifying a fixed value for the product \(\rho \lambda_{o}\). If NULL or NA, the product \(\rho \lambda_{o}\) is estimated. \\
\hline splines_degree & Integer between 0 and 3 (inclusive), specifying the polynomial degree of the PDR between age-grid points. If 0 , then the PDR is considered to be piecewise constant, if 1 then the PDR is considered piecewise linear, if 2 or 3 then the PDR is considered to be a spline of degree 2 or 3 , respectively. The splines_degree influences the analytical properties of the curve, e.g. splines_degree==1 guarantees a continuous curve, splines_degree==2 guarantees a continuous curve and continuous derivative, and so on. A degree of 0 is generally not recommended. \\
\hline condition & Character, either "crown", "stem", "auto", "stemN" or "crownN" (where N is an integer \(>=2\) ), specifying on what to condition the likelihood. If "crown", the likelihood is conditioned on the survival of the two daughter lineages branching off at the root at that time. If "stem", the likelihood is conditioned on the survival of the stem lineage, with the process having started at oldest_age. Note that "crown" and "crownN"" really only make sense when oldest_age is equal to the root age, while "stem" is recommended if oldest_age differs from the root age. If "stem 2 ", the condition is that the process yielded at least two sampled tips, and similarly for "stem3" etc. If "crown3", the condition is that a splitting occurred at the root age, both child clades survived, and in total yielded at least 3 sampled tips (and similarly for "crown4" etc). If "auto", the condition is chosen according to the recommendations mentioned earlier. \\
\hline relative_dt & Strictly positive numeric (unitless), specifying the maximum relative time step allowed for integration over time, when calculating the likelihood. Smaller values increase integration accuracy but increase computation time. Typical values are \(0.0001-0.001\). The default is usually sufficient. \\
\hline
\end{tabular}
\(\left.\begin{array}{ll}\text { Ntrials } & \begin{array}{l}\text { Integer, specifying the number of independent fitting trials to perform, each } \\ \text { starting from a random choice of model parameters. Increasing Ntrials re- } \\ \text { duces the risk of reaching a non-global local maximum in the fitting objective. }\end{array} \\ \text { Nbootstraps } & \begin{array}{l}\text { Integer, specifying an optional number of bootstrap samplings to perform, for } \\ \text { estimating standard errors and confidence intervals of maximum-likelihood fit- } \\ \text { ted parameters. If 0, no bootstrapping is performed. Typical values are 10-100. } \\ \text { At each bootstrap sampling, a random timetree is generated under the birth- } \\ \text { death model according to the fitted PDR and } \rho \lambda_{o} \text {, the parameters are estimated } \\ \text { anew based on the generated tree, and subsequently compared to the original } \\ \text { fitted parameters. Each bootstrap sampling will use roughly the same informa- } \\ \text { tion and similar computational resources as the original maximum-likelihood fit } \\ \text { (e.g., same number of trials, same optimization parameters, same initial guess, } \\ \text { etc). Bootstrapping is only performed for the best grid size. }\end{array} \\ \text { Ntrials_per_bootstrap } \\ \text { Integer, specifying the number of fitting trials to perform for each bootstrap sam- } \\ \text { pling. If NULL, this is set equal to max (1, Ntrials). Decreasing Ntrials_per_bootstrap } \\ \text { will reduce computation time, at the expense of potentially inflating the esti- } \\ \text { mated confidence intervals; in some cases (e.g., for very large trees) this may }\end{array}\right]\)

\section*{Details}

It is generally advised to provide as much information to the function fit_hbd_pdr_on_best_grid_size as possible, including reasonable lower and upper bounds (min_PDR, max_PDR, min_rholambda0 and max_rholambda0) and a reasonable parameter guess (guess_PDR and guess_rholambda0).

\section*{Value}

A list with the following elements:
success Logical, indicating whether the function executed successfully. If FALSE, the returned list will include an additional "error" element (character) providing a description of the error; in that case all other return variables may be undefined.
best_fit A named list containing the fitting results for the best grid size. This list has the same structure as the one returned by fit_hbd_pdr_on_grid.
grid_sizes Numeric vector, listing the grid sizes as provided during the function call.
AICs Numeric vector of the same length as grid_sizes, listing the AIC for each considered grid size. Note that some entries may be NA, if the corresponding grid sizes were not considered (if exhaustive=FALSE).
BICs Numeric vector of the same length as grid_sizes, listing the BIC for each considered grid size. Note that some entries may be NA, if the corresponding grid sizes were not considered (if exhaustive=FALSE).

\section*{Author(s)}

Stilianos Louca

\section*{References}
S. Louca et al. (2018). Bacterial diversification through geological time. Nature Ecology \& Evolution. 2:1458-1467.
S. Louca and M. W. Pennell (2020). Extant timetrees are consistent with a myriad of diversification histories. Nature. 580:502-505.

\section*{See Also}
```

simulate_deterministic_hbd
loglikelihood_hbd
fit_hbd_model_parametric
fit_hbd_model_on_grid
fit_hbd_pdr_parametric
fit_hbd_pdr_on_grid
fit_hbd_psr_on_grid
fit_hbd_psr_on_best_grid_size
model_adequacy_hbd
evaluate_spline

```

\section*{Examples}
```


## Not run:

# Generate a random tree with exponentially varying lambda \& mu

Ntips = 10000
rho = 0.5 \# sampling fraction
time_grid = seq(from=0, to=100, by=0.01)
lambdas = 2*exp(0.1*time_grid)

```
```

mus = 1.5*exp(0.09*time_grid)
sim = generate_random_tree( parameters = list(rarefaction=rho),
max_tips = Ntips/rho,
coalescent = TRUE,
added_rates_times = time_grid,
added_birth_rates_pc = lambdas,
added_death_rates_pc = mus)
tree = sim$tree
root_age = castor::get_tree_span(tree)$max_distance
cat(sprintf("Tree has %d tips, spans %g Myr\n",length(tree\$tip.label),root_age))

# Fit PDR on grid, with the grid size chosen automatically between 1 and 5

fit = fit_hbd_pdr_on_best_grid_size(tree,

| max_PDR | $=100$, |
| :--- | :--- |
| grid_sizes | $=c(1: 5)$, |
| exhaustive | $=$ FALSE, |
| uniform_grid | $=$ FALSE, |
| Ntrials | $=10$, |
| Nthreads | $=4$, |
| verbose | $=$ TRUE, |
| max_model_runtime | $=1)$ |

if(!fit$success){
    cat(sprintf("ERROR: Fitting failed: %s\n",fit$error))
}else{
best_fit = fit$best_fit
    cat(sprintf("Fitting succeeded:\nBest grid size=%d\n",length(best_fit$age_grid)))
\# plot fitted PDR
plot( x = best_fit$age_grid,
            y = best_fit$fitted_PDR,
main = 'Fitted PDR',
xlab = 'age',
ylab = 'PDR',
type = 'b',
xlim = c(root_age,0))
\# get fitted PDR as a function of age
PDR_fun = approxfun(x=best_fit$age_grid, y=best_fit$fitted_PDR)
}

## End(Not run)

```
fit_hbd_pdr_on_grid Fit pulled diversification rates of birth-death models on a time grid.

\section*{Description}

Given an ultrametric timetree, estimate the pulled diversification rate of homogenous birth-death (HBD) models that best explains the tree via maximum likelihood. Every HBD model is defined by some speciation and extinction rates ( \(\lambda\) and \(\mu\) ) over time, as well as the sampling fraction \(\rho\) (fraction of extant species sampled). "Homogenous" refers to the assumption that, at any given moment in time, all lineages exhibit the same speciation/extinction rates. For any given HBD model there exists
an infinite number of alternative HBD models that predict the same deterministic lineages-throughtime curve and yield the same likelihood for any given reconstructed timetree; these "congruent" models cannot be distinguished from one another solely based on the tree.
Each congruence class is uniquely described by the "pulled diversification rate" (PDR; Louca et al 2018), defined as \(P D R=\lambda-\mu+\lambda^{-1} d \lambda / d \tau\) (where \(\tau\) is time before present) as well as the product \(\rho \lambda_{o}\) (where \(\lambda_{o}\) is the present-day speciation rate). That is, two HBD models are congruent if and only if they have the same PDR and the same product \(\rho \lambda_{o}\). This function is designed to estimate the generating congruence class for the tree, by fitting the PDR on a grid of discrete times as well as the product \(\rho \lambda_{o}\).

\section*{Usage}


\section*{Arguments}
tree A rooted ultrametric timetree of class "phylo", representing the time-calibrated phylogeny of a set of extant sampled species.
oldest_age Strictly positive numeric, specifying the oldest time before present ("age") to consider when calculating the likelihood. If this is equal to or greater than the root age, then oldest_age is taken as the stem age, and the classical formula by Morlon et al. (2011) is used. If oldest_age is less than the root age, the tree is split into multiple subtrees at that age by treating every edge crossing that age as the stem of a subtree, and each subtree is considered an independent realization of the HBD model stemming at that age. This can be useful for avoiding points in the tree close to the root, where estimation uncertainty is generally higher. If oldest_age==NULL, it is automatically set to the root age.
\begin{tabular}{ll} 
age0 & \begin{tabular}{l} 
Non-negative numeric, specifying the youngest age (time before present) to con- \\
sider for fitting, and with respect to which rholambda0 is defined. If age0>0, \\
then rholambda0 refers to the product of the sampling fraction at age age0 and \\
the speciation rate at age age0. See below for more details.
\end{tabular} \\
age_grid & \begin{tabular}{l} 
Numeric vector, listing ages in ascending order at which the PDR is allowed to \\
vary independently. This grid must cover at least the age range from age0 to \\
oldest_age. If NULL or of length <=1 (regardless of value), then the PDR is \\
assumed to be time-independent.
\end{tabular} \\
min_PDR & \begin{tabular}{l} 
Numeric vector of length Ngrid (=max (1, length(age_grid))), or a single nu- \\
meric, specifying lower bounds for the fitted PDR at each point in the age grid.
\end{tabular} \\
If a single numeric, the same lower bound applies at all ages. Use -Inf to omit
\end{tabular}
likelihood is conditioned on the survival of the two daughter lineages branching off at the root at that time. If "stem", the likelihood is conditioned on the survival of the stem lineage, with the process having started at oldest_age. Note that "crown" and "crownN"" really only make sense when oldest_age is equal to the root age, while "stem" is recommended if oldest_age differs from the root age. If "stem2", the condition is that the process yielded at least two sampled tips, and similarly for "stem3" etc. If "crown3", the condition is that a splitting occurred at the root age, both child clades survived, and in total yielded at least 3 sampled tips (and similarly for "crown4" etc). If "auto", the condition is chosen according to the recommendations mentioned earlier.
relative_dt Strictly positive numeric (unitless), specifying the maximum relative time step allowed for integration over time, when calculating the likelihood. Smaller values increase integration accuracy but increase computation time. Typical values are \(0.0001-0.001\). The default is usually sufficient.
Ntrials Integer, specifying the number of independent fitting trials to perform, each starting from a random choice of model parameters. Increasing Ntrials reduces the risk of reaching a non-global local maximum in the fitting objective.

Nbootstraps Integer, specifying an optional number of bootstrap samplings to perform, for estimating standard errors and confidence intervals of maximum-likelihood fitted parameters. If 0 , no bootstrapping is performed. Typical values are 10-100. At each bootstrap sampling, a random timetree is generated under the birthdeath model according to the fitted PDR and \(\rho \lambda_{o}\), the parameters are estimated anew based on the generated tree, and subsequently compared to the original fitted parameters. Each bootstrap sampling will use roughly the same information and similar computational resources as the original maximum-likelihood fit (e.g., same number of trials, same optimization parameters, same initial guess, etc).
Ntrials_per_bootstrap
Integer, specifying the number of fitting trials to perform for each bootstrap sampling. If NULL, this is set equal to max (1,Ntrials). Decreasing Ntrials_per_bootstrap will reduce computation time, at the expense of potentially inflating the estimated confidence intervals; in some cases (e.g., for very large trees) this may be useful if fitting takes a long time and confidence intervals are very narrow anyway. Only relevant if Nbootstraps>0.

Nthreads Integer, specifying the number of parallel threads to use for performing multiple fitting trials simultaneously. This should generally not exceed the number of available CPUs on your machine. Parallel computing is not available on the Windows platform.
max_model_runtime
Optional numeric, specifying the maximum number of seconds to allow for each evaluation of the likelihood function. Use this to abort fitting trials leading to parameter regions where the likelihood takes a long time to evaluate (these are often unlikely parameter regions).
fit_control Named list containing options for the nlminb optimization routine, such as iter.max, eval.max or rel.tol. For a complete list of options and default values see the documentation of nlminb in the stats package.
verbose Logical, specifying whether to print progress reports and warnings to the screen. Note that errors always cause a return of the function (see return values success and error).
verbose_prefix Character, specifying the line prefix for printing progress reports to the screen.

\section*{Details}

If age0>0, the input tree is essentially trimmed at age0 (omitting anything younger than age0), and the PDR and rholambda0 are fitted to this new (shorter) tree, with time shifted appropriately. The fitted rholambda0 is thus the product of the sampling fraction at age0 and the speciation rate at age0. Note that the sampling fraction at age0 is simply the fraction of lineages extant at age0 that are represented in the timetree.
It is generally advised to provide as much information to the function fit_hbd_pdr_on_grid as possible, including reasonable lower and upper bounds (min_PDR, max_PDR, min_rholambda0 and max_rholambda0) and a reasonable parameter guess (guess_PDR and guess_rholambda0). It is also important that the age_grid is sufficiently fine to capture the expected major variations of the PDR over time, but keep in mind the serious risk of overfitting when age_grid is too fine and/or the tree is too small.

\section*{Value}

A list with the following elements:
success Logical, indicating whether model fitting succeeded. If FALSE, the returned list will include an additional "error" element (character) providing a description of the error; in that case all other return variables may be undefined.
objective_value
The maximized fitting objective. Currently, only maximum-likelihood estimation is implemented, and hence this will always be the maximized log-likelihood.
objective_name The name of the objective that was maximized during fitting. Currently, only maximum-likelihood estimation is implemented, and hence this will always be "loglikelihood".
loglikelihood The log-likelihood of the fitted model for the given timetree.
fitted_PDR Numeric vector of size Ngrid, listing fitted or fixed pulled diversification rates (PDR) at each age-grid point. Between grid points the fitted PDR should be interpreted as a piecewise polynomial function (natural spline) of degree splines_degree; to evaluate this function at arbitrary ages use the castor routine evaluate_spline.
fitted_rholambda0
Numeric, specifying the fitted or fixed product \(\rho \lambda(0)\).
guess_PDR Numeric vector of size Ngrid, specifying the initial guess for the PDR at each age-grid point.
guess_rholambda0
Numeric, specifying the initial guess for \(\rho \lambda(0)\).
age_grid The age-grid on which the PDR is defined. This will be the same as the provided age_grid, unless the latter was NULL or of length \(<=1\).

NFP Integer, number of fitted (i.e., non-fixed) parameters. If none of the PDRs or \(\rho \lambda 0\) were fixed, this will be equal to Ngrid +1 .
\(\left.\begin{array}{ll}\text { AIC } & \begin{array}{l}\text { The Akaike Information Criterion for the fitted model, defined as } 2 k-2 \log (L), \\
\text { where } k \text { is the number of fitted parameters and } L \text { is the maximized } \operatorname{likelihood.}\end{array} \\
\text { The Bayesian information criterion for the fitted model, defined as } \log (n) k- \\
2 \log (L) \text {, where } k \text { is the number of fitted parameters, } n \text { is the number of data } \\
\text { points (number of branching times), and } L \text { is the maximized likelihood. }\end{array}\right]\)\begin{tabular}{l} 
Logical, specifying whether the maximum likelihood was reached after conver- \\
gence of the optimization algorithm. Note that in some cases the maximum \\
likelihood may have been achieved by an optimization path that did not yet con- \\
verge (in which case it's advisable to increase iter. max and/or eval. max). \\
Integer, specifying the number of iterations performed during the optimization \\
path that yielded the maximum likelihood.
\end{tabular}

\section*{Author(s)}

Stilianos Louca

\section*{References}
S. Louca et al. (2018). Bacterial diversification through geological time. Nature Ecology \& Evolution. 2:1458-1467.
S. Louca and M. W. Pennell (2020). Extant timetrees are consistent with a myriad of diversification histories. Nature. 580:502-505.

\section*{See Also}
```

simulate_deterministic_hbd
loglikelihood_hbd
fit_hbd_model_parametric
fit_hbd_model_on_grid
fit_hbd_pdr_parametric
model_adequacy_hbd
evaluate_spline

```

\section*{Examples}
```


## Not run:

# Generate a random tree with exponentially varying lambda \& mu

Ntips = 10000
rho = 0.5 \# sampling fraction
time_grid = seq(from=0, to=100, by=0.01)
lambdas = 2*exp(0.1*time_grid)
mus = 1.5*exp(0.09*time_grid)
sim = generate_random_tree( parameters = list(rarefaction=rho),
max_tips = Ntips/rho,
coalescent = TRUE,
added_rates_times = time_grid,
added_birth_rates_pc = lambdas,
added_death_rates_pc = mus)
tree = sim$tree
root_age = castor::get_tree_span(tree)$max_distance
cat(sprintf("Tree has %d tips, spans %g Myr\n",length(tree\$tip.label),root_age))

# calculate true PDR

lambda_slopes = diff(lambdas)/diff(time_grid);
lambda_slopes = c(lambda_slopes[1],lambda_slopes)
PDRs = lambdas - mus - (lambda_slopes/lambdas)

# Fit PDR on grid

Ngrid = 10
age_grid = seq(from=0,to=root_age,length.out=Ngrid)
fit = fit_hbd_pdr_on_grid(tree,
age_grid = age_grid,
min_PDR = -100,
max_PDR = +100,
condition = "crown",
Ntrials = 10,\# perform 10 fitting trials
Nthreads = 2,\# use two CPUs
max_model_runtime = 1) \# limit model evaluation to 1 second
if(!fit\$success){

```
```

    cat(sprintf("ERROR: Fitting failed: %s\n",fit$error))
    }else{
cat(sprintf("Fitting succeeded:\nLoglikelihood=%g\n",fit$loglikelihood))
    # plot fitted & true PDR
    plot( x = fit$age_grid,
y = fit$fitted_PDR,
            main = 'Fitted & true PDR',
            xlab = 'age',
            ylab = 'PDR',
            type = 'b',
            col = 'red',
            xlim = c(root_age,0))
    lines(x = sim$final_time-time_grid,
y = PDRs,
type = 'l',
col = 'blue');
\# get fitted PDR as a function of age
PDR_fun = approxfun(x=fit$age_grid, y=fit$fitted_PDR)
}

## End(Not run)

```
fit_hbd_pdr_parametric
    Fit parameterized pulled diversification rates of birth-death models.

\section*{Description}

Given an ultrametric timetree, estimate the pulled diversification rate (PDR) of homogenous birthdeath (HBD) models that best explains the tree via maximum likelihood, assuming that the PDR is given as a parameterized function of time before present. Every HBD model is defined by some speciation and extinction rates ( \(\lambda\) and \(\mu\) ) over time, as well as the sampling fraction \(\rho\) (fraction of extant species sampled). "Homogenous" refers to the assumption that, at any given moment in time, all lineages exhibit the same speciation/extinction rates. For any given HBD model there exists an infinite number of alternative HBD models that generate extant trees with the same probability distributions and yield the same likelihood for any given extant timetree; these "congruent" models cannot be distinguished from one another solely based on an extant timetree.
Each congruence class is uniquely described by its PDR, defined as PDR \(=\lambda-\mu+\lambda^{-1} d \lambda / d \tau\) (where \(\tau\) is time before present) as well as the product \(\rho \lambda_{o}\) (where \(\lambda_{o}\) is the present-day speciation rate). That is, two HBD models are congruent if and only if they have the same PDR and the same product \(\rho \lambda_{o}\). This function is designed to estimate the generating congruence class for the tree, by fitting a finite number of parameters defining the PDR and \(\rho \lambda_{o}\).

\section*{Usage}
fit_hbd_pdr_parametric( tree,
```

param_values,
param_guess = NULL,
param_min = -Inf,
param_max = +Inf,
param_scale = NULL,
oldest_age = NULL,
age0 = 0,
PDR,
rholambda0,
age_grid = NULL,
condition = "auto",
relative_dt = 1e-3,
Ntrials = 1,
max_start_attempts = 1,
Nthreads = 1,
max_model_runtime = NULL,
fit_control = list())

```

\section*{Arguments}
\begin{tabular}{ll} 
tree & \begin{tabular}{l} 
A rooted ultrametric timetree of class "phylo", representing the time-calibrated \\
phylogeny of a set of extant sampled species.
\end{tabular} \\
param_values & \begin{tabular}{l} 
Numeric vector, specifying fixed values for a some or all model parameters. \\
For fitted (i.e., non-fixed) parameters, use NaN or NA. For example, the vector \\
c \((1.5, N A, 40)\) specifies that the 1st and 3rd model parameters are fixed at the
\end{tabular} \\
values 1.5 and 40, respectively, while the 2nd parameter is to be fitted. The \\
length of this vector defines the total number of model parameters. If entries in \\
this vector are named, the names are taken as parameter names. Names should \\
be included if you'd like returned parameter vectors to have named entries, or if \\
the functions PDR or rho query parameter values by name (as opposed to numeric \\
index).
\end{tabular}
oldest_age Strictly positive numeric, specifying the oldest time before present ("age") to consider when calculating the likelihood. If this is equal to or greater than the root age, then oldest_age is taken as the stem age, and the classical formula by Morlon et al. (2011) is used. If oldest_age is less than the root age, the tree is split into multiple subtrees at that age by treating every edge crossing that age as the stem of a subtree, and each subtree is considered an independent realization of the HBD model stemming at that age. This can be useful for avoiding points in the tree close to the root, where estimation uncertainty is generally higher. If oldest_age==NULL, it is automatically set to the root age.
age0 Non-negative numeric, specifying the youngest age (time before present) to consider for fitting, and with respect to which rholambda0 is defined. If age0>0, then rholambda0 refers to the product of the sampling fraction at age age0 and the speciation rate at age age0. See below for more details.

PDR Function specifying the pulled diversification rate at any given age (time before present) and for any given parameter values. This function must take exactly two arguments, the 1 st one being a numeric vector (one or more ages) and the 2 nd one being a numeric vector of size NP (parameter values), and return a numeric vector of the same size as the 1 st argument. Can also be a single number (i.e., PDR is fixed).
rholambda0 Function specifying the product \(\rho \lambda_{o}\) (sampling fraction times speciation rate at age0) for any given parameter values. This function must take exactly one argument, a numeric vector of size NP (parameter values), and return a strictly positive numeric. Can also be a single number (i.e., rholambda0 is fixed).
age_grid Numeric vector, specifying ages at which the PDR function should be evaluated. This age grid must be fine enough to capture the possible variation in the PDR over time, within the permissible parameter range. If of size 1 , then the PDR is assumed to be time-independent. Listed ages must be strictly increasing, and must cover at least the full considered age interval (from age0 to oldest_age). Can also be NULL or a vector of size 1 , in which case the PDR is assumed to be time-independent.
condition Character, either "crown", "stem", "auto", "stemN" or "crownN" (where N is an integer \(>=2\) ), specifying on what to condition the likelihood. If "crown", the likelihood is conditioned on the survival of the two daughter lineages branching off at the root at that time. If "stem", the likelihood is conditioned on the survival of the stem lineage, with the process having started at oldest_age. Note that "crown" and "crownN"" really only make sense when oldest_age is equal to the root age, while "stem" is recommended if oldest_age differs from the root age. If "stem2", the condition is that the process yielded at least two sampled tips, and similarly for "stem3" etc. If "crown3", the condition is that a splitting occurred at the root age, both child clades survived, and in total yielded at least 3 sampled tips (and similarly for "crown4" etc). If "auto", the condition is chosen according to the recommendations mentioned earlier.
relative_dt Strictly positive numeric (unitless), specifying the maximum relative time step allowed for integration over time, when calculating the likelihood. Smaller values increase integration accuracy but increase computation time. Typical values are \(0.0001-0.001\). The default is usually sufficient.

\begin{abstract}
Ntrials Integer, specifying the number of independent fitting trials to perform, each starting from a random choice of model parameters. Increasing Ntrials reduces the risk of reaching a non-global local maximum in the fitting objective.
max_start_attempts
Integer, specifying the number of times to attempt finding a valid start point (per trial) before giving up on that trial. Randomly choosen extreme start parameters may occasionally result in Inf/undefined likelihoods, so this option allows the algorithm to keep looking for valid starting points.

Nthreads Integer, specifying the number of parallel threads to use for performing multiple fitting trials simultaneously. This should generally not exceed the number of available CPUs on your machine. Parallel computing is not available on the Windows platform.
```

max_model_runtime

```

Optional numeric, specifying the maximum number of seconds to allow for each evaluation of the likelihood function. Use this to abort fitting trials leading to parameter regions where the likelihood takes a long time to evaluate (these are often unlikely parameter regions).
fit_control Named list containing options for the nlminb optimization routine, such as iter.max, eval.max or rel.tol. For a complete list of options and default values see the documentation of nlminb in the stats package.
\end{abstract}

\section*{Details}

This function is designed to estimate a finite set of scalar parameters ( \(p_{1}, . ., p_{n} \in \mathrm{R}\) ) that determine the PDR and the product \(\rho \lambda_{o}\) (sampling fraction times present-dat extinction rate), by maximizing the likelihood of observing a given timetree under the HBD model. For example, the investigator may assume that the PDR varies exponentially over time, i.e. can be described by \(P D R(t)=\) \(A \cdot e^{-B t}\) (where \(A\) and \(B\) are unknown coefficients and \(t\) is time before present), and that the product \(\rho \lambda_{o}\) is unknown. In this case the model has 3 free parameters, \(p_{1}=A, p_{2}=B\) and \(p_{3}=\rho \lambda_{o}\), each of which may be fitted to the tree.

If age0>0, the input tree is essentially trimmed at age0 (omitting anything younger than age0), and the PDR and rholambda0 are fitted to this new (shorter) tree, with time shifted appropriately. The fitted rholambda0 is thus the product of the sampling fraction at age0 and the speciation rate at age0. Note that the sampling fraction at age 0 is simply the fraction of lineages extant at age0 that are represented in the timetree. Most users will typically want to leave age \(0=0\).

It is generally advised to provide as much information to the function fit_hbd_pdr_parametric as possible, including reasonable lower and upper bounds (param_min and param_max), a reasonable parameter guess (param_guess) and reasonable parameter scales param_scale. If some model parameters can vary over multiple orders of magnitude, it is advised to transform them so that they vary across fewer orders of magnitude (e.g., via log-transformation). It is also important that the age_grid is sufficiently fine to capture the variation of the PDR over time, since the likelihood is calculated under the assumption that both vary linearly between grid points.

\section*{Value}

A list with the following elements:
\begin{tabular}{|c|c|}
\hline success & Logical, indicating whether model fitting succeeded. If FALSE, the returned list will include an additional "error" element (character) providing a description of the error; in that case all other return variables may be undefined. \\
\hline \multicolumn{2}{|l|}{objective_value} \\
\hline & The maximized fitting objective. Currently, only maximum-likelihood estimation is implemented, and hence this will always be the maximized log-likelihood. \\
\hline objective_name & The name of the objective that was maximized during fitting. Currently, only maximum-likelihood estimation is implemented, and hence this will always be "loglikelihood". \\
\hline param_fitted & Numeric vector of size NP (number of model parameters), listing all fitted or fixed model parameters in their standard order (see details above). If param_names was provided, elements in fitted_params will be named. \\
\hline param_guess & Numeric vector of size NP, listing guessed or fixed values for all model parameters in their standard order. \\
\hline loglikelihood & The \\
\hline NFP & Integer, number of fitted (i.e., non-fixed) model parameters. \\
\hline AIC & The Akaike Information Criterion for the fitted model, defined as \(2 k-2 \log (L)\), where \(k\) is the number of fitted parameters and \(L\) is the maximized likelihood. \\
\hline BIC & The Bayesian information criterion for the fitted model, defined as \(\log (n) k-\) \(2 \log (L)\), where \(k\) is the number of fitted parameters, \(n\) is the number of data points (number of branching times), and \(L\) is the maximized likelihood. \\
\hline converged & Logical, specifying whether the maximum likelihood was reached after convergence of the optimization algorithm. Note that in some cases the maximum likelihood may have been achieved by an optimization path that did not yet converge (in which case it's advisable to increase iter. max and/or eval. max). \\
\hline Niterations & Integer, specifying the number of iterations performed during the optimization path that yielded the maximum likelihood. \\
\hline Nevaluations & Integer, specifying the number of likelihood evaluations performed during the optimization path that yielded the maximum likelihood. \\
\hline \multicolumn{2}{|l|}{trial_start_objectives} \\
\hline & Numeric vector of size Ntrials, listing the initial objective values (e.g., loglikelihoods) for each fitting trial, i.e. at the start parameter values. \\
\hline \multicolumn{2}{|l|}{trial_objective_values} \\
\hline & Numeric vector of size Ntrials, listing the final maximized objective values (e.g., loglikelihoods) for each fitting trial. \\
\hline \multicolumn{2}{|l|}{trial_Nstart_attempts} \\
\hline & Integer vector of size Ntrials, listing the number of start attempts for each fitting trial, until a starting point with valid likelihood was found. \\
\hline \multicolumn{2}{|l|}{trial_Niterations} \\
\hline & Integer vector of size Ntrials, listing the number of iterations needed for each fitting trial. \\
\hline \multicolumn{2}{|l|}{trial_Nevaluations} \\
\hline & Integer vector of size Ntrials, listing the number of likelihood evaluations needed for each fitting trial. \\
\hline
\end{tabular}

\section*{Author(s)}

Stilianos Louca

\section*{References}
H. Morlon, T. L. Parsons, J. B. Plotkin (2011). Reconciling molecular phylogenies with the fossil record. Proceedings of the National Academy of Sciences. 108:16327-16332.
S. Louca et al. (2018). Bacterial diversification through geological time. Nature Ecology \& Evolution. 2:1458-1467.
S. Louca and M. W. Pennell (2020). Extant timetrees are consistent with a myriad of diversification histories. Nature. 580:502-505.

\section*{See Also}
```

simulate_deterministic_hbd
loglikelihood_hbd
fit_hbd_model_on_grid
fit_hbd_model_parametric
fit_hbd_pdr_on_grid
fit_hbd_psr_parametric
model_adequacy_hbd

```

\section*{Examples}
```


## Not run:

# Generate a random tree with exponentially varying lambda \& mu

Ntips = 10000
rho = 0.5 \# sampling fraction
time_grid = seq(from=0, to=100, by=0.01)
lambdas = 2*exp(0.1*time_grid)
mus = 1.5*exp(0.09*time_grid)
tree = generate_random_tree( parameters = list(rarefaction=rho),
max_tips = Ntips/rho,
coalescent = TRUE,
added_rates_times = time_grid,
added_birth_rates_pc = lambdas,
added_death_rates_pc = mus)$tree
root_age = castor::get_tree_span(tree)$max_distance
cat(sprintf("Tree has %d tips, spans %g Myr\n",length(tree\$tip.label),root_age))

# Define a parametric HBD congruence class, with exponentially varying PDR

# The model thus has 3 parameters

PDR_function = function(ages,params){
return(params['A']*exp(-params['B']*ages));
}
rholambda0_function = function(params){
return(params['rholambda0'])
}

```
```


# Define an age grid on which PDR_function shall be evaluated

# Should be sufficiently fine to capture the variation in the PDR

age_grid = seq(from=0,to=100,by=0.01)

# Perform fitting

cat(sprintf("Fitting class to tree..\n"))
fit = fit_hbd_pdr_parametric( tree,
param_values =c(A=NA, B=NA, rholambda0=NA),
param_guess =c(1,0,1),
param_min =c(-10,-10,0),
param_max = c(10,10,10),
param_scale = 1, \# all params are in the order of 1
PDR = PDR_function,
rholambda0 = rholambda0_function,
age_grid = age_grid,
Ntrials = 10, \# perform 10 fitting trials
Nthreads = 2, \# use 2 CPUs
max_model_runtime = 1, \# limit model evaluation to 1 second
fit_control = list(rel.tol=1e-6))
if(!fit$success){
cat(sprintf("ERROR: Fitting failed: %s\n",fit$error))
}else{
cat(sprintf("Fitting succeeded:\nLoglikelihood=%g\n",fit\$loglikelihood))
print(fit)
}

## End(Not run)

```
fit_hbd_psr_on_best_grid_size
    Fit pulled speciation rates of birth-death models on a time grid with
    optimal size.

\section*{Description}

Given an ultrametric timetree, estimate the pulled speciation rate of homogenous birth-death (HBD) models that best explains the tree via maximum likelihood, automatically determining the optimal time-grid size based on the data. Every HBD model is defined by some speciation and extinction rates ( \(\lambda\) and \(\mu\) ) over time, as well as the sampling fraction \(\rho\) (fraction of extant species sampled). "Homogenous" refers to the assumption that, at any given moment in time, all lineages exhibit the same speciation/extinction rates. For any given HBD model there exists an infinite number of alternative HBD models that predict the same deterministic lineages-through-time curve and yield the same likelihood for any given reconstructed timetree; these "congruent" models cannot be distinguished from one another solely based on the tree.
Each congruence class is uniquely described by the "pulled speciation rate" (PSR), defined as the relative slope of the deterministic LTT over time, \(P S R=-M^{-1} d M / d \tau\) (where \(\tau\) is time before present). In other words, two HBD models are congruent if and only if they have the same PSR. This function is designed to estimate the generating congruence class for the tree, by fitting the PSR
on a discrete time grid. Internally, the function uses fit_hbd_psr_on_grid to perform the fitting. The "best" grid size is determined based on some optimality criterion, such as AIC.

\section*{Usage}

\section*{Arguments}

\section*{tree}
oldest_age
age0 Non-negative numeric, specifying the youngest age (time before present) to consider for fitting. If age0>0, the tree essentially is trimmed at age 0 , omitting anything younger than age0, and the PSR is fitted to the trimmed tree while shifting time appropriately.
grid_sizes Numeric vector, listing alternative grid sizes to consider.
uniform_grid Logical, specifying whether to use uniform time grids (equal time intervals) or non-uniform time grids (more grid points towards the present, where more data
fit_hbd_psr_on_best_grid_size
are available).
criterion Character, specifying which criterion to use for selecting the best grid. Options are "AIC" and "BIC".
exhaustive Logical, whether to try all grid sizes before choosing the best one. If FALSE, the grid size is gradually increased until the selection criterio (e.g., AIC) starts becoming worse, at which point the search is halted. This avoids fitting models with excessive grid sizes when an optimum already seems to have been found at a smaller grid size.
min_PSR Numeric vector of length Ngrid (=max(1, length(age_grid))), or a single numeric, specifying lower bounds for the fitted PSR at each point in the age grid. If a single numeric, the same lower bound applies at all ages. Note that the PSR is never negative.
max_PSR Numeric vector of length Ngrid, or a single numeric, specifying upper bounds for the fitted PSR at each point in the age grid. If a single numeric, the same upper bound applies at all ages. Use +Inf to omit upper bounds.
guess_PSR Initial guess for the PSR at each age-grid point. Either NULL (an initial guess will be computed automatically), or a single numeric (guessing a constant PSR at all ages), or a function handle (for generating guesses at each grid point; this function may also return NA at some time points for which a guess shall be computed automatically).
fixed_PSR Optional fixed (i.e. non-fitted) PSR values. Either NULL (none of the PSR values are fixed) or a function handle specifying the PSR for any arbitrary age (PSR will be fixed at any age for which this function returns a finite number). The function fixed_PSR() need not return finite values for all times, in fact doing so would mean that the PSR is not fitted anywhere.
splines_degree Integer between 0 and 3 (inclusive), specifying the polynomial degree of the PSR between age-grid points. If 0 , then the PSR is considered piecewise constant, if 1 then the PSR is considered piecewise linear, if 2 or 3 then the PSR is considered to be a spline of degree 2 or 3 , respectively. The splines_degree influences the analytical properties of the curve, e.g. splines_degree==1 guarantees a continuous curve, splines_degree==2 guarantees a continuous curve and continuous derivative, and so on. A degree of 0 is generally not recommended.
condition Character, either "crown", "stem", "auto", "stemN" or "crownN" (where N is an integer \(>=2\) ), specifying on what to condition the likelihood. If "crown", the likelihood is conditioned on the survival of the two daughter lineages branching off at the root at that time. If "stem", the likelihood is conditioned on the survival of the stem lineage, with the process having started at oldest_age. Note that "crown" and "crownN"" really only make sense when oldest_age is equal to the root age, while "stem" is recommended if oldest_age differs from the root age. If "stem2", the condition is that the process yielded at least two sampled tips, and similarly for "stem3" etc. If "crown3", the condition is that a splitting occurred at the root age, both child clades survived, and in total yielded at least 3 sampled tips (and similarly for "crown4" etc). If "auto", the condition is chosen according to the recommendations mentioned earlier.
\begin{tabular}{ll} 
relative_dt & \begin{tabular}{l} 
Strictly positive numeric (unitless), specifying the maximum relative time step \\
allowed for integration over time, when calculating the likelihood. Smaller val- \\
ues increase integration accuracy but increase computation time. Typical values \\
are 0.0001-0.001. The default is usually sufficient.
\end{tabular} \\
Ntrials & \begin{tabular}{l} 
Integer, specifying the number of independent fitting trials to perform, each \\
starting from a random choice of model parameters. Increasing Ntrials re- \\
duces the risk of reaching a non-global local maximum in the fitting objective. \\
Integer, specifying an optional number of bootstrap samplings to perform, for es- \\
timating standard errors and confidence intervals of maximum-likelihood fitted \\
parameters. If 0, no bootstrapping is performed. Typical values are 10-100. At \\
each bootstrap sampling, a random timetree is generated under the birth-death \\
model according to the fitted PSR, the parameters are estimated anew based on
\end{tabular} \\
the generated tree, and subsequently compared to the original fitted parameters. \\
Each bootstrap sampling will use roughly the same information and similar com- \\
putational resources as the original maximum-likelihood fit (e.g., same number \\
of trials, same optimization parameters, same initial guess, etc). Bootstrapping \\
is only performed for the best grid size.
\end{tabular}

\section*{Details}

It is generally advised to provide as much information to the function fit_hbd_psr_on_best_grid_size as possible, including reasonable lower and upper bounds (min_PSR and max_PSR) and a reasonable parameter guess (guess_PSR).

\section*{Value}

A list with the following elements:
success Logical, indicating whether the function executed successfully. If FALSE, the returned list will include an additional "error" element (character) providing a description of the error; in that case all other return variables may be undefined.
best_fit A named list containing the fitting results for the best grid size. This list has the same structure as the one returned by fit_hbd_psr_on_grid.
grid_sizes Numeric vector, listing the grid sizes as provided during the function call.
AICs Numeric vector of the same length as grid_sizes, listing the AIC for each considered grid size. Note that some entries may be NA, if the corresponding grid sizes were not considered (if exhaustive=FALSE).
BICs Numeric vector of the same length as grid_sizes, listing the BIC for each considered grid size. Note that some entries may be NA, if the corresponding grid sizes were not considered (if exhaustive=FALSE).

\section*{Author(s)}

Stilianos Louca

\section*{References}
S. Louca et al. (2018). Bacterial diversification through geological time. Nature Ecology \& Evolution. 2:1458-1467.
S. Louca and M. W. Pennell (2020). Extant timetrees are consistent with a myriad of diversification histories. Nature. 580:502-505.

\section*{See Also}
```

simulate_deterministic_hbd
loglikelihood_hbd
fit_hbd_model_parametric
fit_hbd_model_on_grid
fit_hbd_pdr_parametric
fit_hbd_pdr_on_grid
fit_hbd_psr_on_grid
fit_hbd_pdr_on_best_grid_size
model_adequacy_hbd

```

\section*{Examples}
```


## Not run:

# Generate a random tree with exponentially varying lambda \& mu

Ntips = 10000
rho = 0.5 \# sampling fraction

```
```

time_grid = seq(from=0, to=100, by=0.01)
lambdas = 2*exp(0.1*time_grid)
mus = 1.5*exp(0.09*time_grid)
sim = generate_random_tree( parameters = list(rarefaction=rho),
max_tips = Ntips/rho,
coalescent = TRUE,
added_rates_times = time_grid,
added_birth_rates_pc = lambdas,
added_death_rates_pc = mus)
tree = sim$tree
root_age = castor::get_tree_span(tree)$max_distance
cat(sprintf("Tree has %d tips, spans %g Myr\n",length(tree\$tip.label),root_age))

# Fit PSR on grid, with the grid size chosen automatically between 1 and 5

fit = fit_hbd_psr_on_best_grid_size(tree,
max_PSR = 100,
grid_sizes = c(1:5),
exhaustive = FALSE,
uniform_grid = FALSE,
Ntrials = 10,
Nthreads = 4,
verbose = TRUE,
max_model_runtime = 1)
if(!fit$success){
    cat(sprintf("ERROR: Fitting failed: %s\n",fit$error))
}else{
best_fit = fit$best_fit
    cat(sprintf("Fitting succeeded:\nBest grid size=%d\n",length(best_fit$age_grid)))
\# plot fitted PSR
plot( x = best_fit$age_grid,
            y = best_fit$fitted_PSR,
main = 'Fitted PSR',
xlab = 'age',
ylab = 'PSR',
type = 'b',
xlim = c(root_age,0))
\# get fitted PSR as a function of age
PSR_fun = approxfun(x=best_fit$age_grid, y=best_fit$fitted_PSR)
}

## End(Not run)

```
fit_hbd_psr_on_grid Fit pulled speciation rates of birth-death models on a time grid.

\section*{Description}

Given an ultrametric timetree, estimate the pulled speciation rate of homogenous birth-death (HBD) models that best explains the tree via maximum likelihood. Every HBD model is defined by some speciation and extinction rates ( \(\lambda\) and \(\mu\) ) over time, as well as the sampling fraction \(\rho\) (fraction of
extant species sampled). "Homogenous" refers to the assumption that, at any given moment in time, all lineages exhibit the same speciation/extinction rates. For any given HBD model there exists an infinite number of alternative HBD models that predict the same deterministic lineages-throughtime curve and yield the same likelihood for any given reconstructed timetree; these "congruent" models cannot be distinguished from one another solely based on the tree.
Each congruence class is uniquely described by the "pulled speciation rate" (PSR), defined as the relative slope of the deterministic LTT over time, \(P S R=-M^{-1} d M / d \tau\) (where \(\tau\) is time before present). In other words, two HBD models are congruent if and only if they have the same PSR. This function is designed to estimate the generating congruence class for the tree, by fitting the PSR on a discrete time grid.

\section*{Usage}
fit_hbd_psr_on_grid( tree,
\begin{tabular}{ll} 
oldest_age & \(=\) NULL, \\
age0 & \(=0\), \\
age_grid & \(=\) NULL, \\
min_PSR & \(=0\), \\
max_PSR & \(=+\) Inf, \\
guess_PSR & \(=\) NULL, \\
fixed_PSR & \(=\) NULL, \\
splines_degree & \(=1\), \\
condition & \(=" a u t o "\), \\
relative_dt & \(=1 e-3\), \\
Ntrials & \(=1\), \\
Nbootstraps & \(=0\), \\
Ntrials_per_bootstrap & \(=\) NULL, \\
Nthreads & \(=1\), \\
max_model_runtime & \(=N U L L\), \\
fit_control & \(=1 i s t()\), \\
verbose & \(=F A L S E\), \\
diagnostics & \(=\) FALSE, \\
verbose_prefix & \(=" ")\)
\end{tabular}

\section*{Arguments}
tree A rooted ultrametric timetree of class "phylo", representing the time-calibrated phylogeny of a set of extant sampled species.
oldest_age Strictly positive numeric, specifying the oldest time before present ("age") to consider when calculating the likelihood. If this is equal to or greater than the root age, then oldest_age is taken as the stem age, and the classical formula by Morlon et al. (2011) is used. If oldest_age is less than the root age, the tree is split into multiple subtrees at that age by treating every edge crossing that age as the stem of a subtree, and each subtree is considered an independent realization of the HBD model stemming at that age. This can be useful for avoiding points in the tree close to the root, where estimation uncertainty is generally higher. If oldest_age==NULL, it is automatically set to the root age.
\begin{tabular}{|c|c|}
\hline age0 & Non-negative numeric, specifying the youngest age (time before present) to consider for fitting. If age \(0>0\), the tree essentially is trimmed at age 0 , omitting anything younger than age0, and the PSR is fitted to the trimmed tree while shifting time appropriately. \\
\hline age_grid & Numeric vector, listing ages in ascending order at which the PSR is allowed to vary independently. This grid must cover at least the age range from age0 to oldest_age. If NULL or of length \(<=1\) (regardless of value), then the PSR is assumed to be time-independent. \\
\hline min_PSR & Numeric vector of length \(\operatorname{Ngrid}(=\max (1\), length (age_grid)) ), or a single numeric, specifying lower bounds for the fitted PSR at each point in the age grid. If a single numeric, the same lower bound applies at all ages. Note that the PSR is never negative. \\
\hline max_PSR & Numeric vector of length Ngrid, or a single numeric, specifying upper bounds for the fitted PSR at each point in the age grid. If a single numeric, the same upper bound applies at all ages. Use +Inf to omit upper bounds. \\
\hline guess_PSR & Initial guess for the PSR at each age-grid point. Either NULL (an initial guess will be computed automatically), or a single numeric (guessing the same PSR at all ages) or a numeric vector of size Ngrid specifying a separate guess at each age-grid point. To omit an initial guess for some but not all age-grid points, set their guess values to NA. Guess values are ignored for non-fitted (i.e., fixed) parameters. \\
\hline fixed_PSR & Optional fixed (i.e. non-fitted) PSR values on one or more age-grid points. Either NULL (PSR is not fixed anywhere), or a single numeric (PSR fixed to the same value at all grid points) or a numeric vector of size Ngrid (PSR fixed at one or more age-grid points, use NA for non-fixed values). \\
\hline splines_degree & Integer between 0 and 3 (inclusive), specifying the polynomial degree of the PSR between age-grid points. If 0 , then the PSR is considered piecewise constant, if 1 then the PSR is considered piecewise linear, if 2 or 3 then the PSR is considered to be a spline of degree 2 or 3 , respectively. The splines_degree influences the analytical properties of the curve, e.g. splines_degree==1 guarantees a continuous curve, splines_degree==2 guarantees a continuous curve and continuous derivative, and so on. A degree of 0 is generally not recommended. \\
\hline condition & Character, either "crown", "stem", "auto", "stemN" or "crownN" (where N is an integer \(>=2\) ), specifying on what to condition the likelihood. If "crown", the likelihood is conditioned on the survival of the two daughter lineages branching off at the root at that time. If "stem", the likelihood is conditioned on the survival of the stem lineage, with the process having started at oldest_age. Note that "crown" and "crownN"" really only make sense when oldest_age is equal to the root age, while "stem" is recommended if oldest_age differs from the root age. If "stem2", the condition is that the process yielded at least two sampled tips, and similarly for "stem3" etc. If "crown3", the condition is that a splitting occurred at the root age, both child clades survived, and in total yielded at least 3 sampled tips (and similarly for "crown4" etc). If "auto", the condition is chosen according to the recommendations mentioned earlier. \\
\hline relative_dt & Strictly positive numeric (unitless), specifying the maximum relative time step allowed for integration over time, when calculating the likelihood. Smaller val- \\
\hline
\end{tabular}
ues increase integration accuracy but increase computation time. Typical values are \(0.0001-0.001\). The default is usually sufficient.
Ntrials Integer, specifying the number of independent fitting trials to perform, each starting from a random choice of model parameters. Increasing Ntrials reduces the risk of reaching a non-global local maximum in the fitting objective.
Nbootstraps Integer, specifying an optional number of bootstrap samplings to perform, for estimating standard errors and confidence intervals of maximum-likelihood fitted parameters. If 0 , no bootstrapping is performed. Typical values are \(10-100\). At each bootstrap sampling, a random timetree is generated under the birth-death model according to the fitted PSR, the parameters are estimated anew based on the generated tree, and subsequently compared to the original fitted parameters. Each bootstrap sampling will use roughly the same information and similar computational resources as the original maximum-likelihood fit (e.g., same number of trials, same optimization parameters, same initial guess, etc).
Ntrials_per_bootstrap
Integer, specifying the number of fitting trials to perform for each bootstrap sampling. If NULL, this is set equal to max (1,Ntrials). Decreasing Ntrials_per_bootstrap will reduce computation time, at the expense of potentially inflating the estimated confidence intervals; in some cases (e.g., for very large trees) this may be useful if fitting takes a long time and confidence intervals are very narrow anyway. Only relevant if Nbootstraps \(>0\).
Nthreads Integer, specifying the number of parallel threads to use for performing multiple fitting trials simultaneously. This should generally not exceed the number of available CPUs on your machine. Parallel computing is not available on the Windows platform.
max_model_runtime
Optional numeric, specifying the maximum number of seconds to allow for each evaluation of the likelihood function. Use this to abort fitting trials leading to parameter regions where the likelihood takes a long time to evaluate (these are often unlikely parameter regions).
fit_control Named list containing options for the nlminb optimization routine, such as iter.max, eval.max or rel.tol. For a complete list of options and default values see the documentation of nlminb in the stats package.
verbose Logical, specifying whether to print progress reports and warnings to the screen. Note that errors always cause a return of the function (see return values success and error).
diagnostics Logical, specifying whether to print detailed information (such as model likelihoods) at every iteration of the fitting routine. For debugging purposes mainly.
verbose_prefix Character, specifying the line prefix for printing progress reports to the screen.

\section*{Details}

It is generally advised to provide as much information to the function fit_hbd_psr_on_grid as possible, including reasonable lower and upper bounds (min_PSR and max_PSR) and a reasonable parameter guess (guess_PSR). It is also important that the age_grid is sufficiently fine to capture the expected major variations of the PSR over time, but keep in mind the serious risk of overfitting when age_grid is too fine and/or the tree is too small.

\section*{Value}

A list with the following elements:
success Logical, indicating whether model fitting succeeded. If FALSE, the returned list will include an additional "error" element (character) providing a description of the error; in that case all other return variables may be undefined.
objective_value
The maximized fitting objective. Currently, only maximum-likelihood estimation is implemented, and hence this will always be the maximized log-likelihood.
objective_name The name of the objective that was maximized during fitting. Currently, only maximum-likelihood estimation is implemented, and hence this will always be "loglikelihood".
loglikelihood The log-likelihood of the fitted model for the given timetree.
fitted_PSR Numeric vector of size Ngrid, listing fitted or fixed pulled speciation rates (PSR) at each age-grid point. Between grid points the fitted PSR should be interpreted as a piecewise polynomial function (natural spline) of degree splines_degree; to evaluate this function at arbitrary ages use the castor routine evaluate_spline.
guess_PSR Numeric vector of size Ngrid, specifying the initial guess for the PSR at each age-grid point.
age_grid The age-grid on which the PSR is defined. This will be the same as the provided age_grid, unless the latter was NULL or of length \(<=1\).

NFP Integer, number of fitted (i.e., non-fixed) parameters. If none of the PSRs were fixed, this will be equal to Ngrid.
AIC The Akaike Information Criterion for the fitted model, defined as \(2 k-2 \log (L)\), where \(k\) is the number of fitted parameters, and \(L\) is the maximized likelihood.
BIC The Bayesian information criterion for the fitted model, defined as \(\log (n) k-\) \(2 \log (L)\), where \(k\) is the number of fitted parameters, \(n\) is the number of data points (number of branching times), and \(L\) is the maximized likelihood.
converged Logical, specifying whether the maximum likelihood was reached after convergence of the optimization algorithm. Note that in some cases the maximum likelihood may have been achieved by an optimization path that did not yet converge (in which case it's advisable to increase iter. max and/or eval.max).
Niterations Integer, specifying the number of iterations performed during the optimization path that yielded the maximum likelihood.
Nevaluations Integer, specifying the number of likelihood evaluations performed during the optimization path that yielded the maximum likelihood.
bootstrap_estimates
If Nbootstraps>0, this will be a numeric matrix of size Nbootstraps x Ngrid, listing the fitted PSR at each grid point and for each bootstrap.
standard_errors
If Nbootstraps>0, this will be a numeric vector of size NGrid, listing bootstrapestimated standard errors for the fitted PSR at each grid point.

CI50lower If Nbootstraps>0, this will be a numeric vector of size Ngrid, listing bootstrapestimated lower bounds of the 50-percent confidence intervals for the fitted PSR at each grid point.
\begin{tabular}{ll} 
CI50upper & \begin{tabular}{l} 
Similar to CI50lower, listing upper bounds of 50-percentile confidence inter- \\
vals.
\end{tabular} \\
CI95lower & \begin{tabular}{l} 
Similar to CI50lower, listing lower bounds of 95-percentile confidence inter- \\
vals.
\end{tabular} \\
CI95upper & \begin{tabular}{l} 
Similar to CI95lower, listing upper bounds of 95-percentile confidence inter- \\
vals.
\end{tabular}
\end{tabular}

\section*{Author(s)}

Stilianos Louca

\section*{References}
S. Louca et al. (2018). Bacterial diversification through geological time. Nature Ecology \& Evolution. 2:1458-1467.
S. Louca and M. W. Pennell (2020). Extant timetrees are consistent with a myriad of diversification histories. Nature. 580:502-505.

\section*{See Also}
```

simulate_deterministic_hbd
loglikelihood_hbd
fit_hbd_model_parametric
fit_hbd_model_on_grid
fit_hbd_pdr_parametric
fit_hbd_pdr_on_grid
fit_hbd_psr_on_best_grid_size
model_adequacy_hbd

```

\section*{Examples}
```


## Not run:

# Generate a random tree with exponentially varying lambda \& mu

Ntips = 10000
rho = 0.5 \# sampling fraction
time_grid = seq(from=0, to=100, by=0.01)
lambdas = 2*exp(0.1*time_grid)
mus = 1.5*exp(0.09*time_grid)
sim = generate_random_tree( parameters = list(rarefaction=rho),
max_tips = Ntips/rho,
coalescent = TRUE,
added_rates_times = time_grid,
added_birth_rates_pc = lambdas,
added_death_rates_pc = mus)
tree = sim$tree
root_age = castor::get_tree_span(tree)$max_distance
cat(sprintf("Tree has %d tips, spans %g Myr\n",length(tree\$tip.label),root_age))

```
```


# Fit PSR on grid

oldest_age=root_age/2 \# only consider recent times when fitting
Ngrid = 10
age_grid = seq(from=0,to=oldest_age,length.out=Ngrid)
fit = fit_hbd_psr_on_grid(tree,
oldest_age = oldest_age,
age_grid = age_grid,
min_PSR = 0,
max_PSR = +100,
condition = "crown",
Ntrials = 10,
Nthreads = 4,
max_model_runtime = 1) \# limit model evaluation to 1 second
if(!fit$success){
    cat(sprintf("ERROR: Fitting failed: %s\n",fit$error))
}else{
cat(sprintf("Fitting succeeded:\nLoglikelihood=%g\n",fit$loglikelihood))
    # plot fitted PSR
    plot( x = fit$age_grid,
y = fit$fitted_PSR,
            main = 'Fitted PSR',
            xlab = 'age',
            ylab = 'PSR',
            type = 'b',
            xlim = c(root_age,0))
    # plot deterministic LTT of fitted model
    plot(x = fit$age_grid,
y = fit$fitted_LTT,
            main = 'Fitted dLTT',
            xlab = 'age',
            ylab = 'lineages',
            type = 'b',
            log = 'y',
            xlim = c(root_age,0))
    # get fitted PSR as a function of age
    PSR_fun = approxfun(x=fit$age_grid, y=fit\$fitted_PSR)
}

## End(Not run)

```
fit_hbd_psr_parametric
    Fit parameterized pulled speciation rates of birth-death models.

\section*{Description}

Given an ultrametric timetree, estimate the pulled speciation rate (PSR) of homogenous birth-death (HBD) models that best explains the tree via maximum likelihood, assuming that the PSR is given as
a parameterized function of time before present. Every HBD model is defined by some speciation and extinction rates ( \(\lambda\) and \(\mu\) ) over time, as well as the sampling fraction \(\rho\) (fraction of extant species sampled). "Homogenous" refers to the assumption that, at any given moment in time, all lineages exhibit the same speciation/extinction rates. For any given HBD model there exists an infinite number of alternative HBD models that generate extant trees with the same probability distributions and yield the same likelihood for any given extant timetree; these "congruent" models cannot be distinguished from one another solely based on an extant timetree.
Each congruence class is uniquely described by its PSR, defined as \(P S R=\lambda \cdot(1-E)\), where \(\tau\) is time before present and \(1-E(\tau)\) is the probability that a lineage alive at age \(\tau\) will survive to the present and be included in the extant tree. That is, two HBD models are congruent if and only if they have the same PSR profile. This function is designed to estimate the generating congruence class for the tree, by fitting a finite number of parameters defining the PSR.

\section*{Usage}
fit_hbd_psr_parametric( tree, param_values,
param_guess = NULL,
param_min \(=-\) Inf,
param_max \(=+\) Inf,
param_scale = NULL,
oldest_age = NULL,
age0 \(=0\),
PSR,
age_grid = NULL,
condition = "auto",
relative_dt \(=1 \mathrm{e}-3\),
Ntrials = 1,
max_start_attempts = 1,
Nthreads \(=1\),
max_model_runtime \(=\) NULL,
fit_control = list(),
verbose = FALSE,
diagnostics = FALSE,
verbose_prefix = "")

\section*{Arguments}
tree A rooted ultrametric timetree of class "phylo", representing the time-calibrated phylogeny of a set of extant sampled species.
param_values Numeric vector, specifying fixed values for a some or all model parameters. For fitted (i.e., non-fixed) parameters, use NaN or NA. For example, the vector \(c(1.5, N A, 40)\) specifies that the 1 st and 3 rd model parameters are fixed at the values 1.5 and 40 , respectively, while the 2 nd parameter is to be fitted. The length of this vector defines the total number of model parameters. If entries in this vector are named, the names are taken as parameter names. Names should be included if you'd like returned parameter vectors to have named entries, or if the function PSR queries parameter values by name (as opposed to numeric index).
\begin{tabular}{ll} 
param_guess & \begin{tabular}{l} 
Numeric vector of size NP, specifying a first guess for the value of each model \\
parameter. For fixed parameters, guess values are ignored. Can be NULL only if \\
all model parameters are fixed.
\end{tabular} \\
param_min & \begin{tabular}{l} 
Optional numeric vector of size NP, specifying lower bounds for model parame- \\
ters. If of size 1, the same lower bound is applied to all parameters. Use -Inf to \\
omit a lower bound for a parameter. If NULL, no lower bounds are applied. For \\
fixed parameters, lower bounds are ignored.
\end{tabular} \\
param_max & \begin{tabular}{l} 
Optional numeric vector of size NP, specifying upper bounds for model param- \\
eters. If of size 1, the same upper bound is applied to all parameters. Use +Inf \\
to omit an upper bound for a parameter. If NULL, no upper bounds are applied.
\end{tabular} \\
param_scale & \begin{tabular}{l} 
For fixed parameters, upper bounds are ignored.
\end{tabular} \\
Optional numeric vector of size NP, specifying typical scales for model parame- \\
ters. If of size 1, the same scale is assumed for all parameters. If NULL, scales are \\
determined automatically. For fixed parameters, scales are ignored. It is strongly \\
advised to provide reasonable scales, as this facilitates the numeric optimization \\
algorithm.
\end{tabular}
the root age, while "stem" is recommended if oldest_age differs from the root age. If "stem2", the condition is that the process yielded at least two sampled tips, and similarly for "stem3" etc. If "crown3", the condition is that a splitting occurred at the root age, both child clades survived, and in total yielded at least 3 sampled tips (and similarly for "crown4" etc). If "auto", the condition is chosen according to the recommendations mentioned earlier.
relative_dt Strictly positive numeric (unitless), specifying the maximum relative time step allowed for integration over time, when calculating the likelihood. Smaller values increase integration accuracy but increase computation time. Typical values are \(0.0001-0.001\). The default is usually sufficient.
Ntrials Integer, specifying the number of independent fitting trials to perform, each starting from a random choice of model parameters. Increasing Ntrials reduces the risk of reaching a non-global local maximum in the fitting objective.
max_start_attempts
Integer, specifying the number of times to attempt finding a valid start point (per trial) before giving up on that trial. Randomly choosen extreme start parameters may occasionally result in Inf/undefined likelihoods, so this option allows the algorithm to keep looking for valid starting points.
Nthreads Integer, specifying the number of parallel threads to use for performing multiple fitting trials simultaneously. This should generally not exceed the number of available CPUs on your machine. Parallel computing is not available on the Windows platform.
max_model_runtime
Optional numeric, specifying the maximum number of seconds to allow for each evaluation of the likelihood function. Use this to abort fitting trials leading to parameter regions where the likelihood takes a long time to evaluate (these are often unlikely parameter regions).
fit_control Named list containing options for the nlminb optimization routine, such as iter.max, eval.max or rel.tol. For a complete list of options and default values see the documentation of nlminb in the stats package.
verbose Logical, specifying whether to print progress reports and warnings to the screen. Note that errors always cause a return of the function (see return values success and error).
diagnostics Logical, specifying whether to print detailed information (such as model likelihoods) at every iteration of the fitting routine. For debugging purposes mainly.
verbose_prefix Character, specifying the line prefix for printing progress reports to the screen.

\section*{Details}

This function is designed to estimate a finite set of scalar parameters ( \(p_{1}, . ., p_{n} \in \mathrm{R}\) ) that determine the PSR and the product \(\rho \lambda_{o}\) (sampling fraction times present-dat extinction rate), by maximizing the likelihood of observing a given timetree under the HBD model. For example, the investigator may assume that the PSR varies exponentially over time, i.e. can be described by \(P S R(t)=\) \(A \cdot e^{-B t}\) (where \(A\) and \(B\) are unknown coefficients and \(t\) is time before present); in this case the model has 2 free parameters, \(p_{1}=A\) and \(p_{2}=B\), each of which may be fitted to the tree. It is also possible to include explicit dependencies on environmental parameters (e.g., temperature).

For example, the investigator may assume that the PSR depends exponentially on global average temperature, i.e. can be described by \(P S R(t)=A \cdot e^{-B T(t)}\) (where \(A\) and \(B\) are unknown fitted parameters and \(T(t)\) is temperature at time \(t\) ). To incorporate such environmental dependencies, one can simply define the function PSR appropriately.
If age0>0, the input tree is essentially trimmed at age0 (omitting anything younger than age 0 ), and the PSR is fitted to this new (shorter) tree, with time shifted appropriately. The fitted \(\operatorname{PSR}(t)\) is thus the product of the speciation rate at time \(t\) and the probability of a lineage being in the tree at time age0. Most users will typically want to leave age \(0=0\).

It is generally advised to provide as much information to the function fit_hbd_psr_parametric as possible, including reasonable lower and upper bounds (param_min and param_max), a reasonable parameter guess (param_guess) and reasonable parameter scales param_scale. If some model parameters can vary over multiple orders of magnitude, it is advised to transform them so that they vary across fewer orders of magnitude (e.g., via log-transformation). It is also important that the age_grid is sufficiently fine to capture the variation of the PSR over time, since the likelihood is calculated under the assumption that both vary linearly between grid points.

\section*{Value}

A list with the following elements:
success Logical, indicating whether model fitting succeeded. If FALSE, the returned list will include an additional "error" element (character) providing a description of the error; in that case all other return variables may be undefined.
objective_value
The maximized fitting objective. Currently, only maximum-likelihood estimation is implemented, and hence this will always be the maximized log-likelihood.
objective_name The name of the objective that was maximized during fitting. Currently, only maximum-likelihood estimation is implemented, and hence this will always be "loglikelihood".
param_fitted Numeric vector of size NP (number of model parameters), listing all fitted or fixed model parameters in their standard order (see details above). If param_names was provided, elements in fitted_params will be named.
param_guess \(\quad\) Numeric vector of size NP, listing guessed or fixed values for all model parameters in their standard order.
loglikelihood The log-likelihood of the fitted model for the given timetree.
NFP Integer, number of fitted (i.e., non-fixed) model parameters.
AIC The Akaike Information Criterion for the fitted model, defined as \(2 k-2 \log (L)\), where \(k\) is the number of fitted parameters and \(L\) is the maximized likelihood.
BIC The Bayesian information criterion for the fitted model, defined as \(\log (n) k-\) \(2 \log (L)\), where \(k\) is the number of fitted parameters, \(n\) is the number of data points (number of branching times), and \(L\) is the maximized likelihood.
converged Logical, specifying whether the maximum likelihood was reached after convergence of the optimization algorithm. Note that in some cases the maximum likelihood may have been achieved by an optimization path that did not yet converge (in which case it's advisable to increase iter. max and/or eval.max).

Niterations Integer, specifying the number of iterations performed during the optimization path that yielded the maximum likelihood.
Nevaluations Integer, specifying the number of likelihood evaluations performed during the optimization path that yielded the maximum likelihood.
trial_start_objectives
Numeric vector of size Ntrials, listing the initial objective values (e.g., loglikelihoods) for each fitting trial, i.e. at the start parameter values.
trial_objective_values
Numeric vector of size Ntrials, listing the final maximized objective values (e.g., loglikelihoods) for each fitting trial.
trial_Nstart_attempts
Integer vector of size Ntrials, listing the number of start attempts for each fitting trial, until a starting point with valid likelihood was found.
trial_Niterations
Integer vector of size Ntrials, listing the number of iterations needed for each fitting trial.
trial_Nevaluations
Integer vector of size Ntrials, listing the number of likelihood evaluations needed for each fitting trial.

