Package 'jti'

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Description

Minimal and memory efficient implementation of the junction tree algorithm using the Lauritzen-Spiegelhalter scheme.

Details

The main functions are cpt_list, compile,jt and query_belief which together is sufficient to make inference using the junction tree algorithm.

Author(s)

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References

Local Computations with Probabilities on Graphical Structures and Their Application to Expert Systems by S. L. Lauritzen and D. J. Spiegelhalter (1988). Journal of the Royal Statistical Society: Series B (Methodological) volume 50, issue 2.

See Also

Useful links:

• https://github.com/mlindsk/jti

asia

Asia

Description

Small synthetic data set from Lauritzen and Spiegelhalter (1988) about lung diseases (tuberculosis, lung cancer or bronchitis) and visits to Asia. This copy of the data was taken from the R package "bnlearn" where all values "yes" have been converted to "y" and all values "no" have been converted to "n".

Usage

asia

Format

An object of class tbl_df (inherits from tbl, data.frame) with 5000 rows and 8 columns.

Details

D (dysponea)

T (tuberculosis)

L (lung cancer)

B (bronchitis)

A (visit to Asia)

S (smoking)

X (chest C-ray)

E (tuberculosis vs cancer/bronchitis)

References

bnlearn-asia

bnfit_to_cpts

asia2

Asia2

Description

See the asia data for information. This version, has class bn.fit.

Usage

asia2

Format

An object of class list of length 8.

References

bnlearn-asia

bnfit_to_cpts

bnfit to cpts

Description

Convert a bn.fit object (a list of cpts from the bnlearn package) into a list of ordinary array-like cpts

Usage

```
bnfit_to_cpts(x)
```

Arguments

Χ

 $A \; \mathsf{bn.fit} \; object$

compile 5

compile

Compile information

Description

Compiled objects are used as building blocks for junction tree inference

Usage

```
compile(
 Х,
  evidence = NULL,
  root_node = "",
  joint_vars = NULL,
  tri = "min_fill",
  pmf_evidence = NULL,
  alpha = NULL,
  initialize_cpts = TRUE
)
## S3 method for class 'cpt_list'
compile(
  х,
 evidence = NULL,
  root_node = "",
  joint_vars = NULL,
  tri = "min_fill",
  pmf_evidence = NULL,
  alpha = NULL,
  initialize_cpts = TRUE
)
```

Arguments

An object returned from cpt_list (baeysian network) or pot_list (decomposable markov random field)

evidence A named vector. The names are the variabes and the elements are the evidence.

root_node A node for which we require it to live in the root clique (the first clique).

joint_vars A vector of variables for which we require them to be in the same clique. Edges between all these variables are added to the moralized graph.

tri The optimization strategy used for triangulation if x originates from a Baeysian network. One of

- 'min_fill'
- 'min_rfill'
- 'min_sp'

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- 'min_ssp'
- 'min_lsp'
- 'min_lssp'
- 'min_elsp'
- 'min_elssp'
- 'min_nei'
- 'minimal''alpha'

pmf evidence

A named vector of frequencies of the expected missingness of a variable. Variables with frequencies of 1 can be neglected; these are inferrred. A value of 0.25 means, that the given variable is expected to be missing (it is not a evidence node) in one fourth of the future cases. Relevant for tri methods 'min_elsp' and 'min_elssp'.

alpha

Character vector. A permutation of the nodes in the graph. It specifies a user-supplied eliminination ordering for triangulation of the moral graph.

initialize_cpts

TRUE if the CPTs should be initialized, i.e. multiplied together to form the clique potentials. If FALSE, the compiled object will save the triangulation and other information that needs only bee computed once. Herafter, it is possible to enter evidence into the CPTs, using set_evidence, saving a lot of computations.