\section*{Author(s)}

Stilianos Louca

\section*{References}
H. Morlon, T. L. Parsons, J. B. Plotkin (2011). Reconciling molecular phylogenies with the fossil record. Proceedings of the National Academy of Sciences. 108:16327-16332.
S. Louca et al. (2018). Bacterial diversification through geological time. Nature Ecology \& Evolution. 2:1458-1467.
S. Louca and M. W. Pennell (2020). Extant timetrees are consistent with a myriad of diversification histories. Nature. 580:502-505.
S. Louca (2020). Simulating trees with millions of species. Bioinformatics. 36:2907-2908.
```

See Also
simulate_deterministic_hbd
loglikelihood_hbd
fit_hbd_model_on_grid
fit_hbd_model_parametric
fit_hbd_pdr_on_grid
fit_hbd_pdr_parametric
model_adequacy_hbd

```

\section*{Examples}
```


## Not run:

# Generate a random tree with exponentially varying lambda \& mu

Ntips = 10000
rho = 0.5 \# sampling fraction
time_grid = seq(from=0, to=100, by=0.01)
lambdas = 2*exp(0.1*time_grid)
mus = 1.5*exp(0.09*time_grid)
tree = generate_random_tree( parameters = list(rarefaction=rho),
max_tips = Ntips/rho,
coalescent = TRUE,
added_rates_times = time_grid,
added_birth_rates_pc = lambdas,
added_death_rates_pc = mus)$tree
root_age = castor::get_tree_span(tree)$max_distance
cat(sprintf("Tree has %d tips, spans %g Myr\n",length(tree\$tip.label),root_age))

# Define a parametric HBD congruence class, with exponentially varying PSR

# The model thus has 2 parameters

PSR_function = function(ages,params){
return(params['A']*exp(-params['B']*ages));
}

# Define an age grid on which PSR_function shall be evaluated

# Should be sufficiently fine to capture the variation in the PSR

age_grid = seq(from=0, to=100,by=0.01)

# Perform fitting

cat(sprintf("Fitting class to tree..\n"))
fit = fit_hbd_psr_parametric( tree,
param_values = c(A=NA, B=NA),
param_guess =c(1,0),
param_min =c(-10,-10),
param_max = c(10,10),
param_scale = 1, \# all params are in the order of 1
PSR = PSR_function,
age_grid = age_grid,
Ntrials = 10, \# perform 10 fitting trials
Nthreads = 2, \# use 2 CPUs
max_model_runtime = 1, \# limit model evaluation to 1 second
fit_control = list(rel.tol=1e-6))
if(!fit$success){
cat(sprintf("ERROR: Fitting failed: %s\n",fit$error))
}else{
cat(sprintf("Fitting succeeded:\nLoglikelihood=%g\n",fit\$loglikelihood))
print(fit)
}

## End(Not run)

```

\section*{Description}

Estimate the transition rate matrix of a continuous-time Markov model for discrete trait evolution ("Mk model") via maximum-likelihood, based on one or more phylogenetic trees and its tips’ states.

\section*{Usage}


\section*{Arguments}
trees Either a single phylogenetic tree of class "phylo", or a list of phylogenetic trees. Edge lengths should correspond (or be analogous) to time. The trees don't need to be ultrametric.
Nstates Integer, specifying the number of possible discrete states that the trait can have.
tip_states
Either an integer vector of size Ntips (only permitted if trees[] is a single tree) or a list containing Ntrees such integer vectors (if trees[] is a list of trees), listing the state of each tip in each tree. Note that tip_states cannot include NAs or NaNs; if the states of some tips are uncertain, you should use the option tip_priors instead. Can also be NULL, in which case tip_priors must be provided.
tip_priors Either a numeric matrix of size Ntips x Nstates (only permitted if trees[] is a single tree), or a list containing Ntrees such matrixes (if trees[] is a list of trees), listing the likelihood of each state at each tip in each tree. Can also be NULL, in which case tip_states must be provided. Hence, tip_priors[t][i,s] is
the likelihood of the observed state of tip i in tree \(t\), if the tip's true state was in state \(s\). For example, if you know for certain that a tip is in state k, then set tip_priors[t][i,s]=1 for s=k and tip_priors[t][i,s]=0 for all other s.
rate_model Rate model to be used for the transition rate matrix. Can be "ER" (all rates equal), "SYM" (transition rate \(i \rightarrow j\) is equal to transition rate \(j->i\) ), "ARD" (all rates can be different), "SUEDE" (only stepwise transitions \(\mathrm{i}->\mathrm{i}+1\) and \(\mathrm{i}->\mathrm{i}-1\) allowed, all 'up' transitions are equal, all 'down' transitions are equal) or "SRD" (only stepwise transitions \(i->i+1\) and \(i->i-1\) allowed, and each rate can be different). Can also be an index matrix that maps entries of the transition matrix to the corresponding independent rate parameter to be fitted. Diagonal entries should map to 0 , since diagonal entries are not treated as independent rate parameters but are calculated from the remaining entries in the transition rate matrix. All other entries that map to 0 represent a transition rate of zero. The format of this index matrix is similar to the format used by the ace function in the ape package. rate_model is only relevant if transition_matrix==NULL.
root_prior Prior probability distribution of the root's states, used to calculate the model's overall likelihood from the root's marginal ancestral state likelihoods. Can be "flat" (all states equal), "empirical" (empirical probability distribution of states across the tree's tips), "stationary" (stationary probability distribution of the transition matrix), "likelihoods" (use the root's state likelihoods as prior), "max_likelihood" (put all weight onto the state with maximum likelihood) or "auto" (will be chosen automatically based on some internal logic). If "stationary" and transition_matrix==NULL, then a transition matrix is first fitted using a flat root prior, and then used to calculate the stationary distribution. root_prior can also be a non-negative numeric vector of size Nstates and with total sum equal to 1 .
oldest_ages Optional numeric or numeric vector of size Ntrees, specifying the oldest age (time before present) for each tree to consider when fitting the Mk model. If NULL, the entire trees are considered from the present all the way to their root. If non-NULL, then each tree is "cut" at the corresponding oldest age, yielding multiple subtrees, each of which is assumed to be an independent realization of the Mk process. If oldest_ages is a single numeric, then all trees are cut at the same oldest age. This option may be useful if temporal variation is suspected in the Mk rates, and only data near the present are to be used for fitting to avoid violating the assumptions of a constant-rates Mk model.
guess_transition_matrix
Optional 2D numeric matrix, specifying a reasonable first guess for the transition rate matrix. May contain NA. May also be NULL, in which case a reasonable first guess is automatically generated.
Ntrials Number of trials (starting points) for fitting the transition rate matrix. A higher number may reduce the risk of landing in a local non-global optimum of the likelihood function, but will increase computation time during fitting.

\section*{max_model_runtime}

Optional positive numeric, specifying the maximum time (in seconds) allowed for a single evaluation of the likelihood function. If a specific Mk model takes longer than this threshold to evaluate, then its likelihood is set to -Inf. This option can be used to avoid badly parameterized models during fitting and can thus reduce fitting time. If NULL or \(<=0\), this option is ignored.
fit_mk
optim_algorithm
Either "optim" or "nlminb", specifying which optimization algorithm to use for maximum-likelihood estimation of the transition matrix.
optim_max_iterations
Maximum number of iterations (per fitting trial) allowed for optimizing the likelihood function.
optim_rel_tol Relative tolerance (stop criterion) for optimizing the likelihood function.
check_input Logical, specifying whether to perform some basic checks on the validity of the input data. If you are certain that your input data are valid, you can set this to FALSE to reduce computation.
Nthreads Number of parallel threads to use for running multiple fitting trials simultaneously. This only makes sense if your computer has multiple cores/CPUs and if Ntrials \(>1\). This option is ignored on Windows, because Windows does not support forking.
Nbootstraps Integer, specifying the number of parametric bootstraps to perform for estimating standard errors and confidence intervals of estimated rate parameters. Set to 0 for no bootstrapping.
Ntrials_per_bootstrap
Integer, specifying the number of fitting trials to perform for each bootstrap sampling. If NULL, this is set equal to max (1,Ntrials). Decreasing Ntrials_per_bootstrap will reduce computation time, at the expense of potentially inflating the estimated confidence intervals; in some cases (e.g., for very large trees) this may be useful if fitting takes a long time and confidence intervals are very narrow anyway. Only relevant if Nbootstraps>0.
verbose Logical, specifying whether to print progress reports and warnings to the screen.
verbose_prefix Character, specifying the line prefix for printing progress reports to the screen.

\section*{Details}

The trait's states must be represented by integers within \(1, \ldots\), ,Nstates, where Nstates is the total number of possible states. If the states are originally in some other format (e.g. characters or factors), you should map them to a set of integers \(1, . .\), Nstates. The order of states (if relevant) should be reflected in their integer representation. For example, if your original states are "small", "medium" and "large" and rate_model=="SUEDE", it is advised to represent these states as integers 1,2,3. You can easily map any set of discrete states to integers using the function map_to_state_space.
This function allows the specification of the precise tip states (if these are known) using the vector tip_states. Alternatively, if some tip states are not fully known, you can pass the state likelihoods using the matrix tip_priors. Note that exactly one of the two arguments, tip_states or tip_priors, must be non-NULL.
Tips must be represented in tip_states or tip_priors in the same order as in tree\$tip.label. None of the input vectors or matrixes need include row or column names; if they do, however, they are checked for consistency (if check_input==TRUE).

The tree is either assumed to be complete (i.e. include all possible species), or to represent a random subset of species chosen independently of their states. If the tree is not complete and tips are not chosen independently of their states, then this method will not be valid.
fit_Mk uses maximum-likelihood to estimate each free parameter of the transition rate matrix. The number of free parameters depends on the rate_model considered; for example, ER implies a single free parameter, while ARD implies Nstates \(x\) (Nstates-1) free parameters. If multiple trees are provided as input, the likelihood is the product of likelihoods for each tree, i.e. as if each tree was an independent realization of the same Markov process.
This function is similar to asr_mk_model, but focused solely on fitting the transition rate matrix (i.e., without estimating ancestral states) and with the ability to utilize multiple trees at once.

\section*{Value}

A named list with the following elements:
\begin{tabular}{|c|c|}
\hline success & Logical, indicating whether the fitting was successful. If FALSE, an additional element error (of type character) is included containing an explanation of the error; in that case the value of any of the other elements is undetermined. \\
\hline \multirow[t]{3}{*}{Nstates transition_ma} & Integer, the nu \\
\hline & \\
\hline & A matrix of size Nstates x Nstates, the fitted transition rate matrix of the model. The [r,c]-th entry is the transition rate from state \(r\) to state \(c\). \\
\hline loglikelihood & Numeric, the log-likelihood of the observed tip states under the fitted model. \\
\hline Niterations & Integer, the number of iterations required to reach the maximum log-likelihood. Depending on the optimization algorithm used (see optim_algorithm), this may be NA. \\
\hline Nevaluations & Integer, the number of evaluations of the likelihood function required to reach the maximum log-likelihood. Depending on the optimization algorithm used (see optim_algorithm), this may be NA. \\
\hline converged & Logical, indicating whether the fitting algorithm converged. Note that fit_Mk may return successfully even if convergence was not achieved; if this happens, the fitted transition matrix may not be reasonable. In that case it is recommended to change the optimization options, for example increasing optim_max_iterations. \\
\hline guess_rate & Numeric, the initial guess used for the average transition rate, prior to fitting. \\
\hline AIC & Numeric, the Akaike Information Criterion for the fitted model, defined as \(2 k-\) \(2 \log (L)\), where \(k\) is the number of independent fitted parameters and \(L\) is the maximized likelihood. \\
\hline \multicolumn{2}{|l|}{standard_errors} \\
\hline & Numeric matrix of size Nstates x Nstates, estimated standard error of the fitted transition rates, based on parametric bootstrapping. Only returned if Nbootstraps>0. \\
\hline CI50lower & Numeric matrix of size Nstates x Nstates, lower bounds of the \(50 \%\) confidence intervals ( \(25-75 \%\) percentile) for the fitted transition rates, based on parametric bootstrapping. Only returned if Nbootstraps>0. \\
\hline CI50upper & Numeric matrix of size Nstates x Nstates, upper bounds of the \(50 \%\) confidence intervals for the fitted transition rates, based on parametric bootstrapping. Only returned if Nbootstraps>0. \\
\hline CI951ower & Numeric matrix of size Nstates x Nstates, lower bounds of the \(95 \%\) confidence intervals (2.5-97.5\% percentile) for the fitted transition rates, based on parametric bootstrapping. Only returned if Nbootstraps \(>0\). \\
\hline
\end{tabular}

CI95upper Numeric matrix of size Nstates x Nstates, upper bounds of the \(95 \%\) confidence intervals for the fitted transition rates, based on parametric bootstrapping. Only returned if Nbootstraps>0.

\section*{Author(s)}

Stilianos Louca

\section*{References}
Z. Yang, S. Kumar and M. Nei (1995). A new method for inference of ancestral nucleotide and amino acid sequences. Genetics. 141:1641-1650.
M. Pagel (1994). Detecting correlated evolution on phylogenies: a general method for the comparative analysis of discrete characters. Proceedings of the Royal Society of London B: Biological Sciences. 255:37-45.

\section*{See Also}
```

asr_mk_model, simulate_mk_model, fit_musse

```

\section*{Examples}
```


## Not run:

# generate random tree

Ntips = 1000
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# create random transition matrix

Nstates = 5
Q = get_random_mk_transition_matrix(Nstates, rate_model="ER", max_rate=0.01)
cat(sprintf("Simulated ER transition rate=%g\n",Q[1,2]))

# simulate the trait's evolution

simulation = simulate_mk_model(tree, Q)
tip_states = simulation\$tip_states

# fit Mk transition matrix

results = fit_mk(tree, Nstates, tip_states, rate_model="ER", Ntrials=2)

# print Mk model fitting summary

cat(sprintf("Mk model: log-likelihood=%g\n",results$loglikelihood))
cat(sprintf("Fitted ER transition rate=%g\n",results$transition_matrix[1,2]))

## End(Not run)

```
\begin{tabular}{ll} 
fit_musse & Fit a discrete-state-dependent diversification model via maximum- \\
likelihood.
\end{tabular}

\section*{Description}

The Binary State Speciation and Extinction (BiSSE) model (Maddison et al. 2007) and its extension to Multiple State Speciation Extinction (MuSSE) models (FitzJohn et al. 2009, 2012), Hidden State Speciation Extinction (HiSSE) models (Beaulieu and O'meara, 2016) or Several Examined and Concealed States-dependent Speciation and Extinction (SecSSE) models (van Els et al. 2018), describe a Poissonian cladogenic process whose birth/death (speciation/extinction) rates depend on the states of an evolving discrete trait. Specifically, extant tips either go extinct or split continuously in time at Poissonian rates, and birth/death rates at each extant tip depend on the current state of the tip; lineages tansition stochastically between states acccording to a continuous-time Markov process with fixed transition rates. At the end of the simulation (i.e., at "present-day"), extant lineages are sampled according to some state-dependent probability ("sampling_fraction"), which may depend on proxy state. Optionally, tips may also be sampled continuously over time according to some Poissonian rate (which may depend on proxy state), in which case the resulting tree may not be ultrametric.
This function takes as main input a phylogenetic tree (ultrametric unless Poissonian sampling is included) and a list of tip proxy states, and fits the parameters of a BiSSE/MuSSE/HiSSE/SecSSE model to the data via maximum-likelihood. Tips can have missing (unknown) proxy states, and the function can account for biases in species sampling and biases in the identification of proxy states. The likelihood is calculated using a mathematically equivalent, but computationally more efficient variant, of the classical postorder-traversal BiSSE/MuSSE/HiSSE/SecSSE algorithm, as described by Louca (2019). This function has been optimized for large phylogenetic trees, with a relatively small number of states (i.e. Nstates \(<N\) Nips); its time complexity scales roughly linearly with Ntips.

\section*{Usage}
```

fit_musse(tree,
Nstates,
NPstates = NULL,
proxy_map = NULL,
state_names = NULL,
tip_pstates = NULL,
tip_priors = NULL,
sampling_fractions = 1,
reveal_fractions = 1,
sampling_rates = 0,
transition_rate_model = "ARD",
birth_rate_model = "ARD",
death_rate_model = "ARD",
transition_matrix = NULL,
birth_rates = NULL,
death_rates = NULL,
first_guess = NULL,

```


\section*{Arguments}
tree

Nstates Integer, specifying the number of possible discrete states a tip can have, influencing speciation/extinction rates. For example, if Nstates==2 then this corresponds to the common Binary State Speciation and Extinction (BiSSE) model (Maddison et al., 2007). In the case of a HiSSE/SecSSE model, Nstates refers to the total number of diversification rate categories. For example, in the case of the HiSSE model described by Beaulieu and O'meara (2016), Nstates=4.

NPstates Integer, optionally specifying a number of "proxy-states" that are observed instead of the underlying speciation/extinction-modulating states. To fit a HiSSE/SecSSE model, NPstates should be smaller than Nstates. Each state corresponds to a different proxy-state, as defined using the variable proxy_map (see below). For BiSSE/MuSSE with no hidden states, NPstates can be set to either NULL or equal to Nstates; in either case, NPstates will be considered equal to Nstates. For example, in the case of the HiSSE model described by Beaulieu and O'meara (2016), NPstates=2.
proxy_map Integer vector of size Nstates and with values in 1,..NPstates, specifying the correspondence between states (i.e. diversification-rate categories) and proxystates, in a HiSSE/SecSSE model. Specifically, proxy_map[s] indicates which proxy-state the state \(s\) is represented by. Each proxy-state can represent multiple
states (i.e. proxies are ambiguous), but each state must be represented by exactly one proxy-state. For example, to setup the HiSSE model described by Beaulieu and O'meara (2016), use proxy_map=c (1, 2, 1, 2). For non-HiSSE models, set this to NULL or to c(1:Nstates). See below for more details.
state_names Optional character vector of size Nstates, specifying a name/description for each state. This does not influence any of the calculations. It is merely used to add human-readable row/column names (rather than integers) to the returned vectors/matrices. If NULL, no row/column names are added.
tip_pstates Integer vector of size Ntips, listing the proxy state at each tip, in the same order as tips are indexed in the tree. The vector may (but need not) include names; if it does, these are checked for consistency with the tree (if check_input==TRUE). Values must range from 1 to NPstates (which is assumed equal to Nstates in the case of BiSSE/MuSSE). States may also be NA, corresponding to unknown tip proxy states (no information available).
tip_priors Numeric matrix of size Ntips x Nstates (or of size Ntips x NPstates), listing prior likelihoods of each state (or each proxy-state) at each tip. Can be provided as an alternative to tip_pstates. Thus, tip_priors[i,s] is the likelihood of observing the data (i.e., sampling tip i and observing the observed state) if the tip i was at state s (or proxy-state s). Hence, tip_priors should account for sampling fractions as well as reveal fractions. Either tip_pstates or tip_priors must be non-NULL, but not both.
sampling_fractions
Numeric vector of size NPstates, with values between 0 and 1 , listing the sampling fractions of extant species depending on proxy-state. That is, sampling_fractions[p] is the probability that an extant species, having proxy state \(p\), is included in the phylogeny at present-day. If all extant species are included in the tree with the same probability (i.e., independent of state), this can also be a single number. If NULL (default), all extant species are assumed to be included in the tree. Irrelevant if tip_priors is provided and valid for all tips.
reveal_fractions
Numeric vector of size NPstates, with values between 0 and 1, listing the probabilities of proxy-state identification depending on proxy-state. That is, reveal_fractions[p] is the probability that a species with proxy-state \(p\) will have a known ("revealed") state, conditional upon being included in the tree. This can be used to incorporate reveal biases for tips, depending on their proxy state. Can also be NULL or a single number (in which case reveal fractions are assumed to be independent of proxy-state). Note that only the relative values in reveal_fractions matter, for example \(c(1,2,1)\) has the same effect as \(c(0.5,1,0.5)\), because reveal_fractions is normalized internally anyway. Irrelevant if tip_priors is provided and valid for all tips.
sampling_rates Numeric vector of size NPstates, listing Poissonian per-lineage sampling rates over time. Hence, sampling_rates [p] is the rate at which lineages are sampled over time when they are in proxy state \(p\). Can also be a single numeric, in which case sampling rates are the same for all proxy states. If NULL, Poissonian sampling is assumed to not occur. Note that earlier MuSSE/HiSSE models (e.g., by Beaulieu and O'Meara, 2016) do not include Poissonian sampling (i.e., all tips are assumed to have been sampled at present-day). Poissonian sampling through
time is common in epidemiological models but uncommon in macroevolution models.
transition_rate_model
Either a character or a 2D integer matrix of size Nstates x Nstates, specifying the model for the transition rates between states. This option controls the parametric complexity of the state transition model, i.e. the number of independent rates and the correspondence between independent and dependent rates. If a character, then it must be one of "ER", "SYM", "ARD", "SUEDE" or "SRD", as used for Mk models (see the function asr_mk_model for details). For example, "ARD" (all rates different) specifies that all transition rates should be considered as independent parameters with potentially different values.
If an integer matrix, then it defines a custom parametric structure for the transition rates, by mapping entries of the transition matrix to a set of independent transition-rate parameters (numbered 1,2, and so on), similarly to the option rate_model in the function asr_mk_model, and as returned for example by the function get_transition_index_matrix. Entries must be between 1 and Nstates, however 0 may also be used to denote a fixed value of zero. For example, if transition_rate_model[1,2]=transition_rate_model[2,1], then the transition rates \(1->2\) and \(2->1\) are assumed to be equal. Entries on the diagonal are ignored, since the diagonal elements are always adjusted to ensure a valid Markov transition matrix. To construct a custom matrix with the proper structure, it may be convenient to first generate an "ARD" matrix using get_transition_index_matrix, and then modify individual entries to reduce the number of independent rates.

\section*{birth_rate_model}

Either a character or an integer vector of length Nstates, specifying the model for the various birth (speciation) rates. This option controls the parametric complexity of the possible birth rates, i.e. the number of independent birth rates and the correspondence between independent and dependent birth rates. If a character, then it must be either "ER" (equal rates) or "ARD" (all rates different). If an integer vector, it must map each state to an indepedent birth-rate parameter (indexed \(1,2, .\). ). For example, the vector \(c(1,2,1)\) specifies that the birth-rates \(\lambda_{1}\) and \(\lambda_{3}\) must be the same, but \(\lambda_{2}\) is independent.
death_rate_model
Either a character or an integer vector of length Nstates, specifying the model for the various death (extinction) rates. Similar to birth_rate_model.
transition_matrix
Either NULL or a 2D matrix of size Nstates x Nstates, specifying known (and thus fixed) transition rates between states. For example, setting some elements to 0 specifies that these transitions cannot occur directly. May also contain NA, indicating rates that are to be fitted. If NULL or empty, all rates are considered unknown and are therefore fitted. Note that, unless transition_rate_model=="ARD", values in transition_matrix are assumed to be consistent with the rate model, that is, rates specified to be equal under the transition rate model are expected to also have equal values in transition_matrix.
birth_rates Either NULL, or a single number, or a numeric vector of length Nstates, specifying known (and thus fixed) birth rates for each state. May contain NA, indicating rates that are to be fitted. For example, the vector \(c(5,0, N A)\) specifies that
\(\lambda_{1}=5, \lambda_{2}=0\) and that \(\lambda_{3}\) is to be fitted. If NULL or empty, all birth rates are considered unknown and are therefore fitted. If a single number, all birth rates are considered fixed at that given value.
death_rates Either NULL, or a single number, or a numeric vector of length Nstates, specifying known (and thus fixed) death rates for each state. Similar to birth_rates.
first_guess Either NULL, or a named list containing optional initial suggestions for various model parameters, i.e. start values for fitting. The list can contain any or all of the following elements:
- transition_matrix: A single number or a 2D numeric matrix of size Nstates x Nstates, specifying suggested start values for the transition rates. May contain NA, indicating rates that should be guessed automatically by the function. If a single number, then that value is used as a start value for all transition rates.
- birth_rates: A single number or a numeric vector of size Nstates, specifying suggested start values for the birth rates. May contain NA, indicating rates that should be guessed automatically by the function (by fitting a simple birth-death model, see fit_tree_model).
- death_rates: A single number or a numeric vector of size Nstates, specifying suggested start values for the death rates. May contain NA, indicating rates that should be guessed automatically by the function (by fitting a simple birth-death model, see fit_tree_model).

Start values are only relevant for fitted (i.e., non-fixed) parameters.
lower Either NULL or a named list containing optional lower bounds for various model parameters. The list can contain any or all of the elements transition_matrix, birth_rates and death_rates, structured similarly to first_guess. For example, list(transition_matrix=0.1,birth_rates=c(5,NA,NA)) specifies that all transition rates between states must be 0.1 or greater, that the birth rate \(\lambda_{1}\) must be 5 or greater, and that all other model parameters have unspecified lower bound. For parameters with unspecified lower bounds, zero is used as a lower bound. Lower bounds only apply to fitted (i.e., non-fixed) parameters.
upper Either NULL or a named list containing optional upper bounds for various model parameters. The list can contain any or all of the elements transition_matrix, birth_rates and death_rates, structured similarly to upper. For example, list(transition_matrix=2, birth_rates=c(10,NA,NA)) specifies that all transition rates between states must be 2 or less, that the birth rate \(\lambda_{1}\) must be 10 or less, and that all other model parameters have unspecified upper bound. For parameters with unspecified upper bounds, infinity is used as an upper bound. Upper bounds only apply to fitted (i.e., non-fixed) parameters.
root_prior Either a character or a numeric vector of size Nstates, specifying the prior probabilities of states for the root, i.e. the weights for obtaining a single model likelihood by averaging the root's state likelihoods. If a character, then it must be one of "flat", "empirical", "likelihoods", "max_likelihood" or "auto". "empirical" means the root's prior is set to the proportions of (estimated) extant species in each state (correcting for sampling fractions and reveal fractions, if applicable). "likelihoods" means that the computed state-likelihoods of the root are used, after normalizing to obtain a probability distribution; this is the approach
used in the package hisse: :hisse v1.8.9 under the option root. \(\mathrm{p}=\) NULL, and the approach in the package diversitree::find.mle v0.9-10 under the option root=ROOT. OBS. If "max_likelihood", then the root's prior is set to a Dirac distribution, with full weight given to the maximum-likelihood state at the root (after applying the conditioning). If a numeric vector, root_prior specifies custom probabilities (weights) for each state. Note that if root_conditioning is "madfitz" or "herr_als" (see below), then the prior is set before the conditioning and not updated afterwards for consistency with other R packages.

\section*{root_conditioning}

Character, specifying an optional modification to be applied to the root's state likelihoods prior to averaging. Can be "none" (no modification), "madfitz", "herr_als", "crown" or "stem". "madfitz" and "herr_als" (after van Els, Etiene and Herrera-Alsina 2018) are the options implemented in the package hisse v1.8.9, conditioning the root's state-likelihoods based on the birth-rates and the computed extinction probability (after or before averaging, respectively). See van Els (2018) for a comparison between "madfitz" and "herr_als". The option "stem" conditions the state likelihoods on the probability that the stem lineage would survive until the present. The option "crown" conditions the state likelihoods on the probability that a split occurred at oldest_age and that the two child lineages survived until the present; this option is only recommended if oldest_age is equal to the root age.
oldest_age Strictly positive numeric, specifying the oldest age (time before present) to consider for fitting. If this is smaller than the tree's root age, then the tree is split into multiple subtrees at oldest_age, and each subtree is considered as an independent realization of the same diversification/evolution process whose parameters are to be estimated. The root_conditioning and root_prior are applied separately to each subtree, prior to calculating the joint (product) likelihood of all subtrees. This option can be used to restrict the fitting to a small (recent) time interval, during which the MuSSE/BiSSE assumptions (e.g., time-independent speciation/extinction/transition rates) are more likely to hold. If oldest_age is NULL, it is automatically set to the root age. In principle oldest_age may also be older than the root age.
Ntrials Non-negative integer, specifying the number of trials for fitting the model, using alternative (randomized) starting parameters at each trial. A larger Ntrials reduces the risk of landing on a local non-global optimum of the likelihood function, and thus increases the chances of finding the truly best fit. If 0 , then no fitting is performed, and only the first-guess (i.e., provided or guessed start params) is evaluated and returned. Hence, setting Ntrials=0 can be used to obtain a reasonable set of start parameters for subsequent fitting or for Markov Chain Monte Carlo.
max_start_attempts
Integer, specifying the number of times to attempt finding a valid start point (per trial) before giving up on that trial. Randomly chosen extreme start parameters may occasionally result in Inf/undefined likelihoods, so this option allows the algorithm to keep looking for valid starting points. For complex models (e.g., with \(>5\) states), setting this to 10,100 or even 1000 may be beneficial.
optim_algorithm
Character, specifying the optimization algorithm for fitting. Must be one of
either "optim", "nlminb" or "subplex" (requires the nloptr package).
optim_max_iterations
Integer, maximum number of iterations allowed for fitting. Only relevant for "optim" and "nlminb".
optim_max_evaluations
Integer, maximum number of function evaluations allowed for fitting. Only relevant for "nlminb" and "subplex" (requires the nloptr package).
optim_rel_tol Numeric, relative tolerance for the fitted log-likelihood.
check_input Logical, specifying whether to check the validity of input variables. If you are certain that all input variables are valid, you can set this to FALSE to reduce computation.
include_ancestral_likelihoods
Logical, specifying whether to include the state likelihoods for each node, in the returned variables. These are the "D" variables calculated as part of the likelihood based on the subtree descending from each node, and may be used for "local" ancestral state reconstructions.
Nthreads Integer, specifying the number of threads for running multiple fitting trials in parallel. Only relevant if Ntrials \(>1\). Should generally not exceed the number of CPU cores on a machine. Must be a least 1.

Nbootstraps Integer, specifying an optional number of bootstrap samplings to perform, for estimating standard errors and confidence intervals of maximum-likelihood fitted parameters. If 0 , no bootstrapping is performed. Typical values are 10-100. At each bootstrap sampling, a simulation of the fitted MuSSE/HiSSE model is performed, the parameters are estimated anew based on the simulation, and subsequently compared to the original fitted parameters. Each bootstrap sampling will thus use roughly as many computational resources as the original maximum-likelihood fit (e.g., same number of trials, same optimization parameters etc).
Ntrials_per_bootstrap
Integer, specifying the number of fitting trials to perform for each bootstrap sampling. If NULL, this is set equal to max (1,Ntrials). Decreasing Ntrials_per_bootstrap will reduce computation time, at the expense of potentially inflating the estimated confidence intervals; in some cases (e.g., for very large trees) this may be useful if fitting takes a long time and confidence intervals are very narrow anyway. Only relevant if Nbootstraps>0.
max_condition_number
Positive unitless number, specifying the maximum permissible condition number for the "G" matrix computed for the log-likelihood. A higher condition number leads to faster computation (roughly on a log-scale) especially for large trees, at the potential expense of lower accuracy. Typical values are 1e2-1e5. See Louca (2019) for further details on the condition number of the G matrix.
relative_ODE_step
Positive unitless number, specifying the default relative time step for the ordinary differential equation solvers.
E_value_step Positive unitless number, specifying the relative difference between subsequent recorded and interpolated E-values, in the ODE solver for the extinction probabilities E (Louca 2019). Typical values are 1e-2 to 1e-5. A smaller E_value_step
increases interpolation accuracy, but also increases memory requirements and adds runtime (scaling with the tree's age span, not Ntips).
D_temporal_resolution
Positive unitless number, specifying the relative resolution for interpolating Gmap over time (Louca 2019). This is relative to the typical time scales at which G-map varies. For example, a resolution of 10 means that within a typical time scale there will be 10 interpolation points. Typical values are 1-1000. A greater resolution increases interpolation accuracy, but also increases memory requirements and adds runtime (scaling with the tree's age span, not Ntips).
max_model_runtime
Numeric, optional maximum number of seconds for evaluating the likelihood of a model, prior to cancelling the calculation and returning Inf. This may be useful if extreme model parameters (e.g., reached transiently during fitting) require excessive calculation time. Parameters for which the calculation of the likelihood exceed this threshold, will be considered invalid and thus avoided during fitting. For example, for trees with 1000 tips a time limit of 10 seconds may be reasonable. If 0 , no time limit is imposed.
verbose Logical, specifying whether to print progress reports and warnings to the screen. In any case, fatal errors are always reported.
diagnostics Logical, specifying whether to print detailed information (such as model likelihoods) at every iteration of the fitting routine. For debugging purposes mainly.
verbose_prefix Character, specifying the line prefix for printing progress reports, warnings and errors to the screen.

\section*{Details}
\(\mathrm{HiSSE} / \mathrm{SecSSE}\) models include two discrete traits, one trait that defines the rate categories of diversification rates (as in BiSSE/MuSSE), and one trait that does not itself influence diversification but whose states (here called "proxy states") each represent one or more of the diversity-modulating states. HiSSE models (Beaulieu and O'meara, 2016) and SecSSE models (van Els et al., 2018) are closely related to BiSSE/MuSSE models, the main difference being the fact that the actual diversification-modulating states are not directly observed. In essence, a HiSSE/SecSSE model is a BiSSE/MuSSE model, where the final tip states are replaced by their proxy states, thus "masking" the underlying diversity-modulating trait. This function is able to fit HiSSE/SecSSE models with appropriate choice of the input variables Nstates, NPstates and proxy_map. Note that the terminology and setup of HiSSE/SecSSE models followed here differs from their description in the original papers by Beaulieu and O'meara (2016) and van Els et al. (2018), in order to achieve what we think is a more intuitive unification of BiSSE/MuSSE/HiSSE/SecSSE. For ease of terminology, when considering a BiSSE/MuSSE model, here we use the terms "states" and "proxystates" interchangeably, since under BiSSE/MuSSE the proxy trait can be considered identical to the diversification-modulating trait. A distinction between "states" and "proxy-states" is only relevant for HiSSE/SecSSE models.

As an example of a HiSSE model, Nstates=4, NPstates=2 and proxy_map=c (1, 2, 1, 2) specifies that states 1 and 3 are represented by proxy-state 1 , and states 2 and 4 are represented by proxystate 2. This is the original case described by Beaulieu and O'Meara (2016); in their terminology, there would be 2 "hidden"" states (" 0 " and "1") and 2 "observed" states ("A" and "B"), and the 4 diversification rate categories (Nstates=4) would be called "0A", "1A", "0B" and "1B". The
somewhat different terminology used here allows for easier generalization to an arbitrary number of diversification-modulating states and an arbitrary number of proxy states. For example, if there are 6 diversification modulating states, represented by 3 proxy-states as \(1->A, 2->A, 3->B, 4->C\), \(5->C, 6->C\), then one would set Nstates=6, NPstates=3 and proxy_map=c ( \(1,1,2,3,3,3\) ).
The run time of this function scales asymptotically linearly with tree size (Ntips), although run times can vary substantially depending on model parameters. As a rule of thumb, the higher the birth/death/transition rates are compared to the tree's overall time span, the slower the calculation becomes.
The following arguments control the tradeoff between accuracy and computational efficiency:
- max_condition_number: A smaller value means greater accuracy, at longer runtime and more memory.
- relative_ODE_step: A smaller value means greater accuracy, at longer runtime.
- E_value_step: A smaller value means greater accuracy, at longer runtime and more memory.
- D_temporal_resolution: A greater value means greater accuracy, at longer runtime and more memory.

Typically, the default values for these arguments should be fine. For smaller trees, where cladogenic and sampling stochasticity is the main source of uncertainty, these parameters can probably be made less stringent (i.e., leading to lower accuracy and faster computation), but then again for small trees computational efficiency may not be an issue anyway.

Value
A named list with the following elements:
success Logical, indicating whether the fitting was successful. If FALSE, an additional element error (of type character) is included containing an explanation of the error; in that case the value of any of the other elements is undetermined.
Nstates Integer, the number of states assumed for the model.
NPstates Integer, the number of proxy states assumed for the model. Note that in the case of a BiSSE/MuSSE model, this will be the same as Nstates.
root_prior Character, or numeric vector of length Nstates, specifying the root prior used.
parameters Named list containing the final maximum-likelihood fitted model parameters. If Ntrials>1, then this contains the fitted parameters yielding the highest likelihood. Will contain the following elements:
- transition_matrix: 2D numeric matrix of size Nstates x Nstates, listing the fitted transition rates between states.
- birth_rates: Numeric vector of length Nstates, listing the fitted statedependent birth rates.
- death_rates: Numeric vector of length Nstates, listing the fitted statedependent death rates.
start_parameters
Named list containing the default start parameter values for the fitting. Structured similarly to parameters. Note that if Ntrials>1, only the first trial will have used these start values, all other trials will have used randomized start values. Will be defined even if Ntrials==0, and can thus be used to obtain a reasonable guess for the start parameters without actually fitting the model.
\begin{tabular}{|c|c|}
\hline loglikelihood & Numeric, the maximized log-likelihood of the model, if fitting succeeded. \\
\hline AIC & Numeric, the Akaike Information Criterion for the fitted model, defined as \(2 k-\) \(2 \log (L)\), where \(k\) is the number of fitted parameters and \(L\) is the maximized likelihood. \\
\hline Niterations & The number of iterations needed for the best fit. Only relevant if the optimization method was "optim" or "nlminb". \\
\hline Nevaluations & Integer, the number of function evaluations needed for the best fit. Only relevant if the optimization method was "nlminb" or "subplex". \\
\hline converged & Logical, indicating whether convergence was successful during fitting. If convergence was not achieved, and the fitting was stopped due to one of the stopping criteria optim_max_iterations or optim_max_evaluations, the final likelihood will still be returned, but the fitted parameters may not be reasonable. \\
\hline warnings & Character vector, listing any warnings encountered during evaluation of the likelihood function at the fitted parameter values. For example, this vector may contain warnings regarding the differential equation solvers or regarding the rank of the G-matrix (Louca, 2019). \\
\hline subroots & Integer vector, listing indices of tips/nodes in the tree that were considered as starting points of independent MuSSE processes. If oldest_age was equal to or greater than the root age, then subroots will simply list the tree's root. \\
\hline \multicolumn{2}{|l|}{ML_subroot_states} \\
\hline & Integer vector, with values between 1 and Nstates, giving the maximum-likelihood estimate of each subroot's state. \\
\hline \multicolumn{2}{|l|}{ML_substem_states} \\
\hline & Integer vector, with values between 1 and Nstates, giving the maximum-likelihood estimate of the state at each subroot's stem (i.e., exactly at oldest_age). \\
\hline \multicolumn{2}{|l|}{trial_start_loglikelihoods} \\
\hline & Numeric vector of length Ntrials, listing the initial loglikelihoods (i.e., at the starting parameter values) for each fitting trial. \\
\hline \multicolumn{2}{|l|}{trial_loglikelihoods} \\
\hline & Numeric vector of length Ntrials, listing the maximized loglikelihoods for each fitting trial. These may be used for diagnosing the robustness of maximumlikelihood estimates and the assessing the needed for increasing Ntrials. \\
\hline \multicolumn{2}{|l|}{trial_Nstart_attempts} \\
\hline & Integer vector of length Ntrials, listing the number of random start attempts for each trial (see option max_start_attempts). \\
\hline \multicolumn{2}{|l|}{trial_Niterations} \\
\hline & Integer vector of length Ntrials, listing the number of iterations of each trial. Depending on the fitting algorithm used (option optim_algorithm), these may be NA (not available). \\
\hline \multicolumn{2}{|l|}{trial_Nevaluations} \\
\hline & Integer vector of length Ntrials, listing the number of likelihood evaluations of each trial. Depending on the fitting algorithm used (option optim_algorithm), these may be NA (not available). \\
\hline \multicolumn{2}{|l|}{standard_errors} \\
\hline & Named list containing the elements "transition_matrix" (numeric matrix of size Nstates x Nstates), "birth_rates" (numeric vector of size Nstates) and "death_rates" \\
\hline
\end{tabular}
(numeric vector of size Nstates), listing standard errors of all model parameters estimated using parametric bootstrapping. Only included if Nbootstraps>0. Note that the standard errors of non-fitted (i.e., fixed) parameters will be zero.
CI50lower Named list containing the elements "transition_matrix" (numeric matrix of size Nstates x Nstates), "birth_rates" (numeric vector of size Nstates) and "death_rates" (numeric vector of size Nstates), listing the lower end of the \(50 \%\) confidence interval (i.e. the \(25 \%\) quantile) for each model parameter, estimated using parametric bootstrapping. Only included if Nbootstraps>0.
CI50upper Similar to CI50lower, but listing the upper end of the \(50 \%\) confidence interval (i.e. the \(75 \%\) quantile) for each model parameter. For example, the confidence interval for he birth-rate \(\lambda_{1}\) will be between CI50lower\$birth_rates[1] and CI50upper\$birth_rates[1]. Only included if Nbootstraps>0.
CI95lower Similar to CI50lower, but listing the lower end of the \(95 \%\) confidence interval (i.e. the \(2.5 \%\) quantile) for each model parameter. Only included if Nbootstraps>0.
CI95upper Similar to CI50upper, but listing the upper end of the \(95 \%\) confidence interval (i.e. the \(97.5 \%\) quantile) for each model parameter. Only included if Nbootstraps>0.
CI 2D numeric matrix, listing maximum-likelihood estimates, standard errors and confidence intervals for all model parameters (one row per parameter, one column for ML-estimates, one column for standard errors, two columns per confidence interval). Standard errors and confidence intervals are as estimated using parametric bootstrapping. This matrix contains the same information as parameters, standard_errors, CI50lower, CI50upper, CI95lower and CI95upper, but in a more compact format. Only included if Nbootstraps>0.
ancestral_likelihoods
2D matrix of size Nnodes x Nstates, listing the computed state-likelihoods for each node in the tree. These may be used for "local" ancestral state reconstructions, based on the information contained in the subtree descending from each node. Note that for each node the ancestral likelihoods have been normalized for numerical reasons, however they should not be interpreted as actual probabilities. For each node \(n\) and state \(s\), ancestral_likelihoods \([n, s]\) is proportional to the likelihood of observing the descending subtree and associated tip proxy states, if node \(n\) was at state \(s\). Only included if include_ancestral_likelihoods==TRUE.

\section*{Author(s)}

Stilianos Louca

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\section*{See Also}
```

simulate_dsse, asr_mk_model, fit_tree_model

```

\section*{Examples}
```


# EXAMPLE 1: BiSSE model

# - - - - - - - - - - - - - -

# Choose random BiSSE model parameters

Nstates = 2
Q = get_random_mk_transition_matrix(Nstates, rate_model="ARD", max_rate=0.1)
parameters = list(birth_rates = runif(Nstates,5,10),
death_rates = runif(Nstates,0,5),
transition_matrix = Q)
rarefaction = 0.5 \# randomly omit half of the tips

# Simulate a tree under the BiSSE model

simulation = simulate_musse(Nstates,
parameters = parameters,
max_tips = 1000,
sampling_fractions = rarefaction)
tree = simulation$tree
tip_states = simulation$tip_states

## Not run:

# fit BiSSE model to tree \& tip data

fit = fit_musse(tree,
Nstates = Nstates,
tip_pstates = tip_states,
sampling_fractions = rarefaction)
if(!fit$success){
    cat(sprintf("ERROR: Fitting failed"))
}else{
    # compare fitted birth rates to true values
    errors = (fit$parameters$birth_rates - parameters$birth_rates)
relative_errors = errors/parameters\$birth_rates
cat(sprintf("BiSSE relative birth-rate errors:\n"))
print(relative_errors)
}

## End(Not run)

```
```


# EXAMPLE 2: HiSSE model, with bootstrapping

# - - - - - - - - - - - - - -

# Choose random HiSSE model parameters

Nstates = 4
NPstates = 2
Q = get_random_mk_transition_matrix(Nstates, rate_model="ARD", max_rate=0.1)
rarefaction = 0.5 \# randomly omit half of the tips
parameters = list(birth_rates = runif(Nstates,5,10),
death_rates = runif(Nstates,0,5),
transition_matrix = Q)

# reveal the state of 30% \& 60% of tips (in state 1 \& 2, respectively)

reveal_fractions = c(0.3,0.6)

# use proxy map corresponding to Beaulieu and O'Meara (2016)

proxy_map = c(1,2,1,2)

# Simulate a tree under the HiSSE model

simulation = simulate_musse(Nstates,
NPstates = NPstates,
proxy_map = proxy_map,
parameters = parameters,
max_tips = 1000,
sampling_fractions = rarefaction,
reveal_fractions = reveal_fractions)
tree = simulation$tree
tip_states = simulation$tip_proxy_states

## Not run:

# fit HiSSE model to tree \& tip data

# run multiple trials to ensure global optimum

# also estimate confidence intervals via bootstrapping

fit = fit_musse(tree,
Nstates
proxy_map = proxy_map,
tip_pstates = tip_states,
sampling_fractions = rarefaction,
reveal_fractions = reveal_fractions,
Ntrials = 5,
Nbootstraps = 10,
max_model_runtime = 0.1)
if(!fit$success){
    cat(sprintf("ERROR: Fitting failed"))
}else{
    # compare fitted birth rates to true values
    errors = (fit$parameters$birth_rates - parameters$birth_rates)
relative_errors = errors/parameters\$birth_rates
cat(sprintf("HiSSE relative birth-rate errors:\n"))
print(relative_errors)

```
```

    # print 95%-confidence interval for first birth rate
    cat(sprintf("CI95 for lambda1: %g-%g",
        fit$CI95lower$birth_rates[1],
        fit$CI95upper$birth_rates[1]))
    }
    ## End(Not run)
    ```
fit_sbm_const Fit a phylogeographic Spherical Brownian Motion model.

\section*{Description}

Given one or more rooted phylogenetic trees and geographic coordinates (latitudes \& longitudes) for the tips of each tree, this function estimates the diffusivity of a Spherical Brownian Motion (SBM) model for the evolution of geographic location along lineages (Perrin 1928; Brillinger 2012). Estimation is done via maximum-likelihood and using independent contrasts between sister lineages.

\section*{Usage}
```

fit_sbm_const(trees,
tip_latitudes,
tip_longitudes,
radius,
phylodistance_matrixes = NULL,
clade_states = NULL,
planar_approximation = FALSE,
only_basal_tip_pairs = FALSE,
only_distant_tip_pairs = FALSE,
min_MRCA_time = 0,
max_MRCA_age = Inf,
max_phylodistance = Inf,
no_state_transitions = FALSE,
only_state = NULL,
min_diffusivity = NULL,
max_diffusivity = NULL,
Nbootstraps = 0,
NQQ = 0,
SBM_PD_functor = NULL,
focal_diffusivities = NULL)

```

\section*{Arguments}
trees
Either a single rooted tree or a list of rooted trees, of class "phylo". The root of each tree is assumed to be the unique node with no incoming edge. Edge lengths are assumed to represent time intervals or a similarly interpretable phylogenetic distance. When multiple trees are provided, it is either assumed that their roots coincide in time (if align_trees_at_root=TRUE) or that each tree's youngest tip was sampled at present day (if align_trees_at_root=FALSE).
tip_latitudes Numeric vector of length Ntips, or a list of vectors, listing latitudes of tips in decimal degrees (from -90 to 90). If trees is a list of trees, then tip_latitudes should be a list of vectors of the same length as trees, listing tip latitudes for each of the input trees.
tip_longitudes Numeric vector of length Ntips, or a list of vectors, listing longitudes of tips in decimal degrees (from - 180 to 180). If trees is a list of trees, then tip_longitudes should be a list of vectors of the same length as trees, listing tip longitudes for each of the input trees.
radius Strictly positive numeric, specifying the radius of the sphere. For Earth, the mean radius is 6371 km .
phylodistance_matrixes
Numeric matrix, or a list of numeric matrixes, listing phylogenetic distances between tips for each tree. If trees is a list of trees, then phylodistance_matrixes should be a list of the same length as trees, whose n-th element should be a numeric matrix comprising as many rows and columns as there are tips in the n-th tree; the entry phylodistance_matrixes[[n]][i,j] is the phylogenetic distance between tips i and j in tree n . If trees is a single tree, then phylodistance_matrixes can be a single numeric matrix. If NULL (default), phylogenetic distances between tips are calculated based on the provided trees, otherwise phylogenetic distances are taken from phylodistance_matrixes; in the latter case the trees are only used for the topology (determining tip pairs for independent contrasts), but not for calculating phylogenetic distances.
clade_states Either NULL, or an integer vector of length Ntips+Nnodes, or a list of integer vectors, listing discrete states of every tip and node in the tree. If trees is a list of trees, then clade_states should be a list of vectors of the same length as trees, listing tip and node states for each of the input trees. For example, clade_states[[2]][10] specifies the state of the 10-th tip or node in the 2 nd tree. States may be, for example, geographic regions, sub-types, discrete traits etc, and can be used to restrict independent contrasts to tip pairs within the same state (see option no_state_transitions).
planar_approximation
Logical, specifying whether to estimate the diffusivity based on a planar approximation of the SBM model, i.e. by assuming that geographic distances between tips are as if tips are distributed on a 2D cartesian plane. This approximation is only accurate if geographical distances between tips are small compared to the sphere's radius.
only_basal_tip_pairs
Logical, specifying whether to only compare immediate sister tips, i.e., tips connected through a single parental node.
only_distant_tip_pairs
Logical, specifying whether to only compare tips at distinct geographic locations.
min_MRCA_time Numeric, specifying the minimum allowed time (distance from root) of the most recent common ancestor (MRCA) of sister tips considered in the fitting. In other words, an independent contrast is only considered if the two sister tips' MRCA has at least this distance from the root. Set min_MRCA_time<=0 to disable this filter.
max_MRCA_age Numeric, specifying the maximum allowed age (distance from youngest tip) of the MRCA of sister tips considered in the fitting. In other words, an independent contrast is only considered if the two sister tips' MRCA has at most this age (time to present). Set max_MRCA_age=Inf to disable this filter.
max_phylodistance
Numeric, maximum allowed geodistance for an independent contrast to be included in the SBM fitting. Set max_phylodistance=Inf to disable this filter.
no_state_transitions
Logical, specifying whether to omit independent contrasts between tips whose shortest connecting paths include state transitions. If TRUE, only tips within the same state and with no transitions between them (as specified in clade_states) are compared. If TRUE, then clade_states must be provided.
only_state Optional integer, specifying the state in which tip pairs (and their connecting ancestral nodes) must be in order to be considered. If specified, then clade_states must be provided.
min_diffusivity
Non-negative numeric, specifying the minimum possible diffusivity. If NULL, this is automatically chosen.
max_diffusivity
Non-negative numeric, specifying the maximum possible diffusivity. If NULL, this is automatically chosen.
Nbootstraps Non-negative integer, specifying an optional number of parametric bootstraps to performs for estimating standard errors and confidence intervals.
NQQ Integer, optional number of simulations to perform for creating QQ plots of the theoretically expected distribution of geodistances vs. the empirical distribution of geodistances (across independent contrasts). The resolution of the returned QQ plot will be equal to the number of independent contrasts used for fitting. If \(<=0\), no QQ plots will be calculated.
SBM_PD_functor SBM probability density functor object. Used internally for efficiency and for debugging purposes, and should be kept at its default value NULL.
focal_diffusivities
Optional numeric vector, listing diffusivities of particular interest and for which the log-likelihoods should be returned. This may be used e.g. for diagnostic purposes, e.g. to see how "sharp" the likelihood peak is at the maximum-likelihood estimate.

\section*{Details}

For short expected transition distances this function uses the approximation formula by Ghosh et al. (2012). For longer expected transition distances the function uses a truncated approximation of the series representation of SBM transition densities (Perrin 1928). It is assumed that tips are sampled randomly without any biases for certain geographic regions. If you suspect strong geographic sampling biases, consider using the function fit_sbm_geobiased_const.

This function can use multiple trees to fit the diffusivity under the assumption that each tree is an independent realization of the same SBM process, i.e. all lineages in all trees dispersed with the same diffusivity.

If edge. length is missing from one of the input trees, each edge in the tree is assumed to have length 1 . The tree may include multifurcations as well as monofurcations, however multifurcations are internally expanded into bifurcations by adding dummy nodes.

\section*{Value}

A list with the following elements:
\begin{tabular}{ll} 
success & \begin{tabular}{l} 
Logical, indicating whether the fitting was successful. If FALSE, then an addi- \\
tional return variable, error, will contain a description of the error; in that case \\
all other return variables may be undefined.
\end{tabular} \\
diffusivity & \begin{tabular}{l} 
Numeric, the estimated diffusivity, in units distance^2/time. Distance units are \\
the same as used for the radius, and time units are the same as the tree's edge \\
lengths. For example, if the radius was specified in km and edge lengths are in \\
Myr, then the estimated diffusivity will be in \(\mathrm{km} \wedge 2 / \mathrm{Myr}\).
\end{tabular}
\end{tabular}
loglikelihood Numeric, the log-likelihood of the data at the estimated diffusivity.
Ncontrasts Integer, number of independent contrasts (i.e., tip pairs) used to estimate the diffusivity. This is the number of independent data points used.
phylodistances Numeric vector of length Ncontrasts, listing the phylogenetic distances of the independent contrasts used in the fitting.
geodistances Numeric vector of length Ncontrasts, listing the geographical distances of the independent contrasts used in the fitting.
focal_loglikelihoods
Numeric vector of the same length as focal_diffusivities, listing the loglikelihoods for the diffusivities provided in focal_diffusivities.
standard_error Numeric, estimated standard error of the estimated diffusivity, based on parametric bootstrapping. Only returned if Nbootstraps \(>0\).

CI50lower Numeric, lower bound of the \(50 \%\) confidence interval for the estimated diffusivity ( \(25-75 \%\) percentile), based on parametric bootstrapping. Only returned if Nbootstraps>0.
CI50upper Numeric, upper bound of the \(50 \%\) confidence interval for the estimated diffusivity, based on parametric bootstrapping. Only returned if Nbootstraps>0.
CI95lower Numeric, lower bound of the \(95 \%\) confidence interval for the estimated diffusivity (2.5-97.5\% percentile), based on parametric bootstrapping. Only returned if Nbootstraps>0.
CI95upper Numeric, upper bound of the \(95 \%\) confidence interval for the estimated diffusivity, based on parametric bootstrapping. Only returned if Nbootstraps>0.
consistency Numeric between 0 and 1, estimated consistency of the data with the fitted model. If \(L\) denotes the loglikelihood of new data generated by the fitted model (under the same model) and \(M\) denotes the expectation of \(L\), then consistency is the probability that \(|L-M|\) will be greater or equal to \(|X-M|\), where \(X\) is the loglikelihood of the original data under the fitted model. Only returned if Nbootstraps>0. A low consistency (e.g., <0.05) indicates that the fitted model is a poor description of the data. See Lindholm et al. (2019) for background.

QQplot Numeric matrix of size Ncontrasts x 2, listing the computed QQ-plot. The first column lists quantiles of geodistances in the original dataset, the 2nd column lists quantiles of hypothetical geodistances simulated based on the fitted model.

SBM_PD_functor SBM probability density functor object. Used internally for efficiency and for debugging purposes.

\section*{Author(s)}

Stilianos Louca

\section*{References}
F. Perrin (1928). Etude mathematique du mouvement Brownien de rotation. 45:1-51.
D. R. Brillinger (2012). A particle migrating randomly on a sphere. in Selected Works of David Brillinger. Springer.
A. Ghosh, J. Samuel, S. Sinha (2012). A Gaussian for diffusion on the sphere. Europhysics Letters. 98:30003.
A. Lindholm, D. Zachariah, P. Stoica, T. B. Schoen (2019). Data consistency approach to model validation. IEEE Access. 7:59788-59796.
S. Louca (2021). Phylogeographic estimation and simulation of global diffusive dispersal. Systematic Biology. 70:340-359.

\section*{See Also}
```

fit_sbm_geobiased_const, simulate_sbm, fit_sbm_parametric, fit_sbm_linear,fit_sbm_on_grid

```

\section*{Examples}
```


## Not run:

# generate a random tree

tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=500)\$tree

# simulate SBM on the tree

D = 1e4
simulation = simulate_sbm(tree, radius=6371, diffusivity=D)

# fit SBM on the tree

fit = fit_sbm_const(tree,simulation$tip_latitudes,simulation$tip_longitudes,radius=6371)
cat(sprintf('True D=%g, fitted D=%g\n',D,fit\$diffusivity))

## End(Not run)

```

Fit a phylogeographic Spherical Brownian Motion model with geographic sampling bias.

\section*{Description}

Given one or more rooted phylogenetic trees and geographic coordinates (latitudes \& longitudes) for the tips of each tree, this function estimates the diffusivity of a Spherical Brownian Motion (SBM) model for the evolution of geographic location along lineages (Perrin 1928; Brillinger 2012), while correcting for geographic sampling biases. Estimation is done via maximum-likelihood and using independent contrasts between sister lineages, while correction for geographic sampling bias is done through an iterative simulation+fitting process until convergence.

\section*{Usage}

\section*{Arguments}
trees
Either a single rooted tree or a list of rooted trees, of class "phylo". The root of each tree is assumed to be the unique node with no incoming edge. Edge lengths are assumed to represent time intervals or a similarly interpretable phylogenetic distance. When multiple trees are provided, it is either assumed that their roots
coincide in time (if align_trees_at_root=TRUE) or that each tree's youngest tip was sampled at present day (if align_trees_at_root=FALSE).
tip_latitudes Numeric vector of length Ntips, or a list of vectors, listing latitudes of tips in decimal degrees (from -90 to 90). If trees is a list of trees, then tip_latitudes should be a list of vectors of the same length as trees, listing tip latitudes for each of the input trees.
tip_longitudes Numeric vector of length Ntips, or a list of vectors, listing longitudes of tips in decimal degrees (from-180 to 180). If trees is a list of trees, then tip_longi tudes should be a list of vectors of the same length as trees, listing tip longitudes for each of the input trees.
radius Strictly positive numeric, specifying the radius of the sphere. For Earth, the mean radius is 6371 km .
reference_latitudes
Optional numeric vector, listing latitudes of reference coordinates based on which to calculate the geographic sampling density. If NULL, the geographic sampling density is estimated based on tip_latitudes and tip_longitudes.
reference_longitudes
Optional numeric vector of the same length as reference_latitudes, listing latitudes of reference coordinates based on which to calculate the geographic sampling density. If NULL, the geographic sampling density is estimated based on tip_latitudes and tip_longitudes.
only_basal_tip_pairs
Logical, specifying whether to only compare immediate sister tips, i.e., tips connected through a single parental node.
only_distant_tip_pairs
Logical, specifying whether to only compare tips at distinct geographic locations.
min_MRCA_time Numeric, specifying the minimum allowed time (distance from root) of the most recent common ancestor (MRCA) of sister tips considered in the fitting. In other words, an independent contrast is only considered if the two sister tips' MRCA has at least this distance from the root. Set min_MRCA_time<=0 to disable this filter.
max_MRCA_age Numeric, specifying the maximum allowed age (distance from youngest tip) of the MRCA of sister tips considered in the fitting. In other words, an independent contrast is only considered if the two sister tips' MRCA has at most this age (time to present). Set max_MRCA_age=Inf to disable this filter.
max_phylodistance
Numeric, maximum allowed geodistance for an independent contrast to be included in the SBM fitting. Set max_phylodistance=Inf to disable this filter.
min_diffusivity
Non-negative numeric, specifying the minimum possible diffusivity. If NULL, this is automatically chosen.
max_diffusivity
Non-negative numeric, specifying the maximum possible diffusivity. If NULL, this is automatically chosen.
\begin{tabular}{ll} 
rarefaction & \begin{tabular}{l} 
Numeric, between 00 and 1, specifying the fraction of extant lineages to sample \\
from the simulated trees. Should be strictly smaller than 1, in order for geo- \\
graphic bias correction to have an effect. Note that regardless of rarefaction, \\
the simulated trees will have the same size as the original trees.
\end{tabular} \\
Nsims & \begin{tabular}{l} 
Integer, number of SBM simulatons to perform per iteration for assessing the \\
effects of geographic bias. Smaller trees require larger Nsims (due to higher \\
stochasticity). This must be at least 2, although values of 100-1000 are recom- \\
mended.
\end{tabular} \\
max_iterations
\end{tabular} \begin{tabular}{l} 
Integer, maximum number of iterations (correction steps) to perform before giv- \\
ing up.
\end{tabular}

\section*{Details}

This function tries to estimate the true spherical diffusivity of an SBM model of geographic diffusive dispersal, while correcting for geographic sampling biases. This is done using an iterative refinement approach, by which trees and tip locations are repeatedly simulated under the current true diffusivity estimate and the diffusivity estimated from those simulated data are compared to the originally uncorrected diffusivity estimate. Trees are simulated according to a birth-death model with constant rates, fitted to the original input trees (a congruent birth-death model is chosen to match the requested rarefaction). Simulated trees are subsampled (rarefied) to match the original input tree sizes, with sampled lineages chosen randomly but in a geographically biased way that resembles the original geographic sampling density (e.g., as inferred from the reference_latitudes and reference_longitudes). Internally, this function repeatedly applies fit_sbm_const and simulate_sbm. If the true sampling fraction of the input trees is unknown, then it is advised to perform the analysis with a few alternative rarefaction values (e.g., 0.01 and 0.1 ) to verify the robustness of the estimates.

If edge. length is missing from one of the input trees, each edge in the tree is assumed to have length 1 . The tree may include multifurcations as well as monofurcations, however multifurcations are internally expanded into bifurcations by adding dummy nodes.

\section*{Value}

A list with the following elements:
\begin{tabular}{ll} 
success & \begin{tabular}{l} 
Logical, indicating whether the fitting was successful. If FALSE, then an addi- \\
tional return variable, error, will contain a description of the error; in that case \\
all other return variables may be undefined. \\
Integer, number of latitude-tiles used for building a map of the geographic sam- \\
pling biases.
\end{tabular} \\
Nlon & \begin{tabular}{l} 
Integer, number of longitude-tiles used for building a map of the geographic \\
sampling biases.
\end{tabular} \\
diffusivity \(\quad\)\begin{tabular}{l} 
Numeric, the estimated true diffusivity, i.e. accounting for geographic sampling \\
biases, in units distance^2/time. Distance units are the same as used for the \\
radius, and time units are the same as the tree's edge lengths. For example, if \\
the radius was specified in km and edge lengths are in Myr, then the estimated \\
diffusivity will be in \(\mathrm{km}^{\wedge} 2 / \mathrm{Myr}\).
\end{tabular}
\end{tabular}

\section*{correction_factor}

Numeric, estimated ratio between the true diffusivity and the original (uncorrected) diffusivity estimate.
Niterations Integer, the number of iterations performed until convergence.
stopping_criterion
Character, a short description of the criterion by which the iteration was eventually halted.
uncorrected_fit_diffusivity
Numeric, the originally estimated (uncorrected) diffusivity.
last_sim_fit_diffusivity
Numeric, the mean uncorrected diffuvity estimated from the simulated data in the last iteration. Convergence means that last_sim_fit_diffusivity came close to uncorrected_fit_diffusivity.
all_correction_factors
Numeric vector of length Niterations, listing the estimated correction factors in each iteration.
all_diffusivity_estimates
Numeric vector of length Niterations, listing the mean uncorrected diffusivity estimated from the simulated data in each iteration.
Ntrees Integer, number of trees considered for the simulations. This might have smaller than length(trees), if for some trees fitting a birth-death model was not possible.
lambda Numeric vector of length Ntrees, listing the birth rates used to simulate the trees.
mu \(\quad\) Numeric vector of length Ntrees, listing the death rates used to simulate the trees.
rarefaction Numeric vector of length Ntrees, listing the rarefactions (sampling fractions) used to simulate the trees. These will typically be equal to the rarefaction provided by the function caller, but may differ for example if the congruence class did not include a birth-death model with the requested rarefaction.
\begin{tabular}{ll} 
Ncontrasts & \begin{tabular}{l} 
Integer, number of independent contrasts (i.e., tip pairs) used to estimate the \\
diffusivity. This is the number of independent data points used.
\end{tabular} \\
standard_error & \begin{tabular}{l} 
Numeric, estimated standard error of the estimated true diffusivity, based on \\
parametric bootstrapping. Only returned if Nbootstraps>0.
\end{tabular} \\
CI50lower & \begin{tabular}{l} 
Numeric, lower bound of the \(50 \%\) confidence interval for the estimated true dif- \\
fusivity (25-75\% percentile), based on parametric bootstrapping. Only returned \\
if Nbootstraps>0.
\end{tabular} \\
CI50upper & \begin{tabular}{l} 
Numeric, upper bound of the \(50 \%\) confidence interval for the estimated true dif- \\
fusivity, based on parametric bootstrapping. Only returned if Nbootstraps>0.
\end{tabular} \\
CI95lower & \begin{tabular}{l} 
Numeric, lower bound of the \(95 \%\) confidence interval for the estimated true \\
diffusivity (2.5-97.5\% percentile), based on parametric bootstrapping. Only re- \\
turned if Nbootstraps>0.
\end{tabular} \\
CI95upper & \begin{tabular}{l} 
Numeric, upper bound of the \(95 \%\) confidence interval for the estimated true dif- \\
fusivity, based on parametric bootstrapping. Only returned if Nbootstraps>0.
\end{tabular} \\
QQplot & \begin{tabular}{l} 
Numeric matrix of size Ncontrasts x 2 , listing the computed QQ-plot. The first \\
column lists quantiles of geodistances in the original dataset, the 2nd column \\
lists quantiles of hypothetical geodistances simulated based on the estimated
\end{tabular} \\
true diffusivity.
\end{tabular}

\section*{Author(s)}

Stilianos Louca

\section*{References}
F. Perrin (1928). Etude mathematique du mouvement Brownien de rotation. 45:1-51.
D. R. Brillinger (2012). A particle migrating randomly on a sphere. in Selected Works of David Brillinger. Springer.
A. Ghosh, J. Samuel, S. Sinha (2012). A Gaussian for diffusion on the sphere. Europhysics Letters. 98:30003.
S. Louca (2021). Phylogeographic estimation and simulation of global diffusive dispersal. Systematic Biology. 70:340-359.
S. Louca (in review as of 2021). The rates of global microbial dispersal.

\section*{See Also}
```

simulate_sbm, fit_sbm_parametric, fit_sbm_linear, fit_sbm_on_grid

```

\section*{Examples}
```


## Not run:

NFullTips = 10000
diffusivity = 1
radius = 6371

# generate tree and run SBM on it

cat(sprintf("Generating tree and simulating SBM (true D=%g)..\n",diffusivity))
tree = castor::generate_tree_hbd_reverse(Ntips = NFullTips,
lambda = 5e-7,
mu = 2e-7,
rho = 1)\$trees[[1]]
SBMsim = simulate_sbm(tree = tree, radius = radius, diffusivity = diffusivity)

# select subset of tips only found in certain geographic regions

min_abs_lat = 30
max_abs_lat = 80
min_lon = 0
max_lon = 90
keep_tips = which((abs(SBMsim$tip_latitudes)<=max_abs_lat)
                    & (abs(SBMsim$tip_latitudes)>=min_abs_lat)
\& (SBMsim$tip_longitudes<=max_lon)
                    & (SBMsim$tip_longitudes>=min_lon))
rarefaction = castor::get_subtree_with_tips(tree, only_tips = keep_tips)
tree = rarefaction$subtree
tip_latitudes = SBMsim$tip_latitudes[rarefaction$new2old_tip]
tip_longitudes = SBMsim$tip_longitudes[rarefaction$new2old_tip]
Ntips = length(tree$tip.label)
rarefaction = Ntips/NFullTips

# fit SBM while correcting for geographic sampling biases

fit = castor:::fit_sbm_geobiased_const(trees = tree,
tip_latitudes = tip_latitudes,
tip_longitudes = tip_longitudes,
radius = radius,
rarefaction = Ntips/NFullTips,
Nsims = 10,
Nthreads = 4,
verbose = TRUE,
verbose_prefix = " ")
if(!fit$success){
        cat(sprintf("ERROR: %s\n",fit$error))
}else{
cat(sprintf("Estimated true D = %g\n",fit\$diffusivity))
}