Details

The Junction Tree Algorithm performs both a forward and inward message pass (collect and distribute). However, when the forward phase is finished, the root clique potential is guaranteed to be the joint pmf over the variables involved in the root clique. Thus, if it is known in advance that a specific variable is of interest, the algorithm can be terminated after the forward phase. Use the root_node to specify such a variable and specify propagate = "collect" in the juntion tree algorithm function jt.

Moreover, if interest is in some joint pmf for variables that end up being in different cliques these variables must be specified in advance using the joint_vars argument. The compilation step then adds edges between all of these variables to ensure that at least one clique contains all of them.

Evidence can be entered either at compile stage or after compilation. Hence, one can also combine evidence from before compilation with evidence after compilation. Before refers to entering evidence in the 'compile' function and after refers to entering evidence in the 'jt' function.

Finally, one can either use a Bayesian network or a decomposable Markov random field (use the ess package to fit these). Bayesian networks must be constructed with cpt_list and decomposable MRFs can be constructed with both pot_list and cpt_list. However, pot_list is just an alias for cpt_list which handles both cases internally.

Examples

```
cptl <- cpt_list(asia2)
cp1 <- compile(cptl, evidence = c(bronc = "yes"), joint_vars = c("bronc", "tub"))
print(cp1)
names(cp1)
dim_names(cp1)</pre>
```

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```
plot(get_graph(cp1))
```

cpt_list

Conditional probability list

Description

A check and conversion of cpts to be used in the junction tree algorithm

Usage

```
cpt_list(x, g = NULL)
## S3 method for class 'list'
cpt_list(x, g = NULL)
## S3 method for class 'data.frame'
cpt_list(x, g)
```

Arguments

x Either a named list with cpts in form of array-like object(s) where names must be the child node or a data.frame

Either a directed acyclic graph (DAG) as an igraph object or a decomposable graph as an igraph object. If x is a list, g must be NULL. The procedure then deduce the graph from the conditional probability tables.

Examples

g

```
library(igraph)
el <- matrix(c(
"A", "T",
"T", "E",
"S", "L",
"S", "B",
"L", "E",
"E", "D",
"B", "D"),
nc = 2,
byrow = TRUE
)

g <- igraph::graph_from_edgelist(el)
cl <- cpt_list(asia, g)

print(cl)
dim_names(cl)</pre>
```

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```
names(cl)
plot(get_graph(cl))
```

dim_names

Various getters

Description

Getter methods for cpt_list, pot_list, charge and jt objects

Usage

```
dim_names(x)
has_inconsistencies(x)
## S3 method for class 'cpt_list'
dim_names(x)
## S3 method for class 'cpt_list'
names(x)
## S3 method for class 'charge'
dim_names(x)
## S3 method for class 'charge'
names(x)
## S3 method for class 'charge'
has_inconsistencies(x)
## S3 method for class 'jt'
dim_names(x)
## S3 method for class 'jt'
names(x)
## S3 method for class 'jt'
has_inconsistencies(x)
```

Arguments

```
x cpt_list, pot_list, charge or jt
```

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get_cliques

Return the cliques of a junction tree

Description

Return the cliques of a junction tree

Usage

```
get_cliques(x)
## S3 method for class 'jt'
get_cliques(x)
## S3 method for class 'charge'
get_cliques(x)
## S3 method for class 'pot_list'
get_clique_root_idx(x)
## S3 method for class 'jt'
get_clique_root_idx(x)
## S3 method for class 'jt'
get_clique_root(x)
## S3 method for class 'jt'
get_clique_root(x)
```

Arguments

Х

A junction tree object, jt.

See Also

jt

Examples

```
# See Example 5 and 6 of the 'jt' function
```

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get_graph

Get graph

Description

Retrieve the graph

Usage

```
get_graph(x)
## S3 method for class 'charge'
get_graph(x)
## S3 method for class 'cpt_list'
get_graph(x)
```

Arguments

X

cpt_list or a compiled object

Value

A graph as an igraph object

get_triang_graph

Get triangulated graph

Description

Retrieve the triangulated graph from

Usage

```
get_triang_graph(x)
```

Arguments

Х

A compiled object

Value

A triangulated graph as a neibor matrix

initialize 11

initialize Initialize

Description

Initialization of CPTs

Usage

```
initialize(x)
## S3 method for class 'charge'
initialize(x)
```

Arguments

Χ

A compiled object.