## End(Not run)

```

\section*{Description}

Given a rooted phylogenetic tree and geographic coordinates (latitudes \& longitudes) for its tips, this function estimates the diffusivity of a Spherical Brownian Motion (SBM) model for the evolution of geographic location along lineages (Perrin 1928; Brillinger 2012), assuming that the diffusivity varies linearly over time. Estimation is done via maximum-likelihood and using independent contrasts between sister lineages. This function is designed to estimate the diffusivity over time, by fitting two parameters defining the diffusivity as a linear function of time. For fitting more general functional forms see fit_sbm_parametric.

\section*{Usage}
```

fit_sbm_linear(tree,
tip_latitudes,
tip_longitudes,
radius,
clade_states = NULL,
planar_approximation = FALSE,
only_basal_tip_pairs = FALSE,
only_distant_tip_pairs= FALSE,
min_MRCA_time = 0,
max_MRCA_age = Inf,
max_phylodistance = Inf,
no_state_transitions = FALSE,
only_state = NULL,
time1 = 0,
time2 = NULL,
Ntrials = 1,
Nthreads = 1,
Nbootstraps = 0,
Ntrials_per_bootstrap = NULL,
Nsignificance = 0,
NQQ = 0,
fit_control = list(),
SBM_PD_functor = NULL,
verbose = FALSE,
verbose_prefix = "")

```

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge. Edge lengths are assumed to represent time intervals or a similarly interpretable phylogenetic distance.
\begin{tabular}{|c|c|}
\hline tip_latitudes & Numeric vector of length Ntips, listing latitudes of tips in decimal degrees (from -90 to 90). The order of entries must correspond to the order of tips in the tree (i.e., as listed in tree\$tip.label). \\
\hline tip_longitudes & Numeric vector of length Ntips, listing longitudes of tips in decimal degrees (from -180 to 180). The order of entries must correspond to the order of tips in the tree (i.e., as listed in tree\$tip. label). \\
\hline radius & Strictly positive numeric, specifying the radius of the sphere. For Earth, the mean radius is 6371 km . \\
\hline clade_states & Optional integer vector of length Ntips+Nnodes, listing discrete states of every tip and node in the tree. The order of entries must match the order of tips and nodes in the tree. States may be, for example, geographic regions, sub-types, discrete traits etc, and can be used to restrict independent contrasts to tip pairs within the same state (see option no_state_transitions). \\
\hline \multicolumn{2}{|l|}{planar_approximation} \\
\hline & Logical, specifying whether to estimate the diffusivity based on a planar approximation of the SBM model, i.e. by assuming that geographic distances between tips are as if tips are distributed on a 2D cartesian plane. This approximation is only accurate if geographical distances between tips are small compared to the sphere's radius. \\
\hline \multicolumn{2}{|l|}{only_basal_tip_pairs} \\
\hline & Logical, specifying whether to only compare immediate sister tips, i.e., tips connected through a single parental node. \\
\hline \multicolumn{2}{|l|}{only_distant_tip_pairs} \\
\hline & Logical, specifying whether to only compare tips at distinct geographic locations. \\
\hline min_MRCA_time & Numeric, specifying the minimum allowed time (distance from root) of the most recent common ancestor (MRCA) of sister tips considered in the fitting. In other words, an independent contrast is only considered if the two sister tips' MRCA has at least this distance from the root. Set min_MRCA_time=0 to disable this filter. \\
\hline max_MRCA_age & Numeric, specifying the maximum allowed age (distance from youngest tip) of the MRCA of sister tips considered in the fitting. In other words, an independent contrast is only considered if the two sister tips' MRCA has at most this age (time to present). Set max_MRCA_age=Inf to disable this filter. \\
\hline
\end{tabular}
```

max_phylodistance

```

Numeric, maximum allowed geodistance for an independent contrast to be included in the SBM fitting. Set max_phylodistance=Inf to disable this filter.
```

no_state_transitions

```

Logical, specifying whether to omit independent contrasts between tips whose shortest connecting paths include state transitions. If TRUE, only tips within the same state and with no transitions between them (as specified in clade_states) are compared.
only_state Optional integer, specifying the state in which tip pairs (and their connecting ancestral nodes) must be in order to be considered. If specified, then clade_states must be provided.
\(\left.\begin{array}{ll}\text { time1 } & \begin{array}{l}\text { Optional numeric, specifying the first time point at which to estimate the diffu- } \\ \text { sivity. By default this is set to root (i.e., time 0). } \\ \text { Optional numeric, specifying the first time point at which to estimate the diffu- } \\ \text { sivity. By default this is set to the present day (i.e., the maximum distance of } \\ \text { any tip from the root). }\end{array} \\ \text { time2 } & \begin{array}{l}\text { Integer, specifying the number of independent fitting trials to perform, each } \\ \text { starting from a random choice of model parameters. Increasing Ntrials re- } \\ \text { duces the risk of reaching a non-global local maximum in the fitting objective. }\end{array} \\ \text { Ntrials } & \begin{array}{l}\text { Integer, specifying the number of parallel threads to use for performing multiple } \\ \text { fitting trials simultaneously. This should generally not exceed the number of } \\ \text { available CPUs on your machine. Parallel computing is not available on the }\end{array} \\ \text { Nthreads } \begin{array}{l}\text { Windows platform. }\end{array} \\ \text { Nbootstraps } \quad \begin{array}{l}\text { Integer, specifying the number of parametric bootstraps to perform for estimat- } \\ \text { ing standard errors and confidence intervals of estimated model parameters. Set } \\ \text { to } 0 \text { for no bootstrapping. }\end{array} \\ \text { Ntrials_per_bootstrap } \\ \text { Integer, specifying the number of fitting trials to perform for each bootstrap sam- } \\ \text { pling. If NULL, this is set equal to max (1, Ntrials). Decreasing Ntrials_per_bootstrap } \\ \text { will reduce computation time, at the expense of potentially inflating the esti- } \\ \text { mated confidence intervals; in some cases (e.g., for very large trees) this may } \\ \text { be useful if fitting takes a long time and confidence intervals are very narrow }\end{array}\right\}\)

\section*{Details}

This function is essentially a wrapper for the more general function fit_sbm_parametric, with the addition that it can estimate the statistical significance of the fitted linear slope.

The statistical significance of the slope is the probability that a constant-diffusivity SBM model would generate data that would yield a fitted linear slope equal to or greater than the one fitted to the original data; the significance is estimated by simulating Nsignificance constant-diffusivity
models and then fitting a linear-diffusivity model. The constant diffusivity assumed in these simulations is the maximum-likelihood diffusivity fitted internally using fit_sbm_const.
Note that estimation of diffusivity at older times is only possible if the timetree includes extinct tips or tips sampled at older times (e.g., as is often the case in viral phylogenies). If tips are only sampled once at present-day, i.e. the timetree is ultrametric, reliable diffusivity estimates can only be achieved near present times.
For short expected transition distances this function uses the approximation formula by Ghosh et al. (2012) to calculate the probability density of geographical transitions along edges. For longer expected transition distances the function uses a truncated approximation of the series representation of SBM transition densities (Perrin 1928).
If edge. length is missing from one of the input trees, each edge in the tree is assumed to have length 1 . The tree may include multifurcations as well as monofurcations, however multifurcations are internally expanded into bifurcations by adding dummy nodes.

\section*{Value}

A list with the following elements:
\(\begin{array}{ll}\text { success } & \begin{array}{l}\text { Logical, indicating whether the fitting was successful. If FALSE, then an addi- } \\ \text { tional return variable, error, will contain a description of the error; in that case } \\ \text { all other return variables may be undefined. }\end{array} \\ \text { objective_value }\end{array}\) The maximized fitting objective. Currently, only maximum-likelihood estima- \(\left.\begin{array}{ll}\text { Tion is implemented, and hence this will always be the maximized log-likelihood. }\end{array}\right\}\)
\begin{tabular}{|c|c|}
\hline Niterations & Integer, specifying the number of iterations performed during the optimization path that yielded the maximum likelihood. \\
\hline Nevaluations & Integer, specifying the number of likelihood evaluations performed during the optimization path that yielded the maximum likelihood. \\
\hline \multicolumn{2}{|l|}{trial_start_objectives} \\
\hline & Numeric vector of size Ntrials, listing the initial objective values (e.g., loglikelihoods) for each fitting trial, i.e. at the start parameter values. \\
\hline \multicolumn{2}{|l|}{trial_objective_values} \\
\hline & Numeric vector of size Ntrials, listing the final maximized objective values (e.g., loglikelihoods) for each fitting trial. \\
\hline \multicolumn{2}{|l|}{trial_Nstart_attempts} \\
\hline & Integer vector of size Ntrials, listing the number of start attempts for each fitting trial, until a starting point with valid likelihood was found. \\
\hline \multicolumn{2}{|l|}{trial_Niterations} \\
\hline & Integer vector of size Ntrials, listing the number of iterations needed for each fitting trial. \\
\hline \multicolumn{2}{|l|}{trial_Nevaluations} \\
\hline & Integer vector of size Ntrials, listing the number of likelihood evaluations needed for each fitting trial. \\
\hline \multicolumn{2}{|l|}{standard_errors} \\
\hline & Numeric vector of size 2, estimated standard error of the fitted diffusivity at the root and present, based on parametric bootstrapping. Only returned if Nbootstraps>0. \\
\hline CI50lower & Numeric vector of size 2, lower bound of the \(50 \%\) confidence interval ( \(25-75 \%\) percentile) for the fitted diffusivity at the root and present, based on parametric bootstrapping. Only returned if Nbootstraps>0. \\
\hline CI50upper & Numeric vector of size 2, upper bound of the \(50 \%\) confidence interval for the fitted diffusivity at the root and present, based on parametric bootstrapping. Only returned if Nbootstraps>0. \\
\hline CI951ower & Numeric vector of size 2, lower bound of the \(95 \%\) confidence interval (2.5\(97.5 \%\) percentile) for the fitted diffusivity at the root and present, based on parametric bootstrapping. Only returned if Nbootstraps>0. \\
\hline CI95upper & Numeric vector of size 2, upper bound of the \(95 \%\) confidence interval for the fitted diffusivity at the root and present, based on parametric bootstrapping. Only returned if Nbootstraps>0. \\
\hline consistency & Numeric between 0 and 1, estimated consistency of the data with the fitted model. See the documentation of fit_sbm_const for an explanation. Only returned if Nbootstraps>0. \\
\hline significance & Numeric between 0 and 1, estimate statistical significance of the fitted linear slope. Only returned if Nsignificance>0. \\
\hline QQplot & Numeric matrix of size Ncontrasts x 2, listing the computed QQ-plot. The first column lists quantiles of geodistances in the original dataset, the 2nd column lists quantiles of hypothetical geodistances simulated based on the fitted model. \\
\hline SBM_PD_functor & SBM probability density functor object. Used internally for efficiency and for debugging purposes. \\
\hline
\end{tabular}

\section*{Author(s)}

Stilianos Louca

\section*{References}
F. Perrin (1928). Etude mathematique du mouvement Brownien de rotation. 45:1-51.
D. R. Brillinger (2012). A particle migrating randomly on a sphere. in Selected Works of David Brillinger. Springer.
A. Ghosh, J. Samuel, S. Sinha (2012). A Gaussian for diffusion on the sphere. Europhysics Letters. 98:30003.
S. Louca (2021). Phylogeographic estimation and simulation of global diffusive dispersal. Systematic Biology. 70:340-359.

\section*{See Also}
```

simulate_sbm, fit_sbm_const, fit_sbm_parametric, fit_sbm_on_grid

```

\section*{Examples}
```


## Not run:

# generate a random tree, keeping extinct lineages

tree_params = list(birth_rate_factor=1, death_rate_factor=0.95)
tree = generate_random_tree(tree_params,max_tips=1000,coalescent=FALSE)\$tree

# calculate max distance of any tip from the root

max_time = get_tree_span(tree)\$max_distance

# simulate time-dependent SBM on the tree

# we assume that diffusivity varies linearly with time

# in this example we measure distances in Earth radii

radius = 1
diffusivity_functor = function(times, params){
return(params[1] + (times/max_time)*(params[2]-params[1]))
}
true_params = c(1, 2)
time_grid = seq(0,max_time,length.out=2)
simulation = simulate_sbm(tree,
radius = radius,
diffusivity = diffusivity_functor(time_grid,true_params),
time_grid = time_grid)

# fit time-independent SBM to get a rough estimate

fit_const = fit_sbm_const(tree,simulation$tip_latitudes,simulation$tip_longitudes,radius=radius)

# fit SBM model with linearly varying diffusivity

fit = fit_sbm_linear(tree,
simulation$tip_latitudes,
    simulation$tip_longitudes,
radius = radius,
Ntrials = 10)

```
```


# compare fitted \& true params

print(true_params)
print(fit\$diffusivities)

## End(Not run)

```
fit_sbm_on_grid Fit a phylogeographic Spherical Brownian Motion model with
piecewise-linear diffusivity.

\section*{Description}

Given a rooted phylogenetic tree and geographic coordinates (latitudes \& longitudes) for its tips, this function estimates the diffusivity of a Spherical Brownian Motion (SBM) model with timedependent diffusivity for the evolution of geographic location along lineages (Perrin 1928; Brillinger 2012). Estimation is done via maximum-likelihood and using independent contrasts between sister lineages. This function is designed to estimate the diffusivity over time, approximated as a piecewise linear profile, by fitting the diffusivity on a discrete set of time points. The user thus provides a set of time points (time_grid), and fit_sbm_on_grid estimates the diffusivity on each time point, while assuming that the diffusivity varies linearly between time points.

\section*{Usage}
```

fit_sbm_on_grid(tree,
tip_latitudes,
tip_longitudes,
radius,
clade_states = NULL,
planar_approximation = FALSE,
only_basal_tip_pairs = FALSE,
only_distant_tip_pairs= FALSE,
min_MRCA_time = 0,
max_MRCA_age = Inf,
max_phylodistance = Inf,
no_state_transitions = FALSE,
only_state = NULL,
time_grid = 0,
guess_diffusivity = NULL,
min_diffusivity = NULL,
max_diffusivity = Inf,
Ntrials = 1,
Nthreads = 1,
Nbootstraps = 0,
Ntrials_per_bootstrap = NULL,
NQQ = 0,
fit_control = list(),

```
\begin{tabular}{ll} 
SBM_PD_functor & \(=\) NULL, \\
verbose & \(=\) FALSE, \\
verbose_prefix & \(=" ")\)
\end{tabular}

\section*{Arguments}

A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge. Edge lengths are assumed to represent time intervals or a similarly interpretable phylogenetic distance.
tip_latitudes Numeric vector of length Ntips, listing latitudes of tips in decimal degrees (from -90 to 90 ). The order of entries must correspond to the order of tips in the tree (i.e., as listed in tree\$tip.label).
tip_longitudes Numeric vector of length Ntips, listing longitudes of tips in decimal degrees (from -180 to 180). The order of entries must correspond to the order of tips in the tree (i.e., as listed in tree\$tip. label).
radius Strictly positive numeric, specifying the radius of the sphere. For Earth, the mean radius is 6371 km .
clade_states Optional integer vector of length Ntips+Nnodes, listing discrete states of every tip and node in the tree. The order of entries must match the order of tips and nodes in the tree. States may be, for example, geographic regions, sub-types, discrete traits etc, and can be used to restrict independent contrasts to tip pairs within the same state (see option no_state_transitions).
planar_approximation
Logical, specifying whether to estimate the diffusivity based on a planar approximation of the SBM model, i.e. by assuming that geographic distances between tips are as if tips are distributed on a 2D cartesian plane. This approximation is only accurate if geographical distances between tips are small compared to the sphere's radius.
only_basal_tip_pairs
Logical, specifying whether to only compare immediate sister tips, i.e., tips connected through a single parental node.
only_distant_tip_pairs
Logical, specifying whether to only compare tips at distinct geographic locations.
min_MRCA_time Numeric, specifying the minimum allowed time (distance from root) of the most recent common ancestor (MRCA) of sister tips considered in the fitting. In other words, an independent contrast is only considered if the two sister tips' MRCA has at least this distance from the root. Set min_MRCA_time \(=0\) to disable this filter.
max_MRCA_age Numeric, specifying the maximum allowed age (distance from youngest tip) of the MRCA of sister tips considered in the fitting. In other words, an independent contrast is only considered if the two sister tips' MRCA has at most this age (time to present). Set max_MRCA_age=Inf to disable this filter.
max_phylodistance
Numeric, maximum allowed geodistance for an independent contrast to be included in the SBM fitting. Set max_phylodistance=Inf to disable this filter.

Logical, specifying whether to omit independent contrasts between tips whose shortest connecting paths include state transitions. If TRUE, only tips within the same state and with no transitions between them (as specified in clade_states) are compared.
only_state Optional integer, specifying the state in which tip pairs (and their connecting ancestral nodes) must be in order to be considered. If specified, then clade_states must be provided.
time_grid Numeric vector, specifying discrete time points (counted since the root) at which the diffusivity should be fitted; between these time points the diffusivity is assumed to vary linearly. This time grid should be fine enough to sufficiently capture the variation in the diffusivity over time, but must not be too big to avoid overfitting. If NULL or of size 1 , then the diffusivity is assumed to be timeindependent. Listed times must be strictly increasing, and should cover at least the full considered time interval (from 0 to the maximum distance of any tip from the root); otherwise, constant extrapolation is used to cover missing times. Note that time is measured in the same units as the tree's edge lengths.

Optional numeric vector, specifying a first guess for the diffusivity. Either of size 1 (the same first guess for all time points), or of the same length as time_grid (different first guess for each time point, NA are replaced with an automatically chosen first guess). If NULL, the first guess is chosen automatically.
min_diffusivity
Optional numeric vector, specifying lower bounds for the fitted diffusivity. Either of size 1 (the same lower bound is assumed for all time points), or of the same length as time_grid (different lower bound for each time point, NA are replaced with an automatically chosen lower bound). If NULL, lower bounds are chosen automatically.
max_diffusivity
Optional numeric vector, specifying upper bounds for the fitted diffusivity. Either of size 1 (the same upper bound is assumed for all time points), or of the same length as time_grid (different upper bound for each time point, NA are replaced with infinity). If NULL, no upper bound is imposed.
Ntrials Integer, specifying the number of independent fitting trials to perform, each starting from a random choice of model parameters. Increasing Ntrials reduces the risk of reaching a non-global local maximum in the fitting objective.
Nthreads Integer, specifying the number of parallel threads to use for performing multiple fitting trials simultaneously. This should generally not exceed the number of available CPUs on your machine. Parallel computing is not available on the Windows platform.
Nbootstraps Integer, specifying the number of parametric bootstraps to perform for estimating standard errors and confidence intervals of estimated model parameters. Set to 0 for no bootstrapping.
Ntrials_per_bootstrap
Integer, specifying the number of fitting trials to perform for each bootstrap sampling. If NULL, this is set equal to max (1,Ntrials). Decreasing Ntrials_per_bootstrap
will reduce computation time, at the expense of potentially inflating the estimated confidence intervals; in some cases (e.g., for very large trees) this may be useful if fitting takes a long time and confidence intervals are very narrow anyway. Only relevant if Nbootstraps>0.
NQQ Integer, optional number of simulations to perform for creating QQ plots of the theoretically expected distribution of geodistances vs. the empirical distribution of geodistances (across independent contrasts). The resolution of the returned QQ plot will be equal to the number of independent contrasts used for fitting. If \(<=0\), no QQ plots will be calculated.
fit_control Named list containing options for the nlminb optimization routine, such as iter.max, eval.max or rel.tol. For a complete list of options and default values see the documentation of nlminb in the stats package.
SBM_PD_functor SBM probability density functor object. Used internally for efficiency and for debugging purposes, and should be kept at its default value NULL.
verbose Logical, specifying whether to print progress reports and warnings to the screen. Note that errors always cause a return of the function (see return values success and error).
verbose_prefix Character, specifying the line prefix for printing progress reports to the screen.

\section*{Details}

This function is designed to estimate the diffusivity profile over time, approximated by a piecewise linear function. Fitting is done by maximizing the likelihood of observing the given tip coordinates under the SBM model. Internally, this function uses fit_sbm_parametric.
It is generally advised to provide as much information to the function fit_sbm_on_grid as possible, including reasonable lower and upper bounds (min_diffusivity and max_diffusivity). It is important that the time_grid is sufficiently fine to capture the variation of the true diffusivity over time, since the likelihood is calculated under the assumption that the diffusivity varies linearly between grid points. However, depending on the size of the tree, the grid size must not be too large, since otherwise overfitting becomes very likely. The time_grid does not need to be uniform, i.e., you may want to use a finer grid in regions where there's more data (tips) available.
Note that estimation of diffusivity at older times is only possible if the timetree includes extinct tips or tips sampled at older times (e.g., as is often the case in viral phylogenies). If tips are only sampled once at present-day, i.e. the timetree is ultrametric, reliable diffusivity estimates can only be achieved near present times. If the tree is ultrametric, you should consider using fit_sbm_const instead.

If edge. length is missing from one of the input trees, each edge in the tree is assumed to have length 1 . The tree may include multifurcations as well as monofurcations, however multifurcations are internally expanded into bifurcations by adding dummy nodes.

\section*{Value}

A list with the following elements:
success Logical, indicating whether the fitting was successful. If FALSE, then an additional return variable, error, will contain a description of the error; in that case all other return variables may be undefined.
\begin{tabular}{|c|c|}
\hline & The maximized fitting objective. Currently, only maximum-likelihood estimation is implemented, and hence this will always be the maximized log-likelihood. \\
\hline objective_name & The name of the objective that was maximized during fitting. Currently, only maximum-likelihood estimation is implemented, and hence this will always be "loglikelihood". \\
\hline time_grid & Numeric vector, the time-grid on which the diffusivity was fitted. \\
\hline diffusivity & Numeric vector of size Ngrid (length of time_grid), listing the fitted diffusivities at the various time-grid points. \\
\hline loglikelihood & The \\
\hline NFP & Integer, number of fi \\
\hline Ncontrasts & Integer, number of in \\
\hline phylodistances & Numeric vector of length Ncontrasts, listing phylogenetic (patristic) distances of the independent contrasts. \\
\hline geodistances & Numeric vector of length Ncontrasts, listing geographic (great circle) distances of the independent contrasts. \\
\hline child_times1 & Numeric vector of length Ncontrasts, listing the times (distance from root) of the first tip in each independent contrast. \\
\hline child_times2 & Numeric vector of length Ncontrasts, listing the times (distance from root) of the second tip in each independent contrast. \\
\hline MRCA_times & Numeric vector of length Ncontrasts, listing the times (distance from root) of the MRCA of the two tips in each independent contrast. \\
\hline AIC & The Akaike Information Criterion for the fitted model, defined as \(2 k-2 \log (L)\), where \(k\) is the number of fitted parameters and \(L\) is the maximized likelihood. \\
\hline BIC & The Bayesian information criterion for the fitted model, defined as \(\log (n) k-\) \(2 \log (L)\), where \(k\) is the number of fitted parameters, \(n\) is the number of data points (number of independent contrasts), and \(L\) is the maximized likelihood. \\
\hline converged & Logical, specifying whether the maximum likelihood was reached after convergence of the optimization algorithm. Note that in some cases the maximum likelihood may have been achieved by an optimization path that did not yet converge (in which case it's advisable to increase iter. max and/or eval.max). \\
\hline Niterations & Integer, specifying the number of iterations performed during the optimization path that yielded the maximum likelihood. \\
\hline Nevaluations & Integer, specifying the number of likelihood evaluations performed during the optimization path that yielded the maximum likelihood. \\
\hline \multicolumn{2}{|l|}{trial_start_objectives} \\
\hline & Numeric vector of size Ntrials, listing the initial objective values (e.g., loglikelihoods) for each fitting trial, i.e. at the start parameter values. \\
\hline \multicolumn{2}{|l|}{trial_objective_values} \\
\hline & Numeric vector of size Ntrials, listing the final maximized objective values (e.g., loglikelihoods) for each fitting trial. \\
\hline \multicolumn{2}{|l|}{trial_Nstart_attempts} \\
\hline & Integer vector of size Ntrials, listing the number of start attempts for each fitting trial, until a starting point with valid likelihood was found. \\
\hline
\end{tabular}
fit_sbm_on_grid
trial_Niterations
Integer vector of size Ntrials, listing the number of iterations needed for each fitting trial.
trial_Nevaluations
Integer vector of size Ntrials, listing the number of likelihood evaluations needed for each fitting trial.
standard_errors
Numeric vector of size NP, estimated standard error of the parameters, based on parametric bootstrapping. Only returned if Nbootstraps>0.
medians Numeric vector of size NP, median the estimated parameters across parametric bootstraps. Only returned if Nbootstraps>0.
CI50lower \(\quad\) Numeric vector of size NP, lower bound of the \(50 \%\) confidence interval (25\(75 \%\) percentile) for the parameters, based on parametric bootstrapping. Only returned if Nbootstraps>0.
CI50upper Numeric vector of size NP, upper bound of the \(50 \%\) confidence interval for the parameters, based on parametric bootstrapping. Only returned if Nbootstraps>0.
CI95lower \(\quad\) Numeric vector of size NP, lower bound of the \(95 \%\) confidence interval (2.5\(97.5 \%\) percentile) for the parameters, based on parametric bootstrapping. Only returned if Nbootstraps>0.
CI95upper Numeric vector of size NP, upper bound of the \(95 \%\) confidence interval for the parameters, based on parametric bootstrapping. Only returned if Nbootstraps \(>0\).
consistency Numeric between 0 and 1, estimated consistency of the data with the fitted model. See the documentation of fit_sbm_const for an explanation.
QQplot Numeric matrix of size Ncontrasts x 2, listing the computed QQ-plot. The first column lists quantiles of geodistances in the original dataset, the 2nd column lists quantiles of hypothetical geodistances simulated based on the fitted model.
SBM_PD_functor SBM probability density functor object. Used internally for efficiency and for debugging purposes.

\section*{Author(s)}

Stilianos Louca

\section*{References}
F. Perrin (1928). Etude mathematique du mouvement Brownien de rotation. 45:1-51.
D. R. Brillinger (2012). A particle migrating randomly on a sphere. in Selected Works of David Brillinger. Springer.
A. Ghosh, J. Samuel, S. Sinha (2012). A Gaussian for diffusion on the sphere. Europhysics Letters. 98:30003.
S. Louca (2021). Phylogeographic estimation and simulation of global diffusive dispersal. Systematic Biology. 70:340-359.

\section*{See Also}
```

simulate_sbm, fit_sbm_const, fit_sbm_parametric,fit_sbm_linear

```

\section*{Examples}
```


## Not run:

# generate a random tree, keeping extinct lineages

tree_params = list(birth_rate_factor=1, death_rate_factor=0.95)
tree = generate_random_tree(tree_params,max_tips=2000,coalescent=FALSE)\$tree

# calculate max distance of any tip from the root

max_time = get_tree_span(tree)\$max_distance

# simulate time-dependent SBM on the tree

# using a diffusivity that varies roughly exponentially with time

# In this example we measure distances in Earth radii

radius = 1
fine_time_grid = seq(from=0, to=max_time, length.out=10)
fine_D = 0.01 + 0.03*exp(-2*fine_time_grid/max_time)
simul = simulate_sbm(tree,
radius = radius,
diffusivity= fine_D,
time_grid = fine_time_grid)

# fit time-dependent SBM on a time-grid of size 4

fit = fit_sbm_on_grid(tree,
simul$tip_latitudes,
    simul$tip_longitudes,
radius = radius,
time_grid = seq(from=0,to=max_time,length.out=4),
Nthreads = 3, \# use 3 CPUs
Ntrials = 30) \# avoid local optima through multiple trials

# visually compare fitted \& true params

plot(x = fine_time_grid,
y = fine_D,
type = 'l',
col = 'black',
xlab = 'time',
ylab = 'D',
ylim = c(0,max(fine_D)))
lines(x = fit$time_grid,
    y = fit$diffusivity,
type = 'l',
col = 'blue')

## End(Not run)

```

\footnotetext{
fit_sbm_parametric Fit a time-dependent phylogeographic Spherical Brownian Motion model.
}

\section*{Description}

Given a rooted phylogenetic tree and geographic coordinates (latitudes \& longitudes) for its tips, this function estimates the diffusivity of a Spherical Brownian Motion (SBM) model with timedependent diffusivity for the evolution of geographic location along lineages (Perrin 1928; Brillinger 2012). Estimation is done via maximum-likelihood and using independent contrasts between sister lineages. This function is designed to estimate the diffusivity over time, by fitting a finite number of parameters defining the diffusivity as a function of time. The user thus provides the general functional form of the diffusivity that depends on time and NP parameters, and fit_sbm_parametric estimates each of the free parameters.

\section*{Usage}
```

fit_sbm_parametric(tree,
tip_latitudes,
tip_longitudes,
radius,
param_values,
param_guess,
diffusivity,
time_grid = NULL,
clade_states = NULL,
planar_approximation = FALSE,
only_basal_tip_pairs = FALSE,
only_distant_tip_pairs= FALSE,
min_MRCA_time = 0,
max_MRCA_age = Inf,
max_phylodistance = Inf,
no_state_transitions = FALSE,
only_state = NULL,
param_min = -Inf,
param_max = +Inf,
param_scale = NULL,
Ntrials = 1,
max_start_attempts = 1,
Nthreads = 1,
Nbootstraps = 0,
Ntrials_per_bootstrap = NULL,
NQQ = 0,
fit_control = list(),
SBM_PD_functor = NULL,
focal_param_values = NULL,
verbose = FALSE,
verbose_prefix = "")

```

\section*{Arguments}
tree
A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge. Edge lengths are assumed to represent time intervals or a
similarly interpretable phylogenetic distance.
tip_latitudes Numeric vector of length Ntips, listing latitudes of tips in decimal degrees (from -90 to 90 ). The order of entries must correspond to the order of tips in the tree (i.e., as listed in tree\$tip. label).
tip_longitudes Numeric vector of length Ntips, listing longitudes of tips in decimal degrees (from -180 to 180). The order of entries must correspond to the order of tips in the tree (i.e., as listed in tree\$tip. label).
radius Strictly positive numeric, specifying the radius of the sphere. For Earth, the mean radius is 6371 km .
param_values Numeric vector of length NP, specifying fixed values for a some or all model parameters. For fitted (i.e., non-fixed) parameters, use NaN or NA. For example, the vector \(\mathrm{c}(1.5, \mathrm{NA}, 40)\) specifies that the 1 st and 3 rd model parameters are fixed at the values 1.5 and 40 , respectively, while the 2 nd parameter is to be fitted. The length of this vector defines the total number of model parameters. If entries in this vector are named, the names are taken as parameter names. Names should be included if you'd like returned parameter vectors to have named entries, or if the diffusivity function queries parameter values by name (as opposed to numeric index).
param_guess Numeric vector of size NP, specifying a first guess for the value of each model parameter. For fixed parameters, guess values are ignored. Can be NULL only if all model parameters are fixed.
diffusivity Function specifying the diffusivity at any given time (time since the root) and for any given parameter values. This function must take exactly two arguments, the 1 st one being a numeric vector (one or more times) and the 2 nd one being a numeric vector of size NP (parameter values), and return a numeric vector of the same size as the 1st argument.
time_grid Numeric vector, specifying times (counted since the root) at which the diffusivity function should be evaluated. This time grid must be fine enough to capture the possible variation in the diffusivity over time, within the permissible parameter range. If of size 1 , then the diffusivity is assumed to be time-independent. Listed times must be strictly increasing, and should cover at least the full considered time interval (from 0 to the maximum distance of any tip from the root); otherwise, constant extrapolation is used to cover missing times. Can also be NULL or a vector of size 1 , in which case the diffusivity is assumed to be timeindependent. Note that time is measured in the same units as the tree's edge lengths.
clade_states Optional integer vector of length Ntips+Nnodes, listing discrete states of every tip and node in the tree. The order of entries must match the order of tips and nodes in the tree. States may be, for example, geographic regions, sub-types, discrete traits etc, and can be used to restrict independent contrasts to tip pairs within the same state (see option no_state_transitions).
planar_approximation
Logical, specifying whether to estimate the diffusivity based on a planar approximation of the SBM model, i.e. by assuming that geographic distances between tips are as if tips are distributed on a 2D cartesian plane. This approximation is only accurate if geographical distances between tips are small compared to the sphere's radius.

Logical, specifying whether to only compare immediate sister tips, i.e., tips connected through a single parental node.
only_distant_tip_pairs
Logical, specifying whether to only compare tips at distinct geographic locations.
min_MRCA_time Numeric, specifying the minimum allowed time (distance from root) of the most recent common ancestor (MRCA) of sister tips considered in the fitting. In other words, an independent contrast is only considered if the two sister tips' MRCA has at least this distance from the root. Set min_MRCA_time \(=0\) to disable this filter.
max_MRCA_age Numeric, specifying the maximum allowed age (distance from youngest tip) of the MRCA of sister tips considered in the fitting. In other words, an independent contrast is only considered if the two sister tips' MRCA has at most this age (time to present). Set max_MRCA_age=Inf to disable this filter.
max_phylodistance
Numeric, maximum allowed geodistance for an independent contrast to be included in the SBM fitting. Set max_phylodistance=Inf to disable this filter.
no_state_transitions
Logical, specifying whether to omit independent contrasts between tips whose shortest connecting paths include state transitions. If TRUE, only tips within the same state and with no transitions between them (as specified in clade_states) are compared.
only_state Optional integer, specifying the state in which tip pairs (and their connecting ancestral nodes) must be in order to be considered. If specified, then clade_states must be provided.
param_min Optional numeric vector of size NP, specifying lower bounds for model parameters. If of size 1 , the same lower bound is applied to all parameters. Use -Inf to omit a lower bound for a parameter. If NULL, no lower bounds are applied. For fixed parameters, lower bounds are ignored.
param_max Optional numeric vector of size NP, specifying upper bounds for model parameters. If of size 1 , the same upper bound is applied to all parameters. Use +Inf to omit an upper bound for a parameter. If NULL, no upper bounds are applied. For fixed parameters, upper bounds are ignored.
param_scale Optional numeric vector of size NP, specifying typical scales for model parameters. If of size 1 , the same scale is assumed for all parameters. If NULL, scales are determined automatically. For fixed parameters, scales are ignored. It is strongly advised to provide reasonable scales, as this facilitates the numeric optimization algorithm.
Ntrials Integer, specifying the number of independent fitting trials to perform, each starting from a random choice of model parameters. Increasing Ntrials reduces the risk of reaching a non-global local maximum in the fitting objective.
max_start_attempts
Integer, specifying the number of times to attempt finding a valid start point (per trial) before giving up on that trial. Randomly choosen extreme start parameters may occasionally result in Inf/undefined likelihoods, so this option allows the algorithm to keep looking for valid starting points.
\begin{tabular}{ll} 
Nthreads & \begin{tabular}{l} 
Integer, specifying the number of parallel threads to use for performing multiple \\
fitting trials simultaneously. This should generally not exceed the number of \\
available CPUs on your machine. Parallel computing is not available on the
\end{tabular} \\
Windows platform.
\end{tabular}
verbose_prefix Character, specifying the line prefix for printing progress reports to the screen.

\section*{Details}

This function is designed to estimate a finite set of scalar parameters ( \(p_{1}, . ., p_{n} \in \mathrm{R}\) ) that determine the diffusivity over time, by maximizing the likelihood of observing the given tip coordinates under the SBM model. For example, the investigator may assume that the diffusivity exponentially over time, i.e. can be described by \(D(t)=A \cdot e^{-B t}\) (where \(A\) and \(B\) are unknown coefficients and \(t\) is time since the root). In this case the model has 2 free parameters, \(p_{1}=A\) and \(p_{2}=B\), each of which may be fitted to the tree.

It is generally advised to provide as much information to the function fit_sbm_parametric as possible, including reasonable lower and upper bounds (param_min and param_max), a reasonable parameter guess (param_guess) and reasonable parameter scales param_scale. If some model parameters can vary over multiple orders of magnitude, it is advised to transform them so that
they vary across fewer orders of magnitude (e.g., via log-transformation). It is also important that the time_grid is sufficiently fine to capture the variation of the diffusivity over time, since the likelihood is calculated under the assumption that the diffusivity varies linearly between grid points.
Estimation of diffusivity at older times is only possible if the timetree includes extinct tips or tips sampled at older times (e.g., as is often the case in viral phylogenies). If tips are only sampled once at present-day, i.e. the timetree is ultrametric, reliable diffusivity estimates can only be achieved near present times. If the tree is ultrametric, you should consider using fit_sbm_const instead.
For short expected transition distances this function uses the approximation formula by Ghosh et al. (2012) to calculate the probability density of geographical transitions along edges. For longer expected transition distances the function uses a truncated approximation of the series representation of SBM transition densities (Perrin 1928).
If edge. length is missing from one of the input trees, each edge in the tree is assumed to have length 1 . The tree may include multifurcations as well as monofurcations, however multifurcations are internally expanded into bifurcations by adding dummy nodes.

\section*{Value}

A list with the following elements:
success Logical, indicating whether the fitting was successful. If FALSE, then an additional return variable, error, will contain a description of the error; in that case all other return variables may be undefined.
objective_value
The maximized fitting objective. Currently, only maximum-likelihood estimation is implemented, and hence this will always be the maximized log-likelihood.
objective_name The name of the objective that was maximized during fitting. Currently, only maximum-likelihood estimation is implemented, and hence this will always be "loglikelihood".
param_fitted Numeric vector of size NP (number of model parameters), listing all fitted or fixed model parameters in their standard order (see details above).
loglikelihood The log-likelihood of the fitted model for the given data.
NFP Integer, number of fitted (i.e., non-fixed) model parameters.
Ncontrasts Integer, number of independent contrasts used for fitting.
phylodistances Numeric vector of length Ncontrasts, listing phylogenetic (patristic) distances of the independent contrasts.
geodistances Numeric vector of length Ncontrasts, listing geographic (great circle) distances of the independent contrasts.
child_times 1 Numeric vector of length Ncontrasts, listing the times (distance from root) of the first tip in each independent contrast.
child_times2 Numeric vector of length Ncontrasts, listing the times (distance from root) of the second tip in each independent contrast.
MRCA_times Numeric vector of length Ncontrasts, listing the times (distance from root) of the MRCA of the two tips in each independent contrast.

AIC The Akaike Information Criterion for the fitted model, defined as \(2 k-2 \log (L)\), where \(k\) is the number of fitted parameters and \(L\) is the maximized likelihood.
BIC \begin{tabular}{l} 
The Bayesian information criterion for the fitted model, defined as log \((n) k-\) \\
\(2 \log (L)\), where \(k\) is the number of fitted parameters, \(n\) is the number of data \\
points (number of independent contrasts), and \(L\) is the maximized likelihood. \\
Logical, specifying whether the maximum likelihood was reached after conver- \\
gence of the optimization algorithm. Note that in some cases the maximum \\
likelihood may have been achieved by an optimization path that did not yet con- \\
verge (in which case it's advisable to increase iter.max and/or eval.max). \\
Integer, specifying the number of iterations performed during the optimization \\
path that yielded the maximum likelihood. \\
Integer, specifying the number of likelihood evaluations performed during the
\end{tabular}
Niterations \begin{tabular}{l} 
optimization path that yielded the maximum likelihood.
\end{tabular}
Nevaluations

CI95upper Numeric vector of size NP, upper bound of the \(95 \%\) confidence interval for the parameters, based on parametric bootstrapping. Only returned if Nbootstraps>0.
consistency Numeric between 0 and 1, estimated consistency of the data with the fitted model. See the documentation of fit_sbm_const for an explanation.
QQplot Numeric matrix of size Ncontrasts x 2, listing the computed QQ-plot. The first column lists quantiles of geodistances in the original dataset, the 2nd column lists quantiles of hypothetical geodistances simulated based on the fitted model.
SBM_PD_functor SBM probability density functor object. Used internally for efficiency and for debugging purposes.

\section*{Author(s)}

Stilianos Louca

\section*{References}
F. Perrin (1928). Etude mathematique du mouvement Brownien de rotation. 45:1-51.
D. R. Brillinger (2012). A particle migrating randomly on a sphere. in Selected Works of David Brillinger. Springer.
A. Ghosh, J. Samuel, S. Sinha (2012). A Gaussian for diffusion on the sphere. Europhysics Letters. 98:30003.
S. Louca (2021). Phylogeographic estimation and simulation of global diffusive dispersal. Systematic Biology. 70:340-359.

\section*{See Also}
```

simulate_sbm, fit_sbm_const, fit_sbm_linear

```

\section*{Examples}
```


## Not run:

# generate a random tree, keeping extinct lineages

tree_params = list(birth_rate_factor=1, death_rate_factor=0.95)
tree = generate_random_tree(tree_params,max_tips=1000,coalescent=FALSE)\$tree

# calculate max distance of any tip from the root

max_time = get_tree_span(tree)\$max_distance

# simulate time-dependent SBM on the tree

# we assume that diffusivity varies linearly with time

# in this example we measure distances in Earth radii

radius = 1
diffusivity_functor = function(times, params){
return(params[1] + (times/max_time)*(params[2]-params[1]))
}
true_params = c(1, 2)
time_grid = seq(0,max_time,length.out=2)
simulation = simulate_sbm(tree,
radius = radius,

```
```

    diffusivity = diffusivity_functor(time_grid,true_params),
    time_grid = time_grid)
    
# fit time-independent SBM to get a rough estimate

fit_const = fit_sbm_const(tree,simulation$tip_latitudes,simulation$tip_longitudes,radius=radius)

# fit time-dependent SBM, i.e. fit the 2 parameters of the linear form

fit = fit_sbm_parametric(tree,
simulation$tip_latitudes,
    simulation$tip_longitudes,
radius = radius,
param_values = c(NA,NA),
param_guess = c(fit_const$diffusivity,fit_const$diffusivity),
diffusivity = diffusivity_functor,
time_grid = time_grid,
Ntrials = 10)

# compare fitted \& true params

print(true_params)
print(fit\$param_fitted)

## End(Not run)

```
fit_tree_model Fit a cladogenic model to an existing tree.

\section*{Description}

Fit the parameters of a tree generation model to an existing phylogenetic tree; branch lengths are assumed to be in time units. The fitted model is a stochastic cladogenic process in which speciations (births) and extinctions (deaths) are Poisson processes, as simulated by the function generate_random_tree. The birth and death rates of tips can each be constant or power-law functions of the number of extant tips. For example,
\[
B=I+F \cdot N^{E}
\]
where \(B\) is the birth rate, \(I\) is the intercept, \(F\) is the power-law factor, \(N\) is the current number of extant tips and \(E\) is the power-law exponent. Each of the parameters I, F, E can be fixed or fitted.

Fitting can be performed via maximum-likelihood estimation, based on the waiting times between subsequent speciation and/or extinction events represented in the tree. Alternatively, fitting can be performed using least-squares estimation, based on the number of lineages represented in the tree over time ("diversity-vs-time" curve, a.k.a. "lineages-through-time"" curve). Note that the birth and death rates are NOT per-capita rates, they are absolute rates of species appearance and disappearance per time.

\section*{Usage}
fit_tree_model( tree, parameters = list(),
\begin{tabular}{ll} 
first_guess & \(=\) list(), \\
min_age & \(=0\), \\
max_age & \(=0\), \\
age_centile & \(=\) NULL, \\
Ntrials & \(=1\), \\
Nthreads & \(=1\), \\
coalescent & \(=\) FALSE, \\
discovery_fraction & \(=\) NULL, \\
fit_control & \(=1 i s t()\), \\
min_R2 & \(=-I n f\), \\
min_wR2 & \(=-I n f\), \\
grid_size & \(=100\), \\
max_model_runtime & \(=\) NULL, \\
objective & \(=' L L ')\)
\end{tabular}

\section*{Arguments}
tree
A phylogenetic tree, in which branch lengths are assumed to be in time units. The tree may be a coalescent tree (i.e. only include extant clades) or a tree including extinct clades; the tree type influences what type of models can be fitted with each method.
parameters A named list specifying fixed and/or unknown birth-death model parameters, with one or more of the following elements:
- birth_rate_intercept: Non-negative number. The intercept of the Poissonian rate at which new species (tips) are added. In units 1/time.
- birth_rate_factor: Non-negative number. The power-law factor of the Poissonian rate at which new species (tips) are added. In units 1/time.
- birth_rate_exponent: Numeric. The power-law exponent of the Poissonian rate at which new species (tips) are added. Unitless.
- death_rate_intercept: Non-negative number. The intercept of the Poissonian rate at which extant species (tips) go extinct. In units \(1 /\) time.
- death_rate_factor: Non-negative number. The power-law factor of the Poissonian rate at which extant species (tips) go extinct. In units \(1 /\) time.
- death_rate_exponent: Numeric. The power-law exponent of the Poissonian rate at which extant species (tips) go extinct. Unitless.
- resolution: Numeric. Resolution at which the tree was collapsed (i.e. every node of age smaller than this resolution replaced by a single tip). In units time. A resolution of 0 means the tree was not collapsed.
- rarefaction: Numeric. Species sampling fraction, i.e. fraction of extant species represented (as tips) in the tree. A rarefaction of 1, for example, implies that the tree is complete, i.e. includes all extant species. Rarefaction is assumed to have occurred after collapsing.
- extant_diversity: The current total extant diversity, regardless of the rarefaction and resolution of the tree at hand. For example, if resolution==0 and rarefaction==0.5 and the tree has 1000 tips, then extant_diversity should be 2000. If resolution is fixed at 0 and rarefaction is also fixed, this can be left NULL and will be inferred automatically by the function.
\begin{tabular}{|c|c|}
\hline & Each of the above elements can also be NULL, in which case the parameter is fitted. Elements can also be vectors of size 2 (specifying constraint intervals), in which case the parameters are fitted and constrained within the intervals specified. For example, to fit death_rate_factor while constraining it to the interval [1,2], set its value to \(\mathrm{c}(1,2)\). \\
\hline first_guess & A named list (with entries named as in parameters) specifying starting values for any of the fitted model parameters. Note that if Ntrials>1, then start values may be randomly modified in all but the first trial. For any parameters missing from first_guess, initial values are always randomly chosen. first_guess can also be NULL. \\
\hline min_age & Numeric. Minimum distance from the tree crown, for a node/tip to be considered in the fitting. If \(<=0\) or NULL, this constraint is ignored. Use this option to omit most recent nodes. \\
\hline max_age & Numeric. Maximum distance from the tree crown, for a node/tip to be considered in the fitting. If \(<=0\) or NULL, this constraint is ignored. Use this option to omit old nodes, e.g. with highly uncertain placements. \\
\hline age_centile & Numeric within 0 and 1. Fraction of youngest nodes/tips to consider for the fitting. This can be used as an alternative to max_age. E.g. if set to 0.6, then the \(60 \%\) youngest nodes/tips are considered. Either age_centile or max_age must be non-NULL, but not both. \\
\hline Ntrials & Integer. Number of fitting attempts to perform, each time using randomly varied start values for fitted parameters. The returned fitted parameter values will be taken from the trial with greatest achieved fit objective. A larger number of trials will decrease the chance of hitting a local non-global optimum during fitting. \\
\hline Nthreads & Number of threads to use for parallel execution of multiple fitting trials. On Windows, this option has no effect because Windows does not support forks. \\
\hline coalescent & Logical, specifying whether the input tree is a coalescent tree (and thus the coalescent version of the model should be fitted). Only available if objective=='R2' \\
\hline
\end{tabular}

Function handle, mapping age to the fraction of discovered lineages in a tree. That is, discovery_fraction(tau) is the probability that a lineage at age tau, that has an extant descendant today, will be represented (discovered) in the coalescent tree. In particular, discovery_fraction(0) equals the fraction of extant lineages represented in the tree. If this is provided, then parameters \(\$\) rarefaction is fixed to 1 , and discovery_fraction is applied after simulation. Only relevant if coalescent==TRUE. Experimental, so leave this NULL if you don't know what it means.
fit_control Named list containing options for the stats: :nlminb optimization routine, such as eval. max (max number of evaluations), iter.max (max number of iterations) and rel.tol (relative tolerance for convergence).
min_R2 Minimum coefficient of determination of the diversity curve (clade counts vs time) of the model when compared to the input tree, for a fitted model to be accepted. For example, if set to 0.5 then only fit trials achieving an R2 of at least 0.5 will be considered. Set this to -Inf to not filter fitted models based on the R2.
\begin{tabular}{ll} 
min_wR2 & \begin{tabular}{l} 
Similar to min_R2, but applying to the weighted R2, where squared-error weights \\
are proportional to the inverse squared diversities.
\end{tabular} \\
grid_size & \begin{tabular}{l} 
Integer. Number of equidistant time points to consider when calculating the R2 \\
of a model's diversity-vs-time curve.
\end{tabular} \\
max_model_runtime \\
Numeric. Maximum runtime (in seconds) allowed for each model evaluation \\
during fitting. Use this to escape from badly parameterized models during fitting \\
(this will likely cause the affected fitting trial to fail). If NULL or <=0, this option \\
is ignored.
\end{tabular}

\section*{Value}

A named list with the following elements:
success Logical, indicating whether the fitting was successful.
objective_value
Numeric. The achieved maximum value of the objective function (log-likelihood, R2 or weighted R2).
parameters A named list listing all model parameters (fixed and fitted).
start_parameters
A named list listing the start values of all model parameters. In the case of multiple fitting trials, this will list the initial (non-randomized) guess.
R2 Numeric. The achieved coefficient of determination of the fitted model, based on the diversity-vs-time curve.
wR2 Numeric. The achieved weighted coefficient of determination of the fitted model, based on the diversity-vs-time curve. Weights of squared errors are proportional to the inverse squared diversities observed in the tree.
1R2 Numeric. The achieved coefficient of determination of the fitted model on a log axis, i.e. based on the logarithm of the diversity-vs-time curve.
Nspeciations Integer. Number of speciation events (=nodes) considered during fitting. This only includes speciations visible in the tree.
Nextinctions Integer. Number of extinction events (=non-crown tips) considered during fitting. This only includes extinctions visible in the tree, i.e. tips whose distance from the root is lower than the maximum.
grid_times Numeric vector. Time points considered for the diversity-vs-time curve. Times will be constrained between min_age and max_age if these were specified.
tree_diversities
Number of lineages represented in the tree through time, calculated for each of grid_times.
model_diversities
Number of lineages through time as predicted by the model (in the deterministic limit), calculated for each of grid_times. If coalescent==TRUE then these are the number of lineages expected to be represented in the coalescent tree (this may be lower than the actual number of extant clades at any given time point, if the model includes extinctions).
fitted_parameter_names
Character vector, listing the names of fitted (i.e. non-fixed) parameters.
locally_fitted_parameters
Named list of numeric vectors, listing the fitted values for each parameter and for each fitting trial. For example, if birth_rate_factor was fitted, then locally_fitted_parameters\$birth_rate_factor will be a numeric vector of size Ntrials (or less, if some trials failed or omitted), listing the locallyoptimized values of the parameter for each considered fitting trial. Mainly useful for diagnostic purposes.
objective Character. The name of the objective function used for fitting ("LL", "R2" or "wR2").
Ntips The number of tips in the input tree.
Nnodes The number of nodes in the input tree.
min_age The minimum age of nodes/tips considered during fitting.
max_age The maximum age of nodes/tips considered during fitting.
age_centile Numeric or NULL, equal to the age_centile specified as input to the function.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
generate_random_tree, simulate_diversification_model reconstruct_past_diversification

\section*{Examples}
```


# Generate a tree using a simple speciation model

parameters = list(birth_rate_intercept = 1,
birth_rate_factor = 0,
birth_rate_exponent = 0,
death_rate_intercept = 0,
death_rate_factor = 0,
death_rate_exponent = 0,
resolution =0,
rarefaction = 1)
tree = generate_random_tree(parameters, max_tips=100)

# Fit model to the tree

fitting_parameters = parameters
fitting_parameters\$birth_rate_intercept = NULL \# fit only this parameter
fitting = fit_tree_model(tree,fitting_parameters)

```
\# compare fitted to true value
T = parameters\$birth_rate_intercept
F = fitting\$parameters\$birth_rate_intercept
cat(sprintf("birth_rate_intercept: true=\%g, fitted=\%g\n", T,F))

\section*{gamma_statistic Calculate the gamma-statistic of a tree.}

\section*{Description}

Given a rooted ultrametric phylogenetic tree, calculate the gamma-statistic (Pybus and Harevy, 2000).

\section*{Usage}
gamma_statistic(tree)

\section*{Arguments}
tree A rooted tree of class "phylo". The tree is assumed to be ultrametric; any deviations from ultrametricity are ignored.

\section*{Details}

The tree may include multifurcations and monofurcations. If edge lengths are missing (i.e. edge. length=NULL), then each edge is assumed to have length 1.
This function is similar to the function gammaStat in the R package ape v5.3.

\section*{Value}

Numeric, the gamma-statistic of the tree.

\section*{Author(s)}

Stilianos Louca

\section*{References}
O. G. Pybus and P. H. Harvey (2000). Testing macro-evolutionary models using incomplete molecular phylogenies. Proceedings of the Royal Society of London. Series B: Biological Sciences. 267:2267-2272.

\section*{Examples}
```


# generate a random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),Ntips)\$tree

# calculate \& print gamma statistic

gammastat = gamma_statistic(tree)
cat(sprintf("Tree has gamma-statistic %g\n",gammastat))

```
generate_gene_tree_msc

Generate a gene tree based on the multi-species coalescent model.

\section*{Description}

Generate a random gene tree within a given species timetree, based on the multi-species coalescent (MSC) model. In this implementation of the MSC, every branch of the species tree has a specific effective population size \((\mathrm{Ne})\) and a specific generation time \((\mathrm{T})\), and gene alleles coalesce backward in time according to the Wright-Fisher model. This model does not account for gene duplication/loss, nor for hybridization or horizontal gene transfer. It is only meant to model "incomplete lineage sorting", otherwise known as "deep coalescence", which is one of the many mechanisms that can cause discordance between gene trees and species trees.

\section*{Usage}
generate_gene_tree_msc( species_tree,
\begin{tabular}{ll} 
allele_counts & \(=1\), \\
population_sizes & \(=1\), \\
generation_times & \(=1\), \\
mutation_rates & \(=1\), \\
gene_edge_unit & \(="\) time", \\
Nsites & \(=1\), \\
bottleneck_at_speciation & \(=\) FALSE, \\
force_coalescence_at_root & \(=\) FALSE, \\
ploidy & \(=1\), \\
gene_tip_labels & \(=\) NULL)
\end{tabular}

\section*{Arguments}
species_tree Rooted timetree of class "phylo". The tree can include multifurcations and monofurcations. The tree need not necessarily be ultrametric, i.e. it may include extinct species. Edge lengths are assumed to be in time units.
allele_counts Integer vector, listing the number of alleles sampled per species. Either NULL (1 allele per species), or a single integer (same number of alleles per species), or a vector of length Ntips listing the numbers of alleles sampled per species. In the latter case, the total number of tips in the returned gene tree will be equal to the sum of entries in allele_counts. Some entries in allele_counts may be zero (no alleles sampled from those species).

\section*{population_sizes}

Integer vector, listing the effective population size on the edge leading into each tip/node in the species tree. Either NULL (all population sizes are 1), or a single integer (same population sizes for all edges), or a vector of length Ntips+Nnodes, listing population sizes for each clade's incoming edge (including the root). The population size for the root's incoming edge corresponds to the population size at the tree's stem (only relevant if force_coalescence_at_root=FALSE).
generation_times
Numeric vector, listing the generation time along the edge leading into each clade. Either NULL (all generation times are 1), or a single integer (same generation time for all edges) or a vector of length Ntips+Nnodes, listing generation times for each clade's incoming edge (including the root). The generation time for the root's incoming edge corresponds to the generation time at the tree's stem (only relevant if force_coalescence_at_root=FALSE).
mutation_rates Numeric vector, listing the mutation rate (per site and per generation) along the edge leading into each clade. Either NULL (all mutation rates are 1), or a single integer (same mutation rate for all edges) or a vector of length Ntips+Nnodes, listing mutation rates for each clade's incoming edge (including the root). The mutation rate for the root's incoming edge corresponds to the mutation rate at the tree's stem (only relevant if force_coalescence_at_root=FALSE). The value of mutation_rates is only relevant if gene_edge_unit is "mutations_expected" or "mutations_random". Mutation rates represent probabilities, and so they must be between 0 and 1 .
gene_edge_unit Character, either "time", "generations", "mutations_expected" (expected mean number of mutations per site), or "mutations_random" (randomly generated mean number of mutations per site), specifying how edge lengths in the gene tree should be measured. By default, gene-tree edges are measured in time, as is the case for the input species tree.

Nsites Integer, specifying the number of sites (nucleotides) in the gene. Only relevant when generating edge lengths in terms of random mutation counts, i.e. if gene_edge_unit=="mutations_random".
bottleneck_at_speciation
Logical. If TRUE, then all but one children at each node are assumed to have emerged from a single mutant individual, and thus all gene lineages within these bottlenecked species lineages must coalesce at a younger or equal age as the speciation event. Only the first child at each node is excluded from this assumption, corresponding to the "resident population" during the speciation event. This option deviates from the classical MSC model, and is experimental.
force_coalescence_at_root
Logical. If TRUE, all remaining orphan gene lineages that haven't coalesced before reaching the species-tree's root, will be combined at the root (via multiple adjacent bifurcations). If FALSE, coalescence events may extend beyond the species-tree's root into the stem lineage, as long as it takes until all gene lineages have coalesced.
ploidy Integer, specifying the assumed genetic ploidy, i.e. number of gene copies per individual. Typically 1 for haploids, or 2 for diploids.
```

gene_tip_labels

```

Character vector specifying tip labels for the gene tree (i.e., for each of the sampled alleles) in the order of the corresponding species tips. Can also be NULL, in which case gene tips will be set to <species_tip_label>.<allele index>.

\section*{Details}

This function assumes that Kingman's coalescent assumption is met, i.e. that the effective population size is much larger than the number of allele lineages coalescing within any given branch.
The function assumes that the species tree is a time tree, i.e. with edge lengths given in actual time units. To simulate gene trees in coalescence time units, choose population_sizes and generation_times accordingly (this only makes sense if the product of population_sizes \(\times\) generation_times is the same everywhere). If species_tree is ultrametric and gene_edge_unit=="time", then the gene tree will be ultrametric as well.

If gene_edge_unit is "mutations_random", then the number of generations elapsed along each time segment is translated into a randomly distributed number of accumulated mutations, according to a binomial distribution where the probability of success is equal to the mutation rate and the number of trials is equal to the number of generations multiplied by Nsites; this number of mutations is averaged across all sites, i.e. the edge lengths in the returned gene tree always refer to the mean number of mutations per site. In cases where the mutation rate varies across the species tree and a single gene edge spans multiple species edges, the gene edge length will be a sum of multiple binomially distributed mutation counts (again, divided by the number of sites), corresponding to the times spent in each species edge.

\section*{Value}

A named list with the following elements:
```

success Logical, indicating whether the gene tree was successfully generated. If FALSE,
the only other value returned is error.
tree The generated gene tree, of class "phylo". This tree will be rooted and bifurcat-
ing. It is only guaranteed to be ultrametric if species_tree was ultrametric.
gene_tip2species_tip
Integer vector of length NGtips (where NGtips is the number of tips in the gene
tree), mapping gene-tree tips to species-tree tips.
gene_node2species_edge
Integer vector of length NGnodes (where NGnodes is the number of internal
nodes in the gene tree), mapping gene-tree nodes (=coalescence events) to the
species-tree edges where the coalescences took place.
gene_clade_times
Numeric vector of size NGtips+NGnodes, listing the time (total temporal distance from species root) of each tip and node in the gene tree. The units will be the same as the time units assumed for the species tree. Note that this may include negative values, if some gene lineages coalesce at a greater age than the root.
error Character, containing an explanation of the error that occurred. Only included if success==FALSE.

```

\section*{Author(s)}

Stilianos Louca

\section*{References}
J. H. Degnan, N. A. Rosenberg (2009). Gene tree discordance, phylogenetic inference and the multispecies coalescent. Trends in Ecology \& Evolution. 24:332-340.
B. Rannala, Z. Yang (2003). Bayes estimation of species divergence times and ancestral population sizes using DNA sequences from multiple loci. Genetics. 164:1645-1656.

\section*{See Also}
generate_random_tree, generate_gene_tree_msc_hgt_dl

\section*{Examples}
```


# Simulate a simple species tree

parameters = list(birth_rate_factor=1)
Nspecies = 10
species_tree = generate_random_tree(parameters,max_tips=Nspecies)\$tree

# Simulate a haploid gene tree within the species tree

# Assume the same population size and generation time everywhere

# Assume the number of alleles samples per species is poisson-distributed

results = generate_gene_tree_msc(species_tree,
allele_counts = rpois(Nspecies,3),
population_sizes = 1000,
generation_times = 1,
ploidy = 1);
if(!results$success){
    # simulation failed
    cat(sprintf(" ERROR: %s\n",results$error))
}else{
\# simulation succeeded
gene_tree = results$tree
    cat(sprintf(" Gene tree has %d tips\n",length(gene_tree$tip.label)))
}

```
generate_gene_tree_msc_hgt_dl

Generate gene trees based on the multi-species coalescent, horizontal gene transfers and duplications/losses.

\section*{Description}

Generate a random gene tree within a given species timetree, based on an extension of the multispecies coalescent (MSC) model that includes horizontal gene transfers (HGT, incorporation of non-homologous genes as new loci), gene duplication and gene loss. The simulation consists of
two phases. In the first phase a random "locus tree" is generated in forward time, according to random HGT, duplication and loss events. In the 2 nd phase, alleles picked randomly from each locus are coalesced in backward time according to the multispecies coalescent, an extension of the Wright-Fisher model to multiple species. This function does not account for hybridization.

\section*{Usage}
generate_gene_tree_msc_hgt_dl( species_tree, allele_counts = 1, population_sizes \(=1\),
generation_times \(=1\),
mutation_rates \(=1\),
HGT_rates \(=0\),
duplication_rates \(=0\),
loss_rates \(=0\),
gene_edge_unit = "time",
Nsites = 1,
bottleneck_at_speciation = FALSE,
force_coalescence_at_root = FALSE,
ploidy \(=1\),
HGT_source_by_locus = FALSE,
HGT_only_to_empty_clades = FALSE,
no_loss_before_time \(=0\),
max_runtime = NULL,
include_event_times = TRUE)

\section*{Arguments}
species_tree Rooted timetree of class "phylo". The tree can include multifurcations and monofurcations. The tree need not necessarily be ultrametric, i.e. it may include extinct species. Edge lengths are assumed to be in time units.
allele_counts Integer vector, listing the number of alleles sampled per species and per locus. This can be interpreted as the number if individual organisms surveyed from each species, assuming that all loci are included once from each individual. The number of tips in the generated gene tree will be equal to the sum of allele counts across all species. allele_counts can either be NULL (1 allele per species), or a single integer (same number of alleles per species), or a vector of length Ntips listing the numbers of alleles sampled per species. In the latter case, the total number of tips in the returned gene tree will be equal to the sum of entries in allele_counts. Some entries in allele_counts may be zero (no alleles sampled from those species).
population_sizes
Integer vector, listing the effective population size on the edge leading into each tip/node in the species tree. Either NULL (all population sizes are 1), or a single integer (same population sizes for all edges), or a vector of length Ntips+Nnodes, listing population sizes for each clade's incoming edge (including the root). The population size for the root's incoming edge corresponds to the population size at the tree's stem (only relevant if force_coalescence_at_root=FALSE).

\section*{generation_times}

Numeric vector, listing the generation time along the edge leading into each clade. Either NULL (all generation times are 1), or a single integer (same generation time for all edges) or a vector of length Ntips+Nnodes, listing generation times for each clade's incoming edge (including the root). The generation time for the root's incoming edge corresponds to the generation time at the tree's stem (only relevant if force_coalescence_at_root=FALSE).
mutation_rates Numeric vector, listing the probability of mutation per site and per generation along the edge leading into each clade. Either NULL (all mutation rates are 1), or a single integer (same mutation rate for all edges) or a vector of length Ntips+Nnodes, listing mutation rates for each clade's incoming edge (including the root). The mutation rate for the root's incoming edge corresponds to the mutation rate at the tree's stem (only relevant if force_coalescence_at_root=FALSE). The value of mutation_rates is only relevant if gene_edge_unit is "mutations_expected" or "mutations_random". Mutation rates represent probabilities, and so they must be between 0 and 1 .
HGT_rates Numeric vector, listing horizontal gene transfer rates per lineage per time, along the edge leading into each clade. Either NULL (all HGT rates are 0) or a single integer (same HGT rate for all edges) or a vector of length Ntips+Nnodes, listing HGT rates for each clade's incoming edge (including the root).
duplication_rates
Numeric vector, listing gene duplication rates per locus per lineage per time, along the edge leading into each clade. Either NULL (all duplication rates are 0 ) or a single integer (same duplication rate for all edges) or a vector of length Ntips+Nnodes listing duplication rates for each clade's incoming edge (including the root).
loss_rates Numeric vector, listing gene loss rates per locus per lineage per time, along the edge leading into each clade. Either NULL (all loss rates are 0 ) or a single integer (same loss rate for all edges) or a vector of length Ntips+Nnodes listing loss rates for each clade's incoming edge (including the root).
gene_edge_unit Character, either "time", "generations", "mutations_expected" (expected mean number of mutations per site), or "mutations_random" (randomly generated mean number of mutations per site), specifying how edge lengths in the gene tree should be measured. By default, gene-tree edges are measured in time, as is the case for the input species tree.
Nsites Integer, specifying the number of sites (nucleotides) in the gene. Only relevant when generating edge lengths in terms of random mutation counts, i.e. if gene_edge_unit=="mutations_random".
bottleneck_at_speciation
Logical. If TRUE, then all but one children at each node are assumed to have emerged from a single mutant individual, and thus all gene lineages within these bottlenecked species lineages must coalesce at a younger or equal age as the speciation event. Only the first child at each node is excluded from this assumption, corresponding to the "resident population" during the speciation event. This option deviates from the classical MSC model, and is experimental.
force_coalescence_at_root
Logical. If TRUE, all remaining orphan gene lineages that haven't coalesced before reaching the species-tree's root, will be combined at the root (via multiple
adjacent bifurcations). If FALSE, coalescence events may extend beyond the species-tree's root into the stem lineage, as long as it takes until all gene lineages have coalesced.
ploidy Integer, specifying the assumed genetic ploidy, i.e. number of gene copies per individual. Typically 1 for haploids, or 2 for diploids.
HGT_source_by_locus
Logical. If TRUE, then at any HGT event, every extant locus is chosen as source locus with the same probability (hence the probability of a lineage to be a source is proportional to the number of current loci in it). If FALSE, source lineages are chosen with the same probability (regardless of the number of current loci in them) and the source locus within the source lineage is chosen randomly.
HGT_only_to_empty_clades
Logical, specifying whether HGT transfers only occur into clades with no current loci.
```

no_loss_before_time

```

Numeric, optional time since the root during which no gene losses shall occur (even if loss_rate>0). This option can be used to reduce the probability of an early extinction of the entire gene tree, by giving the gene tree some "startup time" to spread into various species lineages. If zero, gene losses are possible right from the start of the simulation.
max_runtime Numeric, optional maximum computation time (in seconds) to allow for the simulation. Use this to avoid occasional explosions of runtimes, for example due to very large generated trees. Aborted simulations will return with the flag success=FALSE (i.e., no tree is returned at all).
include_event_times
Logical, specifying whether the times of HGT, duplication and loss events should be returned as well. If these are not needed, then set include_event_times=FALSE for efficiency.

\section*{Details}

This function assumes that the species tree is a time tree, i.e. with edge lengths given in actual time units. If species_tree is ultrametric and gene_edge_unit=="time", then the gene tree (but not necessarily the locus tree) will be ultrametric as well. The root of the locus and gene tree coincides with the root of the species tree.
The meaning of gene_edge_unit is the same as for the function generate_gene_tree_msc.

\section*{Value}

A named list with the following elements:
success Logical, indicating whether the gene tree was successfully generated. If FALSE, the only other value returned is error.
locus_tree The generated locus timetree, of class "phylo". The locus tree describes the genealogy of loci due to HGT, duplication and loss events. Each tip and node of the locus tree is embedded within a specific species edge. For example, tips of the locus tree either coincide with tips of the species tree (if the locus persisted
until the species went extinct or until the present) or they correspond to gene loss events. In the absence of any HGT, duplication and loss events, the locus tree will resemble the species tree.
locus_type Character vector of length NLtips + NLnodes (where NLtips and NLnodes are the number of tips and nodes in the locus tree, respectively), specifying the type/origin of each tip and node in the locus tree. For nodes, type 'h' corresponds to an HGT event, type 'd' to a duplication event, and type 's' to a speciation event. For tips, type ' 1 ' represents a loss event, and type ' \(t\) ' a terminal locus (i.e., coinciding with a species tip). For example, if the input species tree was an ultrametric tree representing only extant species, then the locus tree tips of type ' t ' are the loci that could potentially be sampled from those extant species.
locus2clade Integer vector of length NLtips + NLnodes, with values in NStips+NSnodes, specifying for every locus tip or node the correspondng "host" species tip or node.
HGT_times Numeric vector, listing HGT event times (counted since the root) in ascending order. Only included if include_event_times==TRUE.
HGT_source_clades
Integer vector of the same length as HGT_times and with values in \(1, . .\), Ntips+Nnodes, listing the "source" species tip/node of each HGT event (in order of occurrence). The source tip/node is the tip/node from whose incoming edge a locus originated at the time of the transfer. Only included if include_event_times==TRUE.
HGT_target_clades
Integer vector of the same length as HGT_times and with values in \(1, . .\), Ntips+Nnodes, listing the "target" species tip/node of each HGT event (in order of occurrence). The target (aka. recipient) tip/node is the tip/node within whose incoming edge a locus was created by the transfer. Only included if include_event_times==TRUE.
duplication_times
Numeric vector, listing gene duplication event times (counted since the root) in ascending order. Only included if include_event_times==TRUE.
duplication_clades
Integer vector of the same length as duplication_times and with values in \(1, . .\), Ntips + Nnodes, listing the species tip/node in whose incoming edge each duplication event occurred (in order of occurrence). Only included if include_event_times==TRUE.
loss_times Numeric vector, listing gene loss event times (counted since the root) in ascending order. Only included if include_event_times==TRUE.
loss_clades Integer vector of the same length as loss_t imes and with values in \(1, . .\), Ntips+Nnodes, listing the species tip/node in whose incoming edge each loss event occurred (in order of occurrence). Only included if include_event_times==TRUE.
gene_tree The generated gene tree, of type "phylo".
gene_tip2species_tip
Integer vector of length NGtips (where NGtips is the number of tips in the gene tree) with values in \(1, .\), Ntips + Nnodes, mapping gene-tree tips to species-tree tips.
gene_tip2locus_tip
Integer vector of length NGtips with values in 1,..,NLtips, mapping gene-tree tips to locus-tree tips.
```

gene_node2locus_edge
Integer vector of length NGnodes with values in 1,..,NLedges, mapping gene-
tree nodes to locus-tree edges.
gene_clade_times
Numeric vector of size NGtips+NGnodes, listing the time (temporal distance
from species root) of each tip and node in the gene tree. The units will be the
same as the time units of the species tree. Note that this may include negative
values, if some gene lineages coalesce at a greater age than the root.
error Character, containing an explanation of the error that occurred. Only included
if success==FALSE.

```

\section*{Author(s)}

Stilianos Louca

\section*{References}
J. H. Degnan, N. A. Rosenberg (2009). Gene tree discordance, phylogenetic inference and the multispecies coalescent. Trends in Ecology \& Evolution. 24:332-340.
B. Rannala, Z. Yang (2003). Bayes estimation of species divergence times and ancestral population sizes using DNA sequences from multiple loci. Genetics. 164:1645-1656.

\section*{See Also}
generate_random_tree, generate_gene_tree_msc

\section*{Examples}
```