Details

Multiply the CPTs and allocate them to clique potentials.

jt Junction Tree

Description

Construction of a junction tree and message passing

Usage

```
jt(x, evidence = NULL, flow = "sum", propagate = "full")
## S3 method for class 'charge'
jt(x, evidence = NULL, flow = "sum", propagate = "full")
```

Arguments

x An object return from compile

evidence A named vector. The names are the variabes and the elements are the evidence

flow Either "sum" or "max"

propagate Either "no", "collect" or "full".

jt jt

Details

Evidence can be entered either at compile stage or after compilation. Hence, one can also combine evidence from before compilation with evidence after compilation. Before refers to entering evidence in the 'compile' function and after refers to entering evidence in the 'jt' function.

Value

A jt object

See Also

```
query_belief, mpe, get_cliques, get_clique_root, propagate
```

Examples

```
# Setting up the network
# -----
library(igraph)
el <- matrix(c(
"A", "T",
"T", "E",
"S", "L",
"S", "B",
"L", "E",
"E", "X",
"E", "D",
"B", "D"),
nc = 2,
 byrow = TRUE
g <- igraph::graph_from_edgelist(el)</pre>
plot(g)
# Data
# We use the asia data; see the man page (?asia)
# Compilation
cl <- cpt_list(asia, g) # Checking and conversion</pre>
cp <- compile(cl)</pre>
# After the network has been compiled, the graph has been triangulated and
# moralized. Furthermore, all conditional probability tables (CPTs) has been
# designated one of the cliques (in the triangulated and moralized graph).
# Example 1: sum-flow without evidence
```

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```
jt1 <- jt(cp)
plot(jt1)
print(jt1)
query_belief(jt1, c("E", "L", "T"))
query_belief(jt1, c("B", "D", "E"), type = "joint")
# Notice, that jt1 is equivalent to:
# jt1 <- jt(cp, propagate = "no")</pre>
# jt1 <- propagate(jt1, prop = "full")</pre>
# That is; it is possible to postpone the actual propagation
# In this setup, the junction tree is saved in the jt1 object,
# and one can repeadetly enter evidence for new observations
# using the set_evidence function on jt1 and then query
# several probabilites without repeadetly calculating the
# the junction tree over and over again. One just needs
# to use the propagate function on jt1.
# Example 2: sum-flow with evidence
# -----
e2 <- c(A = "y", X = "n")
jt2 <- jt(cp, e2)
query_belief(jt2, c("B", "D", "E"), type = "joint")
# Notice that, the configuration (D,E,B) = (y,y,n) has changed
# dramatically as a consequence of the evidence
# We can get the probability of the evidence:
query_evidence(jt2)
# Example 3: max-flow without evidence
# -----
jt3 \leftarrow jt(cp, flow = "max")
mpe(jt3)
# Example 4: max-flow with evidence
# -----
e4 <- c(T = "y", X = "y", D = "y")
jt4 \leftarrow jt(cp, e4, flow = "max")
mpe(jt4)
\# Notice, that T, E, S, B, X and D has changed from "n" to "y"
# as a consequence of the new evidence e4
# Example 5: specifying a root node and only collect to save run time
 cp5 <- compile(cpt_list(asia, g), root_node = "X")</pre>
```

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```
jt5 <- jt(cp5, propagate = "collect")</pre>
  query_belief(jt5, get_clique_root(jt5), "joint")
# We can only query from the variables in the root clique now
# but we have ensured that the node of interest, "X", does indeed live in
# this clique. The variables are found using 'get_clique_root'
# Example 6: Compiling from a list of conditional probabilities
# * We need a list with CPTs which we extract from the asia2 object
    - the list must be named with child nodes
     - The elements need to be array-like objects
cl <- cpt_list(asia2)</pre>
cp6 <- compile(cl)</pre>
# Inspection; see if the graph correspond to the cpts
# g <- get_graph(cp6)</pre>
# plot(g)
# This time we specify that no propagation should be performed
jt6 <- jt(cp6, propagate = "no")</pre>
# We can now inspect the collecting junction tree and see which cliques
# are leaves and parents
plot(jt6)
get_cliques(jt6)
get_clique_root(jt6)
leaves(jt6)
unlist(parents(jt6))
# That is;
# - clique 2 is parent of clique 1
# - clique 3 is parent of clique 4 etc.
# Next, we send the messages from the leaves to the parents
jt6 <- send_messages(jt6)</pre>
# Inspect again
plot(jt6)
# Send the last message to the root and inspect
jt6 <- send_messages(jt6)</pre>
plot(jt6)
# The arrows are now reversed and the outwards (distribute) phase begins
leaves(jt6)
parents(jt6)
# Clique 2 (the root) is now a leave and it has 1, 3 and 6 as parents.
```

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```
# Finishing the message passing
jt6 <- send_messages(jt6)
jt6 <- send_messages(jt6)

# Queries can now be performed as normal
query_belief(jt6, c("either", "tub"), "joint")</pre>
```

jt_nbinary_ops

Number of Binary Operations

Description

Number of binary operations needed to propagate in a junction tree given evidence, using the Lauritzen-Spiegelhalter scheme

Usage

```
jt_nbinary_ops(x, evidence = list(), root = NULL, nc = 1)
## S3 method for class 'triangulation'
jt_nbinary_ops(x, evidence = list(), root = NULL, nc = 1)
```

Arguments

Х	A junction tree object or an object returned from the triangulation function
evidence	List of character vectors with evidence nodes
root	Integer specifying the root node in the junction tree
nc	Integer. The number of cores to be used in parallel

leaves

Query Parents or Leaves in a Junction Tree

Description

Return the clique indices of current parents or leaves in a junction tree

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Usage

```
leaves(jt)
## S3 method for class 'jt'
leaves(jt)
parents(jt)
## S3 method for class 'jt'
parents(jt)
```

Arguments

jt

A junction tree object, jt.

See Also

```
jt, get_cliques
```

Examples

```
# See example 6 in the help page for the jt function
```

 mpd

Maximal Prime Decomposition

Description

Find the maximal prime decomposition and its associated junction tree

Usage

```
mpd(x, save_graph = TRUE)
## S3 method for class 'matrix'
mpd(x, save_graph = TRUE)
## S3 method for class 'cpt_list'
mpd(x, save_graph = TRUE)
```

Arguments

x Either a neighbor matrix or a cpt_list object

save_graph Logical indicating if the moralized graph should be kept. Useful when x is a

cpt_list object.

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Value

- prime_ints: a list with the prime components, - flawed: indicating which prime components that are triangulated - jt_collect: the MPD junction tree prepared for collecting

Examples

```
library(igraph)
el <- matrix(c(
"A", "T",
"T", "E",
"S", "L",
"S", "B",
"L", "E",
"E", "X",
"E", "D",
nc = 2,
byrow = TRUE
)

g <- igraph::graph_from_edgelist(el, directed = FALSE)
A <- igraph::as_adjacency_matrix(g, sparse = FALSE)
mpd(A)</pre>
```

mpe

Most Probable Explanation

Description

Returns the most probable explanation given the evidence entered in the junction tree

Usage

```
mpe(x)
## S3 method for class 'jt'
mpe(x)
```

Arguments

Х

A junction tree object, jt, with max-flow.

See Also

jt

Examples