# Simulate a simple species tree

parameters = list(birth_rate_factor=1)
Nspecies = 10
species_tree = generate_random_tree(parameters,max_tips=Nspecies)\$tree

# Simulate a haploid gene tree within the species tree, including HGTs and gene loss

# Assume the same population size and generation time everywhere

# Assume the number of alleles samples per species is poisson-distributed

results = generate_gene_tree_msc_hgt_dl(species_tree,
allele_counts = rpois(Nspecies,3),
population_sizes = 1000,
generation_times = 1,
ploidy = 1,
HGT_rates = 0.1,
loss_rates = 0.05);
if(!results$success){
    # simulation failed
    cat(sprintf(" ERROR: %s\n",results$error))
}else{
\# simulation succeeded
gene_tree = results$gene_tree
    cat(sprintf(" Gene tree has %d tips\n",length(gene_tree$tip.label)))
}

```
generate_random_tree Generate a tree using a Poissonian speciation/extinction model.

\section*{Description}

Generate a random timetree via simulation of a Poissonian speciation/extinction (birth/death) process. New species are added (born) by splitting of a randomly chosen extant tip. The tree-wide birth and death rates of tips can each be constant or power-law functions of the number of extant tips. For example,
\[
B=I+F \cdot N^{E}
\]
where \(B\) is the tree-wide birth rate (species generation rate), \(I\) is the intercept, \(F\) is the power-law factor, \(N\) is the current number of extant tips and \(E\) is the power-law exponent. Optionally, the percapita (tip-specific) birth and death rates can be extended by adding a custom time series provided by the user.

\section*{Usage}
\[
\begin{aligned}
& \text { generate_random_tree(parameters = list(), } \\
& \text { max_tips = NULL, } \\
& \text { max_extant_tips = NULL, } \\
& \text { max_time = NULL, } \\
& \text { max_time_eq = NULL, } \\
& \text { coalescent = TRUE, } \\
& \text { as_generations = FALSE, } \\
& \text { no_full_extinction = TRUE, } \\
& \text { Nsplits = 2, } \\
& \text { added_rates_times = NULL, } \\
& \text { added_birth_rates_pc = NULL, } \\
& \text { added_death_rates_pc = NULL, } \\
& \text { added_periodic = FALSE, } \\
& \text { tip_basename = "", } \\
& \text { node_basename = NULL, } \\
& \text { edge_basename = NULL, } \\
& \text { include_birth_times = FALSE, } \\
& \text { include_death_times = FALSE) }
\end{aligned}
\]

\section*{Arguments}
parameters A named list specifying the birth-death model parameters, with one or more of the following entries:
birth_rate_intercept: Non-negative number. The intercept of the Poissonian rate at which new species (tips) are added. In units 1/time. By default this is 0 .
birth_rate_factor: Non-negative number. The power-law factor of the Poissonian rate at which new species (tips) are added. In units 1/time. By default this is 0 .
birth_rate_exponent: Numeric. The power-law exponent of the Poissonian rate at which new species (tips) are added. Unitless. By default this is 1.
death_rate_intercept: Non-negative number. The intercept of the Poissonian rate at which extant species (tips) go extinct. In units \(1 /\) time. By default this is 0 .
death_rate_factor: Non-negative number. The power-law factor of the Poissonian rate at which extant species (tips) go extinct. In units \(1 /\) time. By default this is 0 .
death_rate_exponent: Numeric. The power-law exponent of the Poissonian rate at which extant species (tips) go extinct. Unitless. By default this is 1.
resolution: Non-negative numeric, specifying the resolution (in time units) at which to collapse the final tree by combining closely related tips. Any node whose age is smaller than this threshold, will be represented by a single tip. Set resolution \(=0\) to not collapse tips (default).
rarefaction: Numeric between 0 and 1. Rarefaction to be applied to the final tree (fraction of random tips kept in the tree). Note that if coalescent==FALSE, rarefaction may remove both extant as well as extinct clades. Set rarefaction=1 to not perform any rarefaction (default).
max_tips Integer, maximum number of tips of the tree to be generated. If coalescent=TRUE, this refers to the number of extant tips. Otherwise, it refers to the number of extinct + extant tips. If NULL or \(<=0\), this halting condition is ignored.
max_extant_tips
Integer, maximum number of extant lineages allowed at any moment during the simulation. If this number is reached, the simulation is halted. If NULL or \(<=0\), this halting condition is ignored.
max_time Numeric, maximum duration of the simulation. If NULL or \(<=0\), this constraint is ignored.
max_time_eq Maximum duration of the simulation, counting from the first point at which speciation/extinction equilibrium is reached, i.e. when (birth rate - death rate) changed sign for the first time. If NULL or \(<0\), this constraint is ignored.
coalescent Logical, specifying whether only the coalescent tree (i.e. the tree spanning the extant tips) should be returned. If coalescent==FALSE and the death rate is non-zero, then the tree may include non-extant tips (i.e. tips whose distance from the root is less than the total time of evolution). In that case, the tree will not be ultrametric.
as_generations Logical, specifying whether edge lengths should correspond to generations. If FALSE, then edge lengths correspond to time.
no_full_extinction
Logical, specifying whether to prevent complete extinction of the tree. Full extinction is prevented by temporarily disabling extinctions whenever the number of extant tips is 1 . Note that, strictly speaking, the trees generated do not exactly follow the proper probability distribution when no_full_extinction is TRUE.

Nsplits Integer greater than 1. Number of child-tips to generate at each diversification event. If set to 2 , the generated tree will be bifurcating. If \(>2\), the tree will be multifurcating.
added_rates_times
Numeric vector, listing time points (in ascending order) for the custom percapita birth and/or death rates time series (see added_birth_rates_pc and added_death_rates_pc below). Can also be NULL, in which case the custom time series are ignored.
added_birth_rates_pc
Numeric vector of the same size as added_rates_times, listing per-capita birth rates to be added to the power law part. Can also be NULL, in which case this option is ignored and birth rates are purely described by the power law.
added_death_rates_pc
Numeric vector of the same size as added_rates_times, listing per-capita death rates to be added to the power law part. Can also be NULL, in which case this option is ignored and death rates are purely described by the power law.
added_periodic Logical, indicating whether added_birth_rates_pc and added_death_rates_pc should be extended periodically if needed (i.e. if not defined for the entire simulation time). If FALSE, added birth \& death rates are extended with zeros.
tip_basename Character. Prefix to be used for tip labels (e.g. "tip."). If empty (""), then tip labels will be integers " 1 ", " 2 " and so on.
node_basename Character. Prefix to be used for node labels (e.g. "node."). If NULL, no node labels will be included in the tree.
edge_basename Character. Prefix to be used for edge labels (e.g. "edge."). Edge labels (if included) are stored in the character vector edge. label. If NULL, no edge labels will be included in the tree.
include_birth_times
Logical. If TRUE, then the times of speciation events (in order of occurrence) will also be returned.
include_death_times
Logical. If TRUE, then the times of extinction events (in order of occurrence) will also be returned.

\section*{Details}

If max_time==NULL, then the returned tree will always contain max_tips tips. In particular, if at any moment during the simulation the tree only includes a single extant tip, the death rate is temporarily set to zero to prevent the complete extinction of the tree. If max_tips==NULL, then the simulation is ran as long as specified by max_time. If neither max_time nor max_tips is NULL, then the simulation halts as soon as the time exceeds max_time or the number of tips (extant tips if coalescent is TRUE) exceeds max_tips. If max_tips! \(=\) NULL and Nsplits \(>2\), then the last diversification even may generate fewer than Nsplits children, in order to keep the total number of tips within the specified limit.

If rarefaction<1 and resolution>0, collapsing of closely related tips (at the resolution specified) takes place prior to rarefaction (i.e., subsampling applies to the already collapsed tips).

Both the per-capita birth and death rates can be made into completely arbitrary functions of time, by setting all power-law coefficients to zero and providing custom time series added_birth_rates_pc and added_death_rates_pc.

\section*{Value}

A named list with the following elements:
\begin{tabular}{ll} 
success & \begin{tabular}{l} 
Logical, indicating whether the tree was successfully generated. If FALSE, the \\
only other value returned is error.
\end{tabular} \\
A rooted bifurcating (if Nsplits==2) or multifurcating (if Nsplits>2) tree of \\
class "phylo", generated according to the specified birth/death model. If coalescent==TRUE \\
or if all death rates are zero, and only if as_generations==FALSE, then the tree \\
will be ultrametric. If as_generations==TRUE and coalescent==FALSE, all \\
edges will have unit length.
\end{tabular}

Numeric, giving the first time where the sign of (death rate - birth rate) changed from the beginning of the simulation, i.e. when speciation/extinction equilibrium was reached. May be infinite if the simulation stoped before reaching this point.
extant_tips Integer vector, listing indices of extant tips in the tree. If coalescent==TRUE, all tips will be extant.
Nbirths Total number of birth events (speciations) that occurred during tree growth. This may be lower than the total number of tips in the tree if death rates were non-zero and coalescent==TRUE, or if Nsplits \(>2\).
Ndeaths Total number of deaths (extinctions) that occurred during tree growth.
Ncollapsed Number of tips removed from the tree while collapsing at the resolution specified.
Nrarefied Number of tips removed from the tree due to rarefaction.
birth_times Numeric vector, listing the times of speciation events during tree growth, in order of occurrence. Note that if coalescent==TRUE, then speciation_times may be greater than the phylogenetic distance to the coalescent root.
death_times Numeric vector, listing the times of extinction events during tree growth, in order of occurrence. Note that if coalescent==TRUE, then speciation_times may be greater than the phylogenetic distance to the coalescent root.
error Character, containing an explanation of ther error that occurred. Only included if success==FALSE.

\section*{Author(s)}

Stilianos Louca

\section*{References}
D. J. Aldous (2001). Stochastic models and descriptive statistics for phylogenetic trees, from Yule to today. Statistical Science. 16:23-34.
M. Steel and A. McKenzie (2001). Properties of phylogenetic trees generated by Yule-type speciation models. Mathematical Biosciences. 170:91-112.

\section*{Examples}
```


# Simple speciation model

parameters = list(birth_rate_intercept=1)
tree = generate_random_tree(parameters,max_tips=100)\$tree

# Exponential growth rate model

parameters = list(birth_rate_factor=1)
tree = generate_random_tree(parameters,max_tips=100)\$tree

```
generate_tree_hbds Generate a tree from a birth-death-sampling model in forward time.

\section*{Description}

Generate a random timetree according to a homogenous birth-death-sampling model with arbitrary time-varying speciation/extinction/sampling rates. Lineages split (speciate) or die (go extinct) at Poissonian rates and independently of each other. Lineages are sampled continuously (i.e., at Poissonian rates) in time and/or during concentrated sampling attempts (i.e., at specific time points). Sampled lineages are assumed to continue in the pool of extant lineages at some given "retention probability". The final tree can be restricted to sampled lineages only, but may optionally include extant (non-sampled) as well as extinct lineages. Speciation, extinction and sampling rates as well as retention probabilities may depend on time. This function may be used to simulate trees commonly encountered in viral epidemiology, where sampled patients are assumed to exit the pool of infectious individuals.

\section*{Usage}
```

generate_tree_hbds( max_sampled_tips = NULL,
max_sampled_nodes = NULL,
max_extant_tips = NULL,
max_extinct_tips = NULL,
max_tips = NULL,
max_time = NULL,
include_extant = FALSE,
include_extinct = FALSE,
as_generations = FALSE,
time_grid = NULL,
lambda = NULL,
mu = NULL,
psi = NULL,

```
```

kappa = NULL,
splines_degree = 1,
CSA_times = NULL,
CSA_probs = NULL,
CSA_kappas = NULL,
no_full_extinction = FALSE,
max_runtime = NULL,
tip_basename = "",
node_basename = NULL,
edge_basename = NULL,
include_birth_times = FALSE,
include_death_times = FALSE)

```

\section*{Arguments}
```

max_sampled_tips

```

Integer, maximum number of sampled tips. The simulation is halted once this number is reached. If NULL or \(<=0\), this halting criterion is ignored.
max_sampled_nodes
Integer, maximum number of sampled nodes, i.e., of lineages that were sampled but kept in the pool of extant lineages. The simulation is halted once this number is reached. If NULL or \(<=0\), this halting criterion is ignored.
max_extant_tips
Integer, maximum number of extant tips. The simulation is halted once the number of concurrently extant tips reaches this threshold. If NULL or \(<=0\), this halting criterion is ignored.
max_extinct_tips
Integer, maximum number of extant tips. The simulation is halted once this number is reached. If NULL or \(<=0\), this halting criterion is ignored.
max_tips Integer, maximum number of tips (extant+extinct+sampled). The simulation is halted once this number is reached. If NULL or \(<=0\), this halting criterion is ignored.
max_time Numeric, maximum duration of the simulation. If NULL or \(<=0\), this halting criterion is ignored.
include_extant Logical, specifying whether to include extant tips (i.e., neither extinct nor sampled) in the final tree.
include_extinct
Logical, specifying whether to include extant tips (i.e., neither extant nor sampled) in the final tree.
as_generations Logical, specifying whether edge lengths should correspond to generations. If FALSE, then edge lengths correspond to time. If TRUE, then the time between two subsequent events (speciation, extinction, sampling) is counted as "one generation".
time_grid Numeric vector, specifying time points (in ascending order) on which the rates lambda, mu and psi are provided. Rates are interpolated polynomially between time grid points as needed (according to splines_degree). The time grid should
generally cover the maximum possible simulation time, otherwise it will be polynomially extrapolated as needed.
lambda Numeric vector, of the same size as time_grid (or size 1 if time_grid==NULL), listing per-lineage speciation (birth) rates ( \(\lambda\), in units \(1 /\) time) at the times listed in time_grid. Speciation rates must be non-negative, and are assumed to vary as a spline between grid points (see argument splines_degree). Can also be a single numeric, in which case \(\lambda\) is assumed to be constant over time.

Numeric vector, of the same size as time_grid (or size 1 if time_grid==NULL), listing per-lineage extinction (death) rates ( \(\mu\), in units \(1 /\) time) at the times listed in time_grid. Extinction rates must be non-negative, and are assumed to vary as a spline between grid points (see argument splines_degree). Can also be a single numeric, in which case \(\mu\) is assumed to be constant over time. If omitted, the extinction rate is assumed to be zero.
psi Numeric vector, of the same size as time_grid (or size 1 if time_grid==NULL), listing per-lineage sampling rates ( \(\psi\), in units \(1 /\) time) at the times listed in time_grid. Sampling rates must be non-negative, and are assumed to vary as a spline between grid points (see argument splines_degree). Can also be a single numeric, in which case \(\psi\) is assumed to be constant over time. If omitted, the continuous sampling rate is assumed to be zero.
kappa Numeric vector, of the same size as time_grid (or size 1 if time_grid==NULL), listing retention probabilities ( \(\kappa\), unitless) of continuously (Poissonian) sampled lineages at the times listed in time_grid. Retention probabilities must be true probabilities (i.e., between 0 and 1), and are assumed to vary as a spline between grid points (see argument splines_degree). Can also be a single numeric, in which case \(\kappa\) is assumed to be constant over time. If omitted, the retention probability is assumed to be zero (a common assumption in epidemiology).
splines_degree Integer, either \(0,1,2\) or 3 , specifying the polynomial degree of the provided lambda, mu and psi between grid points in age_grid. For example, if splines_degree==1, then the provided lambda, mu and psi are interpreted as piecewise-linear curves; if splines_degree==2 the lambda, mu and psi are interpreted as quadratic splines; if splines_degree==3 the lambda, mu and psi is interpreted as cubic splines. If your age_grid is fine enough, then splines_degree=1 is usually sufficient.
CSA_times Optional numeric vector, listing times of concentrated sampling attempts, in ascending order. Concentrated sampling is performed in addition to any continuous (Poissonian) sampling specified by psi.
CSA_probs Optional numeric vector of the same size as CSA_times, listing sampling probabilities at each concentrated sampling time. Note that in contrast to the sampling rates psi, the CSA_probs are interpreted as probabilities and must thus be between 0 and 1. CSA_probs must be provided if and only if CSA_times is provided.

CSA_kappas Optional numeric vector of the same size as CSA_times, listing sampling retention probabilities at each concentrated sampling time, i.e. the probability at which a sampled lineage is kept in the pool of extant lineages. Note that the CSA_kappas are probabilities and must thus be between 0 and 1. CSA_kappas must be provided if and only if CSA_times is provided.
```

no_full_extinction
Logical, specifying whether to prevent complete extinction of the tree. Full ex-
tinction is prevented by temporarily disabling extinctions whenever the number
of extant tips is 1. Note that, strictly speaking, the trees generated do not exactly
follow the proper probability distribution when no_full_extinction is TRUE.
max_runtime Numeric, optional maximum computation time (in seconds) to allow for the
simulation. Use this to avoid occasional explosions of runtimes, for example
due to very large generated trees. Aborted simulations will return with the flag
success=FALSE (i.e., no tree is returned at all).
tip_basename Character. Prefix to be used for tip labels (e.g. "tip."). If empty (""), then tip
labels will be integers "1", "2" and so on.
node_basename Character. Prefix to be used for node labels (e.g. "node."). If NULL, no node
labels will be included in the tree.
edge_basename Character. Prefix to be used for edge labels (e.g. "edge."). Edge labels (if
included) are stored in the character vector edge. label. If NULL, no edge labels
will be included in the tree.
include_birth_times
Logical. If TRUE, then the times of speciation events (in order of occurrence)
will also be returned.
include_death_times
Logical. If TRUE, then the times of extinction events (in order of occurrence)
will also be returned.

```

\section*{Details}

The simulation proceeds in forward time, starting with a single root. Speciation/extinction and continuous (Poissonian) sampling events are drawn at exponentially distributed time steps, according to the rates specified by lambda, mu and psi. Sampling also occurs at the optional CSA_times. Only extant lineages are sampled at any time point, and sampled lineages are removed from the pool of extant lineages at probability 1-kappa.
The simulation halts as soon as one of the halting criteria are met, as specified by the options max_sampled_tips, max_sampled_nodes, max_extant_tips, max_extinct_tips, max_tips and max_time, or if no extant tips remain, whichever occurs first. Note that in some scenarios (e.g., if extinction rates are very high) the simulation may halt too early and the generated tree may only contain a single tip (i.e., the root lineage); in that case, the simulation will return an error (see return value success).
The function returns a single generated tree, as well as supporting information such as which tips are extant, extinct or sampled.

\section*{Value}

A named list with the following elements:
success Logical, indicating whether the simulation was successful. If FALSE, then the returned list includes an additional 'error' element (character) providing a description of the error; all other return variables may be undefined.
tree The generated timetree, of class "phylo". Note that this tree need not be ultrametric, for example if sampling occurs at multiple time points.
\begin{tabular}{|c|c|}
\hline root_time & Numeric, giving the time at which the tree's root was first split during the simulation. Note that this may be greater than 0, i.e., if the tips of the final tree do not coalesce all the way back to the simulation's start. \\
\hline final_time & Numeric, giving the final time at the end of the simulation. \\
\hline root_age & Numeric, giving the age (time before present) at the tree's root. This is equal to final_time-root_time. \\
\hline Nbirths & Integer, the total number of speciation (birth) events that occured during the simulation. \\
\hline Ndeaths & Integer, the total number of extinction (death) events that occured during the simulation. \\
\hline Nsamplings & Integer, the total number of sampling events that occured during the simulation. \\
\hline Nretentions & Integer, the total number of sampling events that occured during the simulation and for which lineages were kept in the pool of extant lineages. \\
\hline sampled_clades & Integer vector, specifying indices (from 1 to Ntips+Nnodes) of sampled tips and nodes in the final tree (regardless of whether their lineages were subsequently retained or removed from the pool). \\
\hline \multicolumn{2}{|l|}{retained_clades} \\
\hline & Integer vector, specifying indices (from 1 to Ntips+Nnodes) of sampled tips and nodes in the final tree that were retained, i.e., not removed from the pool following sampling. \\
\hline extant_tips & Integer vector, specifying indices (from 1 to Ntips) of extant (non-sampled and non-extinct) tips in the final tree. Will be empty if include_extant==FALSE. \\
\hline extinct_tips & Integer vector, specifying indices (from 1 to Ntips) of extinct (non-sampled and non-extant) tips in the final tree. Will be empty if include_extinct==FALSE. \\
\hline
\end{tabular}

\section*{Author(s)}

Stilianos Louca

\section*{References}
T. Stadler (2010). Sampling-through-time in birth-death trees. Journal of Theoretical Biology. 267:396-404.
T. Stadler et al. (2013). Birth-death skyline plot reveals temporal changes of epidemic spread in HIV and hepatitis C virus (HCV). PNAS. 110:228-233.

\section*{See Also}
generate_tree_hbd_reverse, generate_gene_tree_msc, generate_random_tree, fit_hbds_model_parametric, simulate_deterministic_hbds

\section*{Examples}
```


# define time grid on which lambda, mu and psi will be specified

time_grid = seq(0,100,length.out=1000)

```
```


# specify the time-dependent extinction rate mu on the time-grid

mu_grid = 0.5*time_grid/(10+time_grid)

# define additional concentrated sampling attempts

CSA_times = c(5,7,9)
CSA_probs = c(0.5, 0.5, 0.5)
CSA_kappas = c(0.2, 0.1, 0.1)

# generate tree with a constant speciation \& sampling rate,

# time-variable extinction rate and additional discrete sampling points

# assuming that all continuously sampled lineages are removed from the pool

simul = generate_tree_hbds( max_time = 10,
include_extant = FALSE,
include_extinct = FALSE,
time_grid = time_grid,
lambda = 1,
mu = mu_grid,
psi = 0.1,
kappa = 0,
CSA_times = CSA_times,
CSA_probs = CSA_probs,
CSA_kappas = CSA_kappas);
if(!simul$success){
    cat(sprintf("ERROR: Could not simulate tree: %s\n",simul$error))
}else{
\# simulation succeeded. print some basic info about the generated tree
tree = simul$tree
    cat(sprintf("Generated tree has %d tips\n",length(tree$tip.label)))
}

```
generate_tree_hbd_reverse

Generate a tree from a birth-death model in reverse time.

\section*{Description}

Generate an ultrametric timetree (comprising only extant lineages) in reverse time (from present back to the root) based on the homogenous birth-death (HBD; Morlon et al., 2011) model, conditional on a specific number of extant species sampled and (optionally) conditional on the crown age or stem age.
The probability distribution of such trees only depends on the congruence class of birth-death models (e.g., as specified by the pulled speciation rate) but not on the precise model within a congruence class (Louca and Pennell, 2019). Hence, in addition to allowing specification of speciation and extinction rates, this function can alternatively simulate trees simply based on some pulled speciation rate (PSR), or based on some pulled diversification rate (PDR) and the product \(\rho \lambda_{o}\) (present-day sampling fraction times present-day speciation rate).
This function can be used to generate bootstrap samples after fitting an HBD model or HBD congruence class to a real timetree.

\section*{Usage}
generate_tree_hbd_reverse( Ntips,


\section*{Arguments}

Ntips Number of tips in the tree, i.e. number of extant species sampled at present day.
stem_age Numeric, optional stem age on which to condition the tree. If NULL or \(<=0\), the tree is not conditioned on the stem age.
crown_age Numeric, optional crown age (aka. root age or MRCA age) on which to condition the tree. If NULL or \(<=0\), the tree is not conditioned on the crown age. If both stem_age and crown_age are specified, only the crown age is used; in that case for consistency crown_age must not be greater than stem_age.
age_grid Numeric vector, listing discrete ages (time before present) on which the PSR is specified. Listed ages must be strictly increasing, and should cover at least the present day (age 0 ) as well as a sufficient duration into the past. If conditioning on the stem or crown age, that age must also be covered by age_grid. When not conditioning on crown nor stem age, and the generated tree ends up extending beyond the last time point in age_grid, the PSR will be extrapolated as a constant (with value equal to the last value in PSR) as necessary. age_grid also be NULL or a vector of size 1 , in which case the PSR is assumed to be time-independent.
lambda Numeric vector, of the same size as age_grid (or size 1 if age_grid==NULL), listing speciation rates ( \(\lambda\), in units \(1 /\) time \()\) at the ages listed in age_grid. Speciation rates must be non-negative, and are assumed to vary as a spline between grid points (see argument splines_degree). Can also be NULL, in which case either PSR, or PDR and rholambda0, must be provided.
mu
Numeric vector, of the same size as age_grid (or size 1 if age_grid==NULL), listing extinction rates ( \(\mu\), in units \(1 /\) time ) at the ages listed in age_grid. Extinction rates must be non-negative, and are assumed to vary as a spline between grid points (see argument splines_degree). Can also be NULL, in which case either PSR, or PDR and rholambda0, must be provided.
\begin{tabular}{|c|c|}
\hline rho & Numeric, sampling fraction at present day (fraction of extant species included in the tree). Can also be NULL, in which case either PSR, or PDR and rholambda0, must be provided. \\
\hline PSR & Numeric vector, of the same size as age_grid (or size 1 if age_grid==NULL), listing pulled speciation rates ( \(\lambda_{p}\), in units \(1 /\) time) at the ages listed in age_grid. The PSR must be non-negative (and strictly positive almost everywhere), and is assumed to vary as a spline between grid points (see argument splines_degree). Can also be NULL, in which case either lambda and mu and rho, or PDR and rholambda0, must be provided. \\
\hline PDR & Numeric vector, of the same size as age_grid (or size 1 if age_grid==NULL), listing pulled diversification rates ( \(r_{p}\), in units \(1 /\) time) at the ages listed in age_grid. The PDR is assumed to vary polynomially between grid points (see argument splines_degree). Can also be NULL, in which case either lambda and mu and rho, or PSR, must be provided. \\
\hline rholambda0 & Strictly positive numeric, specifying the product \(\rho \lambda_{o}\) (present-day species sampling fraction times present-day speciation rate). Can also be NULL, in which case PSR must be provided. \\
\hline force_max_age & Numeric, specifying an optional maximum allowed age for the tree's root. If the tree ends up expanding past that age, all remaining lineages are forced to coalesce at that age. This is not statistically consistent with the provided HBD model (in fact it corresponds to a modified HBD model with a spike in the PSR at that time). This argument merely provides a way to prevent excessively large trees if the PSR is close to zero at older ages and when not conditioning on the stem nor crown age, while still keeping the original statistical properties at younger ages. To disable this feature set force_max_age to Inf. \\
\hline splines_degree & Integer, either \(0,1,2\) or 3 , specifying the polynomial degree of the provided rates PSR, PDR, lambda, mu and rho between grid points in age_grid. For example, if splines_degree==1, then the provided rates are interpreted as piecewise-linear curves; if splines_degree==2 the rates are interpreted as quadratic splines; if splines_degree==3 the rates are interpreted as cubic splines. The splines_degree influences the analytical properties of the curve, e.g. splines_degree==1 guarantees a continuous curve, splines_degree==2 guarantees a continuous curve and continuous derivative, and so on. If your age_grid is fine enough, then splines_degree=1 is usually sufficient. \\
\hline relative_dt & Strictly positive numeric (unitless), specifying the maximum relative time step allowed for integration over time. Smaller values increase integration accuracy but increase computation time. Typical values are 0.0001-0.001. The default is usually sufficient. \\
\hline Ntrees & Integer, number of trees to generate. The computation time per tree is lower if you generate multiple trees at once. \\
\hline tip_basename & Character. Prefix to be used for tip labels (e.g. "tip."). If empty (""), then tip labels will be integers "1", "2" and so on. \\
\hline node_basename & Character. Prefix to be used for node labels (e.g. "node."). If NULL, no node labels will be included in the tree. \\
\hline edge_basename & Character. Prefix to be used for edge labels (e.g. "edge."). Edge labels (if included) are stored in the character vector edge. label. If NULL, no edge labels will be included in the tree. \\
\hline
\end{tabular}

\section*{Details}

This function requires that the BD model, or the BD congruence class (Louca and Pennell, 2019), is specified using one of the following sets of arguments:
- Using the speciation rate \(\lambda\), the extinctin rate \(\mu\), and the present-day sampling fraction \(\rho\).
- Using the pulled diversification rate (PDR) and the product \(\rho \lambda(0)\). The PDR is defined as \(r_{p}=\lambda-\mu+\frac{1}{\lambda} \frac{d \lambda}{d \tau}\), where \(\tau\) is age (time before present), \(\lambda(\tau)\) is the speciation rate at age \(\tau\) and \(\mu(\tau)\) is the extinction rate.
- Using the pulled speciation rate (PSR). The \(\operatorname{PSR}\left(\lambda_{p}\right)\) is defined as \(\lambda_{p}(\tau)=\lambda(\tau) \cdot \Phi(\tau)\), where and \(\Phi(\tau)\) is the probability that a lineage extant at age \(\tau\) will survive until the present and be represented in the tree.

Concurrently using/combining more than one the above parameterization methods is not supported.
Either the PSR, or the PDR and rholambda0, provide sufficient information to fully describe the probability distribution of the tree (Louca and Pennell, 2019). For example, the probability distribution of generated trees only depends on the PSR, and not on the specific speciation rate \(\lambda\) or extinction rate \(\mu\) (various combinations of \(\lambda\) and \(\mu\) can yield the same PSR; Louca and Pennell, 2019). To calculate the PSR and PDR for any arbitrary \(\lambda, \mu\) and \(\rho\) you can use the function simulate_deterministic_hbd.

When not conditioning on the crown age, the age of the root of the generated tree will be stochastic (i.e., non-fixed). This function then assumes a uniform prior distribution (in a sufficiently large time interval) for the origin of the forward HBD process that would have generated the tree, based on a generalization of the EBDP algorithm provided by (Stadler, 2011). When conditioning on stem or crown age, this function is based on the algorithm proposed by Hoehna (2013, Eq. 8).
Note that HBD trees can also be generated using the function generate_random_tree. That function, however, generates trees in forward time, and hence when conditioning on the final number of tips the total duration of the simulation is unpredictable; consequently, speciation and extinction rates cannot be specified as functions of "age" (time before present). The function presented here provides a means to generate trees with a fixed number of tips, while specifying \(\lambda, \mu, \lambda_{p}\) or \(r_{p}\) as functions of age (time before present).

\section*{Value}

A named list with the following elements:
success Logical, indicating whether the simulation was successful. If FALSE, then the returned list includes an additional 'error' element (character) providing a description of the error; all other return variables may be undefined.
trees A list of length Ntrees, listing the generated trees. Each tree will be an ultrametric timetree of class "phylo".

\section*{Author(s)}

Stilianos Louca

\section*{References}
H. Morlon, T. L. Parsons, J. B. Plotkin (2011). Reconciling molecular phylogenies with the fossil record. Proceedings of the National Academy of Sciences. 108:16327-16332.
T. Stadler (2011). Simulating trees with a fixed number of extant species. Systematic Biology. 60:676-684.
S. Hoehna (2013). Fast simulation of reconstructed phylogenies under global time-dependent birthdeath processes. Bioinformatics. 29:1367-1374.
S. Louca and M. W. Pennell (in review as of 2019). Phylogenies of extant species are consistent with an infinite array of diversification histories.

\section*{See Also}
loglikelihood_hbd, simulate_deterministic_hbd, generate_random_tree

\section*{Examples}
```


# EXAMPLE 1: Generate trees based on some speciation and extinction rate

# In this example we assume an exponentially decreasing speciation rate

# and a temporary mass extinction event

# define parameters

age_grid = seq(0,100,length.out=1000)
lambda = 0.1 + exp(-0.5*age_grid)
mu = 0.05 + exp(-(age_grid-5)^2)
rho = 0.5 \# species sampling fraction at present-day

# generate a tree with 100 tips and no specific crown or stem age

sim = generate_tree_hbd_reverse(Ntips = 100,
age_grid = age_grid,
lambda = lambda,
mu = mu,
rho = rho)
if(!sim$success){
    cat(sprintf("Tree generation failed: %s\n",sim$error))
}else{
cat(sprintf("Tree generation succeeded\n"))
tree = sim\$trees[[1]]
}

```

\section*{\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#}
```

\# EXAMPLE 2: Generate trees based on the pulled speciation rate
\# Here we condition the tree on some fixed crown (MRCA) age
\# specify the PSR on a sufficiently fine and wide age grid
age_grid $=\operatorname{seq}(0,1000$, length.out=10000)
PSR $\quad=0.1+\exp (-0.1 *$ age_grid) \# exponentially decreasing PSR
\# generate a tree with 100 tips and MRCA age 10
sim = generate_tree_hbd_reverse(Ntips = 100,

```
```

    age_grid = age_grid,
    PSR = PSR,
    crown_age = 10)
    if(!sim$success){
    cat(sprintf("Tree generation failed: %s\n",sim$error))
    }else{
        cat(sprintf("Tree generation succeeded\n"))
        tree = sim$trees[[1]]
    }

```
generate_tree_with_evolving_rates

Generate a random tree with evolving speciation/extinction rates.

\section*{Description}

Generate a random phylogenetic tree via simulation of a Poissonian speciation/extinction (birth/death) process. New species are added (born) by splitting of a randomly chosen extant tip. Per-capita birth and death rates (aka. speciation and extinction rates) evolve under some stochastic process (e.g. Brownian motion) along each edge. Thus, the probability rate of a tip splitting or going extinct depends on the tip, with closely related tips having more similar per-capita birth and death rates.

\section*{Usage}

\section*{Arguments}
parameters A named list specifying the model parameters for the evolving birth/death rates. The precise entries expected depend on the chosen rate_model (see details below).
rate_model Character, specifying the model for the evolving per-capita birth/death rates. Must be one of the following: 'BM' (Brownian motion constrained to a finite interval via reflection), 'Mk' (discrete-state continuous-time Markov chain with fixed transition rates).
\(\left.\begin{array}{ll}\text { max_tips } & \begin{array}{l}\text { Maximum number of tips of the tree to be generated. If coalescent=TRUE, this } \\
\text { refers to the number of extant tips. Otherwise, it refers to the number of extinct } \\
\text { + extant tips. If NULL or <=0, the number of tips is unlimited (so be careful). }\end{array} \\
\text { max_time } & \begin{array}{l}\text { Maximum duration of the simulation. If NULL or <=0, this constraint is ignored. }\end{array} \\
\text { max_time_eq } \\
\text { Maximum duration of the simulation, counting from the first point at which } \\
\text { speciation/extinction equilibrium is reached, i.e. when (birth rate - death rate) } \\
\text { changed sign for the first time. If NULL or <0, this constraint is ignored. }\end{array}\right\}\)\begin{tabular}{l} 
Logical, specifying whether only the coalescent tree (i.e. the tree spanning the \\
extant tips) should be returned. If coalescent==FALSE and the death rate is \\
non-zero, then the tree may include non-extant tips (i.e. tips whose distance \\
from the root is less than the total time of evolution). In that case, the tree will \\
not be ultrametric.
\end{tabular}

\section*{Details}

If max_time==NULL, then the returned tree will always contain max_tips tips. In particular, if at any moment during the simulation the tree only includes a single extant tip, the death rate is temporarily set to zero to prevent the complete extinction of the tree. If max_tips==NULL, then the simulation is ran as long as specified by max_time. If neither max_time nor max_tips is NULL, then the simulation halts as soon as the time exceeds max_time or the number of tips (extant tips if coalescent is TRUE) exceeds max_tips.
If rate_model=='BM', then per-capita birth rates (speciation rates) and per-capita death rates (extinction rates) evolve according to Brownian Motion, constrained to a finite interval via reflection. Note that speciation and extinction rates are only updated at branching points, i.e. during speciation events, while waiting times until speciation/extinction are based on rates at the previous branching point. The argument parameters should be a named list including one or more of the following elements:
- birth_rate_diffusivity: Non-negative number. Diffusivity constant for the Brownian motion model of the evolving per-capita birth rate. In units \(1 /\) time^ \({ }^{\wedge}\). See simulate_bm_model for an explanation of the diffusivity parameter.
- min_birth_rate_pc: Non-negative number. The minimum allowed per-capita birth rate of a clade. In units \(1 /\) time. By default this is 0 .
- max_birth_rate_pc: Non-negative number. The maximum allowed per-capita birth rate of a clade. In units 1/time. By default this is 1 .
- death_rate_diffusivity: Non-negative number. Diffusivity constant for the Brownian motion model of the evolving per-capita death rate. In units \(1 /\) time^3. See simulate_bm_model for an explanation of the diffusivity parameter.
- min_death_rate_pc: Non-negative number. The minimum allowed per-capita death rate of a clade. In units \(1 /\) time. By default this is 0 .
- max_death_rate_pc: Non-negative number. The maximum allowed per-capita death rate of a clade. In units \(1 /\) time. By default this is 1 .
- root_birth_rate_pc: Non-negative number, between min_birth_rate_pc and max_birth_rate_pc, specifying the initial per-capita birth rate of the root. If left unspecified, this will be chosen randomly and uniformly within the allowed interval.
- root_death_rate_pc: Non-negative number, between min_death_rate_pc and max_death_rate_pc, specifying the initial per-capita death rate of the root. If left unspecified, this will be chosen randomly and uniformly within the allowed interval.
- rarefaction: Numeric between 0 and 1 . Rarefaction to be applied at the end of the simulation (fraction of random tips kept in the tree). Note that if coalescent==FALSE, rarefaction may remove both extant as well as extinct clades. Set rarefaction=1 to not perform any rarefaction.

If rate_model=='Mk', then speciation/extinction rates are determined by a tip's current "state", which evolves according to a continuous-time discrete-state Markov chain (Mk model) with constant transition rates. The argument parameters should be a named list including one or more of the following elements:
- Nstates: Number of possible discrete states a tip can have. For example, if Nstates then this corresponds to the common Binary State Speciation and Extinction (BiSSE) model (Maddison et al., 2007). By default this is 1.
- state_birth_rates: Numeric vector of size Nstates, listing the per-capita birth rate (speciation rate) at each state. Can also be a single number (all states have the same birth rate).
- state_death_rates: Numeric vector of size Nstates, listing the per-capita death rate (extinction rate) at each state. Can also be a single number (all states have the same death rate).
- transition_matrix: 2D numeric matrix of size Nstates x Nstates. Transition rate matrix for the Markov chain model of birth/death rate evolution.
- start_state: Integer within \(1, . .\), Nstates, specifying the initial state of the first created lineage. If left unspecified, this is chosen randomly and uniformly among all possible states.
- rarefaction: Same as when rate_model=='BM'.

Note: The option rate_model=='Mk' is deprecated and included for backward compatibility purposes only. To generate a tree with Markov transitions between states (known as Multiple State Speciation and Extinction model), use the command simulate_dsse instead.

\section*{Value}

A named list with the following elements:
success Logical, indicating whether the simulation was successful. If FALSE, an additional element error (of type character) is included containing an explanation of the error; in that case the value of any of the other elements is undetermined.
\begin{tabular}{|c|c|}
\hline tree & A rooted bifurcating tree of class "phylo", generated according to the specified birth/death model. \\
\hline & If coalescent==TRUE or if all death rates are zero, and only if as_generations==FALSE, then the tree will be ultrametric. If as_generations==TRUE and coalescent==FALSE, all edges will have unit length. \\
\hline root_time & Numeric, giving the time at which the tree's root was first split during the simulation. Note that if coalescent==TRUE, this may be later than the first speciation event during the simulation. \\
\hline final_time & Numeric, giving the final time at the end of the simulation. If coalescent==TRUE, then this may be greater than the total time span of the tree (since the root of the coalescent tree need not correspond to the first speciation event). \\
\hline equilibrium_tim & \\
\hline & Numeric, giving the first time where the sign of (death rate - birth rate) changed from the beginning of the simulation, i.e. when speciation/extinction equilibrium was reached. May be infinite if the simulation stoped before reaching this point. \\
\hline Nbirths & Total number of birth events (speciations) that occurred during tree growth. This may be lower than the total number of tips in the tree if death rates were non-zero and coalescent==TRUE. \\
\hline Ndeaths & Total number of deaths (extinctions) that occurred during tree growth. \\
\hline birth_times & Numeric vector, listing the times of speciation events during tree growth, in order of occurrence. Note that if coalescent==TRUE, then speciation_times may be greater than the phylogenetic distance to the coalescent root. Only returned if include_event_times==TRUE. \\
\hline death_times & Numeric vector, listing the times of extinction events during tree growth, in order of occurrence. Note that if coalescent==TRUE, then speciation_times may be greater than the phylogenetic distance to the coalescent root. Only returned if include_event_times==TRUE. \\
\hline birth_rates_pc & Numeric vector of length Ntips+Nnodes, listing the per-capita birth rate of each tip and node in the tree. The length of an edge in the tree was thus drawn from an exponential distribution with rate equal to the per-capita birth rate of the child tip or node. \\
\hline death_rates_pc & Numeric vector of length Ntips+Nnodes, listing the per-capita death rate of each tip and node in the tree. \\
\hline states & Integer vector of size Ntips+Nnodes, listing the discrete state of each tip and node in the tree. Only included if rate_model=="Mk". \\
\hline start_state & Integer, specifying the initial state of the first created lineage (either provided during the function call, or generated randomly). Only included if rate_model=="Mk". \\
\hline root_birth_rate & \\
\hline & Numeric, specifying the initial per-capita birth rate of the root (either provided during the function call, or generated randomly). Only included if rate_model=="BM". \\
\hline root_death_rate & _pc \\
\hline & Numeric, specifying the initial per-capita death rate of the root (either provided during the function call, or generated randomly). Only included if rate_model=="BM". \\
\hline
\end{tabular}

\section*{Author(s)}

Stilianos Louca

\section*{References}
D. J. Aldous (2001). Stochastic models and descriptive statistics for phylogenetic trees, from Yule to today. Statistical Science. 16:23-34.
W. P. Maddison, P. E. Midford, S. P. Otto (2007). Estimating a binary character's effect on speciation and extinction. Systematic Biology. 56:701-710.

\section*{See Also}
```

simulate_dsse

```

\section*{Examples}
```


# Example 1

# Generate tree, with rates evolving under Brownian motion

parameters = list(birth_rate_diffusivity = 1,
min_birth_rate_pc = 1,
max_birth_rate_pc = 2,
death_rate_diffusivity = 0.5,
min_death_rate_pc = 0,
max_death_rate_pc = 1)
simulation = generate_tree_with_evolving_rates(parameters,
rate_model='BM',
max_tips=1000,
include_rates=TRUE)
tree = simulation$tree
Ntips = length(tree$tip.label)

# plot per-capita birth \& death rates of tips

plot( x=simulation$birth_rates_pc[1:Ntips],
    y=simulation$death_rates_pc[1:Ntips],
type='p',
xlab="pc birth rate",
ylab="pc death rate",
main="Per-capita birth \& death rates across tips (BM model)",
las=1)

```
```

\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#

# Example 2

# Generate tree, with rates evolving under a binary-state model

Q = get_random_mk_transition_matrix(Nstates=2, rate_model="ER", max_rate=0.1)
parameters = list(Nstates = 2,
state_birth_rates = c(1,1.5),
state_death_rates = 0.5,
transition_matrix = Q)
simulation = generate_tree_with_evolving_rates(parameters,
rate_model='Mk',

```
```

    max_tips=1000,
    include_rates=TRUE)
    tree = simulation$tree
Ntips = length(tree$tip.label)

# plot distribution of per-capita birth rates of tips

rates = simulation\$birth_rates_pc[1:Ntips]
barplot(table(rates)/length(rates),
xlab="rate",
main="Distribution of pc birth rates across tips (Mk model)")

```
geographic_acf

Phylogenetic autocorrelation function of geographic locations.

\section*{Description}

Given a rooted phylogenetic tree and geographic coordinates (latitudes \& longitudes) of each tip, calculate the phylogenetic autocorrelation function (ACF) of the geographic locations. The ACF is a function of phylogenetic distance \(x\), i.e., \(\operatorname{ACF}(x)\) is the autocorrelation between two tip locations conditioned on the tips having phylogenetic ("patristic") distance \(x\).

\section*{Usage}
geographic_acf( trees, tip_latitudes, tip_longitudes, Npairs \(=10000\), Nbins = NULL, min_phylodistance \(=0\), max_phylodistance = NULL, uniform_grid = FALSE, phylodistance_grid = NULL)

\section*{Arguments}
trees Either a single rooted tree of class "phylo", or a list of multiple such trees.
tip_latitudes Either a numeric vector of size Ntips (if trees was a single tree), specifying the latitudes (decimal degrees) of the tree's tips, or a list of such numeric vectors (if trees contained multiple trees) specifying the latitudes of each tree's tips. Note that tip_latitudes[k][i] must correspond to the i-th tip in the k-th input tree, i.e. as listed in trees[[k]]\$tip.label. By convention, positive latitudes correspond to the northern hemisphere.
tip_longitudes Similar to tip_latitudes, but listing the latitudes (decimal degrees) of each tip in each input tree. By convention, positive longitudes correspond to the hemisphere East of the prime meridian.

Npairs Maximum number of random tip pairs to draw from each tree. A greater number of tip pairs will improve the accuracy of the estimated ACF within each distance bin. Tip pairs are drawn randomly with replacement, if Npairs is lower than the number of tip pairs in a tree. If Npairs=Inf, then every tip pair of every tree is included exactly once (for small and moderately sized trees this is recommended).
Nbins Number of phylogenetic distance bins to consider. A greater number of bins will increase the resolution of the ACF as a function of phylogenetic distance, but will decrease the number of tip pairs falling within each bin (which reduces the accuracy of the estimated ACF). If NULL, then Nbins is automatically and somewhat reasonably chosen based on the size of the input trees.
min_phylodistance
Numeric, minimum phylogenetic distance to conssider. Only relevant if phylodistance_grid is NULL.
max_phylodistance
Numeric, optional maximum phylogenetic distance to consider. If NULL, this is automatically set to the maximum phylodistance between any two tips.
uniform_grid Logical, specifying whether the phylodistance grid should be uniform, i.e., with equally sized phylodistance bins. If FALSE, then the grid is chosen non-uniformly (i.e., each bin has different size) such that each bin roughly contains the same number of tip pairs. Only relevant if phylodistance_grid is NULL. It is generally recommended to keep uniform_grid=FALSE, to avoid uneven estimation errors across bins.
phylodistance_grid
Numeric vector, optional explicitly specified phylodistance bins (left boundaries thereof) on which to evaluate the ACF. Must contain non-negative numbers in strictly ascending order. Hence, the first bin will range from phylodistance_grid[1] to phylodistance_grid[2], while the last bin will range from tail (phylodistance_grid, 1) to max_phylodistance. Can be used as an alternative to Nbins. If non-NULL, then Nbins, min_phylodistance and uniform_grid are irrelevant.

\section*{Details}

The autocorrelation between random geographic locations is defined as the expectation of \(<X, Y>\), where \(<>\) is the scalar product and \(X\) and \(Y\) are the unit vectors pointing towards the two random locations on the sphere. For comparison, for a spherical Brownian Motion model with constant diffusivity \(D\) and radius \(r\) the autocorrelation function is given by \(A C F(t)=e^{-2 D t / r^{2}}\) (see e.g. simulate_sbm). Note that this function assumes that Earth is a perfect sphere.

The phylogenetic autocorrelation function (ACF) of the geographic distribution of species can give insight into the dispersal processes shaping species distributions over global scales. An ACF that decays slowly with increasing phylogenetic distance indicates a strong phylogenetic conservatism of the location and thus slow dispersal, whereas a rapidly decaying ACF indicates weak phylogenetic conservatism and thus fast dispersal. Similarly, if the mean distance between two random tips increases with phylogenetic distance, this indicates a phylogenetic autocorrelation of species locations. Here, phylogenetic distance between tips refers to their patristic distance, i.e. the minimum cumulative edge length required to connect the two tips.

Since the phylogenetic distances between all possible tip pairs do not cover a continuoum (as there is only a finite number of tips), this function randomly draws tip pairs from the tree, maps them
onto a finite set of phylodistance bins and then estimates the ACF for the centroid of each bin based on tip pairs in that bin. In practice, as a next step one would usually plot the estimated ACF (returned vector autocorrelations) over the centroids of the phylodistance bins (returned vector phylodistances). When multiple trees are provided as input, then the ACF is first calculated separately for each tree, and then averaged across trees (weighted by the number of tip pairs included from each tree in each bin).
Phylogenetic distance bins can be specified in two alternative ways: Either a set of bins (phylodistance grid) is automatically calculated based on the provided Nbins, min_phylodistance, max_phylodistance and uniform_grid, or a phylodistance grid is explicitly provided via phylodistance_grid and max_phylodistance.
The trees may include multi-furcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child). If edge lengths are missing from the trees, then every edge is assumed to have length 1 . The input trees must be rooted at some node for technical reasons (see function root_at_node), but the choice of the root node does not influence the result.
This function assumes that each tip is assigned exactly one geographic location. This might be problematic in situations where each tip covers multiple geographic locations, for example if tips are species and multiple individuals were sampled from each species. In that case, one might consider representing each individual as a separate tip in the tree, so that each tip has exactly one geographic location.

\section*{Value}

A list with the following elements:
```

success Logical, indicating whether the calculation was successful. If FALSE, an additional element error (character) is returned that provides a brief description of the error that occurred; in that case all other return values may be undefined.
phylodistances Numeric vector of size Nbins, storing the center of each phylodistance bin in increasing order. This is equal to $0.5 *$ (left_phylodistances+right_phylodistances). Typically, you will want to plot autocorrelations over phylodistances.
left_phylodistances

```

Numeric vector of size Nbins, storing the left boundary of each phylodistance bin in increasing order.
right_phylodistances
Numeric vector of size Nbins, storing the right boundary of each phylodistance bin in increasing order.
autocorrelations
Numeric vector of size Nbins, storing the estimated geographic autocorrelation for each phylodistance bin.
```

std_autocorrelations

```

Numeric vector of size Nbins, storing the standard deviation of geographic autocorrelations encountered in each phylodistance bin. Note that this is not the standard error of the estimated ACF; it is a measure for how different the geographic locations are between tip pairs within each phylodistance bin.
mean_geodistances
Numeric vector of size Nbins, storing the mean geographic distance between tip pairs in each distance bin, in units of sphere radii. If you want geographic
distances in km , you need to multiply these by Earth's mean radius in km (about 6371). If multiple input trees were provided, this is the average across all trees, weighted by the number of tip pairs included from each tree in each bin.
std_geodistances
Numeric vector of size Nbins, storing the standard deviation of geographic distances between tip pairs in each distance bin, in units of sphere radii.
Npairs_per_distance
Integer vector of size Nbins, storing the number of random tip pairs associated with each distance bin.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

consentrait_depth, get_trait_acf

```

\section*{Examples}
```


# generate a random tree

tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=1000)\$tree

# simulate spherical Brownian Motion on the tree

simul = simulate_sbm(tree, radius=1, diffusivity=0.1)
tip_latitudes = simul$tip_latitudes
tip_longitudes = simul$tip_longitudes

# calculate geographical autocorrelation function

ACF = geographic_acf(tree, tip_latitudes, tip_longitudes, Nbins=10)

# plot ACF (autocorrelation vs phylogenetic distance)

plot(ACF$phylodistances, ACF$autocorrelations, type="l", xlab="distance", ylab="ACF")

```
get_all_distances_to_root
    Get distances of all tips and nodes to the root.

\section*{Description}

Given a rooted phylogenetic tree, calculate the phylogenetic distance (cumulative branch length) of the root to each tip and node.

\section*{Usage}
```

get_all_distances_to_root(tree, as_edge_count=FALSE)

```

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
as_edge_count Logical, specifying whether distances should be counted in number of edges, rather than cumulative edge length. This is the same as if all edges had length 1.

\section*{Details}

If tree\$edge.length is missing, then every edge in the tree is assumed to be of length 1 . The tree may include multi-furcations as well as mono-furcations (i.e. nodes with only one child). The asymptotic average time complexity of this function is O (Nedges), where Nedges is the number of edges in the tree.

\section*{Value}

A numeric vector of size Ntips+Nnodes, with the i-th element being the distance (cumulative branch length) of the i-th tip or node to the root. Tips are indexed \(1, . ., \mathrm{Ntips}\) and nodes are indexed (Ntips+1),..,(Ntips+Nnodes).

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

get_pairwise_distances

```

\section*{Examples}
```


# generate a random tree

Ntips = 1000
tree = generate_random_tree(list(birth_rate_intercept=1,
death_rate_intercept=0.5),
max_tips=Ntips)\$tree

# calculate distances to root

all_distances = get_all_distances_to_root(tree)

# extract distances of nodes to root

node_distances = all_distances[(Ntips+1):(Ntips+tree\$Nnode)]

# plot histogram of distances (across all nodes)

hist(node_distances, xlab="distance to root", ylab="\# nodes", prob=FALSE);

```
get_all_node_depths Get the phylogenetic depth of each node in a tree.

\section*{Description}

Given a rooted phylogenetic tree, calculate the phylogenetic depth of each node (mean distance to its descending tips).

\section*{Usage}
get_all_node_depths(tree, as_edge_count=FALSE)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
as_edge_count Logical, specifying whether distances should be counted in number of edges, rather than cumulative edge length. This is the same as if all edges had length 1.

\section*{Details}

If tree\$edge.length is missing, then every edge in the tree is assumed to be of length 1 . The tree may include multi-furcations as well as mono-furcations (i.e. nodes with only one child). The asymptotic average time complexity of this function is O (Nedges), where Nedges is the number of edges in the tree.

\section*{Value}

A numeric vector of size Nnodes, with the i-th element being the mean distance of the i-th node to all of its tips.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

get_all_distances_to_root

```

\section*{Examples}
```


# generate a random tree

Ntips = 1000
tree = generate_random_tree(list(birth_rate_intercept=1,
death_rate_intercept=0.5),
max_tips=Ntips)\$tree

# calculate node phylogenetic depths

```
```

node_depths = get_all_node_depths(tree)

# plot histogram of node depths

hist(node_depths, xlab="phylogenetic depth", ylab="\# nodes", prob=FALSE);

```
get_all_pairwise_distances

Get distances between all pairs of tips and/or nodes.

\section*{Description}

Calculate phylogenetic ("patristic") distances between all pairs of tips or nodes in the tree, or among a subset of tips/nodes requested.

\section*{Usage \\ get_all_pairwise_distances( tree, only_clades = NULL, as_edge_counts = FALSE, check_input = TRUE)}

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
only_clades Optional integer vector or character vector, listing tips and/or nodes to which to restrict pairwise distance calculations. If an integer vector, it must list indices of tips (from 1 to Ntips) and/or nodes (from Ntips+1 to Ntips+Nnodes). If a character vector, it must list tip and/or node names.
For example, if only_clades=c('apple','lemon', 'pear'), then only the distance between 'apple' and 'lemon', between 'apple' and 'pear', and between 'lemon' and 'pear' are calculated. If only_clades==NULL, then this is equivalent to only_clades=c(1:(Ntips+Nnodes)).
check_input Logical, whether to perform basic validations of the input data. If you know for certain that your input is valid, you can set this to FALSE to reduce computation time.
as_edge_counts Logical, specifying whether distances should be calculated in terms of edge counts, rather than cumulative edge lengths. This is the same as if all edges had length 1.

\section*{Details}

The "patristic distance" between two tips and/or nodes is the shortest cumulative branch length that must be traversed along the tree in order to reach one tip/node from the other.This function returns a square distance matrix, containing the patristic distance between all possible pairs of tips/nodes in the tree (or among the ones provided in only_clades).

If tree\$edge. length is missing, then each edge is assumed to be of length 1 ; this is the same as setting as_edge_counts=TRUE. The tree may include multi-furcations as well as mono-furcations (i.e. nodes with only one child). The input tree must be rooted at some node for technical reasons (see function root_at_node), but the choice of the root node does not influence the result. If only_clades is a character vector, then tree\$tip. label must exist. If node names are included in only_clades, then tree\$node. label must also exist.

The asymptotic average time complexity of this function for a balanced binary tree is \(\mathrm{O}\left(\mathrm{NC}^{*} \mathrm{NC} * \mathrm{Nanc}\right.\) + Ntips), where NC is the number of tips/nodes considered (e.g., the length of only_clades) and Nanc is the average number of ancestors per tip.

\section*{Value}

A 2D numeric matrix of size NC x NC, where NC is the number of tips/nodes considered, and with the entry in row \(r\) and column \(c\) listing the distance between the \(r\)-th and the c-th clade considered (e.g., between clades only_clades[r] and only_clades[c]). Note that if only_clades was specified, then the rows and columns in the returned distance matrix correspond to the entries in only_clades (i.e., in the same order). If only_clades was NULL, then the rows and columns in the returned distance matrix correspond to tips ( \(1, . ., \mathrm{Ntips}\) ) and nodes (Ntips+1,..,Ntips+Nnodes)

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

get_all_distances_to_root,get_pairwise_distances

```

\section*{Examples}
```


# generate a random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),Ntips)\$tree

# calculate distances between all internal nodes

only_clades = c((Ntips+1):(Ntips+tree\$Nnode))
distances = get_all_pairwise_distances(tree, only_clades)

# reroot at some other node

tree = root_at_node(tree, new_root_node=20, update_indices=FALSE)
new_distances = get_all_pairwise_distances(tree, only_clades)

# verify that distances remained unchanged

plot(distances,new_distances,type='p')

```

\section*{Description}

Given a tree in standard "phylo" format, calculate an alternative representation of the tree structure as a list of tips/nodes with basic information on parents, children and incoming edge lengths. This function is analogous to the function read. tree. nodes in the R package phybase.

\section*{Usage \\ get_clade_list(tree, postorder=FALSE, missing_value=NA)}

\section*{Arguments}
tree A tree of class "phylo". If postorder==TRUE, then the tree must be rooted.
postorder Logical, specifying whether nodes should be ordered and indexed in postorder traversal, i.e. with the root node listed last. Note that regardless of the value of postorder, tips will always be listed first and indexed in the order in which they are listed in the input tree.
missing_value Value to be used to denote missing information in the returned arrays, for example to denote the (non-existing) parent of the root node.

\section*{Details}

This function is analogous to the function read. tree. nodes in the R package phybase v1.4, but becomes multiple orders of magnitude faster than the latter for large trees (i.e. with 1000-1000,000 tips). Specifically, calling get_clade_list with postorder=TRUE and missing_value=-9 on a bifurcating tree yields a similar behavior as calling read.tree.nodes with the argument "name" set to the tree's tip labels.
The input tree can include monofurcations, bifurcations and multifurcations. The asymptotic average time complexity of this function is O (Nedges), where Nedges is the number of edges in the tree.

\section*{Value}

A named list with the following elements:
success Logical, indicating whether model fitting succeeded. If FALSE, the returned list will include an additional "error" element (character) providing a description of the error; in that case all other return variables may be undefined.
Nsplits The maximum number of children of any node in the tree. For strictly bifurcating trees this will be 2 .
\begin{tabular}{ll} 
clades & \begin{tabular}{l} 
2D integer matrix of size Nclades \(x\) (Nsplits+1), with every row representing a \\
specific tip/node in the tree. If postorder==FALSE, then rows are in the same \\
order as tips/nodes in the original tree, otherwise nodes (but not tips) will be \\
re-ordered and re-indexed in postorder fashion, with the root being the last row. \\
The first column lists the parent node index, the remaining columns list the child \\
tip/node indices. For the root, the parent index will be set to missing_value; for \\
the tips, the child indices will be set to missing_value. For nodes with fewer \\
than Nsplits children, superfluous column entries will also be missing_value.
\end{tabular} \\
lengths & \begin{tabular}{l} 
Numeric vector of size Nclades, listing the lengths of the incoming edges at each \\
tip/node in clades. For the root, the value will be missing_value. If the tree's \\
edge_length was NULL, then lengths will be NULL as well.
\end{tabular} \\
old2new_clade \(\quad\)\begin{tabular}{l} 
Integer vector of size Nclades, mapping old tip/node indices to tip/node indices \\
in the returned clades and lengths arrays. If postorder==FALSE, this will \\
simply be c \((1:\) Nclades \()\).
\end{tabular}
\end{tabular}

\section*{Author(s)}

Stilianos Louca

\section*{Examples}
\# generate a random bifurcating tree
tree \(=\) generate_random_tree(list(birth_rate_intercept=1), max_tips=100)\$tree
\# get tree structure as clade list
\# then convert into a similar format as would be
\# returned by phybase::read.tree.nodes v1.4
results = get_clade_list(tree, postorder=TRUE, missing_value=-9)
nodematrix \(=\) cbind( results\$clades,
results\$lengths,
matrix(-9, nrow=nrow(results\$clades), ncol=3))
phybaseformat \(=\) list \((\operatorname{nodes}=\) nodematrix, names \(=\) tree\$tip.label, root \(=\) TRUE)
```

get_independent_contrasts

```

Phylogenetic independent contrasts for continuous traits.

\section*{Description}

Calculate phylogenetic independent contrasts (PICs) for one or more continuous traits on a phylogenetic tree, as described by Felsenstein (1985). The trait states are assumed to be known for all tips of the tree. PICs are commonly used to calculate correlations between multiple traits, while accounting for shared evolutionary history at the tips. This function also returns an estimate for the state of the root or, equivalently, the phylogenetically weighted mean of the tip states (Garland et al., 1999).

\section*{Usage}
```

get_independent_contrasts(tree,
tip_states,
scaled = TRUE,
only_bifurcations = FALSE,
check_input = TRUE)

```

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
tip_states A numeric vector of size Ntips, or a 2D numeric matrix of size Ntips x Ntraits, specifying the numeric state of each trait at each tip in the tree.
scaled Logical, specifying whether to divide (standardize) PICs by the square root of their expected variance, as recommended by Felsenstein (1985).
only_bifurcations
Logical, specifying whether to only calculate PICs for bifurcating nodes. If FALSE, then multifurcations are temporarily expanded to bifurcations, and an additional PIC is calculated for each created bifurcation. If TRUE, then multifurcations are not expanded and PICs will not be calculated for them.
check_input Logical, specifying whether to perform some basic checks on the validity of the input data. If you are certain that your input data are valid, you can set this to FALSE to reduce computation.

\section*{Details}

If the tree is bifurcating, then one PIC is returned for each node. If multifurcations are present and only_bifurcations==FALSE, these are internally expanded to bifurcations and an additional PIC is returned for each such bifurcation. PICs are never returned for monofurcating nodes. Hence, in general the number of returned PICs is the number of bifurcations in the tree, potentially after multifurcations have been expanded to bifurcations (if only_bifurcations==FALSE).
If tree\$edge. length is missing, each edge in the tree is assumed to have length 1 . The tree may include multifurcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child). Edges with length 0 will be adjusted internally to some tiny length (chosen to be much smaller than the smallest non-zero length).

Tips must be represented in tip_states in the same order as in tree\$tip.label. The vector tip_states need not include item names; if it does, however, they are checked for consistency (if check_input==TRUE).
The function has asymptotic time complexity \(O\) (Nedges x Ntraits). It is more efficient to calculate PICs of multiple traits with the same function call, than to calculate PICs for each trait separately. For a single trait, this function is equivalent to the function ape: : pic, with the difference that it can handle multifurcating trees.

\section*{Value}

A list with the following elements:

PICs A numeric vector (if tip_states is a vector) or a numeric matrix (if tip_states is a matrix), listing the phylogenetic independent contrasts for each trait and for each bifurcating node (potentially after multifurcations have been expanded). If a matrix, then PICs [: , T] will list the PICs for the T-th trait. Note that the order of elements in this vector (or rows, if PICs is a matrix) is not necesssarily the order of nodes in the tree, and that PICs may contain fewer or more elements (or rows) than there were nodes in the input tree.
distances Numeric vector of the same size as PICs. The "evolutionary distances" (or time) corresponding to the PICs under a Brownian motion model of trait evolution. These roughly correspond to the cumulative edge lengths between sister nodes from which PICs were calculated; hence their units are the same as those of edge lengths. They do not take into account the actual trait values. See Felsenstein (1985) for details.
nodes Integer vector of the same size as PICs, listing the node indices for which PICs are returned. If only_bifurcations==FALSE, then this vector may contain NAs, corresponding to temporary nodes created during expansion of multifurcations.
If only_bifurcations==TRUE, then this vector will only list nodes that were bifurcating in the input tree. In that case, PICs[1] will correspond to the node with name tree\$node.label[nodes[1]], whereas PICs[2] will correspond to the node with name tree\$node.label[nodes[2]], and so on.
root_state Numeric vector of size Ntraits, listing the globally estimated state for the root or, equivalently, the phylogenetically weighted mean of the tip states.
root_standard_error
Numeric vector of size Ntraits, listing the phylogenetically estimated standard errors of the root state under a Brownian motion model. The standard errors have the same units as the traits and depend both on the tree topology as well as the tip states. Calculated according to the procedure described by Garland et al. (1999, page 377).
root_CI95 Numeric vector of size Ntraits, listing the radius (half width) of the \(95 \%\) confidence interval of the root state. Calculated according to the procedure described by Garland et al. (1999, page 377). Note that in contrast to the CI95 returned by the ace function in the ape package (v. 0.5-64), root_CI95 has the same units as the traits and depends both on the tree topology as well as the tip states.

\section*{Author(s)}

Stilianos Louca

\section*{References}
J. Felsenstein (1985). Phylogenies and the Comparative Method. The American Naturalist. 125:115.
T. Garland Jr., P. E. Midford, A. R. Ives (1999). An introduction to phylogenetically based statistical methods, with a new method for confidence intervals on ancestral values. American Zoologist. 39:374-388.

\section*{See Also}
```

asr_independent_contrasts

```

\section*{Examples}
```


# generate random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),Ntips)\$tree

# simulate a continuous trait

tip_states = simulate_bm_model(tree, diffusivity=0.1, include_nodes=FALSE)\$tip_states;

# calculate PICs

results = get_independent_contrasts(tree, tip_states, scaled=TRUE, only_bifurcations=TRUE)

# assign PICs to the bifurcating nodes in the input tree

PIC_per_node = rep(NA, tree$Nnode)
valids = which(!is.na(results$nodes))
PIC_per_node[results$nodes[valids]] = results$PICs[valids]

```
get_mrca_of_set Most recent common ancestor of a set of tips/nodes.

\section*{Description}

Given a rooted phylogenetic tree and a set of tips and/or nodes ("descendants"), calculate the most recent common ancestor (MRCA) of those descendants.

\section*{Usage \\ get_mrca_of_set(tree, descendants)}

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
descendants An integer vector or character vector, specifying the tips/nodes for which to find the MRCA. If an integer vector, it must list indices of tips (from 1 to Ntips) and/or nodes (from Ntips+1 to Ntips+Nnodes), where Ntips and Nnodes is the number of tips and nodes in the tree, respectively. If a character vector, it must list tip and/or node names. In this case tree must include tip.label, as well as node. label if nodes are included in descendants.

\section*{Details}

The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child). Duplicate entries in descendants are ignored.

\section*{Value}

An integer in \(1, . .,(\) Ntips+Nnodes), representing the MRCA using the same index as in tree\$edge. If the MRCA is a tip, then this index will be in \(1, . .\), Ntips. If the MRCA is a node, then this index will be in (Ntips+1),..,(Ntips+Nnodes).

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

get_pairwise_mrcas, get_tips_for_mrcas

```

\section*{Examples}
```


# generate a random tree

Ntips = 1000
tree = generate_random_tree(list(birth_rate_intercept=1),Ntips)\$tree

# pick 3 random tips or nodes

descendants = sample.int(n=(Ntips+tree\$Nnode), size=3, replace=FALSE)

# calculate MRCA of picked descendants

mrca = get_mrca_of_set(tree, descendants)

```
get_pairwise_distances
Get distances between pairs of tips or nodes.

\section*{Description}

Calculate phylogenetic ("patristic") distances between tips or nodes in some list A and tips or nodes in a second list B of the same size.

\section*{Usage}
get_pairwise_distances(tree, A, B, as_edge_counts=FALSE, check_input=TRUE)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.

A
An integer vector or character vector of size Npairs, specifying the first of the two members of each pair for which to calculate the distance. If an integer vector, it must list indices of tips (from 1 to Ntips) and/or nodes (from Ntips+1 to Ntips+Nnodes). If a character vector, it must list tip and/or node names.

An integer vector or character vector of size Npairs, specifying the second of the two members of each pair for which to calculate the distance. If an integer vector, it must list indices of tips (from 1 to Ntips) and/or nodes (from Ntips+1 to Ntips+Nnodes). If a character vector, it must list tip and/or node names.
check_input Logical, whether to perform basic validations of the input data. If you know for certain that your input is valid, you can set this to FALSE to reduce computation time.
as_edge_counts Logical, specifying whether distances should be calculated in terms of edge counts, rather than cumulative edge lengths. This is the same as if all edges had length 1 .

\section*{Details}

The "patristic distance" between two tips and/or nodes is the shortest cumulative branch length that must be traversed along the tree in order to reach one tip/node from the other. Given a list of tips and/or nodes A, and a 2nd list of tips and/or nodes B of the same size, this function will calculate patristic distance between each pair ( \(\mathrm{A}[\mathrm{i}], \mathrm{B}[\mathrm{i}]\) ), where \(\mathrm{i}=1,2, .\). ,Npairs.
If tree\$edge. length is missing, then each edge is assumed to be of length 1 ; this is the same as setting as_edge_counts=TRUE. The tree may include multi-furcations as well as mono-furcations (i.e. nodes with only one child). The input tree must be rooted at some node for technical reasons (see function root_at_node), but the choice of the root node does not influence the result. If A and/or B is a character vector, then tree\$tip. label must exist. If node names are included in A and/or B, then tree\$node. label must also exist.
The asymptotic average time complexity of this function for a balanced binary tree is \(\mathrm{O}(\mathrm{Ntips}+\mathrm{Npairs} * \log 2(\mathrm{Ntips})\) ).

\section*{Value}

A numeric vector of size Npairs, with the i-th element being the patristic distance between the tips/nodes \(\mathrm{A}[\mathrm{i}]\) and \(\mathrm{B}[\mathrm{i}]\).

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

get_all_distances_to_root,get_all_pairwise_distances

```

\section*{Examples}
```


# generate a random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),Ntips)\$tree

# pick 3 random pairs of tips or nodes

Npairs = 3
A = sample.int(n=(Ntips+tree$Nnode), size=Npairs, replace=FALSE)
B = sample.int(n=(Ntips+tree$Nnode), size=Npairs, replace=FALSE)

```
```


# calculate distances

distances = get_pairwise_distances(tree, A, B)

# reroot at some other node

tree = root_at_node(tree, new_root_node=20, update_indices=FALSE)
new_distances = get_pairwise_distances(tree, A, B)

# verify that distances remained unchanged

print(distances)
print(new_distances)

```
get_pairwise_mrcas Get most recent common ancestors of tip/node pairs.

\section*{Description}

Given a rooted phylogenetic tree and one or more pairs of tips and/or nodes, for each pair of tips/nodes find the most recent common ancestor (MRCA). If one clade is descendant of the other clade, the latter will be returned as MRCA.

\section*{Usage}
get_pairwise_mrcas(tree, A, B, check_input=TRUE)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.

A
An integer vector or character vector of size Npairs, specifying the first of the two members of each pair of tips/nodes for which to find the MRCA. If an integer vector, it must list indices of tips (from 1 to Ntips) and/or nodes (from Ntips+1 to Ntips+Nnodes). If a character vector, it must list tip and/or node names.
B An integer vector or character vector of size Npairs, specifying the second of the two members of each pair of tips/nodes for which to find the MRCA. If an integer vector, it must list indices of tips (from 1 to Ntips) and/or nodes (from Ntips+1 to Ntips+Nnodes). If a character vector, it must list tip and/or node names.
check_input Logical, whether to perform basic validations of the input data. If you know for certain that your input is valid, you can set this to FALSE to reduce computation time.

\section*{Details}

The tree may include multi-furcations as well as mono-furcations (i.e. nodes with only one child). If tree\$edge. length is missing, then each edge is assumed to be of length 1 . Note that in some cases the MRCA of two tips may be a tip, namely when both tips are the same.

If \(A\) and/or \(B\) is a character vector, then tree \(\$\) tip. label must exist. If node names are included in A and/or B, then tree\$node. label must also exist.
The asymptotic average time complexity of this function is O (Nedges), where Nedges is the number of edges in the tree.

\section*{Value}

An integer vector of size Npairs with values in 1,..,Ntips (tips) and/or in (Ntips+1),..,(Ntips+Nnodes) (nodes), with the i-th element being the index of the MRCA of tips/nodes A[i] and B[i].

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
get_mrca_of_set, get_tips_for_mrcas

\section*{Examples}
```


# generate a random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),Ntips)\$tree

# pick 3 random pairs of tips or nodes

Npairs = 3
A = sample.int(n=(Ntips+tree$Nnode), size=Npairs, replace=FALSE)
B = sample.int(n=(Ntips+tree$Nnode), size=Npairs, replace=FALSE)

# calculate MRCAs

MRCAs = get_pairwise_mrcas(tree, A, B)

```
get_random_diffusivity_matrix

Create a random diffusivity matrix for a Brownian motion model.

\section*{Description}

Create a random diffusivity matrix for a Brownian motion model of multi-trait evolution. This may be useful for testing purposes. The diffusivity matrix is drawn from the Wishart distribution of symmetric, nonnegative-definite matrixes:
\[
D=X^{T} \cdot X, \quad X[i, j] \sim N(0, V), \quad i=1, . ., n, j=1, . ., p
\]
where n is the degrees of freedom, p is the number of traits and V is a scalar scaling.

\section*{Usage}
```

get_random_diffusivity_matrix(Ntraits, degrees=NULL, V=1)

```

\section*{Arguments}

Ntraits The number of traits modelled. Equal to the number of rows and the number of columns of the returned matrix.
degrees Degrees of freedom for the Wishart distribution. Must be equal to or greater than Ntraits. Can also be NULL, which is the same as setting it equal to Ntraits.
V Positive number. A scalar scaling for the Wishart distribution.

\section*{Value}

A real-valued quadratic symmetric non-negative definite matrix of size Ntraits x Ntraits. Almost surely (in the probabilistic sense), this matrix will be positive definite.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

get_random_mk_transition_matrix, simulate_bm_model

```

\section*{Examples}
```


# generate a 5x5 diffusivity matrix

D = get_random_diffusivity_matrix(Ntraits=5)
\# check that it is indeed positive definite
if(all(eigen(D)\$values>0)){
cat("Indeed positive definite\n");
}else{
cat("Not positive definite\n");
}

```
get_random_mk_transition_matrix
                                    Create a random transition matrix for an Mk model.

\section*{Description}

Create a random transition matrix for a fixed-rates continuous-time Markov model of discrete trait evolution ("Mk model"). This may be useful for testing purposes.

\section*{Usage}
```

get_random_mk_transition_matrix(Nstates, rate_model, min_rate=0, max_rate=1)

```

\section*{Arguments}
\[
\begin{array}{ll}
\text { Nstates } & \begin{array}{l}
\text { The number of distinct states represented in the transition matrix (number of } \\
\text { rows \& columns). }
\end{array} \\
\text { rate_model } & \begin{array}{l}
\text { Rate model that the transition matrix must satisfy. Can be "ER" (all rates equal), } \\
\text { "SYM" (transition rate } i->j \text { is equal to transition rate } j->\mathrm{i} \text { ), "ARD" (all rates can } \\
\text { be different) or "SUEDE" (only stepwise transitions } \mathrm{i}->\mathrm{i}+1 \text { and } \mathrm{i}->\mathrm{i}-1 \text { allowed, } \\
\text { all 'up' transitions are equal, all 'down' transitions are equal). }
\end{array} \\
\text { min_rate } & \begin{array}{l}
\text { A non-negative number, specifying the minimum rate in off-diagonal entries of } \\
\text { the transition matrix. }
\end{array} \\
\text { max_rate } & \begin{array}{l}
\text { A non-negative number, specifying the maximum rate in off-diagonal entries of } \\
\text { the transition matrix. Must not be smaller than min_rate. }
\end{array}
\end{array}
\]

\section*{Value}

A real-valued quadratic matrix of size Nstates \(x\) Nstates, representing a transition matrix for an Mk model. Each row will sum to 0 . The [ \(\mathrm{r}, \mathrm{c}]\)-th entry represents the transition rate \(\mathrm{r} \rightarrow \mathrm{c}\). The number of unique off-diagonal rates will depend on the rate_model chosen.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
exponentiate_matrix, get_stationary_distribution

\section*{Examples}
\# generate a \(5 \times 5\) Markov transition rate matrix
Q = get_random_mk_transition_matrix(Nstates=5, rate_model="ARD")

\section*{Description}

Calculate the relative evolutionary divergence (RED) of each node in a rooted phylogenetic tree. The RED of a node is a measure of its relative placement between the root and the node's descending tips (Parks et al. 2018). The root's RED is always 0 , the RED of each tip is 1 , and the RED of each node is between 0 and 1 .

\section*{Usage}
```

get_reds(tree)

```

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.

\section*{Details}

The RED of a node measures its relative placement between the root and the node's descending tips (Parks et al. 2018). The root's RED is set to 0 . Traversing from root to tips (preorder traversal), for each node the RED is set to \(P+(a /(a+b)) \cdot(1-P)\), where \(P\) is the RED of the node's parent, \(a\) is the edge length connecting the node to its parent, and \(b\) is the average distance from the node to its descending tips. The RED of a tip would always be 1 .

The RED may be useful for defining taxonomic ranks based on a molecular phylogeny (e.g. see Parks et al. 2018). This function is similar to the PhyloRank v0.0.27 script published by Parks et al. (2018).

The time complexity of this function is O (Nedges). The input tree may include multi-furcations (i.e. nodes with more than 2 children) as well as mono-furcations (i.e. nodes with only one child). If tree\$edge. length is NULL, then all edges in the input tree are assumed to have length 1.

\section*{Value}

A numeric vector of length Nnodes, listing the RED of each node in the tree. The REDs of tips are not included, since these would always be equal to 1 .

\section*{Author(s)}

Stilianos Louca

\section*{References}
D. H. Parks, M. Chuvochina et al. (2018). A proposal for a standardized bacterial taxonomy based on genome phylogeny. bioRxiv 256800. DOI:10.1101/256800

\section*{Examples}
```


# generate a random tree

params = list(birth_rate_intercept=1, death_rate_intercept=0.8)
tree = generate_random_tree(params, max_time=100, coalescent=FALSE)\$tree

# calculate and print REDs

REDs = get_reds(tree)
print(REDs)

```
```

get_stationary_distribution

```

Stationary distribution of Markov transition matrix.

\section*{Description}

Calculate the stationary probability distribution vector p for a transition matrix Q of a continuoustime Markov chain. That is, calculate \(p \in[0,1]^{n}\) such that \(\operatorname{sum}(p)==0\) and \(p^{T} Q=0\).

\section*{Usage}
get_stationary_distribution(Q)

\section*{Arguments}

Q A valid transition rate matrix of size Nstates \(x\) Nstates, i.e. a quadratic matrix in which every row sums up to zero.

\section*{Details}

A stationary distribution of a discrete-state continuous-time Markov chain is a probability distribution across states that remains constant over time, i.e. \(p^{T} Q=0\). Note that in some cases (i.e. if Q is not irreducible), there may be multiple distinct stationary distributions. In that case, which one is returned by this function is unpredictable. Internally, p is estimated by stepwise minimization of the norm of \(p^{T} Q\), starting with the vector p in which every entry equals \(1 /\) Nstates.

\section*{Value}

A numeric vector of size Nstates and with non-negative entries, satisfying the conditions \(\mathrm{p} \% * \% \mathrm{Q}==0\) and \(\operatorname{sum}(p)==1.0\).

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
exponentiate_matrix

\section*{Examples}
```


# generate a random 5x5 Markov transition matrix

Q = get_random_mk_transition_matrix(Nstates=5, rate_model="ARD")

# calculate stationary probability distribution

p = get_stationary_distribution(Q)
print(p)

# test correctness (p*Q should be 0, apart from rounding errors)

```
```

    cat(sprintf("max(abs(p*Q)) = %g\n",max(abs(p %*% Q))))
    ```
get_subtrees_at_nodes Extract subtrees descending from specific nodes.

\section*{Description}

Given a tree and a list of focal nodes, extract the subtrees descending from those focal nodes, with the focal nodes becoming the roots of the extracted subtrees.

\section*{Usage}
get_subtrees_at_nodes(tree, nodes)

\section*{Arguments}
tree A tree of class "phylo".
nodes Character vector or integer vector specifying the names or indices, respectively, of the focal nodes at which to extract the subtrees. If an integer vector, entries must be between 1 and tree \(\$\) Nnode. If a character vector, each entry must be a valid entry in tree\$node. label.

\section*{Details}

The input tree need not be rooted, however "descendance" from a focal node is inferred based on the direction of edges in tree\$edge. The input tree may include multi-furcations (i.e. nodes with more than 2 children) as well as mono-furcations (i.e. nodes with only one child).

\section*{Value}

A list with the following elements:
\begin{tabular}{ll} 
subtrees & \begin{tabular}{l} 
List of the same length as nodes, with each element being a new tree of class \\
"phylo", containing the subtrees descending from the focal nodes. Each subtree \\
will be rooted at the corresponding focal node.
\end{tabular} \\
new2old_tip \(\quad\)\begin{tabular}{l} 
List of the same length as nodes, with the \(n\)-th element being an integer vector \\
with values in 1,..,Ntips, mapping tip indices of the n-th subtree to tip indices in \\
the original tree. In particular, tree\$tip.label[new2old_tip[[n]]] will be \\
equal to subtrees[[n]]\$tip.label.
\end{tabular} \\
new2old_node \(\quad\)\begin{tabular}{l} 
List of the same length as nodes, with the n-th element being an integer vector \\
with values in 1,..,Nnodes, mapping node indices of the n-th subtree to node \\
indices in the original tree.
\end{tabular} \\
\begin{tabular}{l} 
For example, new2old_node[[2]][1] is the index that the 1st node of the 2nd \\
subtree had within the original tree. In particular, tree\$node.label[new2old_node[[n] \\
will be equal to subtrees[[n]]\$node.label (if node labels are available).
\end{tabular} \\
new2old_edge \(\quad\)\begin{tabular}{l} 
List of the same length as nodes, with the n-th element being an integer vector \\
with values in 1,..,Nedges, mapping edge indices of the n-th subtree to edge in- \\
dices in the original tree. In particular, tree\$edge.length[new2old_edge[[n]]] \\
will be equal to subtrees[[n]]\$edge.length (if edge lengths are available).
\end{tabular}
\end{tabular}

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
get_subtree_at_node,
```

get_subtree_with_tips

```

\section*{Examples}
```


# generate a random tree

Ntips = 1000
tree = generate_random_tree(list(birth_rate_intercept=1),Ntips)\$tree

# extract subtrees descending from random nodes

nodes = sample.int(tree$Nnode,size=10)
subtrees = get_subtrees_at_nodes(tree, nodes)$subtrees

# print summaries of extracted subtrees

for(n in length(nodes)){
cat(sprintf("Subtree at %d-th node has %d tips\n",nodes[n],length(subtrees[[n]]\$tip.label)))
}

```
get_subtree_at_node Extract a subtree descending from a specific node.

\section*{Description}

Given a tree and a focal node, extract the subtree descending from the focal node and place the focal node as the root of the extracted subtree.

\section*{Usage}
get_subtree_at_node(tree, node)

\section*{Arguments}
tree A tree of class "phylo".
node Character or integer specifying the name or index, respectively, of the focal node at which to extract the subtree. If an integer, it must be between 1 and tree \(\$\) Nnode. If a character, it must be a valid entry in tree\$node. label.

\section*{Details}

The input tree need not be rooted, however "descendance" from the focal node is inferred based on the direction of edges in tree\$edge. The input tree may include multi-furcations (i.e. nodes with more than 2 children) as well as mono-furcations (i.e. nodes with only one child).

\section*{Value}

A list with the following elements:

\begin{abstract}
subtree A new tree of class "phylo", containing the subtree descending from the focal node. This tree will be rooted, with the new root being the focal node.
new2old_tip Integer vector of length Ntips_kept (=number of tips in the extracted subtree) with values in \(1, . .\), Ntips, mapping tip indices of the subtree to tip indices in the original tree. In particular, tree\$tip.label[new2old_tip] will be equal to subtree\$tip.label.
new2old_node Integer vector of length Nnodes_kept (=number of nodes in the extracted subtree) with values in \(1, . .\), Nnodes, mapping node indices of the subtree to node indices in the original tree.
For example, new2old_node[1] is the index that the first node of the subtree had within the original tree. In particular, tree\$node.label[new2old_node] will be equal to subtree\$node. label (if node labels are available).
new2old_edge Integer vector of length Nedges_kept (=number of edges in the extracted subtree), with values in \(1, \ldots\), Nedges, mapping edge indices of the subtree to edge indices in the original tree. In particular, tree\$edge.length[new2old_edge] will be equal to subtree\$edge. length (if edge lengths are available).
\end{abstract}

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

get_subtree_with_tips

```

\section*{Examples}
```


# generate a random tree

Ntips = 1000
tree = generate_random_tree(list(birth_rate_intercept=1),Ntips)\$tree

# extract subtree descending from a random node

node = sample.int(tree$Nnode,size=1)
subtree = get_subtree_at_node(tree, node)$subtree

# print summary of subtree

cat(sprintf("Subtree at %d-th node has %d tips\n",node,length(subtree\$tip.label)))

```

\section*{Description}

Given a rooted tree and a subset of tips, extract the subtree containing only those tips. The root of the tree is kept.

\section*{Usage}
get_subtree_with_tips(tree,
\[
\begin{array}{ll}
\text { only_tips } & =\text { NULL, } \\
\text { omit_tips } & =\text { NULL, } \\
\text { collapse_monofurcations } & =\text { TRUE, } \\
\text { force_keep_root } & =\text { FALSE })
\end{array}
\]

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
only_tips Either a character vector listing tip names to keep, or an integer vector listing tip indices to keep (between 1 and Ntips). Can also be NULL. Tips listed in only_tips not found in the tree will be silently ignored.
omit_tips Either a character vector listing tip names to omit, or an integer vector listing tip indices to omit (between 1 and Ntips). Can also be NULL. Tips listed in omit_tips not found in the tree will be silently ignored.
collapse_monofurcations
A logical specifying whether nodes with a single outgoing edge remaining should be collapsed (removed). Incoming and outgoing edge of such nodes will be concatenated into a single edge, connecting the parent (or earlier) and child (or later) of the node. In that case, the returned tree will have edge lengths that reflect the concatenated edges.
force_keep_root
Logical, specifying whether to keep the root even if collapse_monofurcations==TRUE and the root of the subtree is left with a single child. If FALSE, and collapse_monofurcations==TRUE, the root may be removed and one of its descendants may become root.

\section*{Details}

If both only_tips and omit_tips are NULL, then all tips are kept and the tree remains unchanged. If both only_tips and omit_tips are non-NULL, then only tips listed in only_tips and not listed in omit_tips will be kept. If only_tips and/or omit_tips is a character vector listing tip names, then tree\$tip. label must exist.

If the input tree does not include edge. length, each edge in the input tree is assumed to have length 1. The root of the tree (which is always kept) is assumed to be the unique node with no incoming
edge. The input tree may include multi-furcations (i.e. nodes with more than 2 children) as well as mono-furcations (i.e. nodes with only one child).

The asymptotic time complexity of this function is O (Nnodes+Ntips), where Ntips is the number of tips and Nnodes the number of nodes in the input tree.

When only_tips==NULL, omit_tips!=NULL, collapse_monofurcations==TRUE and force_keep_root==FALSE, this function is analogous to the function drop. tip in the ape package with option trim_internal=TRUE (v. 0.5-64).

\section*{Value}

A list with the following elements:
\begin{tabular}{ll} 
subtree & \begin{tabular}{l} 
A new tree of class "phylo", containing only the tips specified by tips_to_keep \\
and the nodes \& edges connecting those tips to the root. The returned tree will \\
include edge.lengh as a member variable, listing the lengths of the remaining \\
(possibly concatenated) edges.
\end{tabular} \\
root_shift & \begin{tabular}{l} 
Numeric, indicating the phylogenetic distance between the old and the new root. \\
Will always be non-negative.
\end{tabular} \\
new2old_tip \(\quad\)\begin{tabular}{l} 
Integer vector of length Ntips_kept (=number of tips in the extracted subtree) \\
with values in 1,..,Ntips, maping tip indices of the subtree to tip indices in the \\
original tree. In particular, tree\$tip.label[new2old_tip] will be equal to \\
subtree\$tip.label.
\end{tabular} \\
new2old_node \(\quad\)\begin{tabular}{l} 
Integer vector of length Nnodes_kept (=number of nodes in the extracted sub- \\
tree) with values in 1,..,Nnodes, mapping node indices of the subtree to node \\
indices in the original tree.
\end{tabular} \\
old2new_tip \(\quad\)\begin{tabular}{l} 
For example, new2old_node[1] is the index that the first node of the subtree \\
had within the original tree. In particular, tree\$node.label[new2old_node] \\
will be equal to subtree\$node.label (if node labels are available).
\end{tabular} \\
\begin{tabular}{l} 
Integer vector of length Ntips, with values in \(1, \ldots\), Ntips_kept, mapping tip indices \\
of the original tree to tip indices in the subtree (a value of 0 is used whenever
\end{tabular} \\
a tip is absent in the subtree). This is essentially the inverse of the mapping \\
new2old_tip.
\end{tabular}

\section*{Author(s)}

Stilianos Louca

\section*{See Also}

\section*{Examples}
```


# generate a random tree

Ntips = 1000
tree = generate_random_tree(list(birth_rate_intercept=1),Ntips)\$tree

# choose a random subset of tips

tip_subset = sample.int(Ntips, size=as.integer(Ntips/10), replace=FALSE)

# extract subtree spanning the chosen tip subset

subtree = get_subtree_with_tips(tree, only_tips=tip_subset)$subtree
    # print summary of subtree
    cat(sprintf("Subtree has %d tips and %d nodes\n",length(subtree$tip.label), subtree\$Nnode))

```
get_tips_for_mrcas Find tips with specific most recent common ancestors.

\section*{Description}

Given a rooted phylogenetic tree and a list of nodes ("MRCA nodes"), for each MRCA node find a set of descending tips ("MRCA-defining tips") such that their most recent common ancestor (MRCA) is that node. This may be useful for cases where nodes need to be described as MRCAs of tip pairs for input to certain phylogenetics algorithms (e.g., for tree dating).

\section*{Usage}
get_tips_for_mrcas(tree, mrca_nodes, check_input=TRUE)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
mrca_nodes Either an integer vector or a character vector, listing the nodes for each of which an MRCA-defining set of tips is to be found. If an integer vector, it should list node indices (i.e. from 1 to Nnodes). If a character vector, it should list node names; in that case tree\$node. label must exist.
check_input Logical, whether to perform basic validations of the input data. If you know for certain that your input is valid, you can set this to FALSE to reduce computation time.

\section*{Details}

At most 2 MRCA-defining tips are assigned to each MRCA node. This function assumes that each of the mrca_nodes has at least two children or has a child that is a tip (otherwise the problem is not well-defined). The tree may include multi-furcations as well as mono-furcations (i.e. nodes with only one child).
The asymptotic time complexity of this function is O (Ntips+Nnodes) +O (Nmrcas), where Ntips is the number of tips, Nnodes is the number of nodes in the tree and Nmrcas is equal to length(mrca_nodes).

\section*{Value}

A list of the same size as mrca_nodes, whose \(n\)-th element is an integer vector of tip indices (i.e. with values in \(1, . ., \mathrm{Ntips}\) ) whose MRCA is the n -th node listed in mrca_nodes.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

get_pairwise_mrcas,get_mrca_of_set

```

\section*{Examples}
```


# generate a random tree

Ntips = 1000
tree = generate_random_tree(list(birth_rate_intercept=1),Ntips)\$tree

# pick random nodes

focal_nodes = sample.int(n=tree\$Nnode, size=3, replace=FALSE)

# get tips for mrcas

tips_per_focal_node = get_tips_for_mrcas(tree, focal_nodes);

# check correctness (i.e. calculate actual MRCAs of tips)

for(n in 1:length(focal_nodes)){
mrca = get_mrca_of_set(tree, tips_per_focal_node[[n]])
cat(sprintf("Focal node = %d, should match mrca of tips = %d\n",focal_nodes[n],mrca-Ntips))
}

```
get_trait_acf Phylogenetic autocorrelation function of a numeric trait.

\section*{Description}

Given a rooted phylogenetic tree and a numeric (typically continuous) trait with known value (state) on each tip, calculate the phylogenetic autocorrelation function (ACF) of the trait. The ACF is a function of phylogenetic distance x , where \(\mathrm{ACF}(\mathrm{x})\) is the Pearson autocorrelation of the trait between two tips, provided that the tips have phylogenetic ("patristic") distance x . The function get_trait_acf also calculates the mean absolute difference and the mean relative difference of the trait between any two random tips at phylogenetic distance x (see details below).

\section*{Usage}
get_trait_acf(tree, tip_states, Npairs \(\quad=10000\), Nbins = NULL,
```

min_phylodistance = 0,
max_phylodistance = NULL,
uniform_grid = FALSE,
phylodistance_grid= NULL)

```

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
tip_states A numeric vector of size Ntips, specifying the value of the trait at each tip in the tree. Note that tip_states[i] (where i is an integer index) must correspond to the i-th tip in the tree.
Npairs Total number of random tip pairs to draw. A greater number of tip pairs will improve the accuracy of the estimated ACF within each distance bin. Tip pairs are drawn randomly with replacement. If Npairs<=0, then every tip pair is included exactly once.
Nbins Number of distance bins to consider within the range of phylogenetic distances encountered between tip pairs in the tree. A greater number of bins will increase the resolution of the ACF as a function of phylogenetic distance, but will decrease the number of tip pairs falling within each bin (which reduces the accuracy of the estimated ACF). If NULL, then Nbins is automatically and somewhat reasonably chosen based on the size of the input trees.
min_phylodistance
Numeric, minimum phylogenetic distance to conssider. Only relevant if phylodistance_grid is NULL.
max_phylodistance
Numeric, optional maximum phylogenetic distance to consider. If NULL, this is automatically set to the maximum phylodistance between any two tips.
uniform_grid Logical, specifying whether the phylodistance grid should be uniform, i.e., with equally sized phylodistance bins. If FALSE, then the grid is chosen non-uniformly (i.e., each bin has different size) such that each bin roughly contains the same number of tip pairs. Only relevant if phylodistance_grid is NULL. It is generally recommended to keep uniform_grid=FALSE, to avoid uneven estimation errors across bins.
phylodistance_grid
Numeric vector, optional explicitly specified phylodistance bins (left boundaries thereof) on which to evaluate the ACF. Must contain non-negative numbers in strictly ascending order. Hence, the first bin will range from phylodistance_grid[1] to phylodistance_grid[2], while the last bin will range from tail (phylodistance_grid, 1) to max_phylodistance. Can be used as an alternative to Nbins. If non-NULL, then Nbins, min_phylodistance and uniform_grid are irrelevant.

\section*{Details}

The phylogenetic autocorrelation function (ACF) of a trait can give insight into the evolutionary processes shaping its distribution across clades. An ACF that decays slowly with increasing phylogenetic distance indicates a strong phylogenetic conservatism of the trait, whereas a rapidly decaying ACF indicates weak phylogenetic conservatism. Similarly, if the mean absolute difference
in trait value between two random tips increases with phylogenetic distance, this indicates a phylogenetic autocorrelation of the trait (Zaneveld et al. 2014). Here, phylogenetic distance between tips refers to their patristic distance, i.e. the minimum cumulative edge length required to connect the two tips.
Since the phylogenetic distances between all possible tip pairs do not cover a continuoum (as there is only a finite number of tips), this function randomly draws tip pairs from the tree, maps them onto a finite set of equally-sized distance bins and then estimates the ACF for the centroid of each distance bin based on tip pairs in that bin. In practice, as a next step one would usually plot the estimated ACF (returned vector autocorrelations) over the centroids of the distance bins (returned vector distances).
Phylogenetic distance bins can be specified in two alternative ways: Either a set of bins (phylodistance grid) is automatically calculated based on the provided Nbins, min_phylodistance, max_phylodistance and uniform_grid, or a phylodistance grid is explicitly provided via phylodistance_grid and max_phylodistance.
The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child). If tree\$edge. length is missing, then every edge is assumed to have length 1 . The input tree must be rooted at some node for technical reasons (see function root_at_node), but the choice of the root node does not influence the result.
This function assumes that each tip is assigned exactly one trait value. This might be problematic in situations where each tip covers a range of trait values, for example if tips are species and multiple individuals were sampled from each species. In that case, one might consider representing each individual as a separate tip in the tree, so that each tip has exactly one trait value.

\section*{Value}

A list with the following elements:
phylodistances Numeric vector of size Nbins, storing the center of each phylodistance bin in increasing order. This is equal to \(0.5 *\) (left_phylodistances+right_phylodistances). Typically, you will want to plot autocorrelations over phylodistances.
left_phylodistances
Numeric vector of size Nbins, storing the left boundary of each phylodistance bin in increasing order.
right_phylodistances
Numeric vector of size Nbins, storing the right boundary of each phylodistance bin in increasing order.
autocorrelations
Numeric vector of size Nbins, storing the estimated Pearson autocorrelation of the trait for each distance bin.
mean_abs_differences
Numeric vector of size Nbins, storing the mean absolute difference of the trait between tip pairs in each distance bin.
mean_rel_differences
Numeric vector of size Nbins, storing the mean relative difference of the trait between tip pairs in each distance bin. The relative difference between two values \(X\) and \(Y\) is 0 if \(X==Y\), and equal to
\[
\frac{|X-Y|}{0.5 \cdot(|X|+|Y|)}
\]
otherwise.
Npairs_per_distance
Integer vector of size Nbins, storing the number of random tip pairs associated with each phylodistance bin.

\section*{Author(s)}

Stilianos Louca

\section*{References}
J. R. Zaneveld and R. L. V. Thurber (2014). Hidden state prediction: A modification of classic ancestral state reconstruction algorithms helps unravel complex symbioses. Frontiers in Microbiology. 5:431.

\section*{See Also}
consentrait_depth, geographic_acf

\section*{Examples}
\# generate a random tree
tree \(=\) generate_random_tree(list(birth_rate_intercept=1), max_tips=1000)\$tree
\# simulate continuous trait evolution on the tree
tip_states = simulate_bm_model(tree, diffusivity=1)\$tip_states
\# calculate autocorrelation function
ACF = get_trait_acf(tree, tip_states, Npairs=1e7, Nbins=10)
\# plot ACF (autocorrelation vs phylogenetic distance)
plot(ACF\$phylodistances, ACF\$autocorrelations, type="l", xlab="distance", ylab="ACF")
```

get_trait_stats_over_time

```

Calculate mean \& standard deviation of a numeric trait on a dated tree over time.

\section*{Description}

Given a rooted and dated phylogenetic tree, and a scalar numeric trait with known value on each node and tip of the tree, calculate the mean and the variance of the trait's states across the tree at discrete time points. For example, if the trait represents "body size", then this function calculates the mean body size of extant clades over time.

\section*{Usage}
get_trait_stats_over_time(tree,
states,
Ntimes \(=\) NULL,
times \(=\) NULL,
include_quantiles = TRUE,
check_input \(=\) TRUE)

\section*{Arguments}
tree A rooted tree of class "phylo", where edge lengths represent time intervals (or similar).
states Numeric vector, specifying the trait's state at each tip and each node of the tree (in the order in which tips \& nodes are indexed). May include NA or NaN if values are missing for some tips/nodes.
Ntimes Integer, number of equidistant time points for which to calculade clade counts. Can also be NULL, in which case times must be provided.
times Integer vector, listing time points (in ascending order) for which to calculate clade counts. Can also be NULL, in which case Ntimes must be provided.
include_quantiles
Logical, specifying whether to include information on quantiles (e.g., median, CI95, CI50) of the trait over time, in addition to the means and standard deviations. This option increases computation time and memory needs for large trees, so if you only care about means and standard deviations you can set this to FALSE.
check_input Logical, specifying whether to perform some basic checks on the validity of the input data. If you are certain that your input data are valid, you can set this to FALSE to reduce computation.

\section*{Details}

If tree\$edge. length is missing, then every edge in the tree is assumed to be of length 1 . The tree may include multi-furcations as well as mono-furcations (i.e. nodes with only one child). The tree need not be ultrametric (e.g. may include extinct tips), although in general this function only makes sense if edge lengths correspond to time (or similar).
Either Ntimes or times must be non-NULL, but not both. states need not include names; if it does, then these are checked to be in the same order as in the tree (if check_input==TRUE).

\section*{Value}

A list with the following elements:
Ntimes Integer, indicating the number of returned time points. Equal to the provided Ntimes if applicable.
times \(\quad\) Numeric vector of size Ntimes, listing the considered time points in increasing order. If times was provided as an argument to the function, then this will be the same as provided.
\begin{tabular}{ll} 
clade_counts & \begin{tabular}{l} 
Integer vector of size Ntimes, listing the number of tips or nodes considered at \\
each time point.
\end{tabular} \\
means & \begin{tabular}{l} 
Numeric vector of size Ntimes, listing the arithmetic mean of trait states at each \\
time point.
\end{tabular} \\
stds & \begin{tabular}{l} 
Numeric vector of size Ntimes, listing the standard deviation of trait states at \\
each time point.
\end{tabular} \\
medians & \begin{tabular}{l} 
Numeric vector of size Ntimes, listing the median trait state at each time point. \\
Only returned if include_uantiles=TRUE.
\end{tabular} \\
CI50lower & \begin{tabular}{l} 
Numeric vector of size Ntimes, listing the lower end of the equal-tailed 50\% \\
range of trait states (i.e., the 25\% percentile) at each time point. Only returned \\
if include_uantiles=TRUE.
\end{tabular} \\
CI50upper & \begin{tabular}{l} 
Numeric vector of size Ntimes, listing the upper end of the equal-tailed \(50 \%\) \\
range of trait states (i.e., the 75\% percentile) at each time point. Only returned \\
if include_uantiles=TRUE.
\end{tabular} \\
CI95lower & \begin{tabular}{l} 
Numeric vector of size Ntimes, listing the lower end of the equal-tailed 95\% \\
range of trait states (i.e., the \(2.5 \%\) percentile) at each time point. Only returned \\
if include_uantiles=TRUE.
\end{tabular} \\
CI95upper & \begin{tabular}{l} 
Numeric vector of size Ntimes, listing the upper end of the equal-tailed 95\% \\
range of trait states (i.e., the \(97.5 \% ~ p e r c e n t i l e) ~ a t ~ e a c h ~ t i m e ~ p o i n t . ~ O n l y ~ r e t u r n e d ~\)
\end{tabular} \\
if include_uantiles=TRUE.
\end{tabular}

\section*{Author(s)}

Stilianos Louca

\section*{Examples}
```


# generate a random tree

tree = generate_random_tree(list(birth_rate_intercept=1), max_tips=1000)\$tree

# simulate a numeric trait under Brownian-motion

trait = simulate_bm_model(tree, diffusivity=1)
states = c(trait$tip_states,trait$node_states)

# calculate trait stats over time

results = get_trait_stats_over_time(tree, states, Ntimes=100)

# plot trait stats over time (mean +/- std)

M = results$means
S = results$stds
matplot(x=results\$times,
y=matrix(c(M-S,M+S),ncol=2, byrow=FALSE),
main = "Simulated BM trait over time",
lty = 1, col="black",
type="l", xlab="time", ylab="mean +/- std")

```
```

get_transition_index_matrix

```

Create an index matrix for a Markov transition model.

\section*{Description}

Create an index matrix encoding the parametric structure of the transition rates in a discrete-state continuous-time Markov model (e.g., Mk model of trait evolution). Such an index matrix is required by certain functions for mapping independent rate parameters to transition rates. For example, an index matrix may encode the information that each rate \(i->j\) is equal to its reversed counterpart \(j->i\).

\section*{Usage}
get_transition_index_matrix(Nstates, rate_model)

\section*{Arguments}

Nstates Integer, the number of distinct states represented in the transition matrix (number of rows \& columns).
rate_model Rate model that the transition matrix must satisfy. Can be "ER" (all rates equal), "SYM" (transition rate \(i->j\) is equal to transition rate \(j->i\) ), "ARD" (all rates can be different) or "SUEDE" (only stepwise transitions \(\mathrm{i}->\mathrm{i}+1\) and \(\mathrm{i}->\mathrm{i}-1\) allowed, all 'up' transitions are equal, all 'down' transitions are equal).

\section*{Details}

The returned index matrix will include as many different positive integers as there are independent rate parameters in the requested rate model, plus potentially the value 0 (which has a special meaning, see below).

\section*{Value}

A named list with the following elements:
index_matrix Integer matrix of size Nstates x Nstates, with values between 0 and Nstates, assigning each entry in the transition matrix to an independent transition rate parameter. A value of 0 means that the corresponding rate is fixed to zero (if off-diagonal) or will be adjusted to ensure a valid Markov transition rate matrix (if on the diagonal).
Nrates Integer, the number of independent rate parameters in the model.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
get_random_mk_transition_matrix

\section*{Description}

Given a rooted phylogenetic tree, calculate the minimum and maximum phylogenetic distance (cumulative branch length) of any tip from the root.

\section*{Usage}
get_tree_span(tree, as_edge_count=FALSE)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
as_edge_count Logical, specifying whether distances should be counted in number of edges, rather than cumulative edge length. This is the same as if all edges had length 1.

\section*{Details}

If tree\$edge.length is missing, then every edge in the tree is assumed to be of length 1 . The tree may include multi-furcations as well as mono-furcations (i.e. nodes with only one child). The asymptotic average time complexity of this function is O (Nedges), where Nedges is the number of edges in the tree.

\section*{Value}

A named list with the following elements:
min_distance Minimum phylogenetic distance that any of the tips has to the root.
max_distance Maximum phylogenetic distance that any of the tips has to the root.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

get_pairwise_distances

```

\section*{Examples}
```


# generate a random tree

Ntips = 1000
params = list(birth_rate_intercept=1, death_rate_intercept=0.5)
tree = generate_random_tree(params, max_tips=Ntips, coalescent=FALSE)\$tree

# calculate min \& max tip distances from root

tree_span = get_tree_span(tree)
cat(sprintf("Tip min dist = %g, max dist = %g\n",
tree_span$min_distance,
    tree_span$max_distance))

```
get_tree_traversal_root_to_tips

Traverse tree from root to tips.

\section*{Description}

Create data structures for traversing a tree from root to tips, and for efficient retrieval of a node's outgoing edges and children.

\section*{Usage}
get_tree_traversal_root_to_tips(tree, include_tips)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
include_tips Include tips in the tarversal queue. If FALSE, then only nodes are included in the queue.

\section*{Details}

Many dynamic programming algorithms for phylogenetics involve traversing the tree in a certain direction (root to tips or tips to root), and efficient ( \(\mathrm{O}(1)\) complexity) access to a node's direct children can significantly speed up those algorithms. This function is meant to provide data structures that allow traversing the tree's nodes (and optionally tips) in such an order that each node is traversed prior to its descendants (root->tips) or such that each node is traversed after its descendants (tips \(\rightarrow\) root). This function is mainly meant for use in other algorithms, and is probably of little relevance to the average user.

The tree may include multi-furcations as well as mono-furcations (i.e. nodes with only one child).
The asymptotic time and memory complexity of this function is O (Ntips), where Ntips is the number of tips in the tree.

\section*{Value}

A list with the following elements:
\[
\begin{array}{ll}
\text { queue } & \begin{array}{l}
\text { An integer vector of size Nnodes (if include_tips was FALSE) or of size Nn- } \\
\text { odes+Ntips (if include_tips was TRUE), listing indices of nodes (and option- } \\
\text { ally tips) in the order root }->\text { tips described above. In particular, queue[1] will } \\
\text { be the index of the tree's root (typically Ntips+1). }
\end{array} \\
\text { edges } & \begin{array}{l}
\text { An integer vector of size Nedges (=nrow(tree\$edge)), listing indices of edges } \\
\text { (corresponding to tree\$edge) such that outgoing edges of the same node are } \\
\text { listed in consequtive order. }
\end{array} \\
\text { node2first_edge }
\end{array} \quad \begin{aligned}
& \text { An integer vector of size Nnodes listing the location of the first outgoing edge of } \\
& \text { each node in edges. That is, edges[node2first_edge[n]] points to the first } \\
& \text { outgoing edge of node } n \text { in tree\$edge. }
\end{aligned}
\]

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

reorder_tree_edges

```

\section*{Examples}
```


## Not run:

# generate a random tree

tree = generate_random_tree(list(birth_rate_factor=1), max_tips=100)\$tree

# get tree traversal

traversal = get_tree_traversal_root_to_tips(tree, include_tips=TRUE)

## End(Not run)

``` bution.

\section*{Description}

Estimate the state probabilities for a binary trait at ancestral nodes and tips with unknown (hidden) state, by fitting the probability parameter of a binomial distribution to empirical state frequencies. For each node, the states of its descending tips are assumed to be drawn randomly and independently according to some a prior unknown probability distribution. The probability P1 (probability of any random descending tip being in state 1) is estimated separately for each node based on the observed states in the descending tips via maximum likelihood.
This function can account for potential state-measurement errors, hidden states and reveal biases (i.e., tips in one particular state being more likely to be measured than in the other state). Only nodes with a number of non-hidden tips above a certain threshold are included in the ML-estimation phase. All other nodes and hidden tips are then assigned the probabilities estimated for the most closely related ancestral node with estimated probabilities. This function is a generalization of hsp_empirical_probabilities that can account for potential state-measurement errors and reveal biases.

\section*{Usage}

\section*{Arguments}
tree A rooted tree of class "phylo".
tip_states Integer vector of length Ntips, specifying the state of each tip in the tree (either 1 or 2). tip_states can include NA to indicate a hidden (non-measured) tip state.
reveal_probs 2D numeric matrix of size Ntips x 2, listing tip-specific reveal probabilities at each tip conditional on the tip's true state. Hence reveal_probs[n,s] is the probability that tip \(n\) would have a measured (non-hidden) state if its true state was s. May also be a vector of length 2 (same reveal_probs for all tips) or NULL (unbiased reveal probs).
state1_probs 2D numeric matrix of size Ntips x 2, listing the probability of measuring state 1 (potentially erroneously) at each tip conditional upon its true state and conditional upon its state having been measured (i.e., being non-hidden). For example, for an incompletely sequenced genome with completion level C_n and state 1 indicating presence and state 2 indicating absence of a gene, and assuming error-free detection of genes within the covered regions, one has state1_probs[n,1] \(=\) C_n and state1_probs[n,2]=0. state1_probs may also be a vector of length 2 (same probabilities for all tips) or NULL. If NULL, state measurements are assumed error-free, and hence this is the same as \(c(1,0)\).
min_revealed Non-negative integer, specifying the minimum number of tips with non-hidden state that must descend from a node for estimating its P1 via maximum likelihood. For nodes with too few descending tips with non-hidden state, the proba-
bility P1 will not be estimated via maximum likelihood, and instead will be set to the P1 estimated for the nearest possible ancestral node. It is advised to set this threshold greater than zero (typical values are 2-10).
max_STE Non-negative numeric, specifying the maximum acceptable estimated standard error (STE) for the estimated probability P1 for a node. If the STE for a node exceeds this threshold, the P1 for that node is set to the P1 of the nearest ancestor with STE below that threshold. Setting this to Inf disables this functionality. The STE is estimated based on the Observed Fisher Information Criterion (which, strictly speaking, only provides a lower bound for the STE).
check_input Logical, specifying whether to perform some additional time-consuming checks on the validity of the input data. If you are certain that your input data are valid, you can set this to FALSE to reduce computation.

\section*{Details}

This function currently only supports binary traits, and states must be represented by integers 1 or 2. Any NA entries in tip_states are interpreted as hidden (non-revealed) states.

The algorithm proceeds in two phases ("ASR" phase and "HSP" phase). In the ASR phase the state probability P1 is estimated separately for every node and tip satisfying the thresholds min_revealed and max_STE, via maximum-likelihood. In the HSP phase, the P1 of nodes and tips not included in the ASR phase is set to the P1 of the nearest ancestral node with estimated P1, as described by Zaneveld and Thurber (2014).
This function yields estimates for the state probabilities P1 (note that P2=1-P1). In order to obtain point estimates for tip states one needs to interpret these probabilities in a meaningful way, for example by choosing as point estimate for each tip the state with highest probability P1 or P2; the closest that probability is to 1 , the more reliable the point estimate will be.

The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child). This function has asymptotic time complexity O (Nedges x Nstates). Tips must be represented in tip_states in the same order as in tree\$tip.label. The vector tip_states need not include names; if it does, however, they are checked for consistency (if check_input==TRUE).

\section*{Value}

A list with the following elements:
success Logical, indicating whether HSP was successful. If FALSE, an additional element error (character) will be returned describing the error, while all other return values may be NULL.
P1 Numeric vector of length Ntips+Nnodes, listing the estimated probability of being in state 1 for each tip and node. A value of \(\mathrm{P} 1[\mathrm{n}]=0\) or \(\mathrm{P} 1[\mathrm{n}]=1\) means that the \(n\)-th tip/node is in state 2 or state 1 with absolute certainty, respectively. Note that even tips with non-hidden state may have have a P1 that is neither 0 or 1 , if state measurements are erroneous (i.e., if state1_probs[n,] differs from \((1,0)\) ).

STE
Numeric vector of length Ntips+Nnodes, listing the standard error of the estimated P1 at each tip and node, according to the Observed Fisher Information

Criterion. Note that the latter strictly speaking only provides a lower bound on the standard error.
reveal_counts Integer vector of length Ntips+Nnodes, listing the number of tips with nonhidden state descending from each tip and node.
inheritted Logical vector of length Ntips+Nnodes, specifying for each tip or node whether its returned P1 was directly maximum-likelihood estimated duirng the ASR phase (inheritted[n]==FALSE) or set to the P1 estimated for an ancestral node during the HSP phase (inheritted[n]==TRUE).

\section*{Author(s)}

Stilianos Louca

\section*{References}
J. R. Zaneveld and R. L. V. Thurber (2014). Hidden state prediction: A modification of classic ancestral state reconstruction algorithms helps unravel complex symbioses. Frontiers in Microbiology. 5:431.

\section*{See Also}
hsp_max_parsimony, hsp_mk_model, hsp_empirical_probabilities

\section*{Examples}
```


## Not run:

# generate random tree

Ntips =50
tree = generate_random_tree(list(birth_rate_factor=1),max_tips=Ntips)\$tree

# simulate a binary trait on the tips

Q = get_random_mk_transition_matrix(Nstates=2, rate_model="ER", min_rate=0.1, max_rate=0.5)
tip_states = simulate_mk_model(tree, Q)\$tip_states

# print tip states

cat(sprintf("True tip states:\n"))
print(tip_states)

# hide some of the tip states

# include a reveal bias

reveal_probs = c(0.8, 0.3)
revealed = sapply(1:Ntips, FUN=function(n) rbinom(n=1,size=1,prob=reveal_probs[tip_states[n]]))
input_tip_states = tip_states
input_tip_states[!revealed] = NA

# predict state probabilities P1 and P2

hsp = hsp_binomial(tree, input_tip_states, reveal_probs=reveal_probs, max_STE=0.2)
probs = cbind(hsp$P1,1-hsp$P1)

# pick most likely state as a point estimate

# only accept point estimate if probability is sufficiently high

```
```

estimated_tip_states = max.col(probs[1:Ntips,])
estimated_tip_states[probs[cbind(1:Ntips,estimated_tip_states)]<0.8] = NA
cat(sprintf("ML-predicted tip states:\n"))
print(estimated_tip_states)

# calculate fraction of correct predictions

predicted = which((!revealed) \& (!is.na(estimated_tip_states)))
if(length(predicted)>0){
Ncorrect = sum(tip_states[predicted]==estimated_tip_states[predicted])
cat(sprintf("%.2g%% of predictions are correct\n",(100.0*Ncorrect)/length(predicted)))
}else{
cat(sprintf("None of the tip states could be reliably predicted\n"))
}

## End(Not run)

```
```

hsp_empirical_probabilities

```

Hidden state prediction via empirical probabilities.

\section*{Description}

Reconstruct ancestral discrete states of nodes and predict unknown (hidden) states of tips on a tree based on empirical state probabilities across tips. This is a very crude HSP method, and other more sophisticated methods should be preferred (e.g. hsp_mk_model).

\section*{Usage}
hsp_empirical_probabilities(tree, tip_states, Nstates=NULL, check_input=TRUE)

\section*{Arguments}
\begin{tabular}{ll} 
tree & \begin{tabular}{l} 
A rooted tree of class "phylo". The root is assumed to be the unique node with \\
no incoming edge.
\end{tabular} \\
tip_states \(\quad\)\begin{tabular}{l} 
An integer vector of size Ntips, specifying the state of each tip in the tree as an \\
integer from 1 to Nstates, where Nstates is the possible number of states (see \\
below). tip_states can include NA to indicate an unknown tip state that is to \\
be predicted.
\end{tabular} \\
Nstates & \begin{tabular}{l} 
Either NULL, or an integer specifying the number of possible states of the trait. If \\
NULL, then it will be computed based on the maximum non-NA value encountered \\
in tip_states
\end{tabular} \\
check_input \(\quad\)\begin{tabular}{l} 
Logical, specifying whether to perform some basic checks on the validity of the \\
input data. If you are certain that your input data are valid, you can set this to \\
FALSE to reduce computation.
\end{tabular}
\end{tabular}

\section*{Details}

For this function, the trait's states must be represented by integers within \(1, . .\), Nstates, where Nstates is the total number of possible states. If the states are originally in some other format (e.g. characters or factors), you should map them to a set of integers \(1, \ldots\), Nstates. You can easily map any set of discrete states to integers using the function map_to_state_space.
Any NA entries in tip_states are interpreted as unknown states. Prior to ancestral state reconstruction, the tree is temporarily prunned, keeping only tips with known state. The function then calculates the empirical state probabilities for each node in the pruned tree, based on the states across tips descending from each node. The state probabilities of tips with unknown state are set to those of the most recent ancestor with reconstructed states, as described by Zaneveld and Thurber (2014).

The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child). This function has asymptotic time complexity O (Nedges x Nstates).
Tips must be represented in tip_states in the same order as in tree\$tip.label. The vector tip_states need not include names; if it does, however, they are checked for consistency (if check_input==TRUE).

This function is meant for reconstructing ancestral states in all nodes of a tree as well as predicting the states of tips with an a priory unknown state. If the state of all tips is known and only ancestral state reconstruction is needed, consider using functions such as asr_empirical_probabilities for improved efficiency.

\section*{Value}

A list with the following elements:
success Logical, indicating whether HSP was successful. If FALSE, some return values may be NULL.
likelihoods A 2D numeric matrix, listing the probability of each tip and node being in each state. This matrix will have (Ntips+Nnodes) rows and Nstates columns, where Nstates was either explicitly provided as an argument or inferred based on the number of unique values in tip_states (if Nstates was passed as NULL). In the latter case, the column names of this matrix will be the unique values found in tip_states. The rows in this matrix will be in the order in which tips and nodes are indexed in the tree, i.e. the rows \(1, . ., \mathrm{Ntips}\) store the probabilities for tips, while rows (Ntips+1),..,(Ntips+Nnodes) store the probabilities for nodes. Each row in this matrix will sum up to 1 . Note that the return value is named this way for compatibility with other HSP functions.

\section*{Author(s)}

Stilianos Louca

\section*{References}
J. R. Zaneveld and R. L. V. Thurber (2014). Hidden state prediction: A modification of classic ancestral state reconstruction algorithms helps unravel complex symbioses. Frontiers in Microbiology. 5:431.

\section*{See Also}
```

hsp_max_parsimony, hsp_mk_model, map_to_state_space

```

\section*{Examples}
```


## Not run:

# generate random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# simulate a discrete trait

Nstates = 5
Q = get_random_mk_transition_matrix(Nstates, rate_model="ER", max_rate=0.1)
tip_states = simulate_mk_model(tree, Q)\$tip_states

# print states of first 20 tips

print(tip_states[1:20])

# set half of the tips to unknown state

tip_states[sample.int(Ntips,size=as.integer(Ntips/2),replace=FALSE)] = NA

# reconstruct all tip states via MPR

likelihoods = hsp_empirical_probabilities(tree, tip_states, Nstates)\$likelihoods
estimated_tip_states = max.col(likelihoods[1:Ntips,])

# print estimated states of first 20 tips

print(estimated_tip_states[1:20])

## End(Not run)

```
hsp_independent_contrasts

Hidden state prediction via phylogenetic independent contrasts.

\section*{Description}

Reconstruct ancestral states of a continuous (numeric) trait for nodes and predict unknown (hidden) states for tips on a tree using phylogenetic independent contrasts.

\section*{Usage}
hsp_independent_contrasts(tree, tip_states, weighted=TRUE, check_input=TRUE)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
\begin{tabular}{ll} 
tip_states & \begin{tabular}{l} 
A numeric vector of size Ntips, specifying the state of each tip in the tree. \\
tip_states can include NA to indicate an unknown tip state that is to be pre- \\
dicted.
\end{tabular} \\
weighted & \begin{tabular}{l} 
Logical, specifying whether to weight transition costs by the inverted edge lengths \\
during ancestral state reconstruction. This corresponds to the "weighted squared- \\
change parsimony" reconstruction by Maddison (1991) for a Brownian motion \\
model of trait evolution.
\end{tabular} \\
check_input \(\quad\)\begin{tabular}{l} 
Logical, specifying whether to perform some basic checks on the validity of the \\
input data. If you are certain that your input data are valid, you can set this to \\
FALSE to reduce computation.
\end{tabular}
\end{tabular}

\section*{Details}

Any NA entries in tip_states are interpreted as unknown (hidden) states to be estimated. Prior to ancestral state reconstruction, the tree is temporarily prunned, keeping only tips with known state. The function then uses a postorder traversal algorithm to calculate the intermediate " X " variables (a state estimate for each node) introduced by Felsenstein (1985) in his phylogenetic independent contrasts method. Note that these are only local estimates, i.e. for each node the estimate is only based on the tip states in the subtree descending from that node (see discussion in Garland and Ives, 2000). The states of tips with hidden state are set to those of the most recent ancestor with reconstructed state, as described by Zaneveld and Thurber (2014).

This function has asymptotic time complexity O (Nedges). If tree\$edge. length is missing, each edge in the tree is assumed to have length 1 . This is the same as setting weighted=FALSE. The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as mono-furcations (i.e. nodes with only one child).
Tips must be represented in tip_states in the same order as in tree\$tip.label. The vector tip_states need not include item names; if it does, however, they are checked for consistency (if check_input==TRUE).

This function is meant for reconstructing ancestral states in all nodes of a tree as well as predicting the states of tips with an a priory unknown state. If the state of all tips is known and only ancestral state reconstruction is needed, consider using the function asr_independent_contrasts for improved efficiency.

\section*{Value}

A list with the following elements:
success Logical, indicating whether HSP was successful. If FALSE, some return values may be NULL.
states A numeric vector of size Ntips+Nnodes, listing the reconstructed state of each tip and node. The entries in this vector will be in the order in which tips and nodes are indexed in tree\$edge.
total_sum_of_squared_changes
The total sum of squared changes in tree, minimized by the (optionally weighted) squared-change parsimony algorithm. This is equation 7 in (Maddison, 1991). Note that for the root, phylogenetic independent contrasts is equivalent to Maddison's squared-change parsimony.

\section*{Author(s)}

Stilianos Louca

\section*{References}
J. Felsenstein (1985). Phylogenies and the comparative method. The American Naturalist. 125:115.
T. Jr. Garland and A. R. Ives (2000). Using the past to predict the present: Confidence intervals for regression equations in phylogenetic comparative methods. The American Naturalist. 155:346-364.
W. P. Maddison (1991). Squared-change parsimony reconstructions of ancestral states for continuousvalued characters on a phylogenetic tree. Systematic Zoology. 40:304-314.
J. R. Zaneveld and R. L. V. Thurber (2014). Hidden state prediction: A modification of classic ancestral state reconstruction algorithms helps unravel complex symbioses. Frontiers in Microbiology. 5:431.

\section*{See Also}
asr_squared_change_parsimony hsp_max_parsimony, hsp_mk_model,

\section*{Examples}
```


# generate random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# simulate a continuous trait

tip_states = simulate_ou_model(tree, stationary_mean=0, spread=1, decay_rate=0.001)\$tip_states

# print tip states

print(as.vector(tip_states))

# set half of the tips to unknown state

tip_states[sample.int(Ntips,size=as.integer(Ntips/2),replace=FALSE)] = NA

# reconstruct all tip states via weighted PIC

estimated_states = hsp_independent_contrasts(tree, tip_states, weighted=TRUE)\$states

# print estimated tip states

print(estimated_states[1:Ntips])

```
hsp_max_parsimony Hidden state prediction via maximum parsimony.

\section*{Description}

Reconstruct ancestral discrete states of nodes and predict unknown (hidden) states of tips on a tree using maximum parsimony. Transition costs can vary between transitions, and can optionally be weighted by edge length.

\section*{Usage}
```

hsp_max_parsimony(tree, tip_states, Nstates=NULL,
transition_costs="all_equal",
edge_exponent=0.0, weight_by_scenarios=TRUE,
check_input=TRUE)

```

\section*{Arguments}
\begin{tabular}{|c|c|}
\hline tree & A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge. \\
\hline tip_states & An integer vector of size Ntips, specifying the state of each tip in the tree as an integer from 1 to Nstates, where Nstates is the possible number of states (see below). tip_states can include NA to indicate an unknown tip state that is to be predicted. \\
\hline Nstates & Either NULL, or an integer specifying the number of possible states of the trait. If NULL, then it will be computed based on the maximum non-NA value encountered in tip_states \\
\hline \multicolumn{2}{|l|}{transition_costs} \\
\hline & Same as for the function asr_max_parsimony. \\
\hline \multicolumn{2}{|l|}{weight_by_scenarios} \\
\hline & Logical, indicating whether to weight each optimal state of a node by the number of optimal maximum-parsimony scenarios in which the node is in that state. If FALSE, then all possible states of a node are weighted equally (i.e. are assigned equal probabilities). \\
\hline check_input & Logical, specifying whether to perform some basic checks on the validity of the input data. If you are certain that your input data are valid, you can set this to FALSE to reduce computation. \\
\hline
\end{tabular}

\section*{Details}

For this function, the trait's states must be represented by integers within 1,..,Nstates, where Nstates is the total number of possible states. If the states are originally in some other format (e.g. characters or factors), you should map them to a set of integers \(1, . .\), Nstates. The order of states (if relevant) should be reflected in their integer representation. For example, if your original states are "small", "medium" and "large" and transition_costs=="sequential", it is advised to represent these states as integers \(1,2,3\). You can easily map any set of discrete states to integers using the function map_to_state_space.
Any NA entries in tip_states are interpreted as unknown states. Prior to ancestral state reconstruction, the tree is temporarily prunned, keeping only tips with known state. The function then applies Sankoff's (1975) dynamic programming algorithm for ancestral state reconstruction, which determines the smallest number (or least costly if transition costs are uneven) of state changes along edges needed to reproduce the known tip states. The state probabilities of tips with unknown state are set to those of the most recent ancestor with reconstructed states, as described by Zaneveld and Thurber (2014). This function has asymptotic time complexity O(Ntips+Nnodes x Nstates).
If tree\$edge. length is missing, each edge in the tree is assumed to have length 1 . If edge_exponent is 0 , then edge lengths do not influence the result. If edge_exponent \(!=0\), then all edges must have
non-zero length. The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as mono-furcations (i.e. nodes with only one child).
Tips must be represented in tip_states in the same order as in tree\$tip.label. None of the input vectors or matrixes need include row or column names; if they do, however, they are checked for consistency (if check_input==TRUE).

This function is meant for reconstructing ancestral states in all nodes of a tree as well as predicting the states of tips with an a priory unknown state. If the state of all tips is known and only ancestral state reconstruction is needed, consider using the function asr_max_parsimony for improved efficiency.

\section*{Value}

A list with the following elements:
success Logical, indicating whether HSP was successful. If FALSE, some return values may be NULL.
likelihoods A 2D numeric matrix, listing the probability of each tip and node being in each state. This matrix will have (Ntips+Nnodes) rows and Nstates columns, where Nstates was either explicitly provided as an argument or inferred based on the number of unique values in tip_states (if Nstates was passed as NULL). In the latter case, the column names of this matrix will be the unique values found in tip_states. The rows in this matrix will be in the order in which tips and
 tips, while rows (Ntips+1),..,(Ntips+Nnodes) store the probabilities for nodes. Each row in this matrix will sum up to 1 . Note that the return value is named this way for compatibility with other HSP functions.

\section*{Author(s)}

Stilianos Louca

\section*{References}
D. Sankoff (1975). Minimal mutation trees of sequences. SIAM Journal of Applied Mathematics. 28:35-42.
J. Felsenstein (2004). Inferring Phylogenies. Sinauer Associates, Sunderland, Massachusetts.
J. R. Zaneveld and R. L. V. Thurber (2014). Hidden state prediction: A modification of classic ancestral state reconstruction algorithms helps unravel complex symbioses. Frontiers in Microbiology. 5:431.

\section*{See Also}
asr_max_parsimony, asr_mk_model, hsp_mk_model, map_to_state_space

\section*{Examples}
```


## Not run:

# generate random tree

Ntips = 10

```
```

tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# simulate a discrete trait

Nstates = 5
Q = get_random_mk_transition_matrix(Nstates, rate_model="ER")
tip_states = simulate_mk_model(tree, Q)\$tip_states

# print tip states

print(tip_states)

# set half of the tips to unknown state

tip_states[sample.int(Ntips,size=as.integer(Ntips/2),replace=FALSE)] = NA

# reconstruct all tip states via MPR

likelihoods = hsp_max_parsimony(tree, tip_states, Nstates)\$likelihoods
estimated_tip_states = max.col(likelihoods[1:Ntips,])

# print estimated tip states

print(estimated_tip_states)