```
# See the 'jt' function
```

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plot.charge

A plot method for junction trees

Description

A plot method for junction trees

Usage

```
## S3 method for class 'charge' plot(x, ...)
```

Arguments

x A compile object

... For S3 compatability. Not used.

See Also

compile

plot.jt

A plot method for junction trees

Description

A plot method for junction trees

Usage

```
## S3 method for class 'jt' plot(x, ...)
```

Arguments

x A junction tree object, jt.

... For S3 compatability. Not used.

See Also

jt

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pot_list	A check and extraction of clique potentials from a Markov random
	field to be used in the junction tree algorithm

Description

A check and extraction of clique potentials from a Markov random field to be used in the junction tree algorithm

Usage

```
pot_list(x, g)
## S3 method for class 'data.frame'
pot_list(x, g)
```

Arguments

x Character data.frame

g A decomposable Markov random field as an igraph object.

Examples

```
# Typically one would use the ess package:
# library(ess)
# g <- ess::fit_graph(derma)
# pl <- pot_list(derma, ess::as_igraph(g))
# pl

# Another example
g <- igraph::sample_gnm(ncol(asia), 12)
while(!igraph::is.chordal(g)$chordal) g <- igraph::sample_gnm(ncol(asia), 12, FALSE)
igraph::V(g)$name <- colnames(asia)
plot(g)
pot_list(asia, g)</pre>
```

print.charge

A print method for compiled objects

Description

A print method for compiled objects

20 print.cpt_list

Usage

```
## S3 method for class 'charge'
print(x, ...)
```

Arguments

x A compiled object

... For S3 compatability. Not used.

See Also

jt

print.cpt_list

A print method for cpt lists

Description

A print method for cpt lists

Usage

```
## S3 method for class 'cpt_list'
print(x, ...)
```

Arguments

x A cpt_list object

... For S3 compatability. Not used.

See Also

compile

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print.jt

A print method for junction trees

Description

A print method for junction trees

Usage

```
## S3 method for class 'jt'
print(x, ...)
```

Arguments

x A junction tree object, jt.... For S3 compatability. Not used.

See Also

jt

propagate

Propagation of junction trees

Description

Given a junction tree object, propagation is conducted

Usage

```
propagate(x, prop = "full")
## S3 method for class 'jt'
propagate(x, prop = "full")
```

Arguments

x A junction tree object jt prop Either "collect" or "full".

See Also

jt

Examples

```
# See Example 1 in the 'jt' function
```

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query_belief

Query probabilities

Description

Get probabilities from a junction tree object

Usage

```
query_belief(x, nodes, type = "marginal")
## S3 method for class 'jt'
query_belief(x, nodes, type = "marginal")
```

Arguments

x A junction tree object, jt.

nodes The nodes for which the probability is desired

type Either 'marginal' or 'joint'

See Also

```
jt, mpe
```

Examples

```
# See the 'jt' function
```

query_evidence

Query Evidence

Description

Get the probability of the evidence entered in the junction tree object

Usage

```
query_evidence(x)
## S3 method for class 'jt'
query_evidence(x)
```

Arguments

x A junction tree object, jt.

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See Also

```
jt, mpe
```

send_messages

Send Messages in a Junction Tree

Description

Send messages from the current leaves to the current parents in a junction tree

Usage

```
send_messages(jt)
```

Arguments

jt

A jt object return from the jt function

See Also

```
jt, get_cliques, leaves, parents
```

Examples

See example 6 in the help page for the jt function

set_evidence

Enter Evidence

Description

Enter evidence into a the junction tree object that has not been propagated

Usage

```
set_evidence(x, evidence, initialize_cpts = TRUE)
## S3 method for class 'jt'
set_evidence(x, evidence, initialize_cpts = FALSE)
## S3 method for class 'charge'
set_evidence(x, evidence, initialize_cpts = TRUE)
```

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Arguments

x A junction tree object, jt.

evidence A named vector. The names are the variabes and the elements are the evidence. initialize_cpts

TRUE if the CPTs should be initialized and then create the clique potentials. Only relevant on objects returned from compile.

See Also