## End(Not run)

```
hsp_mk_model Hidden state prediction with Mk models and rerooting

\section*{Description}

Reconstruct ancestral states of a discrete trait and predict unknown (hidden) states of tips using a fixed-rates continuous-time Markov model (a.k.a. "Mk model"). This function can fit the model (i.e. estimate the transition matrix) using maximum likelihood, or use a specified transition matrix. The function can optionally calculate marginal ancestral state likelihoods for each node in the tree, using the rerooting method by Yang et al. (1995). A subset of the tips may have completely unknown states; in this case the fitted Markov model is used to predict their state likelihoods based on their most recent reconstructed ancestor, as described by Zaneveld and Thurber (2014). The function can account for biases in which tips have known state ("reveal bias").

\section*{Usage}
hsp_mk_model( tree, tip_states, Nstates = NULL, reveal_fractions = NULL, tip_priors = NULL, rate_model = "ER", transition_matrix = NULL, include_likelihoods = TRUE, root_prior = "empirical", Ntrials = 1, optim_algorithm = "nlminb",
```

optim_max_iterations = 200,
optim_rel_tol = 1e-8,
store_exponentials = TRUE,
check_input = TRUE,
Nthreads = 1)

```

\section*{Arguments}

A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
tip_states An integer vector of size Ntips, specifying the state of each tip in the tree in terms of an integer from 1 to Nstates, where Nstates is the possible number of states (see below). Can also be NULL, in which case tip_priors must not be NULL (see below). tip_states can include NA to indicate an unknown (hidden) tip state that is to be predicted.

Nstates Either NULL, or an integer specifying the number of possible states of the trait. If Nstates==NULL, then it will be computed based on the maximum nonNA value encountered in tip_states or based on the number of columns in tip_priors (whichever is non-NULL).
reveal_fractions
Either NULL, or a numeric vector of size Nstates, specifying the fraction of tips with revealed (i.e., non-hidden) state, depending on the tip state. That is, reveal_fractions[s] is the probability that a given tip at state \(s\) will have known (i.e., non-hidden) state, conditional upon being included in the tree. If the tree only contains a random subset of species (sampled independently of each species' state), then reveal_fractions[s] is the probability of knowing the state of a species (regardless of whether it is included in the tree), if its state is \(s\). This variable can be used to account for biases in which tips have known state, depending on their state. Only the relative ratios among reveal fractions matter, i.e. multiplying reveal_fractions with a constant factor has no effect.
tip_priors A 2D numeric matrix of size Ntips x Nstates, where Nstates is the possible number of states for the character modelled. Can also be NULL. Each row of this matrix must be a probability vector, i.e. it must only contain non-negative entries and must sum up to 1 . The [ \(\mathrm{i}, \mathrm{s}]\)-th entry should be the prior probability of tip i being in state s. If you know for certain that tip i is in some state s, you can set the corresponding entry to 1 and all other entries in that row to 0 . A row can include \(N A\) to indicate that neither the state nor the probability distribution of a state are known for that tip. If for all tips you either know the exact state or have no information at all, you can also use tip_states instead. If tip_priors==NULL, then tip_states must not be NULL (see above).
rate_model Rate model to be used for fitting the transition rate matrix. Similar to the rate_model option in the function asr_mk_model. See the details of asr_mk_model on the assumptions of each rate_model.
transition_matrix
Either a numeric quadratic matrix of size Nstates x Nstates containing fixed transition rates, or NULL. The [r,c]-th entry in this matrix should store the transition (probability) rate from the state \(r\) to state \(c\). Each row in this matrix must have
sum zero. If NULL, then the transition rates will be estimated using maximum likelihood, based on the rate_model specified.
include_likelihoods
Boolean, specifying whether to include the marginal state likelihoods for all tips and nodes, as returned variables. Setting this to TRUE can substantially increase computation time. If FALSE, the Mk model is merely fitted, but ancestral states and hidden tip states are not reconstructed.
root_prior Prior probability distribution of the root's states. Similar to the root_prior option in the function asr_mk_model.
Ntrials Number of trials (starting points) for fitting the transition matrix. Only relevant if transition_matrix=NULL. A higher number may reduce the risk of landing in a local non-global optimum of the likelihood function, but will increase computation time during fitting.
```

optim_algorithm

```

Either "optim" or "nlminb", specifying which optimization algorithm to use for maximum-likelihood estimation of the transition matrix. Only relevant if transition_matrix==NULL.
optim_max_iterations
Maximum number of iterations (per fitting trial) allowed for optimizing the likelihood function.
optim_rel_tol Relative tolerance (stop criterion) for optimizing the likelihood function.
store_exponentials
Logical, specifying whether to pre-calculate and store exponentials of the transition matrix during calculation of ancestral likelihoods. This may reduce computation time because each exponential is only calculated once, but will use up more memory since all exponentials are stored. Only relevant if include_ancestral_likelihoods is TRUE, otherwise exponentials are never stored.
check_input Logical, specifying whether to perform some basic checks on the validity of the input data. If you are certain that your input data are valid, you can set this to FALSE to reduce computation.
Nthreads Number of parallel threads to use for running multiple fitting trials simultaneously. This only makes sense if your computer has multiple cores/CPUs and Ntrials>1, and is only relevant if transition_matrix==NULL.

\section*{Details}

For this function, the trait's states must be represented by integers within 1,..,Nstates, where Nstates is the total number of possible states. Note that Nstates can be chosen to be larger than the number of states observed in the tips of the present tree, to account for potential states not yet observed. If the trait's states are originally in some other format (e.g. characters or factors), you should map them to a set of integers \(1, . .\), Nstates. The order of states (if applicable) should be reflected in their integer representation. For example, if your original states are "small", "medium" and "large" and rate_model=="SUEDE", it is advised to represent these states as integers \(1,2,3\). You can easily map any set of discrete states to integers using the function map_to_state_space.
This function allows the specification of the precise tip states (if these are known) using the vector tip_states. Alternatively, if some tip states are only known in terms of a probability distribution,
you can pass these probability distributions using the matrix tip_priors. Note that exactly one of the two arguments, tip_states or tip_priors, must be non-NULL. In either case, the presence of NA in tip_states or in a row of tip_priors is interpreted as an absence of information about the tip's state (i.e. the tip has "hidden state").
Tips must be represented in tip_states or tip_priors in the same order as in tree\$tip.label. None of the input vectors or matrixes need include row or column names; if they do, however, they are checked for consistency (if check_input==TRUE).

This method assumes that the tree is either complete (i.e. includes all species), or that the tree's tips represent a random subset of species that have been sampled independent of their state. The function does not require that tip state knowledge is independent of tip state, provided that the associated biases are known (provided via reveal_fractions). The rerooting method by Yang et al (2015) is used to reconstruct the marginal ancestral state likelihoods for each node by treating the node as a root and calculating its conditional scaled likelihoods. The state likelihoods of tips with hidden states are calculated from those of the most recent ancestor with previously calculated state likelihoods, using the exponentiated transition matrix along the connecting edges (essentially using the rerooting method). Attention: The state likelihoods for tips with known states or with provided priors are not modified, i.e. they are as provided in the input. In other words, for those tips the returned state likelihoods should not be considered as posteriors in a Bayesian sense.
If tree\$edge. length is missing, each edge in the tree is assumed to have length 1 . The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as mono-furcations (i.e. nodes with only one child).

\section*{Value}

A list with the following elements:
\[
\begin{array}{ll}
\text { success } & \begin{array}{l}
\text { Logical, indicating whether HSP was successful. If FALSE, some return values } \\
\text { may be NULL. } \\
\text { Integer, specifying the number of modeled trait states. }
\end{array} \\
\text { Nstates } & \begin{array}{l}
\text { transition_matrix }
\end{array} \\
& \begin{array}{l}
\text { A numeric quadratic matrix of size Nstates x Nstates, containing the transition } \\
\text { rates of the Markov model. The [r,c]-th entry is the transition rate from state } \mathrm{r} \text { to } \\
\text { state c. Will be the same as the input transition_matrix, if the latter was not } \\
\text { NULL. }
\end{array} \\
\text { loglikelihood } & \begin{array}{l}
\text { Log-likelihood of the Markov model. If transition_matrix was NULL in the } \\
\text { input, then this will be the log-likelihood maximized during fitting. }
\end{array} \\
\text { likelihoods } \quad \begin{array}{l}
\text { A 2D numeric matrix, listing the probability of each tip and node being in } \\
\text { each state. Only included if include_likelihoods was TRUE. This matrix will }
\end{array} \\
& \begin{array}{l}
\text { have (Ntips+Nnodes) rows and Nstates columns, where Nstates was either ex- } \\
\text { plicitly provided as an argument, or inferred from tip_states or tip_priors }
\end{array} \\
\text { (whichever was non-NULL). The rows in this matrix will be in the order in which } \\
\text { tips and nodes are indexed in the tree, i.e. rows 1,..,Ntips store the probabili- } \\
\text { ties for tips, while rows (Ntips+1),..,(Ntips+Nnodes) store the probabilities for }
\end{array}
\]

\section*{Author(s)}

Stilianos Louca

\section*{References}
Z. Yang, S. Kumar and M. Nei (1995). A new method for inference of ancestral nucleotide and amino acid sequences. Genetics. 141:1641-1650.
J. R. Zaneveld and R. L. V. Thurber (2014). Hidden state prediction: A modification of classic ancestral state reconstruction algorithms helps unravel complex symbioses. Frontiers in Microbiology. 5:431.

\section*{See Also}
hsp_max_parsimony, hsp_squared_change_parsimony, asr_mk_model, map_to_state_space

\section*{Examples}
```


## Not run:

# generate random tree

Ntips = 1000
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# simulate a discrete trait

Nstates = 5
Q = get_random_mk_transition_matrix(Nstates, rate_model="ER", max_rate=0.01)
tip_states = simulate_mk_model(tree, Q)\$tip_states
cat(sprintf("Simulated ER transition rate=%g\n",Q[1,2]))

# print states for first 20 tips

print(tip_states[1:20])

# set half of the tips to unknown state

# chose tips randomly, regardless of their state (no biases)

tip_states[sample.int(Ntips,size=as.integer(Ntips/2),replace=FALSE)] = NA

# reconstruct all tip states via Mk model max-likelihood

results = hsp_mk_model(tree, tip_states, Nstates, rate_model="ER", Ntrials=2, Nthreads=2)
estimated_tip_states = max.col(results\$likelihoods[1:Ntips,])

# print Mk model fitting summary

cat(sprintf("Mk model: log-likelihood=%g\n",results$loglikelihood))
cat(sprintf("Universal (ER) transition rate=%g\n",results$transition_matrix[1,2]))

# print estimated states for first 20 tips

print(estimated_tip_states[1:20])

## End(Not run)

```
hsp_nearest_neighbor Hidden state prediction based on nearest neighbor.

\section*{Description}

Predict unknown (hidden) character states of tips on a tree using nearest neighbor matching.

\section*{Usage}
hsp_nearest_neighbor(tree, tip_states, check_input=TRUE)

\section*{Arguments}
tree A rooted tree of class "phylo".
tip_states A vector of length Ntips, specifying the state of each tip in the tree. Tip states can be any valid data type (e.g., characters, integers, continuous numbers, and so on). NA values denote unknown (hidden) tip states to be predicted.
check_input Logical, specifying whether to perform some basic checks on the validity of the input data. If you are certain that your input data are valid, you can set this to FALSE to reduce computation.

\section*{Details}

For each tip with unknown state, this function seeks the closest tip with known state, in terms of patristic distance. The state of the closest tip is then used as a prediction of the unknown state. In the case of multiple equal matches, the precise outcome is unpredictable (this is unlikely to occur if edge lengths are continuous numbers, but may happen frequently if e.g. edge lengths are all of unit length). This algorithm is arguably one of the crudest methods for predicting character states, so use at your own discretion.
Any NA entries in tip_states are interpreted as unknown states. If tree\$edge. length is missing, each edge in the tree is assumed to have length 1 . The tree may include multifurcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child). Tips must be represented in tip_states in the same order as in tree\$tip. label. tip_states need not include names; if names are included, however, they are checked for consistency with the tree's tip labels (if check_input==TRUE).

\section*{Value}

A list with the following elements:
success Logical, indicating whether HSP was successful. If FALSE, some return values may be NULL.
states Vector of length Ntips, listing the known and predicted state for each tip.
nearest_neighbors
Integer vector of length Ntips, listing for each tip the index of the nearest tip with known state. Hence, nearest_neighbors[n] specifies the tip from which the unknown state of tip \(n\) was inferred. If tip \(n\) had known state, nearest_neighbors [ \(n\) ] will be \(n\).
nearest_distances
Numeric vector of length Ntips, listing for each tip the patristic distance to the nearest tip with known state. For tips with known state, distances will be zero.

\section*{Author(s)}

Stilianos Louca

\section*{References}
J. R. Zaneveld and R. L. V. Thurber (2014). Hidden state prediction: A modification of classic ancestral state reconstruction algorithms helps unravel complex symbioses. Frontiers in Microbiology. 5:431.

\section*{See Also}
hsp_max_parsimony, hsp_mk_model,

\section*{Examples}
```


## Not run:

# generate random tree

Ntips = 20
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# simulate a binary trait

Q = get_random_mk_transition_matrix(2, rate_model="ER")
tip_states = simulate_mk_model(tree, Q)\$tip_states

# print tip states

print(tip_states)

# set half of the tips to unknown state

tip_states[sample.int(Ntips,size=as.integer(Ntips/2),replace=FALSE)] = NA

# reconstruct all tip states via nearest neighbor

predicted_states = hsp_nearest_neighbor(tree, tip_states)\$states

# print predicted tip states

print(predicted_states)

## End(Not run)

```
hsp_squared_change_parsimony
Hidden state prediction via squared-change parsimony.

\section*{Description}

Reconstruct ancestral states of a continuous (numeric) trait for nodes and predict unknown (hidden) states for tips on a tree using squared-change (or weighted squared-change) parsimony (Maddison 1991).

\section*{Usage}
hsp_squared_change_parsimony(tree, tip_states, weighted=TRUE, check_input=TRUE)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
tip_states A numeric vector of size Ntips, specifying the state of each tip in the tree. tip_states can include NA to indicate an unknown tip state that is to be predicted.
weighted Logical, specifying whether to weight transition costs by the inverted edge lengths during ancestral state reconstruction. This corresponds to the "weighted squaredchange parsimony" reconstruction by Maddison (1991) for a Brownian motion model of trait evolution.
check_input Logical, specifying whether to perform some basic checks on the validity of the input data. If you are certain that your input data are valid, you can set this to FALSE to reduce computation.

\section*{Details}

Any NA entries in tip_states are interpreted as unknown (hidden) states to be estimated. Prior to ancestral state reconstruction, the tree is temporarily prunned, keeping only tips with known state. The function then uses Maddison's squared-change parsimony algorithm to reconstruct the globally parsimonious state at each node (Maddison 1991). The states of tips with hidden state are set to those of the most recent ancestor with reconstructed state, as described by Zaneveld and Thurber (2014). This function has asymptotic time complexity O (Nedges). If tree\$edge. length is missing, each edge in the tree is assumed to have length 1 . This is the same as setting weighted=FALSE. The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child).
Tips must be represented in tip_states in the same order as in tree\$tip.label. The vector tip_states need not include item names; if it does, however, they are checked for consistency (if check_input==TRUE).
This function is meant for reconstructing ancestral states in all nodes of a tree as well as predicting the states of tips with an a priory unknown state. If the state of all tips is known and only ancestral state reconstruction is needed, consider using the function asr_squared_change_parsimony for improved efficiency.

\section*{Value}

A list with the following elements:
states A numeric vector of size Ntips+Nnodes, listing the reconstructed state of each tip and node. The entries in this vector will be in the order in which tips and nodes are indexed in tree\$edge.
total_sum_of_squared_changes
The total sum of squared changes, minimized by the (optionally weighted) squaredchange parsimony algorithm. This is equation 7 in (Maddison, 1991).

\section*{Author(s)}

Stilianos Louca

\section*{References}
W. P. Maddison (1991). Squared-change parsimony reconstructions of ancestral states for continuousvalued characters on a phylogenetic tree. Systematic Zoology. 40:304-314.
J. R. Zaneveld and R. L. V. Thurber (2014). Hidden state prediction: A modification of classic ancestral state reconstruction algorithms helps unravel complex symbioses. Frontiers in Microbiology. 5:431.

\section*{See Also}
```

asr_squared_change_parsimony hsp_max_parsimony, hsp_mk_model, map_to_state_space

```

\section*{Examples}
```


# generate random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# simulate a continuous trait

tip_states = simulate_ou_model(tree, stationary_mean=0, spread=1, decay_rate=0.001)\$tip_states

# print tip states

print(tip_states)

# set half of the tips to unknown state

tip_states[sample.int(Ntips,size=as.integer(Ntips/2),replace=FALSE)] = NA

# reconstruct all tip states via weighted SCP

estimated_states = hsp_squared_change_parsimony(tree, tip_states, weighted=TRUE)\$states

# print estimated tip states

print(estimated_states[1:Ntips])

```
hsp_subtree_averaging Hidden state prediction via subtree averaging.

\section*{Description}

Reconstruct ancestral states of a continuous (numeric) trait for nodes and predict unknown (hidden) states for tips on a tree using subtree averaging.

\section*{Usage}
hsp_subtree_averaging(tree, tip_states, check_input=TRUE)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
tip_states A numeric vector of size Ntips, specifying the state of each tip in the tree. tip_states can include NA to indicate an unknown tip state that is to be predicted.
check_input Logical, specifying whether to perform some basic checks on the validity of the input data. If you are certain that your input data are valid, you can set this to FALSE to reduce computation.

\section*{Details}

Any NA entries in tip_states are interpreted as unknown (hidden) states to be estimated. For each node the reconstructed state is set to the arithmetic average state of all tips with known state and descending from that node. For each tip with hidden state and each node whose descending tips all have hidden states, the state is set to the state of the closest ancestral node with known or reconstructed state, while traversing from root to tips (Zaneveld and Thurber 2014). Note that reconstructed node states are only local estimates, i.e. for each node the estimate is only based on the tip states in the subtree descending from that node.
Tips must be represented in tip_states in the same order as in tree\$tip.label. The vector tip_states need not include item names; if it does, however, they are checked for consistency (if check_input==TRUE). This function has asymptotic time complexity O (Nedges).
This function is meant for reconstructing ancestral states in all nodes of a tree as well as predicting the states of tips with an a priory unknown state. If the state of all tips is known and only ancestral state reconstruction is needed, consider using the function asr_subtree_averaging for improved efficiency.

\section*{Value}

A list with the following elements:
\begin{tabular}{ll} 
success & Logical, indicating whether HSP was successful. \\
states & A numeric vector of size Ntips+Nnodes, listing the reconstructed state of each \\
tip and node. The entries in this vector will be in the order in which tips and \\
nodes are indexed in tree\$edge.
\end{tabular}

\section*{Author(s)}

Stilianos Louca

\section*{References}
J. R. Zaneveld and R. L. V. Thurber (2014). Hidden state prediction: A modification of classic ancestral state reconstruction algorithms helps unravel complex symbioses. Frontiers in Microbiology. 5:431.

\section*{See Also}
asr_subtree_averaging, hsp_squared_change_parsimony

\section*{Examples}
```


# generate random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# simulate a continuous trait

tip_states = simulate_ou_model(tree, stationary_mean=0, spread=1, decay_rate=0.001)\$tip_states

# print tip states

print(as.vector(tip_states))

# set half of the tips to unknown state

tip_states[sample.int(Ntips,size=as.integer(Ntips/2),replace=FALSE)] = NA

# reconstruct all tip states via subtree averaging

estimated_states = hsp_subtree_averaging(tree, tip_states)\$states

# print estimated tip states

print(estimated_states[1:Ntips])

```
is_bifurcating Determine if a tree is bifurcating.

\section*{Description}

This function determines if a tree is strictly bifurcating, i.e. each node has exactly 2 children. If a tree has monofurcations or multifurcations, this function returns FALSE.

\section*{Usage}
is_bifurcating(tree)

\section*{Arguments}
\[
\text { tree } \quad \text { A tree of class "phylo". }
\]

\section*{Details}

This functions accepts rooted and unrooted trees, that may include monofurcations, bifurcations and multifurcations.

\section*{Value}

A logical, indicating whether the input tree is strictly bifurcating.

\section*{Author(s)}

Stilianos Louca

\section*{Examples}
```


# generate random tree

Ntips = 10
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# check if the tree is bifurcating (as expected)

is_bifurcating(tree)

```
is_monophyletic Determine if a set of tips is monophyletic.

\section*{Description}

Given a rooted phylogenetic tree and a set of focal tips, this function determines whether the tips form a monophyletic group.

\section*{Usage}
is_monophyletic(tree, focal_tips, check_input=TRUE)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
focal_tips Either an integer vector or a character vector, listing the tips to be checked for monophyly. If an integer vector, it should list tip indices (i.e. from 1 to Ntips). If a character vector, it should list tip names; in that case tree\$tip. label must exist.
check_input Logical, whether to perform basic validations of the input data. If you know for certain that your input is valid, you can set this to FALSE to reduce computation time.

\section*{Details}

This function first finds the most recent common ancestor (MRCA) of the focal tips, and then checks if all tips descending from that MRCA fall within the focal tip set.

\section*{Value}

A logical, indicating whether the focal tips form a monophyletic set.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

get_mrca_of_set

```

\section*{Examples}
```


# generate random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# pick a random subset of focal tips

focal_tips = which(sample.int(2, size=Ntips,replace=TRUE)==1)

# check if focal tips form a monophyletic group

is_monophyletic(tree, focal_tips)

```
join_rooted_trees Join two rooted trees.

\section*{Description}

Given two rooted phylogenetic trees, place one tree (tree 2 ) onto an edge of the other tree (tree1), so that tree 2 becomes a monophyletic group of the final joined tree. As a special case, this function can join two trees at their roots, i.e. so that both are disjoint monophyletic clades of the final tree, splitting at the new root.

\section*{Usage}
```

join_rooted_trees( tree1,
tree2,
target_edge1,
target_edge_length1,
root_edge_length2)

```

\section*{Arguments}
tree1 A rooted tree of class "phylo".
tree2 A rooted tree of class "phylo". This tree will become a monophyletic subclade of the final joined tree.
target_edge1 Integer, edge index in tree1 onto which tree2 is to be joined. If \(<=0\), then this refers to the hypothetical edge leading into the root of tree1, in which case both trees will become disjoint monophyletic subclades of the final joined tree.
target_edge_length1
Numeric, length of the edge segment in tree1 from the joining-point to the next child node, i.e. how far from the child of target_edge1 should the joining occur. If target_edge1<=0, then target_edge_length1 is the distance of the root of tree 1 from the final joined tree's root.
root_edge_length2
Numeric, length of the edge leading into the root of tree2, i.e. the distance from the joining point to the root of tree2.

\section*{Details}

The input trees may include multi-furcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child). If any of the input trees does not have edge lengths (i.e., edge. length is NULL), then its edge lengths are assumed to all be 1 .

The tips of the two input trees will become the tips of the final joined tree. The nodes of the two input trees will become nodes of the final joined tree, however one additional node will be added at the joining point. Tip labels and node labels (if available) of the joined tree are inheritted from the two input trees.

\section*{Value}

A list with the following elements:
```

tree A new rooted tree of class "phylo", representing the joined tree.
clade1_to_clade
Integer vector of length Ntips1+Nnodes1, mapping tip/node indices of the input
tree1 to tip/node indices in the final joined tree.
clade2_to_clade
Integer vector of length Ntips2+Nnodes2, mapping tip/node indices of the input
tree2 to tip/node indices in the final joined tree.

```

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

split_tree_at_height

```

\section*{Examples}
```


# generate two random trees, include tip \& node names

tree1 = generate_random_tree(list(birth_rate_intercept=1),
max_tips=10,
tip_basename="tip1.",
node_basename="node1.")$tree
tree2 = generate_random_tree(list(birth_rate_intercept=1),
    max_tips=5,
    tip_basename="tip2.",
    node_basename="node2.")$tree
\# join trees at their roots
\# each subtree's root should have distance 1 from the new root
joined_tree = join_rooted_trees(tree1,
tree2,
target_edge1=0,
target_edge_length1=1,
root_edge_length2=1)\$tree

```

\section*{Description}

Given a rooted ultrametric timetree, and a homogenous birth-death (HBD) model, i.e., with speciation rate \(\lambda\), extinction rate \(\mu\) and sampling fraction \(\rho\), calculate the likelihood of the tree under the model. The speciation and extinction rates may be time-dependent. "Homogenous" refers to the assumption that, at any given moment in time, all lineages exhibit the same speciation/extinction rates (in the literature this is sometimes referred to simply as "birth-death model"). Alternatively to \(\lambda\) and \(\mu\), the likelihood may also be calculated based on the pulled diversification rate (PDR; Louca et al. 2018) and the product \(\rho(0) \cdot \lambda(0)\), or based on the pulled speciation rate (PSR). In either case, the time-profiles of \(\lambda, \mu\), the PDR or the PSR are specified as piecewise polynomially functions (splines), defined on a discrete grid of ages.

\section*{Usage}
loglikelihood_hbd(tree,
\begin{tabular}{|c|c|}
\hline \[
\begin{aligned}
& \text { oldest_age } \\
& \text { age0 }
\end{aligned}
\] & \[
\begin{aligned}
& =\text { NULL, } \\
& =0,
\end{aligned}
\] \\
\hline rho0 & = NULL, \\
\hline rholambda0 & = NULL, \\
\hline age_grid & = NULL, \\
\hline lambda & = NULL, \\
\hline mu & = NULL, \\
\hline PDR & = NULL, \\
\hline PSR & = NULL, \\
\hline splines_degree & \(=1\), \\
\hline condition & = "auto" \\
\hline
\end{tabular}
```

max_model_runtime = -1,
relative_dt = 1e-3)

```

\section*{Arguments}
\begin{tabular}{|c|c|}
\hline tree & A rooted ultrametric tree of class "phylo". \\
\hline oldest_age & Strictly positive numeric, specifying the oldest time before present ("age") to consider when calculating the likelihood. If this is equal to or greater than the root age, then oldest_age is taken as the stem age, and the classical formula by Morlon et al. (2011) is used. If oldest_age is less than the root age, the tree is split into multiple subtrees at that age by treating every edge crossing that age as the stem of a subtree, and each subtree is considered an independent realization of the HBD model stemming at that age. This can be useful for avoiding points in the tree close to the root, where estimation uncertainty is generally higher. If oldest_age==NULL, it is automatically set to the root age. \\
\hline age0 & Non-negative numeric, specifying the youngest age (time before present) to consider for fitting, and with respect to which rho and rholambda0 are defined. If age \(0>0\), then rho refers to the sampling fraction at age age 0 , and rholambda0 to the product between rho and the speciation rate at age age0. See below for more details. \\
\hline rho0 & Numeric between 0 (exclusive) and 1 (inclusive), specifying the sampling fraction of the tree at age0, i.e. the fraction of lineages extant at age0 that are included in the tree. Note that if \(r h o 0<1\), lineages extant at age 0 are assumed to have been sampled randomly at equal probabilities. Can also be NULL, in which case rholambda0 and PDR (see below) must be provided. \\
\hline rholambda0 & Strictly positive numeric, specifying the product of the sampling fraction and the speciation rateat age0, units \(1 /\) time. Can be NULL, in which case rarefaction, lambda and mu must be provided. \\
\hline age_grid & Numeric vector, listing discrete ages (time before present) on which either \(\lambda\) and \(\mu\), or the PDR, are specified. Listed ages must be strictly increasing, and must cover at least the full considered age interval (from age0 to oldest_age). Can also be NULL or a vector of size 1 , in which case the speciation rate, extinction rate and PDR are assumed to be time-independent. \\
\hline lambda & Numeric vector, of the same size as age_grid (or size 1 if age_grid==NULL), listing speciation rates (in units \(1 /\) time) at the ages listed in age_grid. Speciation rates should be non-negative, and are assumed to vary polynomially between grid points (see argument splines_degree). If NULL, then either PDR and rholambda0, or PSR alone, must be provided. \\
\hline mu & Numeric vector, of the same size as age_grid (or size 1 if age_grid==NULL), listing extinction rates (in units \(1 /\) time) at the ages listed in age_grid. Extinction rates should be non-negative, and are assumed to vary polynomially between grid points (see argument splines_degree). If NULL, then PDR and rholambda0, or PSR alone, must be provided. \\
\hline PDR & Numeric vector, of the same size as age_grid (or size 1 if age_grid==NULL), listing pulled diversification rates (in units 1/time) at the ages listed in age_grid. \\
\hline
\end{tabular}

PDRs can be negative or positive, and are assumed to vary polynomially between grid points (see argument splines_degree). If NULL, then either lambda and mu, or PSR alone, must be provided.
PSR Numeric vector, of the same size as age_grid (or size 1 if age_grid==NULL), listing pulled speciation rates (in units 1/time) at the ages listed in age_grid. PSRs should be non-negative, and are assumed to vary polynomially between grid points (see argument splines_degree). If NULL, then either lambda and mu, or PDR and rholambda0, must be provided.
splines_degree Integer, either \(0,1,2\) or 3 , specifying the polynomial degree of the provided lambda, mu, PDR and PSR (whichever applicable) between grid points in age_grid. For example, if splines_degree==1, then the provided lambda, mu, PDR and PSR are interpreted as piecewise-linear curves; if splines_degree==2 they are interpreted as quadratic splines; if splines_degree==3 they are interpreted as cubic splines. The splines_degree influences the analytical properties of the curve, e.g. splines_degree==1 guarantees a continuous curve, splines_degree==2 guarantees a continuous curve and continuous derivative, and so on.
condition Character, either "crown", "stem", "auto" or "none" (the last one is only available if lambda and mu are given), specifying on what to condition the likelihood. If "crown", the likelihood is conditioned on the survival of the two daughter lineages branching off at the root. If "stem", the likelihood is conditioned on the survival of the stem lineage. Note that "crown" really only makes sense when oldest_age is equal to the root age, while "stem" is recommended if oldest_age differs from the root age. "none" is usually not recommended and is only available when lambda and mu are provided. If "auto", the condition is chosen according to the recommendations mentioned earlier.
max_model_runtime
Numeric, maximum allowed runtime (in seconds) for evaluating the likelihood. If the likelihood calculation takes longer than this (appoximate) threshold, it halts and returns with an error. If negative (default), this option is ignored.
relative_dt Strictly positive numeric (unitless), specifying the maximum relative time step allowed for integration over time. Smaller values increase integration accuracy but increase computation time. Typical values are \(0.0001-0.001\). The default is usually sufficient.

\section*{Details}

If age0>0, the input tree is essentially trimmed at age0 (omitting anything younger than age0), and the is likelihood calculated for the trimmed tree while shifting time appropriately. In that case, rho0 is interpreted as the sampling fraction at age0, i.e. the fraction of lineages extant at age0 that are repreented in the tree. Similarly, rholambda0 is the product of the sampling fraction and \(\lambda\) at age 0 .
This function supports three alternative parameterizations of HBD models, either using the speciation and extinction rates and sampling fraction \(\left(\lambda, \mu\right.\) and \(\rho\left(\tau_{o}\right)\) (for some arbitrary age \(\tau_{o}\) ), or using the pulled diversification rate (PDR) and the product \(\rho\left(\tau_{o}\right) \cdot \lambda\left(\tau_{o}\right.\) (sampling fraction times speciation rate at \(\tau_{o}\) ), or using the pulled speciation rate (PSR). The latter two options should be interpreted as a parameterization of congruence classes, i.e. sets of models that have the same likelihood, rather than specific models, since multiple combinations of \(\lambda, \mu\) and \(\rho\left(\tau_{o}\right)\) can have identical PDRs, \(\rho\left(\tau_{o}\right) \cdot \lambda\left(\tau_{o}\right)\) and PSRs (Louca and Pennell, in review).

For large trees the asymptotic time complexity of this function is O (Nips). The tree may include monofurcations as well as multifurcations, and the likelihood formula accounts for those (i.e., as if monofurcations were omitted and multifurcations were expanded into bifurcations).

\section*{Value}

A named list with the following elements:
success Logical, indicating whether the calculation was successful. If FALSE, then the returned list includes an additional 'error' element (character) containing a description of the error; all other return variables may be undefined.
loglikelihood Numeric. If success==TRUE, this will be the natural logarithm of the likelihood of the tree under the given model.

\section*{Author(s)}

Stilianos Louca

\section*{References}
H. Morlon, T. L. Parsons, J. B. Plotkin (2011). Reconciling molecular phylogenies with the fossil record. Proceedings of the National Academy of Sciences. 108:16327-16332.
S. Louca et al. (2018). Bacterial diversification through geological time. Nature Ecology \& Evolution. 2:1458-1467.
S. Louca and M. W. Pennell (in review as of 2019)

\section*{See Also}
```

simulate_deterministic_hbd
fit_hbd_model_parametric
fit_hbd_model_on_grid
fit_hbd_pdr_on_grid
fit_hbd_pdr_parametric

```

\section*{Examples}
```


# generate a random tree with constant rates

Ntips = 100
params = list(birth_rate_factor=1, death_rate_factor=0.2, rarefaction=0.5)
tree = generate_random_tree(params, max_tips=Ntips, coalescent=TRUE)\$tree

# get the loglikelihood for an HBD model with the same parameters that generated the tree

# in particular, assuming time-independent speciation \& extinction rates

LL = loglikelihood_hbd( tree,
rho0 = params$rarefaction,
    age_grid = NULL, # assume time-independent rates
    lambda = params$birth_rate_factor,
mu = params$death_rate_factor)
if(LL$success){

```
```

    cat(sprintf("Loglikelihood for constant-rates model = %g\n",LL$loglikelihood))
    }

# get the likelihood for a model with exponentially decreasing (in forward time) lambda \& mu

beta = 0.01 \# exponential decay rate of lambda over time
age_grid = seq(from=0, to=100, by=0.1) \# choose a sufficiently fine age grid
lambda = 1*exp(beta*age_grid) \# define lambda on the age grid
mu = 0.2*lambda \# assume similarly shaped but smaller mu
LL = loglikelihood_hbd( tree,
rho0 = params$rarefaction,
    age_grid = age_grid,
    lambda = lambda,
    mu = mu)
if(LL$success){
cat(sprintf("Loglikelihood for exponential-rates model = %g\n",LL\$loglikelihood))
}

```
map_to_state_space Map states of a discrete trait to integers.

\section*{Description}

Given a list of states (e.g., for each tip in a tree), map the unique states to integers \(1, .\). ,Nstates, where Nstates is the number of possible states. This function can be used to translate states that are originally represented by characters or factors, into integer states as required by ancestral state reconstruction and hidden state prediction functions in this package.

\section*{Usage}
map_to_state_space(raw_states, fill_gaps=FALSE, sort_order="natural", include_state_values=FALSE)

\section*{Arguments}
raw_states A vector of values (states), each of which can be converted to a different character. This list can include the same value multiple times, for example if values represent the trait's states for tips in a tree.
fill_gaps Logical. If TRUE, then states are converted to integers using as. integer (as. character()), and then all missing intermediate integer values are included as additional possible states. For example, if raw_states contained the values \(2,4,6\), then 3 and 5 are assumed to also be possible states.
sort_order Character, specifying the order in which raw_states should be mapped to ascending integers. Either "natural" or "alphabetical". If "natural", numerical parts of characters are sorted numerically, e.g. as in "3"<"a2"<"a12"<"b1".
include_state_values
Logical, specifying whether to also return a numerical version of the unique states. For example, the states " 3 "," a 2 "," 4.5 " will be mapped to the numeric values 3, NA, 4.5.

\section*{Details}

Several ancestral state reconstruction and hidden state prediction algorithms in the castor package (e.g., asr_max_parsimony) require that the focal trait's states are represented by integer indices within \(1, . .\), Nstates. These indices are then associated, afor example, with column and row indices in the transition cost matrix (in the case of maximum parsimony reconstruction) or with column indices in the returned matrix containing marginal ancestral state probabilities (e.g., in asr_mk_model). The function map_to_state_space can be used to conveniently convert a set of discrete states into integers, for use with the aforementioned algorithms.

\section*{Value}

A list with the following elements:
\(\left.\begin{array}{ll}\text { Nstates } & \begin{array}{l}\text { Integer. Number of possible states for the trait, based on the unique values } \\ \text { encountered in raw_states (after conversion to characters). This may be larger } \\ \text { than the number of unique values in raw_states, if fill_gaps was set to TRUE. }\end{array} \\ \text { state_names } & \begin{array}{l}\text { Character vector of size Nstates, storing the original name (character version) of } \\ \text { each state. For example, if raw_states was c ("b1", " } 3 ", ~ " a 12 ", ~ " a 2 ", ~ " b 1 ", ~ " a 2 ") ~\end{array} \\ \text { and sort_order=="natural", then Nstates will be } 4 \text { and state_names will } \\ \text { be c(" } 3 ", " a 2 ", ~ " a 12 ", ~ " b 1 ") . ~\end{array}\right\}\)

\section*{Author(s)}

Stilianos Louca

\section*{Examples}
```


# generate a sequence of random states

unique_states = c("b","c","a")
raw_states = unique_states[sample.int(3,size=10,replace=TRUE)]

# map to integer state space

mapping = map_to_state_space(raw_states)
cat(sprintf("Checking that original unique states is the same as the one inferred:\n"))
print(unique_states)
print(mapping$state_names)
cat(sprintf("Checking reversibility of mapping:\n"))
print(raw_states)
print(mapping$state_names[mapping\$mapped_states])

```
```

merge_nodes_to_multifurcations
Merge specific nodes into multifurcations.

```

\section*{Description}

Given a rooted tree, merge one or more nodes "upwards" into their parent nodes, thus effectively generating multifurcations. Multiple generations of nodes (i.e., successive branching points) can be merged into a single "absorbing ancestor".

\section*{Usage}
merge_nodes_to_multifurcations( tree, nodes_to_merge,
merge_with_parents = FALSE,
keep_ancestral_ages = FALSE)

\section*{Arguments}
tree A rooted tree of class "phylo".
nodes_to_merge Integer vector or character vector, listing nodes in the tree that should be merged with their parents (if merge_with_parents=TRUE) or with their children (if merge_with_parents=FALSE). If an integer vector, it must contain values in \(1, . .\), Nnodes. If a character vector, it must list node labels, and the tree itself must also include node labels.
merge_with_parents
Logical, specifying whether the nodes listed in nodes_to_merge should be merged with their parents. If FALSE, the specified nodes will be merged with their children (whenever these are not tips).
keep_ancestral_ages
Logical, specifying whether the generated multifurcations should have the same age as the absorbing ancestor. If FALSE, then the age of a multifurcation will be the average of the absorbing ancestor's age and the ages of its merged child nodes (but constrained from below by the ages of non-merged descendants to avoid negative edge lengths). If TRUE, then the ages of multifurcations will be biased towards the root, since their age will be that of the absorbing ancestor.

\section*{Details}

All tips in the input tree are kept and retain their original indices, however the returned tree will include fewer nodes and edges. Edge and node indices may change. When a node is merged into its parent, the incoming edge is lost, and the parent's age remains unchanged.
Nodes are merged in order from root to tips. Hence, if a node B is merged into ("absorbed by") its parent node \(A\), and child node \(C\) is merged into node \(B\), then effectively \(C\) ends up merged into node A (node A is the "absorbing ancestor").
If tree\$edge. length is missing, then all edges in the input tree are assumed to have length 1.

\section*{Value}

A list with the following elements:
tree A new tree of class "phylo". The number of nodes in this tree, Nnodes_new, will generally be lower than of the input tree.
new2old_node Integer vector of length Nnodes_new, mapping node indices in the new tree to node indices in the old tree. Note that nodes merged with their parents are not represented in this list.
old2new_node Integer vector of length Nnodes, mapping node indices in the old tree to node indices in the new tree. Nodes merged with their parents (and thus missing from the new tree) will have value 0 .

Nnodes_removed Integer. Number of nodes removed from the tree, due to being merged into their parents.
Nedges_removed Integer. Number of edges removed from the tree.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
multifurcations_to_bifurcations, collapse_monofurcations

\section*{Examples}
```


# generate a random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1), max_tips=Ntips)\$tree

# merge a few nodes with their parents,

# thus obtaining a multifurcating tree

nodes_to_merge = c(1,3,4)
new_tree = merge_nodes_to_multifurcations(tree, nodes_to_merge)\$tree

# print summary of old and new tree

cat(sprintf("Old tree has %d nodes\n",tree$Nnode))
cat(sprintf("New tree has %d nodes\n",new_tree$Nnode))

```
merge_short_edges Eliminate short edges in a tree by merging nodes into multifurcations.

\section*{Description}

Given a rooted phylogenetic tree and an edge length threshold, merge nodes/tips into multifurcations when their incoming edges are shorter than the threshold.

\section*{Usage}
```

merge_short_edges(tree,

```
                    edge_length_epsilon = 0,
                    force_keep_tips = TRUE,
                        new_tip_prefix = "ex.node.tip.")

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
edge_length_epsilon
Non-negative numeric, specifying the maximum edge length for an edge to be considered "short" and thus to be eliminated. Typically 0 or some small positive number.
force_keep_tips
Logical. If TRUE, then tips are always kept, even if their incoming edges are shorter than edge_length_epsilon. If FALSE, then tips with short incoming edges are removed from the tree; in that case some nodes may become tips.
new_tip_prefix Character or NULL, specifying the prefix to use for new tip labels stemming from nodes. Only relevant if force_keep_tips==FALSE. If NULL, then labels of tips stemming from nodes will be the node labels from the original tree (in this case the original tree should include node labels).

\section*{Details}

The input tree may include multi-furcations (i.e. nodes with more than 2 children) as well as mono-furcations (i.e. nodes with only one child). Whenever a short edge is eliminated, the edges originating from its child are elongated according to the short edge's length. The corresponding grand-children become children of the short edge's parent. Short edges are eliminated in a depth-first-search manner, i.e. traversing from the root to the tips.
Note that existing monofurcations are retained. If force_keep_tips==FALSE, then new monofurcations may also be introduced due to tips being removed.
This function is conceptually similar to the function ape: : di2multi.

\section*{Value}

A list with the following elements:
tree A new rooted tree of class "phylo", containing the (potentially multifurcating) tree.
new2old_clade Integer vector of length equal to the number of tips+nodes in the new tree, with values in \(1, \ldots, N\) Nips+Nnodes, mapping tip/node indices of the new tree to tip/node indices in the original tree.
new2old_edge Integer vector of length equal to the number of edges in the new tree, with values in \(1, \ldots\), Nedges, mapping edge indices of the new tree to edge indices in the original tree.
Nedges_removed Integer. Number of edges that have been eliminated.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

multifurcations_to_bifurcations

```

\section*{Examples}
```


# generate a random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_factor=1),max_tips=Ntips)\$tree

# set some edge lengths to zero

tree\$edge.length[sample.int(n=Ntips, size=10, replace=FALSE)] = 0

# print number of edges

cat(sprintf("Original tree has %d edges\n",nrow(tree\$edge)))

# eliminate any edges of length zero

merged = merge_short_edges(tree, edge_length_epsilon=0)\$tree

# print number of edges

cat(sprintf("New tree has %d edges\n",nrow(merged\$edge)))

```
model_adequacy_hbd \(\quad\) Check if a birth-death model adequately explains a timetree.

\section*{Description}

Given a rooted ultrametric timetree and a homogenous birth-death model, check if the model adequately explains various aspects of the tree, such as the branch length and node age distributions and other test statistics. The function uses bootstrapping to simulate multiple hypothetical trees according to the model and then compares the distribution of those trees to the original tree. This function may be used to quantify the "goodness of fit" of a birth-death model to a timetree.

\section*{Usage}
```

model_adequacy_hbd( tree,
models,
splines_degree = 1,
extrapolate = FALSE,
Nbootstraps = 1000,
Nthreads = 1)

```

\section*{Arguments}

\author{
tree models
}

A rooted ultrametric timetree of class "phylo".
Either a single HBD model or a list of HBD models, specifying the pool of models from which to randomly draw bootstraps. Every model should itself be a named list with some or all of the following elements:
ages: Numeric vector, specifying discrete ages (times before present) in ascending order, on which the pulled speciation rate will be specified. Age increases from tips to root; the youngest tip in the input tree has age 0 . The age grid must cover the present-day (age 0 ) and the root
- PSR: Numeric vector of size NG, listing the pulled speciation rate (PSR) of the HBD model at the corresponding ages. Between grid points, the PSR is assumed to either be constant (if splines_degree=0), or linearly (if splines_degree=1) or quadratically (if splines_degree=2) or cubically (if splines_degree=3). To calculate the PSR of an HBD model based on the speciation and extinction rate, see simulate_deterministic_hbd.
splines_degree Integer, one of \(0,1,2\) or 3 , specifying the polynomial degree of the PSR between age-grid points. For example, splines_degree \(=0\) means piecewise constant, splines_degree=1 means piecewise linear and so on.
extrapolate Logical, specifying whether to extrapolate the model variables \(\lambda, \mu, \psi\) and \(\kappa\) (as constants) beyond the provided age grid all the way to stem_age and end_age if needed.
Nbootstraps Integer, the number of bootstraps (simulations) to perform for calculating statistical significances. A larger number will increase the accuracy of estimated statistical significances.
Nthreads Integer, number of parallel threads to use for bootstrapping. Note that on Windows machines this option is ignored.

\section*{Details}

In addition to model selection, the adequacy of any chosen model should also be assessed in absolute terms, i.e. not just relative to other competing models (after all, all considered models might be bad). This function essentially determines how probable it is for hypothetical trees generated by a candidate model to resemble the tree at hand, in terms of various test statistics (such as the historically popular "gamma" statistic, or the Colless tree imbalance). In particular, the function uses a Kolmogorov-Smirnov test to check whether the probability distributions of edge lengths and node ages in the tree resemble those expected under the model. All statistical significances are calculated using bootstrapping, i.e. by simulating trees from the provided model with the same number of tips and the same root age as the original tree.
Note that even if an HBD model appears to adequately explain a given timetree, this does not mean that the model even approximately resembles the true diversification history (i.e., the true speciation and extinction rates) that generated the tree (Louca and Pennell 2020). Hence, it is generally more appropriate to say that a given model "congruence class" (or PSR) rather than a specific model (speciation rate, extinction rate, and sampling fraction) explains the tree.
This function requires that the HBD model (or more precisely, its congruence class) be defined in terms of the PSR. If your model is defined in terms of speciation/extinction rates and a sampling fraction, or if your model's congruence class is defined in terms of the pulled diversification rate
(PDR) and the product \(\rho \lambda_{o}\), then you can use simulate_deterministic_hbd to first calculate the corresponding PSR.

\section*{Value}

A named list with the following elements:
\begin{tabular}{ll} 
success & \begin{tabular}{l} 
Logical, indicating whether the model evaluation was successful. If FALSE, then \\
an additional return variable, error, will contain a description of the error, in \\
that case all other return variables may be undefined. Note that success does \\
not say whether the model explains the tree, but rather whether the computation \\
was performed without errors.
\end{tabular} \\
Integer, the number of bootstraps used.
\end{tabular}\(\quad\)\begin{tabular}{ll} 
Numeric, gamma statistic (Pybus and Harvey 2000) of the original tree.
\end{tabular}

Numeric, mean KS statistic of the bootstrap trees' edge lengths.
PedgeKS Numeric, the one-sided statistical significance of the tree's edge-length KS statistic, i.e. the probability that the KS statistic of any tree generated by the model would be larger than the original tree's KS statistic. A low value means that the
probability distribution of edge lengths in the original tree differs strongly from that expected based on the model.
tree_nodeKS \(\quad\)\begin{tabular}{l} 
Numeric, Kolmogorov-Smirnov (KS) statistic of the original tree's node ages \\
(divergence times), i.e. the estimated maximum difference between the tree's \\
and the model's (estimated) cumulative distribution function of node ages.
\end{tabular}
bootstrap_mean_nodeKS
Numeric, mean KS statistic of the bootstrap trees' node ages.
PnodeKS Numeric, the one-sided statistical significance of the tree's node-age KS statistic, i.e. the probability that the KS statistic of any tree generated by the model would be larger than the original tree's KS statistic. A low value means that the probability distribution of node ages in the original tree differs strongly from that expected based on the model.
tree_sizeKS Numeric, Kolmogorov-Smirnov (KS) statistic of the original tree's node sizes (number of descending tips per node), i.e. the estimated maximum difference between the tree's and the model's (estimated) cumulative distribution function of node sizes.
bootstrap_mean_sizeKS
Numeric, mean KS statistic of the bootstrap trees' node sizes.
PsizeKS Numeric, the one-sided statistical significance of the tree's node-size KS statistic, i.e. the probability that the KS statistic of any tree generated by the model would be larger than the original tree's KS statistic. A low value means that the probability distribution of node sizes in the original tree differs strongly from that expected based on the model.
statistical_tests
Data frame, listing the above statistical test results in a more compact format (one test statistic per row).
LTT_ages Numeric vector, listing ages (time before present) on which the tree's LTT will be defined.
tree_LTT Numeric vector of the same length as LTT_ages, listing the number of lineages in the tree at every age in LTT_ages.
bootstrap_LTT_CI
Named list containing the elements means, medians, CI50lower, CI50upper, CI95lower and CI95upper. Each of these elements is a numeric vector of length equal to LTT_ages, listing the mean or a specific percentile of LTTs of bootstrap trees at every age in LTT_ages. For example, bootstrap_LTT_CI\$CI95lower[10] and bootstrap_LTT_CI\$CI95upper[10] define the lower and upper bound, respectively, of the \(95 \%\) confidence interval of LTTs generated by the model at age LTT_ages[10].
fraction_LTT_in_CI95
Numeric, fraction of the tree's LTT contained within the equal-tailed \(95 \%\) confidence interval of the distribution of LTT values predicted by the model. For example, a value of 0.5 means that at half of the time points between the present-day and the root, the tree's LTT is contained with the \(95 \%\)-CI of predicted LTTs.

\section*{Author(s)}

Stilianos Louca

\section*{References}
S. Louca and M. W. Pennell (2020). Extant timetrees are consistent with a myriad of diversification histories. Nature. 580:502-505.
O. G. Pybus and P. H. Harvey (2000). Testing macro-evolutionary models using incomplete molecular phylogenies. Proceedings of the Royal Society of London. Series B: Biological Sciences. 267:2267-2272.
M. J. Sackin (1972). "Good" and "Bad" Phenograms. Systematic Biology. 21:225-226.
K.T. Shao, R. R. Sokal (1990). Tree Balance. Systematic Biology. 39:266-276.
M. G. B. Blum and O. Francois (2006). Which random processes describe the Tree of Life? A large-scale study of phylogenetic tree imbalance. Systematic Biology. 55:685-691.

\section*{See Also}
simulate_deterministic_hbd, model_adequacy_hbds

\section*{Examples}
```


# generate a tree

tree = castor::generate_tree_hbd_reverse(Ntips = 50,
lambda = 1,
mu = 0.5,
rho = 1)$trees[[1]]
root_age = castor::get_tree_span(tree)$max_distance

# define \& simulate a somewhat different BD model

model = simulate_deterministic_hbd(LTT0 = 50,
oldest_age = root_age,
lambda = 1.5,
mu = 0.5,
rho0 = 1)

# compare the tree to the model

adequacy = model_adequacy_hbd(tree,
models = model,
Nbootstraps = 100,
Nthreads = 2)
if(!adequacy$success){
    cat(sprintf("Adequacy test failed: %s\n",adequacy$error))
}else{
print(adequacy\$statistical_tests)
}

```

\section*{Description}

Given a rooted timetree and a homogenous birth-death-sampling model (e.g., as used in molecular epidemiology), check if the model adequately explains various aspects of the tree, such as the branch length and node age distributions and other test statistics. The function uses bootstrapping to simulate multiple hypothetical trees according to the model and then compares the distribution of those trees to the original tree. This function may be used to quantify the "goodness of fit" of a birth-death-sampling model to a timetree. For background on the HBDS model see the documentation for generate_tree_hbds.

\section*{Usage}
model_adequacy_hbds(tree, models,
splines_degree \(=1\),
extrapolate = FALSE,
Nbootstraps \(=1000\),
max_sim_attempts \(=1000\),
Nthreads \(=1\),
max_extant_tips = NULL,
max_model_runtime = NULL)

\section*{Arguments}
tree A rooted timetree of class "phylo".
models Either a single HBDS model or a list of HBDS models, specifying the pool of models from which to randomly draw bootstraps. Every model should itself be a named list with some or all of the following elements:
stem_age: Numeric, the age (time before present) at which the HBDS process started. If NULL, this is automatically set to the input tree's root age.
- end_age : Numeric, the age (time before present) at which the HBDS process halted. This will typically be 0 (i.e., at the tree's youngest tip), however it may also be negative if the process actually halted after the youngest tip was sampled.
- ages: Numeric vector, specifying discrete ages (times before present) in ascending order, on which all model variables (e.g., \(\lambda, \mu\) and \(\psi\) ) will be specified. Age increases from tips to root; the youngest tip in the input tree has age 0 . The age grid must cover stem_age and end_age.
- lambda: Numeric vector of the same length as ages, listing the speciation rate \((\lambda)\) of the HBDS model at the corresponding ages. Between grid points, the speciation rate is assumed to either be constant (if splines_degree=0), or linearly (if splines_degree=1) or quadratically (if splines_degree=2) or cubically (if splines_degree=3).
- mu: Numeric vector of the same length as ages, listing the extinction rate \((\mu)\) of the HBDS model at the corresponding ages. Between grid points, the extinction rate is assumed to either be constant (if splines_degree=0), or linearly (if splines_degree=1) or quadratically (if splines_degree=2) or cubically (if splines_degree=3). Note that in epidemiological models \(\mu\) usually corresponds to the recovery rate plus the death rate of infected hosts. If mu is not included, it is assumed to be zero.
- psi: Optional numeric vector of the same length as ages, listing the Poissonian sampling rate \((\mu)\) of the HBDS model at the corresponding ages. Between grid points, the sampling rate is assumed to either be constant (if splines_degree=0), or linearly (if splines_degree=1) or quadratically (if splines_degree=2) or cubically (if splines_degree=3). If psi is not included, it is assumed to be zero.
- kappa: Optional numeric vector of the same length as ages, listing the retention probability upon sampling ( \(\kappa\) ) of the HBDS model at the corresponding ages. Between grid points, the retention probability is assumed to either be constant (if splines_degree=0), or linearly (if splines_degree=1) or quadratically (if splines_degree=2) or cubically (if splines_degree=3). Note that since kappa are actual probabilities, they must all be between 0 and 1. If kappa is not included, it is assumed to be zero.
- CSA_ages: Numeric vector listing the ages (time before present) of concentrated sampling attempts, in ascending order. If empty or NULL, no concentrated sampling attempts are included, i.e. all sampling is assumed to be done according to the Poissonian rate \(\psi\).
- CSA_probs: Optional numeric vector, of the same length as CSA_ages, specifying the sampling probabilities for each concentrated sampling attempt listed in CSA_ages. Hence, a lineage extant at age CSA_ages[k] has probability CSA_probs[k] of being sampled. Note that since CSA_probs are actual probabilities, they must all be between 0 and 1. CSA_probs must be provided if and only if CSA_ages is provided.
- CSA_kappas: Optional numeric vector, of the same length as CSA_ages, specifying the retention probability upon sampling for each concentrated sampling attempt listed in CSA_ages. Note that since CSA_kappas are actual probabilities, they must all be between 0 and 1. CSA_kappas must be provided if and only if CSA_ages is provided.
If you are assessing the adequacy of a single model with specific parameters, then models can be a single model. If you want to assess the adequacy of a distribution of models, such as sampled from the posterior distribution during a Bayesian analysis, models should list those posterior models.
splines_degree Integer, one of \(0,1,2\) or 3, specifying the polynomial degree of the model parameters \(\lambda, \mu, \psi\) and \(\kappa\) between age-grid points. For example, splines_degree=0 means piecewise constant, splines_degree=1 means piecewise linear and so on.
extrapolate Logical, specifying whether to extrapolate the model variables \(\lambda, \mu, \psi\) and \(\kappa\) (as constants) beyond the provided age grid all the way to stem_age and end_age if needed.

\begin{abstract}
Nbootstraps Integer, the number of bootstraps (simulations) to perform for calculating statistical significances. A larger number will increase the accuracy of estimated statistical significances.
max_sim_attempts
Integer, maximum number of simulation attempts per bootstrap, before giving up. Multiple attempts may be needed if the HBDS model has a high probability of leading to extinction early on.

Nthreads Integer, number of parallel threads to use for bootstrapping. Note that on Windows machines this option is ignored.
max_extant_tips
Integer, optional maximum number of extant tips per simulation. A simulation is aborted (and that bootstrap iteration skipped) if the number of extant tips exceeds this threshold. Use this to avoid occasional explosions of runtimes, for example due to very large generated trees.
max_model_runtime
Numeric, optional maximum computation time (in seconds) to allow for each HBDS model simulation (per bootstrap). Use this to avoid occasional explosions of runtimes, for example due to very large generated trees. Aborted simulations will be omitted from the bootstrap statistics. If NULL or \(<=0\), this option is ignored.
\end{abstract}

\section*{Details}

In addition to model selection, the adequacy of any chosen model should also be assessed in absolute terms, i.e. not just relative to other competing models (after all, all considered models might be bad). This function essentially determines how probable it is for hypothetical trees generated by a candidate model (or a distribution of candidate models) to resemble the tree at hand, in terms of various test statistics. In particular, the function uses a Kolmogorov-Smirnov test to check whether the probability distributions of edge lengths and node ages in the tree resemble those expected under the provided models. All statistical significances are calculated using bootstrapping, i.e. by simulating trees from the provided models. For every bootstrap, a model is randomly chosen from the provided models list.

Note that even if an HBDS model appears to adequately explain a given timetree, this does not mean that the model even approximately resembles the true diversification history (i.e., the true speciation, extinction and sampling rates) that generated the tree (Louca and Pennell 2020). Hence, it is generally more appropriate to say that a given model "congruence class" rather than a specific model explains the tree.
Note that here "age" refers to time before present, i.e. age increases from tips to roots and the youngest tip in the input tree has age 0 . In some situations the process that generated the tree (or which is being compared to the tree) might have halted after the last tip was sampled, in which case end_age should be negative. Similarly, the process may have started prior to the tree's root (e.g., sampled tips coalesce at a later time than when the monitoring started), in which case stem_age should be greater than the root's age.

For convenience, it is possible to specify a model without providing an explicit age grid (i.e., omitting ages); in such a model \(\lambda, \mu, \psi\) and \(\kappa\) are assumed to be time-independent, and hence lambda, \(\mathrm{mu}, \mathrm{psi}\) and kappa must be provided as single numerics (or not provided at all).

\section*{Value}

A named list with the following elements:
\begin{tabular}{ll} 
success & \begin{tabular}{l} 
Logical, indicating whether the model evaluation was successful. If FALSE, then \\
an additional return variable, error, will contain a description of the error, in \\
that case all other return variables may be undefined. Note that success does \\
not say whether the model explains the tree, but rather whether the computation \\
was performed without errors.
\end{tabular} \\
Nbootstraps & Integer, the number of bootstraps used. \\
tree_Ntips & Integer, the number of tips in the original tree. \\
bootstrap_mean_Ntips \\
Numeric, mean number of tips in the bootstrap trees.
\end{tabular}

Numeric, mean Colless statistic across all bootstrap trees.
PColless Numeric, two-sided statistical significance of the tree's Colless statistic under the provided null model, i.e. the probability that abs(bootstrap_mean_Colless-tree_Colless) would be as large as observed.
tree_Sackin Numeric, Sackin statistic (Sackin, 1972) of the original tree.
bootstrap_mean_Sackin
Numeric, median Sackin statistic across all bootstrap trees.
PSackin Numeric, two-sided statistical significance of the tree's Sackin statistic under the provided null model, i.e. the probability that abs(bootstrap_mean_Sackin-tree_Sackin) would be as large as observed.
tree_edgeKS Numeric, Kolmogorov-Smirnov (KS) statistic of the original tree's edge lengths, i.e. the estimated maximum difference between the tree's and the model's (estimated) cumulative distribution function of edge lengths.
bootstrap_mean_edgeKS
Numeric, mean KS statistic of the bootstrap trees' edge lengths.
PedgeKS Numeric, the one-sided statistical significance of the tree's edge-length KS statistic, i.e. the probability that the KS statistic of any tree generated by the model would be larger than the original tree's KS statistic. A low value means that the probability distribution of edge lengths in the original tree differs strongly from that expected based on the model.
tree_tipKS Numeric, Kolmogorov-Smirnov (KS) statistic of the original tree's tip ages (sampling times before present), i.e. the estimated maximum difference between the tree's and the model's (estimated) cumulative distribution function of tip ages.
bootstrap_mean_tipKS
Numeric, mean KS statistic of the bootstrap trees' tip ages.
PtipKS \begin{tabular}{l} 
Numeric, the one-sided statistical significance of the tree's tip-age KS statistic, \\
i.e. the probability that the KS statistic of any tree generated by the model \\
would be larger than the original tree's KS statistic. A low value means that the \\
probability distribution of tip ages in the original tree differs strongly from that \\
expected based on the model. \\
Numeric, Kolmogorov-Smirnov (KS) statistic of the original tree's node ages \\
(divergence times before present), i.e. the estimated maximum difference be- \\
tween the tree's and the model's (estimated) cumulative distribution function of \\
node ages. \\
tree_nodeKS
\end{tabular}
bootstrap_mean_nodeKS
Numeric, mean KS statistic of the bootstrap trees' node ages.
PnodeKS
Numeric, the one-sided statistical significance of the tree's node-age KS statis-
tic, i.e. the probability that the KS statistic of any tree generated by the model
would be larger than the original tree's KS statistic. A low value means that the
probability distribution of node ages in the original tree differs strongly from
that expected based on the model.

\section*{Author(s)}

Stilianos Louca

\section*{References}
S. Louca and M. W. Pennell (2020). Extant timetrees are consistent with a myriad of diversification histories. Nature. 580:502-505.
O. G. Pybus and P. H. Harvey (2000). Testing macro-evolutionary models using incomplete molecular phylogenies. Proceedings of the Royal Society of London. Series B: Biological Sciences. 267:2267-2272.
M. J. Sackin (1972). "Good" and "Bad" Phenograms. Systematic Biology. 21:225-226.
K.T. Shao, R. R. Sokal (1990). Tree Balance. Systematic Biology. 39:266-276.

\section*{See Also}
```

simulate_deterministic_hbds, generate_tree_hbds, model_adequacy_hbd

```

\section*{Examples}
```


## Not run:

# generate a tree based on a simple HBDS process

max_time = 10
gen = castor::generate_tree_hbds(max_time = max_time,
lambda = 1,
mu = 0.1,
psi = 0.1,
no_full_extinction = TRUE)
if(!gen$success) stop(sprintf("Could not generate tree: %s",gen$error))
tree = gen$tree
root_age = castor::get_tree_span(tree)$max_distance

# determine age of the stem, i.e. when the HBDS process started

stem_age = gen\$root_time + root_age

# determine age at which the HBDS simulation was halted.

# This might be slightly negative, e.g. if the process

# halted after the last sampled tip

end_age = root_age - (gen$final_time-gen$root_time)

# compare the tree to a slightly different model

model = list(stem_age = stem_age,
end_age = end_age,
lambda = 1.2,
mu = 0.1,
psi = 0.2)
adequacy = model_adequacy_hbds( tree,
models = model,
Nbootstraps = 100)
if(!adequacy$success){
    cat(sprintf("Adequacy test failed: %s\n",adequacy$error))
}else{
print(adequacy\$statistical_tests)
}

## End(Not run)

```
```

multifurcations_to_bifurcations

```

Expand multifurcations to bifurcations.

\section*{Description}

Eliminate multifurcations from a phylogenetic tree, by replacing each multifurcation with multiple bifurcations.

\section*{Usage}
\[
\begin{aligned}
\text { multifurcations_to_bifurcations } & \text { tree, dummy_edge_length=0, } \\
& \text { new_node_basename="node.", } \\
& \text { new_node_start_index=NULL) }
\end{aligned}
\]

\section*{Arguments}
tree A tree of class "phylo".
dummy_edge_length
Non-negative numeric. Length to be used for new (dummy) edges when breaking multifurcations into bifurcations. Typically this will be 0 , but can also be a positive number if zero edge lengths are not desired in the returned tree.
new_node_basename
Character. Name prefix to be used for added nodes (e.g. "node." or "new.node."). Only relevant if the input tree included node labels.
new_node_start_index
Integer. First index for naming added nodes. Can also be NULL, in which case this is set to Nnodes+1, where Nnodes is the number of nodes in the input tree.

\section*{Details}

For each multifurcating node (i.e. with more than 2 children), all children but one will be placed on new bifurcating nodes, connected to the original node through one or more dummy edges.
The input tree need not be rooted, however descendance from each node is inferred based on the direction of edges in tree\$edge. The input tree may include multifurcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child). Monofurcations are kept in the returned tree.

All tips and nodes in the input tree retain their original indices, however the returned tree may include additional nodes and edges. Edge indices may change.
If tree\$edge. length is missing, then all edges in the input tree are assumed to have length 1 . The returned tree will include edge. length, with all new edges having length equal to dummy_edge_length.

\section*{Value}

A list with the following elements:
\begin{tabular}{ll} 
tree & \begin{tabular}{l} 
A new tree of class "phylo", containing only bifurcations (and monofurcations, \\
if these existed in the input tree).
\end{tabular} \\
old2new_edge & \begin{tabular}{l} 
Integer vector of length Nedges, mapping edge indices in the old tree to edge \\
indices in the new tree.
\end{tabular} \\
Nnodes_added \(\quad\)\begin{tabular}{l} 
Integer. Number of nodes added to the new tree.
\end{tabular}
\end{tabular}

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
collapse_monofurcations

\section*{Examples}
```


# generate a random multifurcating tree

Ntips = 1000
tree = generate_random_tree(list(birth_rate_intercept=1), Ntips, Nsplits=5)\$tree

# expand multifurcations to bifurcations

new_tree = multifurcations_to_bifurcations(tree)\$tree

# print summary of old and new tree

cat(sprintf("Old tree has %d nodes\n",tree$Nnode))
cat(sprintf("New tree has %d nodes\n",new_tree$Nnode))

```
pick_random_tips Pick random subsets of tips on a tree.

\section*{Description}

Given a rooted phylogenetic tree, this function picks random subsets of tips by traversing the tree from root to tips, choosing a random child at each node until reaching a tip. Multiple random independent subsets can be generated if needed.

\section*{Usage}
\[
\begin{array}{ll}
\text { pick_random_tips( tree, } & =1, \\
\text { size } & =1, \\
\text { Nsubsets } & =\text { TRUE }, \\
\text { with_replacement } & =\text { TRUE }
\end{array}
\]

\section*{Arguments}
\(\left.\begin{array}{ll}\text { tree } & \begin{array}{l}\text { A rooted tree of class "phylo". The root is assumed to be the unique node with } \\ \text { no incoming edge. }\end{array} \\ \text { size } & \text { Integer. The size of each random subset of tips. } \\ \text { Nsubsets } & \text { Integer. Number of independent subsets to pick. } \\ \text { with_replacement }\end{array} \quad \begin{array}{l}\text { Logical. If TRUE, each tip can be picked multiple times within a subset (i.e. are } \\ \text { "replaced" in the urn). If FALSE, tips are picked without replacement in each } \\ \text { subset. In that case, size must not be greater than the number of tips in the tree. }\end{array}\right\}\).

\section*{Details}

If with_replacement==TRUE, then each child of a node is equally probable to be traversed and each tip can be included multiple times in a subset. If with_replacement==FALSE, then only children with at least one descending tip not included in the subset remain available for traversal; each available child of a node has equal probability to be traversed. In any case, it is always possible for separate subsets to include the same tips.
This random sampling algorithm differs from a uniform sampling of tips at equal probabilities; instead, this algorithm ensures that sister clades have equal probabilities to be picked (if with_replacement==TRUE or if size«Ntips).

The time required by this function per random subset decreases with the number of subsets requested.

\section*{Value}

A 2D integer matrix of size Nsubsets \(x\) size, with each row containing indices of randomly picked tips (i.e. in \(1, .\), Ntips) within a specific subset. If drop_dims==TRUE and Nsubsets==1, then a vector is returned instead of a matrix.

\section*{Author(s)}

Stilianos Louca

\section*{Examples}
```


# generate random tree

Ntips = 1000
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# pick random tip subsets

Nsubsets = 100
size = 50
subsets = pick_random_tips(tree, size, Nsubsets, with_replacement=FALSE)

# count the number of times each tip was picked in a subset ("popularity")

popularities = table(subsets)

```
\# plot histogram of tip popularities
hist(popularities,breaks=20,xlab="popularity",ylab="\# tips",main="tip popularities")
read_tree Load a tree from a string or file in Newick (parenthetic) format.

\section*{Description}

Load a phylogenetic tree from a file or a string, in Newick (parenthetic) format. Any valid Newick format is acceptable. Extended variants including edge labels and edge numbers are also supported.

\section*{Usage}
\[
\begin{aligned}
& \text { read_tree( string = "", } \\
& \text { file = "", } \\
& \text { edge_order = "cladewise", } \\
& \text { include_edge_lengths = TRUE, } \\
& \text { look_for_edge_labels = FALSE, } \\
& \text { look_for_edge_numbers = FALSE, } \\
& \text { include_node_labels = TRUE, } \\
& \text { underscores_as_blanks = FALSE, } \\
& \text { check_label_uniqueness = FALSE, } \\
& \text { interpret_quotes = FALSE, } \\
& \text { trim_white = TRUE) }
\end{aligned}
\]

\section*{Arguments}
string A character containing a single tree in Newick format. Can be used alternatively to file.
file Character, a path to an input text file containing a single tree in Newick format. Can be used alternatively to string.
edge_order Character, one of "cladewise" or "pruningwise", specifying the order in which edges should be listed in the returned tree. This does not influence the topology of the tree or the tip/node labeling, it only affects the way edges are numbered internally.
include_edge_lengths
Logical, specifying whether edge lengths (if available) should be included in the returned tree.
look_for_edge_labels
Logical, specifying whether edge labels may be present in the input tree. If edge labels are found, they are included in the returned tree as a character vector edge. label. Edge labels are sought inside square brackets, which are not part of the standard Newick format but used by some tree creation software (Matsen 2012). If look_for_edge_labels==FALSE, square brackets are read verbatim just like any other character.
look_for_edge_numbers
Logical, specifying whether edge numbers (non-negative integers) may be present in the input tree. If edge numbers are found, they are included in the returned tree as an integer vector edge. number. Edge numbers are sought inside curly braces, which are not part of the standard Newick format but used by some tree creation software (Matsen 2012). If look_for_edge_numbers==FALSE, curly braces are read verbatim just like any other character.
include_node_labels
Logical, specifying whether node labels (if available) should be included in the returned tree.
underscores_as_blanks
Logical, specifying whether underscores ("_") in tip and node labels should be replaced by spaces (" "). This is common behavior in other tree parsers. In any case, tip, node and edge labels (if available) are also allowed to contain explicit whitespace (except for newline characters).
check_label_uniqueness
Logical, specifying whether to check if all tip labels are unique.
interpret_quotes
Logical, specifying whether to interpret quotes as delimiters of tip/node/edge labels. If FALSE, then quotes are read verbatim just like any other character.
trim_white Logical, specifying whether to trim flanking whitespace from tip, node and edge labels.

\section*{Details}

This function is comparable to (but typically much faster than) the ape function read.tree. The function supports trees with monofurcations and multifurcations, trees with or without tip/node labels, and trees with or without edge lengths. The time complexity is linear in the number of edges in the tree.

Either file or string must be specified, but not both. The tree may be arbitrarily split across multiple lines, but no other non-whitespace text is permitted in string or in the input file. Flanking whitespace (space, tab, newlines) is ignored.

\section*{Value}

A single rooted phylogenetic tree in "phylo" format.

\section*{Author(s)}

Stilianos Louca

\section*{References}

Frederick A. Matsen et al. (2012). A format for phylogenetic placements. PLOS One. 7:e31009

\section*{See Also}
write_tree

\section*{Examples}
```


# generate a random tree

tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=100)\$tree

# obtain a string representation of the tree in Newick format

Newick_string = write_tree(tree)

# re-parse tree from string

parsed_tree = read_tree(Newick_string)

```
reconstruct_past_diversification
Reconstruct past diversification dynamics from a diversity time series.

\section*{Description}

Given a time series of past diversities (coalescent or not), this function estimates instantaneous birth (speciation) and death (extinction) rates that would lead to the observed diversity time series. The function is based on a deterministic model (or the continuum limit of a stochastic cladogenic model), in which instantaneous birth and death rates lead to a predictable growth of a tree (one new species per birth event). The reconstruction is non-parametric, i.e. does not rely on fitting a parameterized model. The reconstruction is only accurate in the deterministic limit, i.e. for high diversities where the stochastic nature of the cladogenic process diminishes. Of particular importance is the case where the time series is coalescent, i.e. represents the diversity (lineages-through-time) that would be represented in a coalescent tree with extinctions.
Note: This function is included for legacy reasons mainly. In most cases users should instead use the functions fit_hbd_model_on_grid and fit_hbd_model_parametric to fit birth-death models, or the functions fit_hbd_pdr_on_grid, fit_hbd_pdr_parametric and fit_hbd_psr_on_grid to fit BD model congruence classes (aka. "pulled variables") to a tree.

\section*{Usage}
\[
\begin{array}{lll}
\text { reconstruct_past_diversification( } & \text { times, } & \\
& \text { diversities, } & =\text { NULL, } \\
& \text { birth_rates_pc } & \text { rarefaction } \\
& \text { discovery_fractions } & =\text { NULL, } \\
& \text { discovery_fraction_slopes } & =\text { NULL, } \\
& \text { max_age } & =N U L L, \\
& \text { coalescent } & =\text { FALSE, } \\
& \text { smoothing_span } & =0 \\
& \text { smoothing_order } & =1)
\end{array}
\]

\section*{Arguments}
times Numeric vector, listing the times at which diversities are given. Values must be in ascending order.
diversities Numeric vector of the same size as times, listing diversities (coalescent or not) at each time point.
birth_rates_pc Numeric vector of the same size as times, listing known or assumed per-capita birth rates (speciation rates). Can also be of size 1, in which case the same percapita birth rate is assumed throughout. Alternatively if coalescent==TRUE, then this vector can also be empty, in which case a constant per-capita birth rate is assumed and estimated from the slope of the coalescent diversities at the last time point. The last alternative is not available when coalescent==FALSE.
rarefaction Numeric between 0 and 1 . Optional rarefaction fraction assumed for the diversities at the very end. Set to 1 to assume no rarefaction was performed.
discovery_fractions
Numeric array of size Ntimes, listing the fractions of extant lineages represented in the tree over time. Hence, discovery_fraction[t] is the probability that a lineage at time times[t] with extant representatives will be represented in the tree. Can be used as an alternative to rarefaction, for example if discovery of extant species is non-random or phylogenetically biased. Experimental, so leave this NULL if you don't know what it means.
discovery_fraction_slopes
Numeric array of size Ntimes, listing the 1st derivative of discovery_fractions (w.r.t. time) over time. If NULL, this will be estimated from discovery_fractions via basic finite differences if needed. Experimental, so leave this NULL if you don't know what it means.
max_age Numeric. Optional maximum distance from the end time to be considered. If NULL or \(<=0\) or Inf, all provided time points are considered.
coalescent Logical, indicating whether the provided diversities are from a coalescent tree (only including clades with extant representatives) or total diversities (extant species at each time point).
smoothing_span Non-negative integer. Optional sliding window size (number of time points) for smoothening the diversities time series via Savitzky-Golay-filter. If \(<=2\), no smoothing is done. Smoothening the time series can reduce the effects of noise on the reconstructed diversity dynamics.
smoothing_order
Integer between 1 and 4. Polynomial order of the Savitzky-Golay smoothing filter to be applied. Only relevant if smoothing_span>2. A value of 1 or 2 is typically recommended.

\section*{Details}

This function can be used to fit a birth-death model to a coalescent diversity time series \(N_{c}(\tau)\) at various ages \(\tau\), also known as "lineages-through-time" curve. The reconstruction of the total diversity \(N(\tau)\) is based on the following formulas:
\[
\begin{aligned}
& E(\tau)=1+\frac{\nu(\tau)}{\beta(\tau)} \\
& N(\tau)=\frac{N_{c}}{1-E(\tau)}
\end{aligned}
\]
\[
\nu(\tau)=\frac{1}{N_{c}(\tau)} \frac{d N_{c}(\tau)}{d \tau}
\]
where \(E(\tau)\) is the probability that a clade of size 1 at age \(\tau\) went extinct by the end of the time series and \(\beta\) is the per-capita birth rate. If the per-capita birth rate is not explicitly provided for each time point (see argument birth_rate_pc), the function assumes that the per-capita birth rate (speciation rate) is constant at all times. If birth_rates_pc==NULL and coalescent==TRUE, the constant speciation rate is estimated as
\[
\beta=-\frac{\nu(0)}{\rho}
\]
where \(\rho\) is the fraction of species kept after rarefaction (see argument rarefaction).
Assuming a constant speciation rate may or may not result in accurate estimates of past total diversities and other quantities. If a time-varying speciation rate is suspected but not known, additional information on past diversification dynamics may be obtained using modified ("pulled") quantities that partly resemble the classical extinction rate, diversification rate and total diversity. Such quantities are the "pulled diversification rate":
\[
\eta(\tau)=\delta(\tau)-\beta(\tau)+\frac{1}{\beta(\tau)} \frac{d \beta}{d \tau}
\]
the "pulled extinction rate":
\[
\delta_{p}(\tau)=\delta(\tau)+\left(\beta_{o}-\beta(\tau)\right)-\frac{1}{\beta(\tau)} \frac{d \beta}{d \tau}
\]
and the "pulled total diversity":
\[
N_{p}(\tau)=N(\tau) \cdot \frac{\beta_{o}}{\beta(\tau)}
\]
where \(\beta_{o}\) is the provided or estimated (if not provided) speciation rate at the last time point. The advantage of these quantities is that they can be estimated from the coalescent diversities (lineages-through-time) without any assumptions on how \(\beta\) and \(\delta\) varied over time. The disadvantage is that they differ from their "non-pulled" quantities \((\beta-\delta, \delta\) and \(N\) ), in cases where \(\beta\) varied over time.

\section*{Value}

A named list with the following elements:
success Logical, specifying whether the reconstruction was successful. If FALSE, the remaining elements may not be defined.
Ntimes Integer. Number of time points for which reconstruction is returned.
total_diversities
Numeric vector of the same size as times, listing the total diversity at each time point (number of extant lineages at each time point). If coalescent==FALSE, then these are the same as the diversities passed to the function.
coalescent_diversities
Numeric vector of the same size as times, listing the coalescent diversities at each time point (number of species with at least one extant descendant at the last time point). If coalescent==TRUE, then these are the same as the diversities passed to the function.
birth_rates Numeric vector of the same size as times, listing the estimated birth rates (speciation events per time unit).
death_rates Numeric vector of the same size as times, listing the estimated death rates (extinction events per time unit).

Psurvival Numeric vector of the same size as times, listing the estimated fraction of lineages at each time point that eventually survive. Psurvival[i] is the probability that a clade of size 1 at time times[i] will be extant by the end of the time series. May be NULL in some cases.

Pdiscovery Numeric vector of the same size as times, listing the estimated fraction of lineages at each time point that are eventually discovered, provided that they survive. Pdiscovery[i] is the probability that a clade of size 1 at time times[i] that is extant by the end of the time series, will be discovered. May be NULL in some cases.
Prepresentation
Numeric vector of the same size as times, listing the estimated fraction of lineages at each time point that eventually survive and are discovered. Prepresentation[i] is the probability that a clade of size 1 at time times[i] will be extant by the end of the time series and visible in the coalescent tree after rarefaction. Note that Prepresentation \(=\) Psurvival \(*\) Pdiscovery. May be NULL in some cases.
total_births Numeric, giving the estimated total number of birth events that occurred between times T-max_age and \(T\), where \(T\) is the last time point of the time series.
total_deaths Numeric, giving the estimated total number of death events that occurred between times \(T\)-max_age and \(T\), where \(T\) is the last time point of the time series.
last_birth_rate_pc
The provided or estimated (if not provided) speciation rate at the last time point. This corresponds to the birth rate divided by the estimated true diversity (prior to rarefaction) at the last time point.
last_death_rate_pc
The estimated extinction rate at the last time point. This corresponds to the death rate divided by the estimated true diversity (prior to rarefaction) at the last time point.
pulled_diversification_rates
Numeric vector of the same size as times, listing the estimated pulled diversification rates.
pulled_extinction_rates
Numeric vector of the same size as times, listing the estimated pulled extinction rates.
pulled_total_diversities
Numeric vector of the same size as times, listing the estimated pulled total diversities.

\section*{Author(s)}

Stilianos Louca

\section*{References}

Louca et al (2018). Bacterial diversification through geological time. Nature Ecology \& Evolution. 2:1458-1467.

\section*{See Also}
generate_random_tree, fit_tree_model, count_lineages_through_time, fit_hbd_model_parametric, fit_hbd_model_on_grid

\section*{Examples}
```

\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#

# EXAMPLE 1

# Generate a coalescent tree

params = list(birth_rate_intercept = 0,
birth_rate_factor = 1,
birth_rate_exponent = 1,
death_rate_intercept = 0,
death_rate_factor = 0.05,
death_rate_exponent = 1.3,
rarefaction = 1)
simulation = generate_random_tree(params,max_time_eq=1,coalescent=TRUE)
tree = simulation$tree
time_span = simulation$final_time - simulation$root_time
cat(sprintf("Generated tree has %d tips, spans %g time units\n",length(tree$tip.label),time_span))

# Calculate diversity time series from the tree

counter = count_lineages_through_time(tree, times=seq(0,0.99*time_span,length.out=100))

# print coalescent diversities

print(counter\$lineages)

# reconstruct diversification dynamics based on diversity time series

results = reconstruct_past_diversification( counter$times,
                counter$lineages,
coalescent = TRUE,
smoothing_span = 3,
smoothing_order = 1)

# print reconstructed total diversities

print(results\$total_diversities)

# plot coalescent and reconstructed true diversities

matplot(x = counter$times,
    y = matrix(c(counter$lineages,results\$total_diversities), ncol=2, byrow=FALSE),
type = "b",
xlab = "time",
ylab = "\# clades",
lty = c(1,2), pch = c(1,0), col = c("red","blue"))
legend( "topleft",
legend = c("coalescent (simulated)","true (reconstructed)"),

```
```

col = c("red","blue"), lty = c(1,2), pch = c(1,0));
\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#\#

# EXAMPLE 2

# Generate a non-coalescent tree

params = list(birth_rate_intercept = 0,
birth_rate_factor = 1,
birth_rate_exponent = 1,
death_rate_intercept = 0,
death_rate_factor = 0.05,
death_rate_exponent = 1.3,
rarefaction = 1)
simulation = generate_random_tree(params,max_time_eq=1,coalescent=FALSE)
tree = simulation$tree
time_span = simulation$final_time - simulation$root_time
cat(sprintf("Generated tree has %d tips, spans %g time units\n",length(tree$tip.label),time_span))

# Calculate diversity time series from the tree

counter = count_lineages_through_time(tree, times=seq(0,0.99*time_span,length.out=100))

# print true diversities

print(counter\$lineages)

# reconstruct diversification dynamics based on diversity time series

results = reconstruct_past_diversification( counter$times,
                        counter$lineages,
birth_rates_pc = params\$birth_rate_factor,
coalescent = FALSE,
smoothing_span = 3,
smoothing_order = 1)

# print coalescent diversities

print(results\$coalescent_diversities)

# plot coalescent and reconstructed true diversities

matplot(x = counter$times,
    y = matrix(c(results$coalescent_diversities,counter\$lineages), ncol=2, byrow=FALSE),
type = "b",
xlab = "time",
ylab = "\# clades",
lty = c(1,2), pch = c(1,0), col = c("red","blue"))
legend( "topleft",
legend = c("coalescent (reconstructed)","true (simulated)"),
col = c("red","blue"), lty = c(1,2), pch = c(1,0));

```

\section*{Description}

Given a rooted tree, this function reorders the rows in tree\$edge so that they are listed in preorder (root->tips) or postorder (tips->root) traversal.

\section*{Usage}
\[
\begin{aligned}
\text { reorder_tree_edges } & \text { (tree, root_to_tips=TRUE, } \\
& \text { depth_first_search=TRUE, } \\
& \text { index_only=FALSE) }
\end{aligned}
\]

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
root_to_tips Logical, specifying whether to sort edges in preorder traversal (root->tips), rather than in postorder traversal (tips->roots).
depth_first_search
Logical, specifying whether the traversal (or the reversed traversal, if root_to_tips is FALSE) should be in depth-first-search format rather than breadth-first-search format.
index_only Whether the function should only return a vector listing the reordered row indices of the edge matrix, rather than a modified tree.

\section*{Details}

This function does not change the tree structure, nor does it affect tip/node indices and names. It merely changes the order in which edges are listed in the matrix tree\$edge, so that edges are listed in preorder or postorder traversal. Preorder traversal guarantees that each edge is listed before any of its descending edges. Likewise, postorder guarantees that each edge is listed after any of its descending edges.
With options root_to_tips=TRUE and depth_first_search=TRUE, this function is analogous to the function reorder in the ape package with option order="cladewise".

The tree can include multifurcations (nodes with more than 2 children) as well as monofurcations (nodes with 1 child). This function has asymptotic time complexity O (Nedges).

\section*{Value}

If index_only==FALSE, a tree object of class "phylo", with the rows in edge reordered such that they are listed in direction root \(->\) tips (if root_to_tips==TRUE) or tips \(->\) root. The vector tree\$edge. length will also be updated in correspondence. Tip and node indices and names remain unchanged.
If index_only=TRUE, an integer vector (X) of size Nedges, listing the reordered row indices of tree\$edge, i.e. such that tree\$edge[X,] would be the reordered edge matrix.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

get_tree_traversal_root_to_tips

```

\section*{Examples}
```


## Not run:

# generate a random tree

tree = generate_random_tree(list(birth_rate_factor=1), max_tips=100)\$tree

# get new tree with reordered edges

postorder_tree = reorder_tree_edges(tree, root_to_tips=FALSE)

## End(Not run)

```
root_at_midpoint Root or re-root a tree at the midpoint node.

\section*{Description}

Given a tree (rooted or unrooted), this function changes the direction of edges (tree\$edge) such that the new root satisfies a "midpoint"" criterion. The number of tips and the number of nodes remain unchanged. The root can either be placed on one of the existing nodes (this node will be the one whose maximum distance to any tip is minimized) or in the middle of one of the existing edges (chosen to be in the middle of the longest path between any two tips).

\section*{Usage}

\section*{Arguments}
tree A tree object of class "phylo". Can be unrooted or rooted (but see option is_rooted).
split_edge Logical, specifying whether to place the new root in the middle of an edge (in the middle of the longest path of any two tips), thereby creating a new node. If FALSE, then the root will be placed on one of the existing nodes; note that the resulting tree may no longer be bifurcating at the root.
update_indices Logical, specifying whether to update the node indices such that the new root is the first node in the list, as is common convention. This will modify tree\$node. label (if it exists) and also the node indices listed in tree\$edge. Note that this option is only relevant if split_edge=FALSE; if split_edge=TRUE then update_indices will always be assumed TRUE.
\[
\begin{array}{ll}
\text { as_edge_counts } & \begin{array}{l}
\text { Logical, specifying whether phylogenetic distances should be measured as cu- } \\
\text { mulative edge counts. This is the same if all edges had length } 1 .
\end{array} \\
\text { is_rooted } & \begin{array}{l}
\text { Logical, specifying whether the input tree can be assumed to be rooted. If you } \\
\text { are not certain that the tree is rooted, set this to FALSE. }
\end{array}
\end{array}
\]

\section*{Details}

The input tree may include an arbitrary number of incoming and outgoing edges per node (but only one edge per tip), and the direction of these edges can be arbitrary. Of course, the undirected graph defined by all edges must still be a valid tree. Only set is_rooted=TRUE if you are sure that the input tree is rooted.

If update_indices==FALSE and split_edge=FALSE, then node indices remain unchanged. If update_indices==TRUE (default) or split_edge=TRUE, then node indices are modified such that the new root is the first node (i.e. with index Ntips+1 in edge and with index 1 in node.label), as is common convention. Setting update_indices=FALSE (when split_edge=FALSE) reduces the computation required for rerooting. Tip indices always remain unchanged.

The asymptotic time complexity of this function is O (Nedges).

\section*{Value}

A tree object of class "phylo", with the edge element modified such that the maximum distance of the root to any tip is minimized. The elements tip. label, edge.length and root.edge (if they exist) are the same as for the input tree. If update_indices==FALSE, then the element node. label will also remain the same.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

root_via_outgroup, root_at_node, root_in_edge

```

\section*{Examples}
\# generate a random tree
Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1), max_tips=Ntips)\$tree
\# reroot the tree at its midpoint node
tree = root_at_midpoint(tree)

\section*{Description}

Given a tree (rooted or unrooted) and a specific node, this function changes the direction of edges (tree\$edge) such that the designated node becomes the root (i.e. has no incoming edges and all other tips and nodes descend from it). The number of tips and the number of nodes remain unchanged.

\section*{Usage}
root_at_node(tree, new_root_node, update_indices=TRUE)

\section*{Arguments}
tree A tree object of class "phylo". Can be unrooted or rooted.
new_root_node Character or integer specifying the name or index, respectively, of the node to be turned into root. If an integer, it must be between 1 and tree \(\$ N n o d e\). If a character, it must be a valid entry in tree\$node. label.
update_indices Logical, specifying whether to update the node indices such that the new root is the first node in the list (as is common convention). This will modify tree\$node. label (if it exists) and also the node indices listed in tree\$edge.

\section*{Details}

The input tree may include an arbitrary number of incoming and outgoing edges per node (but only one edge per tip), and the direction of these edges can be arbitrary. Of course, the undirected graph defined by all edges must still be a valid tree. The asymptotic time complexity of this function is O (Nedges).
If update_indices==FALSE, then node indices remain unchanged. If update_indices==TRUE (default), then node indices are modified such that the new root is the first node (i.e. with index Ntips+1 in edge and with index 1 in node. label). This is common convention, but it may be undesirable if, for example, you are looping through all nodes in the tree and are only temporarily designating them as root. Setting update_indices=FALSE also reduces the computation required for rerooting. Tip indices always remain unchanged.

\section*{Value}

A tree object of class "phylo", with the edge element modified such that the node new_root_node is root. The elements tip.label, edge. length and root. edge (if they exist) are the same as for the input tree. If update_indices==FALSE, then the element node. label will also remain the same.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

root_via_outgroup, root_at_midpoint,root_in_edge

```

\section*{Examples}
```


# generate a random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# reroot the tree at the 20-th node

new_root_node = 20
tree = root_at_node(tree, new_root_node, update_indices=FALSE)

# find new root index and compare with expectation

cat(sprintf("New root is %d, expected at %d\n",find_root(tree),new_root_node+Ntips))

```
```

root_in_edge Root or re-root a tree in the middle of an edge.

```

\section*{Description}

Given a tree (rooted or unrooted), this function places the new root on some specified edge, effectively adding one more node, one more edge and changing the direction of edges as required.

\section*{Usage}
```

root_in_edge( tree,
root_edge,
location = 0.5,
new_root_name = NULL,
collapse_monofurcations = TRUE)

```

\section*{Arguments}
tree A tree object of class "phylo". Can be unrooted or rooted.
root_edge Integer, index of the edge into which the new root is to be placed. Must be between 1 and Nedges.
location \(\quad\) Numeric, between 0 and 1, specifying the relative location along the root_edge at which to place the root (relative to the edge length, measured from the upstream node). For example, location=0.5 means the root is placed in the middle of the edge, while location=0.1 means that it will be place closer to the upstream node (i.e., closer to tree\$edge[root_edge, 1]).
new_root_name Character, optional, specifying the node name to use for the new root. Only used if tree\$node. label is not NULL.
collapse_monofurcations
Logical, specifying whether monofurcations in the rerooted tree (e.g. stemming from the old root) should be collapsed by connecting incoming edges with outgoing edges.

\section*{Details}

The input tree may include an arbitrary number of incoming and outgoing edges per node (but only one edge per tip), and the direction of these edges can be arbitrary. Of course, the undirected graph defined by all edges must still be a valid tree.

The number of tips in the rerooted tree remains unchanged, the number of nodes is increased by 1. Node indices may be modified. Tip indices always remain unchanged.
The asymptotic time complexity of this function is O (Nedges).

\section*{Value}

A tree object of class "phylo", representing the (re-)rooted phylogenetic tree. The element tip. label is the same as for the input tree, but all other elements may have changed.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
root_via_outgroup, root_at_node, root_at_midpoint

\section*{Examples}
```


# generate a random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# reroot the tree inside some arbitrary edge

focal_edge = 120
tree = root_in_edge(tree, focal_edge)

```
root_via_outgroup Root or re-root a tree based on an outgroup tip.

\section*{Description}

Given a tree (rooted or unrooted) and a specific tip ("outgroup"), this function changes the direction of edges (tree\$edge) such that the outgroup's parent node becomes the root. The number of tips and the number of nodes remain unchanged.

\section*{Usage}
root_via_outgroup(tree, outgroup, update_indices=TRUE)

\section*{Arguments}
\[
\begin{array}{ll}
\text { tree } & \text { A tree object of class "phylo". Can be unrooted or rooted. } \\
\text { outgroup } & \begin{array}{l}
\text { Character or integer specifying the name or index, respectively, of the outgroup } \\
\text { tip. If an integer, it must be between } 1 \text { and Ntips. If a character, it must be a } \\
\text { valid entry in tree\$tip. label. }
\end{array} \\
\text { update_indices } & \begin{array}{l}
\text { Logical, specifying whether to update the node indices such that the new root is } \\
\text { the first node in the list (as is common convention). This will modify tree\$node. label } \\
\text { (if it exists) and also the node indices listed in tree\$edge. }
\end{array}
\end{array}
\]

\section*{Details}

The input tree may include an arbitrary number of incoming and outgoing edges per node (but only one edge per tip), and the direction of these edges can be arbitrary. Of course, the undirected graph defined by all edges must still be a valid tree. The asymptotic time complexity of this function is O (Nedges).
If update_indices==FALSE, then node indices remain unchanged. If update_indices==TRUE (default), then node indices are modified such that the new root is the first node (i.e. with index Ntips+1 in edge and with index 1 in node. label). This is common convention, but it may be undesirable in some cases. Setting update_indices=FALSE also reduces the computation required for rerooting. Tip indices always remain unchanged.

\section*{Value}

A tree object of class "phylo", with the edge element modified such that the outgroup tip's parent node is root. The elements tip. label, edge. length and root. edge (if they exist) are the same as for the input tree. If update_indices==FALSE, then the element node. label will also remain the same.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
root_at_node, root_at_midpoint, root_in_edge

\section*{Examples}
```


# generate a random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=Ntips)\$tree

# reroot the tree using the 1st tip as outgroup

outgroup = 1
tree = root_via_outgroup(tree, outgroup, update_indices=FALSE)

# find new root index

cat(sprintf("New root is %d\n",find_root(tree)))

```
shift_clade_times Shift the time of specific nodes \& tips.

\section*{Description}

Given a rooted tree, shift the times (distance from root) of specific tips \& nodes.

\section*{Usage}
shift_clade_times( tree,
clades_to_shift,
time_shifts,
shift_descendants = FALSE,
negative_edge_lengths = "error")

\section*{Arguments}
tree A rooted tree of class "phylo".
clades_to_shift
Integer or character vector, listing the tips and/or nodes whose time is to be shifted. If an integer vector, values must correspond to indices and must be in the range \(1, . ., N t i p s+N n o d e s\). If a character vector, values must correspond to tip and/or node labels in the tree; if node labels are listed, the tree must contain node labels (attribute node. label).
time_shifts Numeric vector of the same length as clades_to_shift, specifying the time shifts to apply to every tip/node listed in clades_to_shift. Values can be negative (shift towards the root) or positive (shift away from the root).
shift_descendants
Logical, specifying whether to shift the entire descending subclade when shifting a node. If FALSE, the descending tips \& nodes retain their original time (unless negative edges are created, see option negative_edge_lengths).
negative_edge_lengths
Character, specifying whether and how to fix negative edge lengths resulting from excessive shifting. Must be either "error", "allow" (allow and don't fix negative edge lengths), "move_all_descendants" (move all descendants forward as needed, to make the edge non-negative), "move_all_ancestors" (move all ancestors backward as needed, to make the edge non-negative), "move_child" (only move children to younger ages as needed, traversing the tree root->tips) or "move_parent" (only move parents to older ages as needed, traversing the tree tips->root). Note that "move_child" could result in tips moving, if an ancestral node is shifted too much towards younger ages. Similarly, "move_parent" could result in the root moving towards an older age if some descendant was shifted too far towards the root.

\section*{Details}

The input tree may include multi-furcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child). The input tree does not need to be ultrametric, but edge lengths are interpreted as time. If edge lengths are missing from the tree, it is assumed that each edge has length 1.
All tips, nodes and edges are kept and indexed as in the input tree; the only thing that changes are the edgen lengths.

Note that excessive shifting can result in negative edge lengths, which can be corrected in a variety of alternative ways (see option negative_edge_lengths). However, to avoid changing the overall span of the tree (root age and tip times) in an effort to fix negative edge lengths, you should generally not shift a clade beyond the boundaries of the tree (i.e., resulting in a negative time or a time beyond its descending tips).

\section*{Value}

A list with the following elements:
\[
\begin{array}{ll}
\text { success } & \begin{array}{l}
\text { Logical, specifying whether the operation was successful. If FALSE, an addi- } \\
\text { tional variable error is returned, briefly specifying the error, but all other return } \\
\text { variables may be undefined. }
\end{array} \\
\text { tree } & \text { A new rooted tree of class "phylo", representing the tree with shifted clade times. }
\end{array}
\]

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
get_all_distances_to_root, trim_tree_at_height, get_tree_span

\section*{Examples}
```


# generate a random tree, include node names

tree = generate_random_tree(list(birth_rate_intercept=1),
max_tips=20,
node_basename="node.")\$tree

# shift a few nodes backward in time,

# changing as few of the remaining node timings as possible

clades_to_shift = c("node.2", "node.5", "node.6")
time_shifts = c(-0.5, -0.2, -0.3)
new_tree = shift_clade_times(tree,
clades_to_shift,
time_shifts,
shift_descendants=FALSE,
negative_edge_lengths="move_parent")\$tree

```
simulate_bm_model Simulate a Brownian motion model for multivariate trait co-evolution.

\section*{Description}

Given a rooted phylogenetic tree and a Brownian motion (BM) model for the co-evolution of one or more continuous (numeric) unbounded traits, simulate random outcomes of the model on all nodes and/or tips of the tree. The function traverses nodes from root to tips and randomly assigns a multivariate state to each node or tip based on its parent's previously assigned state and the specified model parameters. The generated states have joint distributions consistent with the multivariate BM model. Optionally, multiple independent simulations can be performed using the same model.

\section*{Usage}
```

simulate_bm_model(tree, diffusivity=NULL, sigma=NULL,
include_tips=TRUE, include_nodes=TRUE,
root_states=NULL, Nsimulations=1, drop_dims=TRUE)

```

\section*{Arguments}
\begin{tabular}{ll} 
tree & \begin{tabular}{l} 
A rooted tree of class "phylo". The root is assumed to be the unique node with \\
no incoming edge.
\end{tabular} \\
diffusivity & \begin{tabular}{l} 
Either NULL, or a single number, or a 2D quadratic positive definite symmetric \\
matrix of size Ntraits x Ntraits. Diffusivity matrix (" \(D\) ") of the multivariate \\
Brownian motion model (in units trait^2/edge_length). The convention is that if \\
the root's state is fixed, then the covariance matrix of a node's state at distance \\
\(L\) from the root will be \(2 L D\) (see mathematical details below).
\end{tabular} \\
Either NULL, or a single number, or a 2D matrix of size Ntraits x Ndegrees, \\
where Ndegrees refers to the degrees of freedom of the model. Noise-amplitude \\
coefficients of the multivariate Brownian motion model (in units trait/sqrt(edge_length)).
\end{tabular}

\section*{Details}

The BM model for Ntraits co-evolving traits is defined by the stochastic differential equation
\[
d X=\sigma \cdot d W
\]
where \(W\) is a multidimensional Wiener process with Ndegrees independent components and \(\sigma\) is a matrix of size Ntraits x Ndegrees. Alternatively, the same model can be defined as a Fokker-Planck equation for the probability density \(\rho\) :
\[
\frac{\partial \rho}{\partial t}=\sum_{i, j} D_{i j} \frac{\partial^{2} \rho}{\partial x_{i} \partial x_{j}}
\]

The matrix \(D\) is referred to as the diffusivity matrix (or diffusion tensor), and \(2 D=\sigma \cdot \sigma^{T}\). Either diffusivity \((D)\) or sigma ( \(\sigma\) ) may be used to specify the BM model, but not both.
If tree\$edge. length is missing, each edge in the tree is assumed to have length 1 . The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as mono-furcations (i.e. nodes with only one child). The asymptotic time complexity of this function is O (Nedges*Nsimulations*Ntraits).

\section*{Value}

A list with the following elements:
\[
\begin{array}{ll}
\text { tip_states } & \begin{array}{l}
\text { Either NULL (if include_tips==FALSE), or a 3D numeric matrix of size Nsim- } \\
\text { ulations x Ntips x Ntraits. The [r,c,i]-th entry of this matrix will be the state } \\
\text { of trait i at tip c generated by the r-th simulation. If drop_dims==TRUE and }
\end{array} \\
\text { Nsimulations==1 and Ntraits==1, then tip_states will be a vector. }
\end{array}
\]

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

simulate_ou_model, simulate_rou_model, simulate_mk_model, fit_bm_model

```

\section*{Examples}
```


# generate a random tree

tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=10000)\$tree

# Example 1: Scalar case

# - - - - - - - - - - - - - - -

# simulate scalar continuous trait evolution on the tree

tip_states = simulate_bm_model(tree, diffusivity=1)\$tip_states

# plot histogram of simulated tip states

```
```

hist(tip_states, breaks=20, xlab="state", main="Trait probability distribution", prob=TRUE)

# Example 2: Multivariate case

# - - - - - - - - - - - - - - -

# simulate co-evolution of 2 traits with 3 degrees of freedom

Ntraits = 2
Ndegrees = 3
sigma = matrix(stats::rnorm(n=Ntraits*Ndegrees, mean=0, sd=1), ncol=Ndegrees)
tip_states = simulate_bm_model(tree, sigma=sigma, drop_dims=TRUE)\$tip_states

# generate scatterplot of traits across tips

plot(tip_states[,1],tip_states[, 2],xlab="trait 1",ylab="trait 2",cex=0.5)

```
simulate_deterministic_hbd

Simulate a deterministic homogenous birth-death model.

\section*{Description}

Given a homogenous birth-death (HBD) model, i.e., with speciation rate \(\lambda\), extinction rate \(\mu\) and sampling fraction \(\rho\), calculate various deterministic features of the model backwards in time, such as the total diversity over time. The speciation and extinction rates may be time-dependent. "Homogenous" refers to the assumption that, at any given moment in time, all lineages exhibit the same speciation/extinction rates (in the literature this is sometimes referred to simply as "birth-death model"; Morlon et al. 2011). "Deterministic" refers to the fact that all calculated properties are completely determined by the model's parameters (i.e. non-random), as if an infinitely large tree was generated (aka. "continuum limit").
Alternatively to \(\lambda\), one may provide the pulled diversification rate (PDR; Louca et al. 2018) and the speciation rate at some fixed age, \(\lambda\left(\tau_{o}\right)\). Similarly, alternatively to \(\mu\), one may provide the ratio of extinction over speciation rate, \(\mu / \lambda\). In either case, the time-profiles of \(\lambda, \mu, \mu / \lambda\) or the \(\operatorname{PDR}\) are specified as piecewise polynomial functions (splines), defined on a discrete grid of ages.

\section*{Usage}
```

simulate_deterministic_hbd(LTT0,
oldest_age,
age0 = 0,
rho0 = 1,
age_grid = NULL,
lambda = NULL,
mu = NULL,
mu_over_lambda = NULL,
PDR = NULL,
lambda0 = NULL,
splines_degree = 1,
relative_dt = 1e-3,
allow_unreal = FALSE)

```

\section*{Arguments}

LTT0 The assumed number of sampled extant lineages at age0, defining the necessary initial condition for the simulation. If the HBD model is supposed to describe a specific timetree, then LTT0 should correspond to the number of lineages in the tree ("lineages through time") at age age0.
oldest_age Strictly positive numeric, specifying the oldest time before present ("age") to include in the simulation.
age0 Non-negative numeric, specifying the age at which LTT0, lambda0 and rho are given. Typically this will be 0 , i.e., corresponding to the present.
rho0 Numeric between 0 (exclusive) and 1 (inclusive), specifying the sampling fraction of the tree at age0, i.e. the fraction of lineages extant at age0 that are included in the tree (aka. "rarefaction"). Note that if rho0<1, lineages extant at age0 are assumed to have been sampled randomly at equal probabilities. Can also be NULL, in which case rho \(0=1\) is assumed.
age_grid Numeric vector, listing discrete ages (time before present) on which either \(\lambda\) and \(\mu\), or the PDR and \(\mu\), are specified. Listed ages must be strictly increasing, and must cover at least the full considered age interval (from age0 to oldest_age). Can also be NULL or a vector of size 1, in which case the speciation rate, extinction rate and PDR are assumed to be time-independent.
lambda Numeric vector, of the same size as age_grid (or size 1 if age_grid==NULL), listing speciation rates ( \(\lambda\), in units \(1 /\) time \()\) at the ages listed in age_grid. Speciation rates should be non-negative, and are assumed to vary polynomially between grid points (see argument splines_degree). If NULL, then PDR and lambda0 must be provided.
mu Numeric vector, of the same size as age_grid (or size 1 if age_grid==NULL), listing extinction rates ( \(\mu\), in units \(1 /\) time) at the ages listed in age_grid. Extinction rates should be non-negative, and are assumed to vary polynomially between grid points (see argument splines_degree). Either mu or mu_over_lambda must be provided, but not both.
mu_over_lambda Numeric vector, of the same size as age_grid (or size 1 if age_grid==NULL), listing the ratio of extinction rates over speciation rates \((\mu / \lambda)\) at the ages listed in age_grid. These ratios should be non-negative, and are assumed to vary polynomially between grid points (see argument splines_degree). Either mu or mu_over_lambda must be provided, but not both.
PDR Numeric vector, of the same size as age_grid (or size 1 if age_grid==NULL), listing pulled diversification rates (in units \(1 /\) time) at the ages listed in age_grid. PDRs can be negative or positive, and are assumed to vary polynomially between grid points (see argument splines_degree). If NULL, then lambda must be provided.
lambda0 Non-negative numeric, specifying the speciation rate (in units 1/time) at age0. Either lambda0 or lambda must be provided, but not both.
splines_degree Integer, either \(0,1,2\) or 3 , specifying the polynomial degree of the provided lambda, mu and PDR between grid points in age_grid. For example, if splines_degree==1, then the provided lambda, mu and PDR are interpreted as piecewise-linear curves; if splines_degree==2 they are interpreted as quadratic splines; if splines_degree==3
they are interpreted as cubic splines. The splines_degree influences the analytical properties of the curve, e.g. splines_degree==1 guarantees a continuous curve, splines_degree==2 guarantees a continuous curve and continuous derivative, and so on.
relative_dt Strictly positive numeric (unitless), specifying the maximum relative time step allowed for integration over time. Smaller values increase integration accuracy but increase computation time. Typical values are 0.0001-0.001. The default is usually sufficient.
allow_unreal Logical, specifying whether HBD models with unrealistic parameters (e.g., negative \(\mu\) ) should be supported. This may be desired for example when examining model congruence classes with negative \(\mu\).

\section*{Details}

This function supports the following alternative parameterizations of HBD models:
- Using the speciation rate \(\lambda\) and extinction rate \(\mu\).
- Using the speciation rate \(\lambda\) and the ratio \(\mu / \lambda\).
- Using the pulled diversification rate (PDR), the extinction rate and the speciation rate given at some fixed age0 (i.e. lambda0).
- Using the PDR, the ratio \(\mu / \lambda\) and the speciation rate at some fixed age0.

The PDR is defined as \(P D R=\lambda-\mu+\lambda^{-1} d \lambda / d \tau\), where \(\tau\) is age (time before present). To avoid ambiguities, only one of the above parameterizations is accepted at a time. The sampling fraction at age0 (i.e., rho0) should always be provided; setting it to NULL is equivalent to setting it to 1 .
Note that in the literature the sampling fraction usually refers to the fraction of lineages extant at present-day that have been sampled (included in the tree); this present-day sampling fraction is then used to parameterize birth-death cladogenic models. The sampling fraction can however be generalized to past times, by defining it as the probability that a lineage extant at any given time is included in the tree. The simulation function presented here allows for specifying this generalized sampling fraction at any age of choice, not just present-day.
The simulated LTT refers to a hypothetical tree sampled at age age_grid[1], i.e. LTT(t) will be the number of lineages extant at age \(t\) that survived until age age_grid[1] and have been sampled, given that the fraction of sampled extant lineages at age 0 is rho0. Similarly, the returned \(\operatorname{Pextinct}(\mathrm{t})\) (see below) is the probability that a lineage extant at age \(t\) would not survive until age_grid[1]. The same convention is used for the returned variables Pmissing, shadow_diversity, PER, PSR, SER and PND.

\section*{Value}

A named list with the following elements:
success Logical, indicating whether the calculation was successful. If FALSE, then the returned list includes an additional 'error' element (character) providing a description of the error; all other return variables may be undefined.
ages Numerical vector of size NG, listing discrete ages (time before present) on which all returned time-curves are specified. Listed ages will be in ascending
order, will cover exactly the range age_grid[1]-oldest_age, may be irregularly spaced, and may be finer than the original provided age_grid. Note that ages[1] corresponds to the latest time point (closer to the tips), while ages[NG] corresponds to the oldest time point (oldest_age).
```

total_diversity

```

Numerical vector of size NG, listing the predicted (deterministic) total diversity (number of extant species, denoted \(N\) ) at the ages given in ages[].
```

shadow_diversity

```

Numerical vector of size NG, listing the predicted (deterministic) "shadow diversity" at the ages given in ages[]. The shadow diversity is defined as \(N_{s}=\) \(N \cdot \rho\left(\tau_{o}\right) \lambda\left(\tau_{o}\right) / \lambda\), where \(\tau_{o}\) is age 0.
Pmissing Numeric vector of size NG, listing the probability that a lineage, extant at a given age, will be absent from the tree either due to extinction or due to incomplete sampling.
Pextinct Numeric vector of size NG, listing the probability that a lineage, extant at a given age, will be fully extinct at present. Note that always Pextinct<=Pmissing.
LTT Numeric vector of size NG, listing the number of lineages represented in the tree at any given age, also known as "lineages-through-time" (LTT) curve. Note that LTT at age 0 will be equal to LTT, and that values in LTT will be non-increasing with age.
lambda Numeric vector of size NG, listing the speciation rate (in units 1/time) at the ages given in ages[].
\(\mathrm{mu} \quad\) Numeric vector of size NG, listing the extinction rate (in units 1/time) at the ages given in ages[].
diversification_rate
Numeric vector of size NG, listing the net diversification rate \((\lambda-\mu)\) at the ages given in ages[].
PDR Numeric vector of size NG, listing the pulled diversification rate (PDR, in units 1/time) at the ages given in ages[].
PND Numeric vector of size NG, listing the pulled normalized diversity (PND, in units \(1 /\) time) at the ages given in ages[]. The PND is defined as \(P N D=\) \(\left(N / N\left(\tau_{o}\right)\right) \cdot \lambda\left(\tau_{o}\right) / \lambda\).

SER Numeric vector of size NG, listing the "shadow extinction rate" (SER, in units \(1 /\) time) at the ages given in ages[]. The SER is defined as \(S E R=\rho\left(\tau_{o}\right) \lambda\left(\tau_{o}\right)-\) \(P D R\).
PER Numeric vector of size NG, listing the "pulled extinction rate" (PER, in units \(1 /\) time) at the ages given in ages[]. The PER is defined as \(S E R=\lambda\left(\tau_{o}\right)-\) \(P D R\) (Louca et al. 2018).

PSR Numeric vector of size NG, listing the "pulled speciation rate" (PSR, in units \(1 /\) time \()\) at the ages given in ages[]. The PSR is defined as \(P S R=\lambda \cdot(1-\) Pmissing).
rholambda0 Non-negative numeric, specifying the product of the sampling fraction and the speciation rate at age \(0, \rho \cdot \lambda\left(\tau_{o}\right)\).

\section*{Author(s)}

Stilianos Louca

\section*{References}
H. Morlon, T. L. Parsons, J. B. Plotkin (2011). Reconciling molecular phylogenies with the fossil record. Proceedings of the National Academy of Sciences. 108:16327-16332.
S. Louca et al. (2018). Bacterial diversification through geological time. Nature Ecology \& Evolution. 2:1458-1467.

\section*{See Also}
loglikelihood_hbd

\section*{Examples}
```


# define an HBD model with exponentially decreasing speciation/extinction rates

Ntips = 1000
beta = 0.01 \# exponential decay rate of lambda over time
oldest_age= 10
age_grid = seq(from=0,to=oldest_age,by=0.1) \# choose a sufficiently fine age grid
lambda = 1*exp(beta*age_grid) \# define lambda on the age grid
mu = 0.2*lambda \# assume similarly shaped but smaller mu

# simulate deterministic HBD model

simulation = simulate_deterministic_hbd(LTT0 = Ntips,
oldest_age = oldest_age,
rho0 = 0.5,
age_grid = age_grid,
lambda = lambda,
mu = mu)

# plot deterministic LTT

plot( x = simulation$ages, y = simulation$LTT, type='l',
main='dLTT', xlab='age', ylab='lineages')

```
```

simulate_deterministic_hbds

```
    Simulate a deterministic homogenous birth-death-sampling model.

\section*{Description}

Given a homogenous birth-death-sampling (HBDS) model, i.e., with speciation rate \(\lambda\), extinction rate \(\mu\), continuous (Poissonian) sampling rate \(\psi\) and retention probability \(\kappa\), calculate various deterministic features of the model backwards in time, such as the total population size and the LTT over time. Continuously sampled lineages are kept in the pool of extant lineages at probability \(\kappa\). The variables \(\lambda, \mu, \psi\) and \(\kappa\) may depend on time. In addition, the model can include concentrated sampling attempts at a finite set of discrete time points \(t_{1}, . ., t_{m}\). "Homogenous" refers to the assumption that, at any given moment in time, all lineages exhibit the same speciation/extinction/sampling
rates and retention proabbility. Every HBDS model is thus defined based on the values that \(\lambda, \mu\), \(\psi\) and \(\kappa\) take over time, as well as the sampling probabilities \(\psi_{1}, . ., \psi_{m}\) and retention probabilities \(\kappa_{1}, . ., \kappa_{m}\) during the concentrated sampling attempts. Special cases of this model are sometimes known as "birth-death-skyline plots" in the literature (Stadler 2013). In epidemiology, these models are often used to describe the phylogenies of viral strains sampled over the course of the epidemic. A "concentrated sampling attempt" is a brief but intensified sampling period that lasted much less than the typical timescales of speciation/extinction. "Deterministic" refers to the fact that all calculated properties are completely determined by the model's parameters (i.e. non-random), as if an infinitely large tree was generated (aka. "continuum limit"). The time-profiles of \(\lambda, \mu, \psi\) and \(\kappa\) are specified as piecewise polynomial curves (splines), defined on a discrete grid of ages.

\section*{Usage}
\begin{tabular}{|c|c|}
\hline simulate_deterministic_hbds(age_grid & = NULL, \\
\hline lambda & = NULL, \\
\hline mu & = NULL, \\
\hline psi & = NULL, \\
\hline kappa & \(=\) NULL, \\
\hline splines_degree & \(=1\), \\
\hline CSA_ages & = NULL, \\
\hline CSA_probs & = NULL, \\
\hline CSA_kappas & = NULL, \\
\hline requested_ages & \(=\) NULL, \\
\hline age0 & \(=0\), \\
\hline N0 & = NULL, \\
\hline LTT0 & \(=\) NULL, \\
\hline ODE_relative_dt & \(=0.001\), \\
\hline ODE_relative_dy & \(=1 \mathrm{e}-4)\) \\
\hline
\end{tabular}

\section*{Arguments}
age_grid Numeric vector, listing discrete ages (time before present) on which either \(\lambda\) and \(\mu\), or the PDR and \(\mu\), are specified. Listed ages must be strictly increasing, and must cover at least the full considered age interval (from age0 to oldest_age). Can also be NULL or a vector of size 1, in which case the speciation rate, extinction rate and PDR are assumed to be time-independent.
lambda Numeric vector, of the same size as age_grid (or size 1 if age_grid==NULL), listing speciation rates ( \(\lambda\), in units \(1 /\) time \()\) at the ages listed in age_grid. Speciation rates should be non-negative, and are assumed to vary polynomially between grid points (see argument splines_degree).
mu Numeric vector, of the same size as age_grid (or size 1 if age_grid==NULL), listing extinction rates ( \(\mu\), in units \(1 /\) time ) at the ages listed in age_grid. Extinction rates should be non-negative, and are assumed to vary polynomially between grid points (see argument splines_degree).
psi Numeric vector, of the same size as age_grid (or size 1 if age_grid==NULL), listing the continuous (Poissonian) sampling rate at the ages listed in age_grid. Sampling rates should be non-negative, and are assumed to vary polynomially between grid points (see argument splines_degree).
\begin{tabular}{|c|c|}
\hline kappa & Numeric vector, of the same size as age_grid (or size 1 if age_grid==NULL), listing the retention probabilities following Poissonian sampling events, at the ages listed in age_grid. The listed values must be true probabilities, i.e. between 0 and 1 , and are assumed to vary polynomially between grid points (see argument splines_degree). The retention probability is the probability that a continuously sampled lineage remains in the pool of extant lineages. Note that many epidemiological models assume kappa to be zero. \\
\hline splines_degree & Integer, either \(0,1,2\) or 3 , specifying the polynomial degree of the provided lambda, mu, psi and kappa between grid points in age_grid. For example, if splines_degree==1, then the provided lambda, mu, psi and kappa are interpreted as piecewise-linear curves; if splines_degree==2 they are interpreted as quadratic splines; if splines_degree==3 they are interpreted as cubic splines. The splines_degree influences the analytical properties of the curve, e.g. splines_degree==1 guarantees a continuous curve, splines_degree==2 guarantees a continuous curve and continuous derivative, and so on. \\
\hline CSA_ages & Optional numeric vector, listing the ages of concentrated sampling attempts, in ascending order. Concentrated sampling is performed in addition to any continuous (Poissonian) sampling specified by psi. \\
\hline CSA_probs & Optional numeric vector of the same size as CSA_ages, listing sampling probabilities at each concentrated sampling attempt. Note that in contrast to the sampling rates psi, the CSA_probs are interpreted as probabilities and must thus be between 0 and 1. CSA_probs must be provided if and only if CSA_ages is provided. \\
\hline CSA_kappas & Optional numeric vector of the same size as CSA_ages, listing retention probabilities at each concentrated sampling event, i.e. the probability at which a sampled lineage is kept in the pool of extant lineages. Note that the CSA_kappas are probabilities and must thus be between 0 and 1. CSA_kappas must be provided if and only if CSA_ages is provided. \\
\hline requested_ages & Optional numeric vector, listing ages (in ascending order) at which the various model variables are requested. If NULL, it will be set to age_grid. \\
\hline age0 & Non-negative numeric, specifying the age at which LTT0 and pop_size0 are specified. Typically this will be 0 , i.e., corresponding to the present. \\
\hline N0 & Positive numeric, specifying the number of extant species (sampled or not) at age0. Used to determine the "scaling factor" for the returned population sizes and LTT. Either pop_size0 or LTT0 must be provided, but not both. \\
\hline LTT0 & Positive numeric, specifying the number of lineages present in the tree at age0. Used to determine the "scaling factor" for the returned population sizes and LTT. Either pop_size0 or LTT0 must be provided, but not both. \\
\hline \multicolumn{2}{|l|}{ODE_relative_dt} \\
\hline & Positive unitless number, specifying the default relative time step for internally used ordinary differential equation solvers. Typical values are 0.01-0.001. \\
\hline ODE_relative_dy & \\
\hline
\end{tabular}

Positive unitless number, specifying the relative difference between subsequent simulated and interpolated values, in internally used ODE solvers. Typical values are \(1 \mathrm{e}-2\) to \(1 \mathrm{e}-5\). A smaller ODE_relative_dy increases interpolation accuracy, but also increases memory requirements and adds runtime (scaling with the tree's age span, not with Ntips).

\section*{Details}

The simulated LTT refers to a hypothetical tree sampled at age 0 , i.e. \(\operatorname{LTT}(\mathrm{t})\) will be the number of lineages extant at age \(t\) that survived and were sampled until by the present day. Note that if a concentrated sampling attempt occurs at age \(\tau\), then \(\operatorname{LTT}(\tau)\) is the number of lineages in the tree right before the occurrence of the sampling attempt, i.e., in the limit where \(\tau\) is approached from above.
Note that in this function age always refers to time before present, i.e., present day age is 0 , and age increases towards the root.

\section*{Value}

A named list with the following elements:
\begin{tabular}{ll} 
success & \begin{tabular}{l} 
Logical, indicating whether the calculation was successful. If FALSE, then the \\
returned list includes an additional 'error' element (character) providing a de- \\
scription of the error; all other return variables may be undefined. \\
Numerical vector of size NG, listing discrete ages (time before present) on which \\
all returned time-curves are specified. Will be equal to requested_ages, if the \\
latter was provided.
\end{tabular} \\
ages & Numerical vector of size NG, listing the predicted (deterministic) total diversity \\
total_diversity \\
(number of extant species, denoted \(N\) ) at the ages given in ages[]. \\
Numeric vector of size NG, listing the number of lineages represented in the tree \\
at any given age, also known as "lineages-through-time" (LTT) curve. Note that \\
LTT at age0 will be equal to LTT0 (if the latter was provided).
\end{tabular}

IPRP Numeric vector of size NG, listing the age-integrated pulled diversification rate at the ages given in ages[], i.e. \(\operatorname{IPDR}(t)=\int_{0}^{t} P D R(s) d s\).
PSR Numeric vector of size NG, listing the "pulled speciation rate" (PSR, in units \(1 /\) time \()\) at the ages given in ages[]. The PSR is defined as \(P S R=\lambda \cdot(1-\) Pmissing).
PRP Numeric vector of size NG, listing the "pulled retention probability" (PRP) at the ages given in ages[]. The PRP is defined as \(P R P=\kappa \cdot(1-P\) missing \()\).
diversification_rate
Numeric vector of size NG, listing the net diversification rate (in units \(1 /\) time) at the ages given in ages[].
branching_density
Numeric vector of size NG, listing the deterministic branching density (PSR * nLTT, in units nodes/time) at the ages given in ages[].
sampling_density
Numeric vector of size NG, listing the deterministic sampling density \((\psi \cdot N / A U C\), in units tips/time, where AUC is the area-under-the-curve calculated for the LTT) at the ages given in ages[].
lambda_psi Numeric vector of size NG, listing the product of the speciation rate and Poissonian sampling rate (in units \(1 /\) time \(^{\wedge} 2\) ) at the ages given in ages[].
kappa_psi Numeric vector of size NG, listing the product of the continuous sampling rate and the continuous retention probability (in units \(1 /\) time) at the ages given in ages[].
Reff \(\quad\) Numeric vector of size NG, listing the effective reproduction ratio ( \(R_{e}=\lambda /(\mu+\) \(\psi(1-\kappa))\) ) at the ages given in ages[].
removal_rate \(\quad\) Numeric vector of size NG, listing the total removal rate \((\mu+\psi)\), also known as "become uninfectious rate", at the ages given in ages[].
sampling_proportion
Numeric vector of size NG, listing the instantaneous sampling proportion \((\psi /(\mu+\) \(\psi)\) ) at the ages given in ages[].
CSA_pulled_probs
Numeric vector of size NG, listing the pulled concentrated sampling probabilities, \(\tilde{\rho}_{k}=\rho_{k} /(1-E)\).
CSA_psis Numeric vector of size NG, listing the continuous (Poissonian) sampling rates during the concentrated sampling attempts, \(\psi\left(t_{1}\right), \ldots, \psi\left(t_{m}\right)\).
CSA_PSRs Numeric vector of size NG, listing the pulled speciation rates during the concentrated sampling attempts.

\section*{Author(s)}

Stilianos Louca

\section*{References}
T. Stadler, D. Kuehnert, S. Bonhoeffer, A. J. Drummond (2013). Birth-death skyline plot reveals temporal changes of epidemic spread in HIV and hepatitis C virus (HCV). PNAS. 110:228-233.

\section*{See Also}
```

generate_tree_hbds, fit_hbds_model_parametric, simulate_deterministic_hbd

```

\section*{Examples}
```


# define an HBDS model with exponentially decreasing speciation/extinction rates

# and constant Poissonian sampling rate psi

oldest_age= 10
age_grid = seq(from=0,to=oldest_age,by=0.1) \# choose a sufficiently fine age grid
lambda = 1*exp(0.01*age_grid) \# define lambda on the age grid
mu = 0.2*lambda \# assume similarly shaped but smaller mu

# simulate deterministic HBD model

# scale LTT such that it is 100 at age 1

simulation = simulate_deterministic_hbds(age_grid = age_grid,
lambda = lambda,
mu = mu,
psi = 0.1,
age0 = 1,
LTT0 = 100)

# plot deterministic LTT

plot( x = simulation$ages, y = simulation$LTT, type='l',
main='dLTT', xlab='age', ylab='lineages', xlim=c(oldest_age,0))

```

\section*{simulate_diversification_model}

\section*{Simulate a deterministic uniform speciation/extinction model.}

\section*{Description}

Simulate a speciation/extinction cladogenic model for diversity over time, in the derministic limit. Speciation (birth) and extinction (death) rates can each be constant or power-law functions of the number of extant species. For example,
\[
B=I+F \cdot N^{E}
\]
where \(B\) is the birth rate, \(I\) is the intercept, \(F\) is the power-law factor, \(N\) is the current number of extant species and \(E\) is the power-law exponent. Optionally, the model can account for incomplete taxon sampling (rarefaction of tips) and for the effects of collapsing a tree at a non-zero resolution (i.e. clustering closely related tips into a single tip).

\section*{Usage}
simulate_diversification_model( times,
\begin{tabular}{ll} 
parameters & \(=\) list (), \\
added_rates_times & \(=\) NULL, \\
added_birth_rates_pc & \(=\) NULL, \\
added_death_rates_pc & \(=\) NULL,
\end{tabular}
\begin{tabular}{ll} 
added_periodic & \(=\) FALSE, \\
start_time & \(=\) NULL, \\
final_time & \(=\) NULL, \\
start_diversity & \(=1\), \\
final_diversity & \(=\) NULL, \\
reverse & \(=\) FALSE, \\
include_coalescent & \(=\) FALSE, \\
include_event_rates & \(=\) FALSE, \\
include_Nevents & \(=\) FALSE, \\
max_runtime & \(=\) NULL)
\end{tabular}

\section*{Arguments}
times Numeric vector, listing the times for which to calculate diversities, as predicted by the model. Values must be in ascending order.
parameters A named list specifying the birth-death model parameters, with one or more of the following entries:
- birth_rate_intercept: Non-negative number. The intercept of the Poissonian rate at which new species (tips) are added. In units 1/time.
- birth_rate_factor: Non-negative number. The power-law factor of the Poissonian rate at which new species (tips) are added. In units 1/time.
- birth_rate_exponent: Numeric. The power-law exponent of the Poissonian rate at which new species (tips) are added. Unitless.
- death_rate_intercept: Non-negative number. The intercept of the Poissonian rate at which extant species (tips) go extinct. In units \(1 /\) time.
- death_rate_factor: Non-negative number. The power-law factor of the Poissonian rate at which extant species (tips) go extinct. In units 1/time.
- death_rate_exponent: Numeric. The power-law exponent of the Poissonian rate at which extant species (tips) go extinct. Unitless.
- resolution: Non-negative number. Time resolution at which the final tree is assumed to be collapsed. Units are time units. E.g. if this is 10 , then all nodes of age 10 or less, are assumed to be collapsed into (represented by) a single tip. This can be used to model OTU trees, obtained after clustering strains by some similarity (=age) threshold. Set to 0 to disable collapsing. If left unspecified, this is set to 0 .
- rarefaction: Numeric between 0 and 1 , specifying the fraction of tips kept in the final tree after random subsampling. Rarefaction is assumed to occur after collapsing at the specified resolution (if applicable). This can be used to model incomplete taxon sampling. If left unspecified, this is set to 1.
added_rates_times
Numeric vector, listing time points (in ascending order) for a custom per-capita birth and/or death rates time series (see added_birth_rates_pc and added_death_rates_pc below). Can also be NULL, in which case the custom time series are ignored.
added_birth_rates_pc
Numeric vector of the same size as added_rates_times, listing per-capita birth rates to be added to the power law part. Added rates are interpolated linearly
between time points in added_rates_times. Can also be NULL, in which case this option is ignored and birth rates are purely described by the power law.
added_death_rates_pc
Numeric vector of the same size as added_rates_times, listing per-capita death rates to be added to the power law part. Added rates are interpolated linearly between time points in added_rates_times. Can also be NULL, in which case this option is ignored and death rates are purely described by the power law.
added_periodic Logical, indicating whether added_birth_rates_pc and added_death_rates_pc should be extended periodically if needed (i.e. if not defined for the entire simulation time). If FALSE, added birth \& death rates are extended with zeros.
start_time Numeric. Start time of the tree (<=times[1]). Can also be NULL, in which case it is set to the first value in times.
final_time Numeric. Final (ending) time of the tree (>=max (times)). Can also be NULL, in which case it is set to the last value in times.
start_diversity
Numeric. Total diversity at start_time. Only relevant if reverse==FALSE.

Numeric. Total diversity at final_time, i.e. the final diversity of the tree (total extant species at age 0 ). Only relevant if reverse==TRUE.
reverse Logical. If TRUE, then the tree model is simulated in backward time direction. In that case, final_diversity is interpreted as the known diversity at the last time point, and all diversities at previous time points are calculated based on the model. If FALSE, then the model is simulated in forward-time, with initial diversity given by start_diversity.
include_coalescent
Logical, specifying whether the diversity corresponding to a coalescent tree (i.e. the tree spanning only extant tips) should also be calculated. If coalescent==TRUE and the death rate is non-zero, then the coalescent diversities will generally be lower than the total diversities.
include_event_rates
Logical. If TRUE, then the birth (speciation) and death (extinction) rates (for each time point) are included as returned values. This comes at a moderate computational overhead.
include_Nevents
Logical. If TRUE, then the cumulative birth (speciation) and death (extinction) events (for each time point) are included as returned values. This comes at a moderate computational overhead.
max_runtime Numeric. Maximum runtime (in seconds) allowed for the simulation. If this time is surpassed, the simulation aborts.

\section*{Details}

The simulation is deterministic, meaning that diversification is modeled using ordinary differential equations, not as a stochastic process. The simulation essentially computes the deterministic diversity over time, not an actual tree. For stochastic cladogenic simulations yielding a random tree, see generate_random_tree and simulate_dsse.

In the special case where per-capita birth and death rates are constant (i.e. \(I=0\) and \(E=1\) for birth and death rates), this function uses an explicit analytical solution to the underlying differential equations, and is thus much faster than in the general case.
If rarefaction<1 and resolution>0, collapsing of closely related tips (at the resolution specified) is assumed to take place prior to rarefaction (i.e., subsampling applies to the already collapsed tips).

\section*{Value}

A named list with the following elements:
\[
\left.\begin{array}{l}
\text { success } \begin{array}{l}
\text { Logical, indicating whether the simulation was successful. If the simulation } \\
\text { aborted due to runtime constraints (option max_runtime), success will be FALSE. } \\
\text { total_diversities } \\
\text { Numeric vector of the same size as times, listing the total diversity (extant at } \\
\text { each the time) for each time point in times. }
\end{array} \\
\text { coalescent_diversities } \\
\text { Numeric vector of the same size as times, listing the coalescent diversity (i.e. } \\
\text { as seen in the coalescent tree spanning only extant species) for each time point } \\
\text { in times. Only included if include_coalescent==TRUE. }
\end{array}\right] \text { birth_rates } \begin{aligned}
& \text { Numeric vector of the same size as times, listing the speciation (birth) rate at } \\
& \text { each time point. Only included if include_event_rates==TRUE. }
\end{aligned}
\]

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
generate_random_tree, count_lineages_through_time

\section*{Examples}
```


# Generate a tree

max_time = 100
parameters = list(birth_rate_intercept = 10,
birth_rate_factor = 0,
birth_rate_exponent = 0,
death_rate_intercept = 0,
death_rate_factor = 0,
death_rate_exponent = 0,
resolution = 20,
rarefaction = 0.5)
generator = generate_random_tree(parameters,max_time=max_time)

```
```

tree = generator$tree
final_total_diversity = length(tree$tip.label)+generator$Nrarefied+generator$Ncollapsed

# Calculate diversity-vs-time curve for the tree

times = seq(from=0, to=0.99*max_time,length.out=50)
tree_diversities = count_lineages_through_time(tree, times=times)\$lineages

# simulate diversity curve based on deterministic model

simulation = simulate_diversification_model(times,
parameters,
reverse=TRUE,
final_diversity=final_total_diversity,
include_coalescent=TRUE)
model_diversities = simulation\$coalescent_diversities

# compare diversities in the tree to the simulated ones

plot(tree_diversities,model_diversities,xlab="tree diversities",ylab="simulated diversities")
abline(a=0,b=1,col="\#A0A0A0") \# show diagonal for reference

```
simulate_dsse
Simulate a Discrete-State Speciation and Extinction (dSSE) model.