```
jt, mpe
```

Examples

```
# See the 'jt' function
```

sim_data_from_bn

Simulate data from a Bayesian network

Description

Simulate data from a Bayesian network

Usage

```
sim_data_from_bn(
  net,
  lvls,
  nsims = 1000,
  increasing_prob = FALSE,
  p1 = 0.8,
  p2 = 1
)
```

Arguments

net A Bayesian network as an igraph object

lvls Named integer vector where each element is the size of the statespace of the

corresponding variable

nsims Number of simulations distributions from which the simulatios are drawn.

increasing_prob

Logical. If true, probabilities in the underlying CPTs increases with as the num-

ber of levels increses.

p1 Probability

p2 Probability

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Examples

```
net <- igraph::graph(as.character(c(1,2,1,3,3,4,3,5,5,4,2,6,6,7,5,7)), directed = TRUE)
nodes_net <- igraph::V(net)$name
lvls_net <- structure(sample(3:9, length(nodes_net)), names = nodes_net)
lvls_net <- structure(rep(3, length(nodes_net)), names = nodes_net)
sim_data_from_bn(net, lvls_net, 10)</pre>
```

 $sim_data_from_dmrf$

Simulate data from a decomposable discrete markov random field

Description

Simulate data from a decomposable discrete markov random field

Usage

```
sim_data_from_dmrf(
  graph,
  lvls,
  nsims = 1000,
  increasing_prob = FALSE,
  p1 = 0.8,
  p2 = 1
)
```

Arguments

	graph	A decomposable discrete markov random field as an igraph object
	lvls	Named integer vector where each element is the size of the statespace of the corresponding variable
	nsims	Number of simulations distributions from which the simulatios are drawn.
increasing_prob		
		Logical. If true, probabilities in the underlying CPTs increases with as the number of levels increses.
	p1	Probability
	p2	Probability

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triangulate

Triangulate a Bayesian network

Description

Given a list of CPTs, this function finds a triangulation

Usage

```
triangulate(
  root_node = "",
  joint_vars = NULL,
  tri = "min_fill",
  pmf_evidence = NULL,
  alpha = NULL,
 perm = FALSE,
 mpd_based = FALSE
)
## S3 method for class 'cpt_list'
triangulate(
  Х,
  root_node = "",
  joint_vars = NULL,
  tri = "min_fill",
  pmf_evidence = NULL,
 alpha = NULL,
 perm = FALSE,
 mpd_based = FALSE
)
```

Arguments

An object returned from cpt_list (baeysian network) or pot_list (decompos-Х able markov random field)

root_node

A node for which we require it to live in the root clique (the first clique).

joint_vars

A vector of variables for which we require them to be in the same clique. Edges between all these variables are added to the moralized graph.

tri

The optimization strategy used for triangulation if x originates from a Baeysian network. One of

- 'min_fill'
- 'min_rfill'
- 'min_sp'
- 'min_ssp'

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- 'min_lsp'
- 'min_lssp'
- 'min_elsp'
- 'min_elssp'
- 'min nei'
- 'minimal'
- · 'alpha'

pmf_evidence

A named vector of frequencies of the expected missingness of a variable. Variables with frequencies of 1 can be neglected; these are inferrred. A value of 0.25 means, that the given variable is expected to be missing (it is not a evidence node) in one fourth of the future cases. Relevant for tri methods 'min_elsp' and 'min_elsp'.

alpha Character vector. A permutation of the nodes in the graph. It specifies a user-

supplied eliminination ordering for triangulation of the moral graph.

perm Logical. If TRUE the moral graph is permuted

mpd_based Logical. True if the triangulation should be performed on a maximal peime

decomposition

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