\section*{Description}

Simulate a random phylogenetic tree in forward time based on a Poissonian speciation/extinction (birth/death) process, with optional Poissonian sampling over time, whereby birth/death/sampling rates are determined by a co-evolving discrete trait. New species are added (born) by splitting of a randomly chosen extant tip. The discrete trait, whose values determine birth/death/sampling rates over time, can evolve in two modes: (A) Anagenetically, i.e. according to a discrete-space continuous-time Markov process along each edge, with fixed transition rates between states, and/or (B) cladogenetically, i.e. according to fixed transition probabilities between states at each speciation event. Poissonian lineage sampling is assumed to lead to a removal of lineages from the pool of extant tips (as is common in epidemiology).
This model class includes the Multiple State Speciation and Extinction (MuSSE) model described by FitzJohn et al. (2009), as well as the Cladogenetic SSE (ClaSSE) model described by Goldberg and Igis (2012). Optionally, the model can be turned into a Hidden State Speciation and Extinction model (Beaulieu and O'meara, 2016), by replacing the simulated tip/node states with "proxy" states, thus hiding the original states actually influencing speciation/extinction rates.

\section*{Usage}
simulate_dsse( Nstates,
\begin{tabular}{ll} 
NPstates & \(=\) NULL, \\
proxy_map & \(=\) NULL, \\
parameters & \(=\) list (), \\
start_state & \(=\) NULL, \\
max_tips & \(=\) NULL, \\
max_extant_tips & \(=N U L L\),
\end{tabular}
```

    max_Psampled_tips = NULL,
    max_time = NULL,
    max_time_eq = NULL,
    max_events = NULL,
    sampling_fractions = NULL,
    reveal_fractions = NULL,
    sampling_rates = NULL,
    coalescent = TRUE,
    as_generations = FALSE,
    no_full_extinction = TRUE,
    tip_basename = "",
    node_basename = NULL,
    include_event_times = FALSE,
    include_rates = FALSE,
    include_labels = TRUE)
    simulate_musse(Nstates, NPstates = NULL, proxy_map = NULL,
parameters = list(), start_state = NULL,
max_tips = NULL, max_extant_tips = NULL, max_Psampled_tips = NULL,
max_time = NULL, max_time_eq = NULL, max_events = NULL,
sampling_fractions = NULL, reveal_fractions = NULL, sampling_rates = NULL,
coalescent = TRUE, as_generations = FALSE, no_full_extinction = TRUE,
tip_basename = "", node_basename = NULL,
include_event_times = FALSE, include_rates = FALSE, include_labels = TRUE)

```

\section*{Arguments}

Nstates Integer, specifying the number of possible discrete states a tip can have, influencing speciation/extinction rates. For example, if Nstates==2 then this corresponds to the common Binary State Speciation and Extinction (BiSSE) model (Maddison et al., 2007). In the case of a HiSSE model, Nstates refers to the total number of diversification rate categories, as described by Beaulieu and O'meara (2016).
NPstates Integer, optionally specifying a number of "proxy-states" that are observed instead of the underlying speciation/extinction-modulating states. To simulate a HiSSE model, this should be smaller than Nstates. Each state corresponds to a different proxy-state, as defined using the variable proxy_map (see below). For BiSSE/MuSSE with no hidden states, NPstates can be set to either NULL or equal to Nstates, and proxy-states are equivalent to states.
proxy_map Integer vector of size Nstates and with values in 1,..NPstates, specifying the correspondence between states (i.e. diversification-rate categories) and (observed) proxy-states, in a HiSSE model. Specifically, proxy_map[s] indicates which proxy-state the state \(s\) is represented by. Each proxy-state can represent multiple states (i.e. proxies are ambiguous), but each state must be represented by exactly one proxy-state. For non-HiSSE models, set this to NULL. See below for more details.
parameters A named list specifying the dSSE model parameters, such as the anagenetic and/or cladogenetic transition rates between states and the state-dependent birth/death
rates (see details below).
start_state Integer within 1,..,Nstates, specifying the initial state, i.e. of the first lineage created. If left unspecified, this is chosen randomly and uniformly among all possible states.
max_tips Integer, maximum number of tips (extant + Poissonian-sampled if coalescent==TRUE, or extant+extinct+Poissonian-sampled if coalescent==FALSE) in the generated tree, shortly before any present-day sampling. If NULL or \(<=0\), the number of tips is not limited, so you should use another stopping criterion such as max_time and/or max_time_eq and/or max_events to stop the simulation.
```

max_extant_tips

```

Integer, maximum number of extant tips in the generated tree, shortly before to any present-day sampling. If NULL or \(<=0\), this constraint is ignored.
```

max_Psampled_tips

```

Integer, maximum number of Poissonian-sampled tips in the generated tree. If NULL or \(<=0\), this constraint is ignored.
max_time Numeric, maximum duration of the simulation. If NULL or \(<=0\), this constraint is ignored.
max_time_eq Numeric, maximum duration of the simulation, counting from the first point at which speciation/extinction equilibrium is reached, i.e. when (birth rate - death rate) changed sign for the first time. If NULL or \(<0\), this constraint is ignored.
max_events Integer, maximum number of speciation/extinction/transition events before halting the simulation. If NULL, this constraint is ignored.
sampling_fractions
A single number, or a numeric vector of size NPstates, listing the sampling fractions for extant tips at the end of the simulation (i.e., at "present-day")", depending on proxy-state. sampling_fractions[p] is the probability of including an extant tip in the final tree, if its proxy-state is p . If a single number, all extant tips are sampled with the same probability, i.e. regardless of their proxy-state. If NULL, this is the same as setting sampling_fractions to 1, i.e., all extant tips are sampled at the end of the simulation.
reveal_fractions
Numeric vector of size NPstates, listing reveal fractions of tip proxy-states, depending on proxy state. reveal_fractions [p] is the probability of knowing a tip's proxy-state, if its proxy state is p. Can also be NULL, in which case all tip proxy states will be known.
sampling_rates Numeric vector of size NPstates, listing Poissonian sampling rates of lineages over time, depending on proxy state. Hence, sampling_rates[p] is the sampling rate of a lineage if its proxy state is p . Can also be a single numeric, thus applying the same sampling rate to all lineages regardless of proxy state. Can also be NULL, in which case Poissonian sampling is not included.
coalescent Logical, specifying whether only the coalescent tree (i.e. the tree spanning the sampled tips) should be returned. If coalescent==FALSE and the death rate is non-zero, then the tree may include extinct tips.
as_generations Logical, specifying whether edge lengths should correspond to generations. If FALSE, then edge lengths correspond to time.
no_full_extinction
Logical, specifying whether to prevent complete extinction of the tree. Full extinction is prevented by temporarily disabling extinctions and Poissonian samplings whenever the number of extant tips is 1 . if no_full_extinction==FALSE and death rates and/or Poissonian sampling rates are non-zero, the tree may go extinct during the simulation; if coalescent==TRUE, then the returned could end up empty, hence the function will return unsuccessfully (i.e. success will be FALSE). By default no_full_extinction is TRUE, however in some special cases it may be desirable to allow full extinctions to ensure that the generated trees are statistically distributed exactly according to the underlying cladogenetic model.
tip_basename Character. Prefix to be used for tip labels (e.g. "tip."). If empty (""), then tip labels will be integers " 1 ", " 2 " and so on.
node_basename Character. Prefix to be used for node labels (e.g. "node."). If NULL, no node labels will be included in the tree.
include_event_times
Logical. If TRUE, then the times of speciation and extinction events (each in order of occurrence) will also be returned.
include_rates Logical. If TRUE, then the per-capita birth \& death rates of all tips and nodes will also be returned.
include_labels Logical, specifying whether to include tip-labels and node-labels (if available) as names in the returned state vectors (e.g. tip_states and node_states). In any case, returned states are always listed in the same order as tips and nodes in the tree. Setting this to FALSE may increase computational efficiency for situations where labels are not required.

\section*{Details}

The function simulate_dsse can be used to simulate a diversification + discrete-trait evolutionary process, in which birth/death (speciation/extinction) and Poissonian sampling rates at each tip are determined by a tip's current "state". Lineages can transition between states anagenetically along each edge (according to fixed Markov transition rates) and/or cladogenetically at each speciation event (according to fixed transition probabilities). In addition to Poissonian sampling through time (commonly included in epidemiological models), extant tips can also be sampled at the end of the simulation (i.e. at "present-day") according to some state-specific sampling_fractions (common in macroevolution).
The function simulate_musse is a simplified variant meant to simulate MuSSE/HiSSE models in the absence of cladogenetic state transitions, and is included mainly for backward-compatibility reasons. The input arguments for simulate_musse are identical to simulate_dsse, with the exception that the parameters argument must include slightly different elements (explained below). Note that the standard MuSSE/HiSSE models published by FitzJohn et al. (2009) and Beaulieu and O'meara (2016) did not include Poissonian sampling through time, i.e. sampling of extant lineages was only done once at present-day.
For simulate_dsse, the argument parameters should be a named list including one or more of the following elements:
- birth_rates: Numeric vector of size Nstates, listing the per-capita birth rate (speciation rate) at each state. Can also be a single number (all states have the same birth rate).
- death_rates: Numeric vector of size Nstates, listing the per-capita death rate (extinction rate) at each state. Can also be a single number (all states have the same death rate).
- transition_matrix_A: 2D numeric matrix of size Nstates x Nstates, listing anagenetic transition rates between states along an edge. Hence, transition_matrix_A[r, c] is the probability rate for transitioning from state \(r\) to state \(c\). Non-diagonal entries must be non-negative, diagonal entries must be non-positive, and the sum of each row must be zero.
- transition_matrix_C: 2D numeric matrix of size Nstates x Nstates, listing cladogenetic transition probabilities between states during a speciation event, seperately for each child. Hence, transition_matrix_C[r,c] is the probability that a child will have state \(c\), conditional upon the occurrence of a speciation event, given that the parent had state \(r\), and independently of all other children. Entries must be non-negative, and the sum of each row must be one.

For simulate_musse, the argument parameters should be a named list including one or more of the following elements:
- birth_rates: Same as for simulate_dsse.
- death_rates: Same as for simulate_dsse.
- transition_matrix: 2D numeric matrix of size Nstates x Nstates, listing anagenetic transition rates between states. This is equivalent to transition_matrix_A in simulate_dsse.

Note that this code generates trees in forward time, and halts as soon as one of the enabled halting conditions is met; the halting conditions chosen affects the precise probability distribution from which the generated trees are drawn (Stadler 2011). If at any moment during the simulation the tree only includes a single extant tip, and if no_full_extinction=TRUE, the death and sampling rate are temporarily set to zero to prevent the complete extinction of the tree. The tree will be ultrametric if coalescent==TRUE (or death rates were zero) and Poissonian sampling was not included.
HiSSE models (Beaulieu and O'meara, 2016) are closely related to BiSSE/MuSSE models, the main difference being the fact that the actual diversification-modulating states are not directly observed. Hence, this function is also able to simulate HiSSE models, with appropriate choice of the input variables Nstates, NPstates and proxy_map. For example, Nstates=4, NPstates=2 and proxy_map=c \((1,2,1,2)\) specifies that states 1 and 3 are represented by proxy-state 1 , and states 2 and 4 are represented by proxy-state 2 . This is the original case described by Beaulieu and O'meara (2016); in their terminology, there would be 2 "hidden"" states ("0" and "1") and 2 "observed" (proxy) states ("A" and "B"), and the 4 diversification rate categories (Nstates=4) would be called " 0 A ", " 1 A ", " 0 B " and " 1 B ", respectively. The somewhat different terminology used here allows for easier generalization to an arbitrary number of diversification-modulating states and an arbitrary number of proxy states. For example, if there are 6 diversification modulating states, represented by 3 proxy-states as \(1->\mathrm{A}, 2->\mathrm{A}, 3->\mathrm{B}, 4->\mathrm{C}, 5->\mathrm{C}, 6->\mathrm{C}\), then one would set Nstates \(=6\), NPstates \(=3\) and proxy_map=c \((1,1,2,3,3,3)\).
The parameter transition_matrix_C can be used to define ClaSSE models (Goldberg and Igic, 2012) or BiSSE-ness models (Magnuson-Ford and Otto, 2012), although care must be taken to properly define the transition probabilities. Here, cladogenetic transitions occur at probabilities that are defined conditionally upon a speciation event, whereas in other software they may be defined as probability rates.

\section*{Value}

A named list with the following elements:
\(\left.\begin{array}{ll}\text { success } & \begin{array}{l}\text { Logical, indicating whether the simulation was successful. If FALSE, an addi- } \\ \text { tional element error (of type character) is included containing an explanation } \\ \text { of the error; in that case the value of any of the other elements is undetermined. }\end{array} \\ \text { A rooted bifurcating tree of class "phylo", generated according to the specified } \\ \text { birth/death model. } \\ \text { If coalescent==TRUE or if all death rates are zero, and only if as_generations==FALSE } \\ \text { and in the absence of Poissonian sampling, then the tree will be ultrametric. } \\ \text { If as_generations==TRUE and coalescent==FALSE, all edges will have unit } \\ \text { length. } \\ \text { Numeric, giving the time at which the tree's root was first split during the simu- } \\ \text { lation. Note that if coalescent==TRUE, this may be later than the first speciation }\end{array}\right\}\)
```

node_states Integer vector of size Nnodes and with values in 1,..,Nstates, listing the state of
each node in the tree.
tip_proxy_states
Integer vector of size Ntips and with values in 1,..,NPstates, listing the proxy
state of each tip in the tree. Only included in the case of HiSSE models.
node_proxy_states
Integer vector of size Nnodes and with values in 1,..,NPstates, listing the proxy
state of each node in the tree. Only included in the case of HiSSE models.
start_state Integer, specifying the state of the first lineage (either provided during the func-
tion call, or generated randomly).
extant_tips Integer vector, listing the indices of any extant tips in the tree.
extinct_tips Integer vector, listing the indices of any extinct tips in the tree. Note that if
coalescent==TRUE, this vector will be empty.
Psampled_tips Integer vector, listing the indices of any Poissonian-sampled tips in the tree.
birth_times Numeric vector, listing the times of speciation events during tree growth, in or-
der of occurrence. Note that if coalescent==TRUE, then speciation_times
may be greater than the phylogenetic distance to the coalescent root. Only re-
turned if include_event_times==TRUE.
death_times Numeric vector, listing the times of extinction events during tree growth, in order
of occurrence. Note that if coalescent==TRUE, then speciation_times may
be greater than the phylogenetic distance to the coalescent root. Only returned
if include_event_times==TRUE.
Psampling_times
Numeric vector, listing the times of Poissonian sampling events during tree
growth, in order of occurrence. Only returned if include_event_times==TRUE.
clade_birth_rates
Numeric vector of size Ntips+Nnodes, listing the per-capita birth rate of each tip and node in the tree. Only included if include_rates==TRUE.
clade_death_rates
Numeric vector of size Ntips+Nnodes, listing the per-capita death rate of each tip and node in the tree. Only included if include_rates==TRUE.

```

\section*{Author(s)}

Stilianos Louca

\section*{References}
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K. Magnuson-Ford, S. P. Otto (2012). Linking the investigations of character evolution and species diversification. The American Naturalist. 180:225-245.
J. M. Beaulieu and B. C. O'Meara (2016). Detecting hidden diversification shifts in models of trait-dependent speciation and extinction. Systematic Biology. 65:583-601.
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S. Louca and M. W. Pennell (2020). A general and efficient algorithm for the likelihood of diversification and discrete-trait evolutionary models. Systematic Biology. 69:545-556.

\section*{See Also}
simulate_tdsse, fit_musse

\section*{Examples}
```


# Simulate a tree under a classical BiSSE model

# I.e., anagenetic transitions between two states, no Poissonian sampling through time.

A = get_random_mk_transition_matrix(Nstates=2, rate_model="ER", max_rate=0.1)
parameters = list(birth_rates = c(1,1.5),
death_rates = 0.5,
transition_matrix_A = A)
simulation = simulate_dsse( Nstates = 2,
parameters = parameters,
max_extant_tips = 1000,
include_rates = TRUE)
tree = simulation$tree
Ntips = length(tree$tip.label)

# plot distribution of per-capita birth rates of tips

rates = simulation\$clade_birth_rates[1:Ntips]
barplot(table(rates)/length(rates),
xlab="rate",
main="Distribution of pc birth rates across tips (BiSSE model)")

```
simulate_mk_model Simulate an Mk model for discrete trait evolution.

\section*{Description}

Given a rooted phylogenetic tree, a fixed-rates continuous-time Markov model for the evolution of a discrete trait ("Mk model", described by a transition matrix) and a probability vector for the root, simulate random outcomes of the model on all nodes and/or tips of the tree. The function traverses nodes from root to tips and randomly assigns a state to each node or tip based on its parent's previously assigned state and the specified transition rates between states. The generated states have joint distributions consistent with the Markov model. Optionally, multiple independent simulations can be performed using the same model.

\section*{Usage}
```

simulate_mk_model(tree, Q, root_probabilities="stationary",
include_tips=TRUE, include_nodes=TRUE,
Nsimulations=1, drop_dims=TRUE)

```

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
Q A numeric matrix of size Nstates x Nstates, storing the transition rates between states. In particular, every row must sum up to zero.
root_probabilities
Probabilities of the different states at the root. Either a character vector with value "stationary" or "flat", or a numeric vector of length Nstates, where Nstates is the number of possible states of the trait. In the later case, root_probabilities must be a valid probability vector, i.e. with non-negative values summing up to 1. "stationary" sets the probabilities at the root to the stationary distribution of Q (see get_stationary_distribution), while "flat" means that each state is equally probable at the root.
include_tips Include random states for the tips. If FALSE, no states will be returned for tips.
include_nodes Include random states for the nodes. If FALSE, no states will be returned for nodes.
Nsimulations Number of random independent simulations to perform. For each node and/or tip, there will be Nsimulations random states generated.
drop_dims Logical, specifying whether the returned tip_states and node_states (see below) should be vectors, if Nsimulations==1. If drop_dims==FALSE, then tip_states and tip_nodes will always be 2D matrices.

\section*{Details}

For this function, the trait's states must be represented by integers within 1,..,Nstates, where Nstates is the total number of possible states. If the states are originally in some other format (e.g. characters or factors), you should map them to a set of integers \(1, . .\), Nstates. These integers should correspond to row \& column indices in the transition matrix Q . You can easily map any set of discrete states to integers using the function map_to_state_space.
If tree\$edge. length is missing, each edge in the tree is assumed to have length 1 . The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as mono-furcations (i.e. nodes with only one child). The time required per simulation decreases with the total number of requested simulations.

\section*{Value}

A list with the following elements:
tip_states Either NULL (if include_tips==FALSE), or a 2D integer matrix of size Nsimulations x Ntips with values in \(1, \ldots\), Nstates, where Ntips is the number of tips in the tree and Nstates is the number of possible states of the trait. The [r,c]-th
entry of this matrix will be the state of tip c generated by the r-th simulation. If drop_dims==TRUE and Nsimulations==1, then tip_states will be a vector.
node_states Either NULL (if include_nodes==FALSE), or a 2D integer matrix of size Nsimulations x Nnodes with values in \(1, \ldots\),.Nstates, where Nnodes is the number of nodes in the tree. The [r,c]-th entry of this matrix will be the state of node c generated by the r-th simulation. If drop_dims==TRUE and Nsimulations==1, then node_states will be a vector.

\section*{Author(s)}

Stilianos Louca
```

See Also
exponentiate_matrix, get_stationary_distribution, simulate_bm_model, simulate_ou_model, simulate_rou_model

```

\section*{Examples}
```


## Not run:

# generate a random tree

tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=1000)\$tree

# simulate discrete trait evolution on the tree (5 states)

Nstates = 5
Q = get_random_mk_transition_matrix(Nstates, rate_model="ARD", max_rate=0.1)
tip_states = simulate_mk_model(tree, Q)\$tip_states

# plot histogram of simulated tip states

barplot(table(tip_states)/length(tip_states), xlab="state")

## End(Not run)

```
simulate_ou_model Simulate an Ornstein-Uhlenbeck model for continuous trait evolution.

\section*{Description}

Given a rooted phylogenetic tree and an Ornstein-Uhlenbeck (OU) model for the evolution of a continuous (numeric) trait, simulate random outcomes of the model on all nodes and/or tips of the tree. The function traverses nodes from root to tips and randomly assigns a state to each node or tip based on its parent's previously assigned state and the specified model parameters. The generated states have joint distributions consistent with the OU model. Optionally, multiple independent simulations can be performed using the same model.

\section*{Usage}
```

simulate_ou_model(tree, stationary_mean, spread, decay_rate,
include_tips=TRUE, include_nodes=TRUE,
Nsimulations=1, drop_dims=TRUE)

```

\section*{Arguments}
\(\left.\begin{array}{ll}\text { tree } & \begin{array}{l}\text { A rooted tree of class "phylo". The root is assumed to be the unique node with } \\ \text { no incoming edge. }\end{array} \\ \text { stationary_mean }\end{array} \quad \begin{array}{l}\text { Numeric. The mean (center) of the stationary distribution of the OU model. } \\ \text { Numeric. The standard deviation of the stationary distribution of the OU model. }\end{array}\right\}\)

\section*{Details}

For each simulation, the state of the root is picked randomly from the stationary distribution of the OU model, i.e. from a normal distribution with mean = stationary_mean and standard deviation = spread.
If tree\$edge. length is missing, each edge in the tree is assumed to have length 1 . The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as mono-furcations (i.e. nodes with only one child). The asymptotic time complexity of this function is O (Nedges*Nsimulations), where Nedges is the number of edges in the tree.

\section*{Value}

A list with the following elements:

> tip_states Either NULL (if include_tips==FALSE), or a 2D numeric matrix of size Nsimulations x Ntips, where Ntips is the number of tips in the tree. The [r,c]-th entry of this matrix will be the state of tip c generated by the r-th simulation. If drop_dims==TRUE and Nsimulations==1, then tip_states will be a vector.
> node_states Either NULL (if include_nodes==FALSE), or a 2D numeric matrix of size Nsimulations x Nnodes, where Nnodes is the number of nodes in the tree. The [r,c]-th entry of this matrix will be the state of node c generated by the r-th simulation. If drop_dims==TRUE and Nsimulations==1, then node_states will be a vector.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

simulate_bm_model, simulate_mk_model, simulate_rou_model

```

\section*{Examples}
```


# generate a random tree

tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=10000)\$tree

# simulate evolution of a continuous trait

tip_states = simulate_ou_model(tree, stationary_mean=10, spread=1, decay_rate=0.1)\$tip_states

# plot histogram of simulated tip states

hist(tip_states, breaks=20, xlab="state", main="Trait probability distribution", prob=TRUE)

```
simulate_rou_model Simulate a reflected Ornstein-Uhlenbeck model for continuous trait evolution.

\section*{Description}

Given a rooted phylogenetic tree and a reflected Ornstein-Uhlenbeck (ROU) model for the evolution of a continuous (numeric) trait, simulate random outcomes of the model on all nodes and/or tips of the tree. The ROU process is similar to the Ornstein-Uhlenbeck process (see simulate_ou_model), with the difference that the ROU process cannot fall below a certain value (its "reflection point"), which (in this implementation) is also its deterministic equilibrium point (Hu et al. 2015). The function traverses nodes from root to tips and randomly assigns a state to each node or tip based on its parent's previously assigned state and the specified model parameters. The generated states have joint distributions consistent with the ROU model. Optionally, multiple independent simulations can be performed using the same model.

\section*{Usage}
```

simulate_rou_model(tree, reflection_point, spread, decay_rate,
include_tips=TRUE, include_nodes=TRUE,
Nsimulations=1, drop_dims=TRUE)

```

\section*{Arguments}
\begin{tabular}{ll} 
tree & \begin{tabular}{l} 
A rooted tree of class "phylo". The root is assumed to be the unique node with \\
no incoming edge.
\end{tabular} \\
reflection_point
\end{tabular}\(\quad\)\begin{tabular}{l} 
Numeric. The reflection point of the ROU model. In castor, this also happens to \\
be the deterministic equilibrium of the ROU process (i.e. if the decay rate were \\
infinite). For example, if a trait can only be positive (but arbitrarily small), then \\
reflection_point may be set to 0.
\end{tabular}
include_nodes Include random states for the nodes. If FALSE, no states will be returned for nodes.
Nsimulations Number of random independent simulations to perform. For each node and/or tip, there will be Nsimulations random states generated.
drop_dims Logical, specifying whether the returned tip_states and node_states (see below) should be vectors, if Nsimulations==1. If drop_dims==FALSE, then tip_states and tip_nodes will always be 2D matrices.

\section*{Details}

For each simulation, the state of the root is picked randomly from the stationary distribution of the ROU model, i.e. from a one-sided normal distribution with mode \(=\) reflection_point and standard deviation = stationary_std.
If tree\$edge. length is missing, each edge in the tree is assumed to have length 1 . The tree may include multi-furcations (i.e. nodes with more than 2 children) as well as mono-furcations (i.e. nodes with only one child). The asymptotic time complexity of this function is O (Nedges*Nsimulations), where Nedges is the number of edges in the tree.

\section*{Value}

A list with the following elements:
\[
\begin{array}{ll}
\text { tip_states } & \text { Either NULL (if include_tips==FALSE), or a 2D numeric matrix of size Nsim- } \\
\text { ulations x Ntips, where Ntips is the number of tips in the tree. The [r,c]-th } \\
\text { entry of this matrix will be the state of tip c generated by the r-th simulation. If } \\
\text { drop_dims==TRUE and Nsimulations }==1 \text {, then tip_states will be a vector. } \\
\text { node_states } & \begin{array}{l}
\text { Either NULL (if include_nodes==FALSE), or a 2D numeric matrix of size Nsim- } \\
\text { ulations } x \text { Nnodes, where Nnodes is the number of nodes in the tree. The [r,c]-th } \\
\text { entry of this matrix will be the state of node c generated by the r-th simulation. If } \\
\text { drop_dims==TRUE and Nsimulations==1, then node_states will be a vector. }
\end{array}
\end{array}
\]

\section*{Author(s)}

Stilianos Louca

\section*{References}
Y. Hu, C. Lee, M. H. Lee, J. Song (2015). Parameter estimation for reflected Ornstein-Uhlenbeck processes with discrete observations. Statistical Inference for Stochastic Processes. 18:279-291.

\section*{See Also}
simulate_ou_model, simulate_bm_model, simulate_mk_model

\section*{Examples}
```


# generate a random tree

tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=10000)\$tree

```
```


# simulate evolution of a continuous trait whose value is always >=1

tip_states = simulate_rou_model(tree, reflection_point=1, spread=2, decay_rate=0.1)\$tip_states

# plot histogram of simulated tip states

hist(tip_states, breaks=20, xlab="state", main="Trait probability distribution", prob=TRUE)

```
```

simulate_sbm

```

Simulate Spherical Brownian Motion on a tree.

\section*{Description}

Given a rooted phylogenetic tree and a Spherical Brownian Motion (SBM) model for the evolution of the geographical location of a lineage on a sphere, simulate random outcomes of the model on all nodes and/or tips of the tree. The function traverses nodes from root to tips and randomly assigns a geographical location to each node or tip based on its parent's previously assigned location and the specified model parameters. The generated states have joint distributions consistent with the SBM model (Perrin 1928; Brillinger 2012). This function generalizes the simple SBM model to support time-dependent diffusivities.

\section*{Usage}
simulate_sbm(tree,
radius, diffusivity,
time_grid \(=\) NULL,
splines_degree = 1 ,
root_latitude = NULL,
root_longitude = NULL)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge. Edge lengths are assumed to represent time intervals or a similarly interpretable phylogenetic distance.
radius Strictly positive numeric, specifying the radius of the sphere. For Earth, the mean radius is 6371 km .
diffusivity Either a single numeric, or a numeric vector of length equal to that of time_grid. Diffusivity (" \(D\) ") of the SBM model (in units distance^2/time). If time_grid is NULL, then diffusivity should be a single number specifying the timeindependent diffusivity. Otherwise diffusivity specifies the diffusivity at each time point listed in time_grid.
Under a planar approximation the squared geographical distance of a node from the root will have expectation \(4 L D\), where \(L\) is the node's phylogenetic distance from the root. Note that distance is measured in the same units as the radius (e.g., km if the radius is given in km ), and time is measured in the same units as the tree's edge lengths (e.g., Myr if edge lengths are given in Myr).
\begin{tabular}{ll} 
time_grid & \begin{tabular}{l} 
Numeric vector of the same length as diffusivity and listing times since the \\
root in ascending order, or NULL. This can be used to specify a time-variable \\
diffusivity (see details below). If NULL, the diffusivity is assumed to be constant \\
over time and equal to diffusivity (which should be a single numeric). Time \\
is measured in the same units as edge lengths, with root having time 0.
\end{tabular} \\
splines_degree & \begin{tabular}{l} 
Integer, either \(0,1,2\) or 3 , specifying the polynomial degree of the provided \\
diffusivity between grid points in time_grid. For example, if splines_degree==1, \\
then the provided diffusivity is interpreted as a piecewise-linear curve; if \\
splines_degree==2 it is interpreted as a quadratic spline; if splines_degree==3 \\
it is interpreted as a cubic spline. The splines_degree influences the analyt- \\
ical properties of the curve, e.g. splines_degree==1 guarantees a continu- \\
ous curve, splines_degree==2 guarantees a continuous curve and continuous \\
derivative, and so on.
\end{tabular} \\
root_latitude & \begin{tabular}{l} 
The latitude of the tree's root, in decimal degrees, between -90 and 90. If NULL, \\
the root latitude is chosen randomly according to the stationary probability dis- \\
tribution of the SBM.
\end{tabular} \\
root_longitude
\end{tabular} \begin{tabular}{l} 
The longitude of the tree's root, in decimal degrees, between -180 and 180. If \\
\\
\begin{tabular}{l} 
NULL, the root longitude is chosen randomly according to the stationary prob- \\
ability distribution of the SBM.
\end{tabular}
\end{tabular}

\section*{Details}

For short expected transition distances this function uses the approximation formula by Ghosh et al. (2012). For longer expected transition distances the function uses a truncated approximation of the series representation of SBM transition densities (Perrin 1928).
The pair time_grid and diffusivity can be used to define a time-dependent diffusivity, with time counted from the root to the tips (i.e. root has time 0 ) in the same units as edge lengths. For example, to define a diffusivity that varies linearly with time, you only need to specify the diffusivity at two time points (one at 0 , and one at the time of the youngest tip), i.e. time_grid and diffusivity would each have length 2. Note that time_grid should cover the full time range of the tree; otherwise, diffusivity will be extrapolated as a constant when needed.

If tree\$edge. length is missing, each edge in the tree is assumed to have length 1 . The tree may include multifurcations as well as monofurcations.

\section*{Value}

A list with the following elements:
success Logical, specifying whether the simulation was successful. If FALSE, then an additional return variable error will contain a brief description of the error that occurred, and all other return variables may be undefined.
tip_latitudes Numeric vector of length Ntips, listing simulated decimal latitudes for each tip in the tree.
tip_longitudes Numeric vector of length Ntips, listing simulated decimal longitudes for each tip in the tree.
node_latitudes Numeric vector of length Nnodes, listing simulated decimal latitudes for each internal node in the tree.
node_longitudes
Numeric vector of length Nnodes, listing simulated decimal longitudes for each internal node in the tree.

\section*{Author(s)}

Stilianos Louca

\section*{References}
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A. Ghosh, J. Samuel, S. Sinha (2012). A Gaussian for diffusion on the sphere. Europhysics Letters. 98:30003.
S. Louca (2021). Phylogeographic estimation and simulation of global diffusive dispersal. Systematic Biology. 70:340-359.

\section*{See Also}
simulate_ou_model, simulate_rou_model, simulate_bm_model, fit_sbm_const

\section*{Examples}
```


## Not run:

# generate a random tree

tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=100)\$tree

# simulate SBM on the tree

simulation = simulate_sbm(tree, radius=6371, diffusivity=1e4,
root_latitude=0, root_longitude=0)

# plot latitudes and longitudes of the tips

plot(simulation$tip_latitudes,simulation$tip_longitudes)

## End(Not run)

```
simulate_tdsse Simulate a time-dependent Discrete-State Speciation and Extinction (tdSSE) model.

\section*{Description}

Simulate a random phylogenetic tree in forward time based on a Poissonian speciation/extinction (birth/death) process, whereby birth and death rates are determined by a co-evolving discrete trait. New species are added (born) by splitting of a randomly chosen extant tip. The discrete trait, whose values determine birth/death rates, can evolve in two modes: (A) Anagenetically, i.e. according to a
discrete-space continuous-time Markov process along each edge, with fixed or time-dependent transition rates between states, and/or (B) cladogenetically, i.e. according to fixed or time-dependent transition probabilities between states at each speciation event. This model class includes the Multiple State Speciation and Extinction (MuSSE) model described by FitzJohn et al. (2009), as well as the Cladogenetic SSE (ClaSSE) model described by Goldberg and Igis (2012). Optionally, the model can be turned into a Hidden State Speciation and Extinction model (Beaulieu and O'meara, 2016), by replacing the simulated tip/node states with "proxy" states, thus hiding the original states actually influencing speciation/extinction rates. This function is similar to simulate_dsse, the main difference being that state-specific speciation/extinction rates as well as state transition rates can be time-dependent.

\section*{Usage}

\section*{Arguments}

Nstates Integer, specifying the number of possible discrete states a tip can have, influencing speciation/extinction rates. For example, if Nstates==2 then this corresponds to the common Binary State Speciation and Extinction (BiSSE) model (Maddison et al., 2007). In the case of a HiSSE model, Nstates refers to the total number of diversification rate categories, as described by Beaulieu and O'meara (2016).

NPstates Integer, optionally specifying a number of "proxy-states" that are observed instead of the underlying speciation/extinction-modulating states. To simulate a HiSSE model, this should be smaller than Nstates. Each state corresponds to a different proxy-state, as defined using the variable proxy_map (see below). For BiSSE/MuSSE with no hidden states, NPstates can be set to either NULL or equal to Nstates, and proxy-states are equivalent to states.
proxy_map Integer vector of size Nstates and with values in 1,..,NPstates, specifying the correspondence between states (i.e. diversification-rate categories) and (observed) proxy-states, in a HiSSE model. Specifically, proxy_map[s] indicates which proxy-state the state \(s\) is represented by. Each proxy-state can represent multiple states (i.e. proxies are ambiguous), but each state must be represented by exactly one proxy-state. For non-HiSSE models, set this to NULL. See below for more details.
time_grid Numeric vector listing discrete times in ascending order, used to define the timedependent rates of the model. The time grid should generally cover the maximum possible simulation time, otherwise it will be polynomially extrapolated (according to splines_degree).
parameters A named list specifying the time-dependent model parameters, including optional anagenetic and/or cladogenetic transition rates between states, as well as the mandatory state-dependent birth/death rates (see details below).
splines_degree Integer, either \(0,1,2\) or 3 , specifying the polynomial degree of time-dependent model parameters (birth_rates, death_rates, transition_rates) between time-grid points. For example, splines_degree=1 means that rates are to be considered linear between adjacent grid points.
start_state Integer within 1,..,Nstates, specifying the initial state, i.e. of the first lineage created. If left unspecified, this is chosen randomly and uniformly among all possible states.
max_tips Maximum number of tips in the generated tree, prior to any subsampling. If coalescent=TRUE, this refers to the number of extant tips, prior to subsampling. Otherwise, it refers to the number of extinct + extant tips, prior to subsampling. If NULL or \(<=0\), the number of tips is not limited, so you should use max_time and/or max_time_eq and/or max_events to stop the simulation.
max_time Numeric, maximum duration of the simulation. If NULL or \(<=0\), this constraint is ignored.
max_events Integer, maximum number of speciation/extinction/transition events before halting the simulation. If NULL, this constraint is ignored.
sampling_fractions
A single number, or a numeric vector of size NPstates, listing tip sub-sampling fractions, depending on proxy-state. sampling_fractions \([p]\) is the probability of including a tip in the final tree, if its proxy-state is p. If NULL, all tips (or all extant tips, if coalescent==TRUE) are included in the tree. If a single number, all tips are included with the same probability, i.e. regardless of their proxy-state.
reveal_fractions
Numeric vector of size NPstates, listing reveal fractions of tip proxy-states, depending on proxy state. reveal_fractions[p] is the probability of knowing a tip's proxy-state, if its proxy state is p. Can also be NULL, in which case all tip proxy states will be known.
coalescent Logical, specifying whether only the coalescent tree (i.e. the tree spanning the extant tips) should be returned. If coalescent==FALSE and the death rate is non-zero, then the tree may include non-extant tips (i.e. tips whose distance from the root is less than the total time of evolution). In that case, the tree will not be ultrametric.
as_generations \begin{tabular}{l} 
Logical, specifying whether edge lengths should correspond to generations. If \\
FALSE, then edge lengths correspond to time.
\end{tabular}
no_full_extinction
Logical, specifying whether to prevent complete extinction of the tree. Full ex-
tinction is prevented by temporarily disabling extinctions whenever the number
of extant tips is 1. if no_full_extinction==FALSE and death rates are non-
zero, the tree may go extinct during the simulation; if coalescent==TRUE, then
the returned tree would be empty, hence the function will return unsuccessfully
(i.e. success will be FALSE). By default no_full_extinction is TRUE, how-
ever in some special cases it may be desirable to allow full extinctions to ensure
that the generated trees are statistically distributed exactly according to the un-
derlying cladogenetic model. \(\quad\)\begin{tabular}{l} 
Integer greater than 1. Number of child-tips to generate at each diversification \\
event. If set to 2, the generated tree will be bifurcating. If >2, the tree will be \\
multifurcating.
\end{tabular}

\section*{Details}

The function simulate_tdsse can be used to simulate a diversification + discrete-trait evolutionary process, in which birth/death (speciation/extinction) rates at each tip are determined by a tip's current "state". Lineages can transition between states anagenetically along each edge (according to some Markov transition rates) and/or cladogenetically at each speciation event (according to some transition probabilities). The speciation and extinction rates, as well as the transition rates, may be specified as time-dependent variables, defined as piecewise polynomial functions (natural splines) on a temporal grid.
In the following, Ngrid refers to the length of the vector time_grid. The argument parameters should be a named list including one or more of the following elements:
- birth_rates: Numeric 2D matrix of size Nstates x Ngrid, listing the per-capita birth rate (speciation rate) at each state and at each time-grid point. Can also be a single number (same birth rate for all states and at all times).
- death_rates: Numeric 2D matrix of size Nstates x Ngrid, listing the per-capita death rate (extinction rate) at each state and at each time-grid point. Can also be a single number (same death rate for all states and at all times) or NULL (no deaths).
- transition_matrix_A: Either a 3D numeric array of size Nstates x Nstates x Ngrid, or a 2D numeric matrix of size Nstates \(x\) Nstates, listing anagenetic transition rates between states along an edge. If a 3D array, then transition_matrix_A[r, \(c, t]\) is the infinitesimal rate for transitioning from state \(r\) to state \(c\) at time time_grid[t]. If a 2D matrix, transition_matrix_A[r,c] is the time-independent infintesimal rate for transitioning from state \(r\) to state \(c\). At each time point (i.e., a fixed \(t\) ), non-diagonal entries in transition_matrix_A[, , \(t\) ] must be non-negative, diagonal entries must be non-positive, and the sum of each row must be zero.
- transition_matrix_C: Either a 3D numeric array of size Nstates x Nstates x Ngrid, or a 2D numeric matrix of size Nstates x Nstates, listing cladogenetic transition probabilities between states during a speciation event, seperately for each child. If a 3D array, then transition_matrix_C[r, \(c, t]\) is the probability that a child emerging at time time_grid[t] will have state \(c\), conditional upon the occurrence of a speciation event, given that the parent had state \(r\), and independently of all other children. If a 2D matrix, then transition_matrix_C[r, \(c]\) is the (timeindependent) probability that a child will have state \(c\), conditional upon the occurrence of a speciation event, given that the parent had state \(r\), and independently of all other children. Entries must be non-negative, and for any fixed \(t\) the sum of each row in transition_matrix[, , t\(]\) must be one.

If max_time==NULL and max_events==NULL, then the returned tree will always contain max_tips tips. If at any moment during the simulation the tree only includes a single extant tip, and if no_full_extinction=TRUE the death rate is temporarily set to zero to prevent the complete extinction of the tree. If max_tips==NULL, then the simulation is ran as long as specified by max_time and/or max_events. If neither max_time, max_tips nor max_events is NULL, then the simulation halts as soon as the time reaches max_time, or the number of tips (extant tips if coalescent is TRUE) reaches max_tips, or the number of speciation/extinction/transition events reaches max_events whichever occurs first. If max_tips! =NULL and Nsplits>2, then the last diversification even may generate fewer than Nspl its children, in order to keep the total number of tips within the specified limit. Note that this code generates trees in forward time, and halts as soon as one of the halting conditions is met; the halting condition chosen affects the precise distribution from which the generated trees are drawn (Stadler 2011).
For additional information on simulating HiSSE models see the related function simulate_dsse.
The parameter transition_matrix_C can be used to define ClaSSE models (Goldberg and Igic, 2012) or BiSSE-ness models (Magnuson-Ford and Otto, 2012), although care must be taken to properly define the transition probabilities. Here, cladogenetic transitions occur at probabilities that are defined conditionally upon a speciation event, whereas in other software they may be defined as probability rates.

\section*{Value}

A named list with the following elements:
success Logical, indicating whether the simulation was successful. If FALSE, an additional element error (of type character) is included containing an explanation of the error; in that case the value of any of the other elements is undetermined.
\begin{tabular}{ll} 
tree & \begin{tabular}{l} 
A rooted bifurcating (if Nsplits==2) or multifurcating (if Nsplits>2) tree of \\
class "phylo", generated according to the specified birth/death model. \\
If coalescent==TRUE or if all death rates are zero, and only if as_generations==FALSE,
\end{tabular} \\
then the tree will be ultrametric. If as_generations==TRUE and coalescent==FALSE, \\
all edges will have unit length. \\
Numeric, giving the time at which the tree's root was first split during the simu- \\
lation. Note that if coalescent==TRUE, this may be later than the first speciation \\
event during the simulation.
\end{tabular}
simulate_tdsse

\section*{Author(s)}

Stilianos Louca

\section*{References}
W. P. Maddison, P. E. Midford, S. P. Otto (2007). Estimating a binary character's effect on speciation and extinction. Systematic Biology. 56:701-710.
R. G. FitzJohn, W. P. Maddison, S. P. Otto (2009). Estimating trait-dependent speciation and extinction rates from incompletely resolved phylogenies. Systematic Biology. 58:595-611
R. G. FitzJohn (2012). Diversitree: comparative phylogenetic analyses of diversification in R. Methods in Ecology and Evolution. 3:1084-1092
E. E. Goldberg, B. Igic (2012). Tempo and mode in plant breeding system evolution. Evolution. 66:3701-3709.
K. Magnuson-Ford, S. P. Otto (2012). Linking the investigations of character evolution and species diversification. The American Naturalist. 180:225-245.
J. M. Beaulieu and B. C. O'Meara (2016). Detecting hidden diversification shifts in models of trait-dependent speciation and extinction. Systematic Biology. 65:583-601.
T. Stadler (2011). Simulating trees with a fixed number of extant species. Systematic Biology. 60:676-684.

\section*{See Also}
```

simulate_dsse, simulate_musse, fit_musse

```

\section*{Examples}
```


## Not run:

# prepare params for time-dependent BiSSE model

# include time-dependent speciation \& extinction rates

# as well as time-dependent anagenetic transition rates

Nstates = 2
reveal_fractions = c(1,0.5)
rarefaction = 0.5 \# species sampling fraction
time2lambda1 = function(times) rep(1,times=length(times))
time2lambda2 = function(times) rep(2,times=length(times))
time2mu1 = function(times) 0.5 + 2.5*exp(-((times-8)**2)/2)
time2mu2 = function(times) 1 + 2*exp(-((times-12)**2)/2)
time_grid = seq(from=0, to=100, length.out=1000)
time2Q12 = function(times) 1*exp(0.1*times)
time2Q21 = function(times) 2*exp(-0.1*times)
QA = array(0, dim=c(Nstates,Nstates,length(time_grid)))
QA[1,2,] = time2Q12(time_grid)
QA[2,1,] = time2Q21(time_grid)
QA[1,1,] = -QA[1,2,]
QA[2, 2,] = -QA[2,1,]
parameters = list()

```
```

parameters$birth_rates = rbind(time2lambda1(time_grid), time2lambda2(time_grid))
parameters$death_rates = rbind(time2mu1(time_grid), time2mu2(time_grid))
parameters\$transition_matrix_A = QA

# simulate time-dependent BiSSE model

cat(sprintf("Simulating tMuSSE model..\n"))
sim = castor::simulate_tdsse(Nstates = Nstates,
time_grid = time_grid,
parameters = parameters,
splines_degree = 1,
max_tips = 10000/rarefaction,
sampling_fractions = rarefaction,
reveal_fractions = reveal_fractions,
coalescent = TRUE,
no_full_extinction = TRUE)
if(!sim$success){
    cat(sprintf("ERROR: %s\n",sim$error))
}else{
\# print some summary info about the generated tree
tree = sim$tree
    Ntips = length(tree$tip.label)
root_age = get_tree_span(tree)$max_distance
    root_time = sim$final_time - root_age
tip_states = sim\$tip_states
Nknown_tips = sum(!is.na(tip_states))
cat(sprintf("Note: Simulated tree has root_age = %g\n",root_age))
cat(sprintf("Note: %d tips have known state\n", Nknown_tips));
}

## End(Not run)

```
spline_coefficients Get the polynomial coefficients of a spline.

\section*{Description}

Given a natural spline function \(Y: \mathrm{R} \rightarrow \mathrm{R}\), defined as a series of Y values on a discrete X grid, obtain its corresponding piecewise polynomial coefficients. Supported splines degrees are 0 ( Y is piecewise constant), 1 (piecewise linear), 2 (piecewise quadratic) and 3 (piecewise cubic).

\section*{Usage}
spline_coefficients(Xgrid,
Ygrid,
splines_degree)

\section*{Arguments}

Xgrid Numeric vector, listing x-values in ascending order.

Ygrid Numeric vector of the same length as Xgrid, listing the values of Y on Xgrid.
splines_degree Integer, either 0,1 , 2 or 3 , specifying the polynomial degree of the spline curve Y between grid points. For example, 0 means Y is piecewise constant, 1 means \(Y\) is piecewise linear and so on.

\section*{Details}

Spline functions are returned by some of castor's fitting routines, so spline_coefficients is meant to aid with the further analysis of such functions. A spline function of degree \(D \geq 1\) has continuous derivatives up to degree \(D-1\).

\section*{Value}

A numeric matrix of size NR x NC, where NR (number of rows) is equal to the length of Xgrid and NC (number of columns) is equal to splines_degree +1 . The r-th row lists the polynomial coefficients (order \(0,1 \mathrm{etc}\) ) of the spline within the interval [Xgrid[r],Xgrid[r+1]]. For exampe, for a spline of order 2 , the value at \(\mathrm{X}=0.5 *(\mathrm{Xgrid}[1]+\mathrm{Xgrid}[2])\) will be equal to \(\mathrm{C}[1,1]+\mathrm{C}[1,2] * \mathrm{X}+\mathrm{C}[1,3] * \mathrm{X} * \mathrm{X}\), where C is the matrix of coefficients.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
```

evaluate_spline

```

\section*{Examples}
```


# The following code defines a quadratic spline on 20 grid points

# The curve's polynomial coefficients are then determined

# and used to evaluate the spline on a fine grid for plotting.

Xgrid = seq(0,10,length.out=20)
Ygrid = sin(Xgrid)
splines_degree = 2
Ycoeff = castor::spline_coefficients(Xgrid, Ygrid, splines_degree)
plot(Xgrid, Ygrid, type='p')
for(g in seq_len(length(Xgrid)-1)){
Xtarget = seq(Xgrid[g], Xgrid[g+1], length.out=100)
Ytarget = rep(Ycoeff[g,1], length(Xtarget))
for(p in seq_len(splines_degree)){
Ytarget = Ytarget + (Xtarget^p) * Ycoeff[g,p+1];
}
lines(Xtarget, Ytarget, type='l', col='red')
}

```
split_tree_at_height Split a tree into subtrees at a specific height.

\section*{Description}

Given a rooted phylogenetic tree and a specific distance from the root ("height"), split the tree into subtrees at the specific height. This corresponds to drawing the tree in rectangular layout and trimming everything below the specified phylogenetic distance from the root: What is obtained is a set of separated subtrees. The tips of the original tree are spread across those subtrees.

\section*{Usage}
split_tree_at_height(tree, height = 0, by_edge_count = FALSE)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
height Numeric, specifying the phylogenetic distance from the root at which to split the tree. If \(<=0\), the original tree is returned as the sole subtree.
by_edge_count Logical. Instead of considering edge lengths, consider edge counts as phylogenetic distance. This is the same as if all edges had length equal to 1.

\section*{Details}

This function can be used to generate multiple smaller trees from one large tree, with each subtree having a time span equal to or lower than a certain threshold. The input tree may include multifurcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child).
Note that while edges are cut exactly at the specified distance from the root, the cut point does not become the root node of the obtained subtree; rather, the first node encountered after the cut will become the subtree's root. The length of the remaining edge segment leading into this node will be used as root. edge in the returned subtree.

\section*{Value}

A list with the following elements:
\begin{tabular}{ll} 
Nsubtrees & Integer, the number of subtrees obtained. \\
subtrees & A list of length Nsubtrees, each element of which is a named list containing the \\
following elements:
\end{tabular}
- tree: A rooted tree of class "phylo", representing a subtree obtained from the original tree.
- new2old_clade: An integer vector of length NStips+NSnodes (where NStips is the number of tips and NSnodes the number of nodes of the subtree), mapping subtree tip and node indices (i.e., \(1, . .\), NStips+NSnodes) to tip and node indices in the original tree.
- new2old_edge: Integer vector of length NSedges (=number of edges in the subtree), mapping subtree edge indices (i.e., \(1, . .\), NSedges) to edge indices in the original tree.
clade2subtree Integer vector of length Ntips+Nnodes and containing values from 1 to Nsubtrees, mapping tip and node indices of the original tree to their assigned subtree.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
trim_tree_at_height

\section*{Examples}
```


# generate a random tree

tree = generate_random_tree(list(birth_rate_intercept=1),
max_tips=100)\$tree

# split tree halfway towards the root

root_age = get_tree_span(tree)\$max_distance
splitting = split_tree_at_height(tree, height=0.5*root_age)

# print number of subtrees obtained

cat(sprintf("Obtained %d subtrees\n",splitting\$Nsubtrees))

```

\section*{Description}

Given two rooted phylogenetic trees with identical tips, calculate their difference using a distance metric or pseudometric.

\section*{Usage}
```

tree_distance( treeA,
treeB,
tipsA2B = NULL,
metric = "RFrooted",
normalized = FALSE,
NLeigenvalues = 10)

```

\section*{Arguments}
treeA
treeB
tipsA2B
metric

A rooted tree of class "phylo".
A rooted tree of class "phylo". Depending on the metric used, this tree may need to have the same number of tips as treeA (see details below).
Optional integer vector of size Ntips, mapping treeA tip indices to treeB tip indices (i.e. tipsA2B[a] is the tip index in treeB corresponding to tip index a in treeA). The mapping must be one-to-one. If left unspecified, it is determined by matching tip labels between the two trees (this assumes that the same tip labels are used in both trees). Only relevant if the metric requires tip matching (i.e., considers labeled trees).

Character, specifying the distance measure to be used. Currently the RobinsonFoulds metric for rooted trees ("RFrooted"), the mean-path-difference ("MeanPathLengthDifference"), "WassersteinNodeAges" and "WassersteinLaplacianSpectrum" are implemented. Note that these distances are not necessarily metrics in the strict mathematical sense; in particular, non-identical trees can sometimes have a zero distance.
"RFrooted" counts the number of clusters (sets of tips descending from a node) in either of the trees but not shared by both trees (Robinson and Foulds, 1981; Day, 1985); this metric does not take into account branch lengths and depends on the position of the root.
"MeanPathLengthDifference" is the square root of the mean squared difference of patristic distances (shortest path lengths) between tip pairs, as described by Steel and Penny (1993); this metric takes into account path lengths and does not depend on the position of the root.
"WassersteinNodeAges" calculates the first Wasserstein distance (Ramdas et al. 2017) between the distributions of node ages in the two trees. It depends on the branch lengths and the rooting, but does not depend on tip labeling nor topology (as long as node ages are the same). Hence, this is only a 'pseudometric' in the space of unlabeled trees - any two trees with identical node ages will have distance 0 .
"WassersteinLaplacianSpectrum" calculates the first Wasserstein distance between the spectra (sets of eigenvalues) of the modified graph Laplacians (Lewitus and Morlon, 2016). This distance depends on tree topology and branch lengths, but not on tip labeling nor on the rooting. Note that Lewitus and Morlon measured the distance between the Laplacian spectra in a different way than here. Also note that if NLeigenvalues \(>0\), only a subset of the eigenvalues may be considered.
Logical, specifying whether the calculated distance should be normalized to be between 0 and 1. For the Robinson-Foulds distance, the distance will be normalized by dividing it by the total number of nodes in the two trees. For MeanPathLengthDifference, normalization is done by dividing each path-length difference by the maximum of the two path-lengths considered. For WassersteinNodeAges, normalization is achieved by scaling all node ages relative to the oldest node age in any of the two trees (hence times are converted to relative times). Note that normalized distances may no longer satisfy the triangle inequality required for metrics, i.e. the resulting distance function may not be a metric in the mathematical sense.

\begin{abstract}
NLeigenvalues Integer, number of top eigenvalues (i.e., with largest magnitude) to consider from the Graph-Laplacian's spectrum (e.g., for the metric "WassersteinLaplacianSpectrum"). This option is mostly provided for computational efficiency reasons, because it is cheaper to compute a small subset of eigenvalues rather than the entire spectrum. If \(<=0\), all eigenvalues are considered, which can substantially increase computation time and memory for large trees.
\end{abstract}

\section*{Details}

For some metrics ("RFrooted", "MeanPathLengthDifference"), the trees must have the same number of tips and their tips must be matched one-to-one. If the trees differ in theis tips, they must be pruned down to their common set of tips. If tips have different labels in the two trees, but are nevertheless equivalent, the mapping between the two trees must be provided using tipsA2B.
The trees may include multi-furcations as well as mono-furcations (i.e. nodes with only one child).
Note that under some Robinson-Foulds variants the trees can be unrooted; in this present implementation trees must be rooted and the placement of the root influences the distance, following the definition by Day (1985).

\section*{Value}

A single non-negative number, representing the distance between the two trees.

\section*{Author(s)}

Stilianos Louca

\section*{References}

Robinson, D. R., Foulds, L. R. (1981). Comparison of phylogenetic trees. Mathematical Biosciences. 53: 131-147.
Day, W. H. E. (1985). Optimal algorithms for comparing trees with labeled leaves. Journal of Classification. 2:7-28.

Steel, M. A., Penny D. (1993). Distributions of tree comparison metrics - Some new results. Systematic Biology. 42:126-141.
Ramdas, A. et al. (2017). On Wasserstein two-sample testing and related families of nonparametric tests. Entropy. 19(2):47.

Lewitus, E. and Morlon, H. (2016). Characterizing and comparing phylogenies from their laplacian spectrum. Systematic Biology. 65:495-507.

\section*{See Also}
congruent_divergence_times

\section*{Examples}
\# generate a random tree
Ntips = 1000
treeA = generate_random_tree(list(birth_rate_intercept=1),
```

max_tips=Ntips)\$tree

# create a second tree with slightly different topology

treeB = treeA
shuffled_tips = sample.int(Ntips, size=Ntips/10, replace=FALSE)
treeB$tip.label[shuffled_tips] = treeB$tip.label[sample(shuffled_tips)]

# calculate Robinson-Foulds distance between trees

distance = tree_distance(treeA, treeB, metric="RFrooted")

```
tree_from_branching_ages
Generate a random timetree with specific branching ages.

\section*{Description}

Generate a random timetree based on specific branching ages (time before present), by randomly connecting tips and nodes. The tree's root will have the greatest age provided. The tree thus corresponds to a homogenous birth-death model, i.e. where at any given time point all lineages were equally likely to split or go extinct.

\section*{Usage}
tree_from_branching_ages( branching_ages,
\[
\begin{array}{ll}
\text { tip_basename } & =" ", \\
\text { node_basename } & =\text { NULL, } \\
\text { edge_basename } & =\text { NULL }
\end{array}
\]

\section*{Arguments}
branching_ages Numeric vector of size Nnodes, listing branching ages (time before present) in ascending order. The last entry will be the root age.
tip_basename Character. Prefix to be used for tip labels (e.g. "tip."). If empty (""), then tip labels will be integers "1", "2" and so on.
node_basename Character. Prefix to be used for node labels (e.g. "node."). If NULL, no node labels will be included in the tree.
edge_basename Character. Prefix to be used for edge labels (e.g. "edge."). Edge labels (if included) are stored in the character vector edge. label. If NULL, no edge labels will be included in the tree.

\section*{Details}

Tips in the generated tree are guaranteed to be connected in random order, i.e. this function can also be used to connect a random set of labeled tips into a tree. Nodes will be indexed in chronological order (i.e. in order of decreasing age). In particular, node 0 will be the root.

\section*{Value}

A named list with the following elements:
success Logical, indicating whether the tree was successfully generated. If FALSE, the only other value returned is error.
tree A rooted, ultrametric bifurcating tree of class "phylo", with the requested branching ages.
error Character, containing an explanation of the error that occurred. Only included if success==FALSE.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
tree_from_sampling_branching_ages

\section*{Examples}
```

Nnodes = 100
branching_intervals = rexp(n=Nnodes, rate=1)
branching_ages = cumsum(branching_intervals)
tree = castor::tree_from_branching_ages(branching_ages)\$tree

```
tree_from_sampling_branching_ages
Generate a random timetree with specific tip/sampling and node/branching ages.

\section*{Description}

Generate a random bifurcating timetree based on specific sampling (tip) ages and branching (node) ages, by randomly connecting tips and nodes. Age refers to time before present, i.e., measured in reverse chronological direction. The tree's root will have the greatest age provided. The tree thus corresponds to a homogenous birth-death-sampling model, i.e. where at any given time point all lineages were equally likely to split, be sampled or go extinct.

\section*{Usage}
tree_from_sampling_branching_ages(sampling_ages, branching_ages, tip_basename = "", node_basename = NULL, edge_basename = NULL)

\section*{Arguments}
sampling_ages Numeric vector of size Ntips, listing sampling ages (time before present) in ascending order.
branching_ages Numeric vector of size Nnodes, listing branching ages (time before present) in ascending order. The last entry will be the root age. Note that Nnodes must be equal to Ntips-1.
tip_basename Character. Prefix to be used for tip labels (e.g. "tip."). If empty (""), then tip labels will be integers "1", "2" and so on.
node_basename Character. Prefix to be used for node labels (e.g. "node."). If NULL, no node labels will be included in the tree.
edge_basename Character. Prefix to be used for edge labels (e.g. "edge."). Edge labels (if included) are stored in the character vector edge. label. If NULL, no edge labels will be included in the tree.

\section*{Details}

Tips and nodes will be indexed in chronological order (i.e. in order of decreasing age). In particular, node 0 will be the root. Note that not all choices of sampling_ages and branching_ages are permissible. Specifically, at any given age T, the number of sampling events with age equal or smaller than T must be greater than the number of branching events with age equal or smaller than T. If this requirement is not satisfied, the function will return with an error.

\section*{Value}

A named list with the following elements:
success Logical, indicating whether the tree was successfully generated. If FALSE, the only other value returned is error.
tree A rooted, ultrametric bifurcating tree of class "phylo", with the requested tip and node ages.
error Character, containing an explanation of the error that occurred. Only included if success==FALSE.

\section*{Author(s)}

Stilianos Louca

\section*{See Also}
tree_from_branching_ages

\section*{Examples}
```

sampling_ages = c(0, 0.1, 0.15, 0.25, 0.9, 1.9, 3)
branching_ages = c(0.3, 0.35, 0.4, 1.1, 2.5, 3.5)
tree = tree_from_sampling_branching_ages(sampling_ages, branching_ages)\$tree

```

\section*{Description}

Given a rooted phylogenetic tree, calculate various "imbalance" statistics of the tree, such as Colless' Index or Sackin's Index.

\section*{Usage}
tree_imbalance(tree, type)

\section*{Arguments}
tree A rooted tree of class "phylo".
type Character, specifying the statistic to be calculated. Must be one of "Colless" (Shao 1990), "Colless_normalized" (Colless normalized by the maximum possible value in the case of a bifurcating tree), "Sackin" (Sackin 1972) or "Blum" (Blum and Francois 2006, Eq. 5).

\section*{Details}

The tree may include multifurcations and monofurcations. Note that the Colless Index is traditionally only defined for bifurcating trees. For non-bifurcating trees this function calculates a generalization of the index, by summing over all children pairs at each node.

\section*{Value}

Numeric, the requested imbalance statistic of the tree.

\section*{Author(s)}

Stilianos Louca

\section*{References}
M. J. Sackin (1972). "Good" and "Bad" Phenograms. Systematic Biology. 21:225-226.
K.T. Shao, R. R. Sokal (1990). Tree Balance. Systematic Biology. 39:266-276.
M. G. B. Blum and O. Francois (2006). Which random processes describe the Tree of Life? A large-scale study of phylogenetic tree imbalance. Systematic Biology. 55:685-691.

\section*{Examples}
```


# generate a random tree

Ntips = 100
tree = generate_random_tree(list(birth_rate_intercept=1),Ntips)\$tree

# calculate Colless statistic

colless_index = tree_imbalance(tree, type="Colless")

```
trim_tree_at_height Trim a rooted tree down to a specific height.

\section*{Description}

Given a rooted phylogenetic tree and a maximum allowed distance from the root ("height"), remove tips and nodes and shorten the remaining terminal edges so that the tree's height does not exceed the specified threshold. This corresponds to drawing the tree in rectangular layout and trimming everything beyond a specific phylogenetic distance from the root. Tips or nodes at the end of trimmed edges are kept, and the affected edges are shortened.

\section*{Usage}
trim_tree_at_height(tree, height = Inf, by_edge_count = FALSE)

\section*{Arguments}
tree A rooted tree of class "phylo". The root is assumed to be the unique node with no incoming edge.
height Numeric, specifying the phylogenetic distance from the root at which to trim.
by_edge_count Logical. Instead of considering edge lengths, consider edge counts as phylogenetic distance. This is the same as if all edges had length equal to 1 .

\section*{Details}

The input tree may include multi-furcations (i.e. nodes with more than 2 children) as well as monofurcations (i.e. nodes with only one child).
Tip labels and uncollapsed node labels of the collapsed tree are inheritted from the original tree. Labels of tips that used to be nodes (i.e. of which all descendants have been removed) will be the node labels from the original tree. If the input tree has no node names, it is advised to first add node names to avoid NA in the resulting tip names.

\section*{Value}

A list with the following elements:
\[
\begin{array}{ll}
\text { tree } & \text { A new rooted tree of class "phylo", representing the trimmed tree. } \\
\text { Nedges_trimmed } & \text { Integer. Number of edges trimmed (shortened). }
\end{array}
\]

Nedges_removed Integer. Number of edges removed.
new2old_clade Integer vector of length equal to the number of tips+nodes in the trimmed tree, with values in 1,..,Ntips+Nnodes, mapping tip/node indices of the trimmed tree to tip/node indices in the original tree. In particular,
c(tree\$tip.label,tree\$node.label)[new2old_clade]
will be equal to:
c(trimmed_tree\$tip.label,trimmed_tree\$node.label).
new2old_edge Integer vector of length equal to the number of edges in the trimmed tree, with values in \(1, . .\), Nedges, mapping edge indices of the trimmed tree to edge indices in the original tree. In particular, tree\$edge.length[new2old_edge] will be equal to trimmed_tree\$edge.length (if edge lengths are available).
new_edges_trimmed
Integer vector, listing edge indices in the trimmed tree that we originally longer edges and have been trimmed. In other words, these are the edges that "crossed" the trimming height.

\section*{Author(s)}

Stilianos Louca

\section*{See Also \\ split_tree_at_height}

\section*{Examples}
```


# generate a random tree, include node names

tree = generate_random_tree(list(birth_rate_intercept=1),
max_time=1000,
node_basename="node.")\$tree

# print number of tips

cat(sprintf("Simulated tree has %d tips\n",length(tree\$tip.label)))

# trim tree at height 500

trimmed = trim_tree_at_height(tree, height=500)\$tree

# print number of tips in trimmed tree

cat(sprintf("Trimmed tree has %d tips\n",length(trimmed\$tip.label)))

```
```

write_tree
Write a tree in Newick (parenthetic) format.

```

\section*{Description}

Write a phylogenetic tree to a file or a string, in Newick (parenthetic) format. If the tree is unrooted, it is first rooted internally at the first node.

\section*{Usage}
write_tree (tree,
file = "",
append \(\quad=\) FALSE ,
digits \(=10\),
quoting \(=0\),
include_edge_labels = FALSE,
include_edge_numbers = FALSE)

\section*{Arguments}
tree A tree of class "phylo".
file An optional path to a file, to which the tree should be written. The file may be overwritten without warning. If left empty (default), then a string is returned representing the tree.
append Logical, specifying whether the tree should be appended at the end of the file, rather than replacing the entire file (if it exists).
digits Integer, number of significant digits for writing edge lengths.
quoting Integer, specifying whether and how to quote tip/node/edge names, as follows: 0 :no quoting at all, 1 :always use single quotes, 2:always use double quotes, 1 :only quote when needed and prefer single quotes if possible, -2 :only quote when needed and prefer double quotes if possible.
include_edge_labels
Logical, specifying whether to include edge labels (if available) in the output tree, inside square brackets. Note that this is an extension (Matsen et al. 2012) to the standard Newick format, as, and edge labels in square brackets may not be supported by all Newick readers.
include_edge_numbers
Logical, specifying whether to include edge numbers (if available) in the output tree, inside curly braces. Note that this is an extension (Matsen et al. 2012) to the standard Newick format, and edge numbers in curly braces may not be supported by all Newick readers.

\section*{Details}

If your tip and/or node and/or edge labels contain special characters (round brackets, commas, colons or quotes) then you should set quoting to non-zero, as appropriate.
If the tree contains edge labels (as a character vector named edge. label) and include_edge_labels==TRUE, then edge labels are written in square brackets (Matsen et al. 2012). If tree contains edge numbers (as an integer vector named edge.number) and include_edge_numbers==TRUE, then edge numbers are written in curly braces (Matsen et al. 2012).
This function is comparable to (but typically much faster than) the ape function write. tree.

\section*{Value}

If file==" ", then a string is returned containing the Newick representation of the tree. Otherwise, the tree is directly written to the file and no value is returned.

\section*{Author(s)}

Stilianos Louca

\section*{References}

Frederick A. Matsen et al. (2012). A format for phylogenetic placements. PLOS One. 7:e31009

\section*{See Also}
read_tree

\section*{Examples}
```


# generate a random tree

tree = generate_random_tree(list(birth_rate_intercept=1),max_tips=100)\$tree

# obtain a string representation of the tree in Newick format

Newick_string = write_tree(tree)

```

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