# Package 'mapscanner'

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Title Print Maps, Draw on Them, Scan Them Back in

Version 0.0.6

**Description** Enables preparation of maps to be printed and drawn on. Modified maps can then be scanned back in, and hand-drawn marks converted to spatial objects.

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URL https://github.com/ropensci/mapscanner

BugReports https://github.com/ropensci/mapscanner/issues

**Depends** R (>= 3.5.0)

**Imports** cli, curl, fs, glue, magick, magrittr, memoise, pdftools, png, purrr, raster, Rcpp, reproj, RNiftyReg, sf, slippymath, tibble

**Suggests** dplyr, ggplot2, gibble, jpeg, knitr, lwgeom, mapview, mmand, osmdata, polyclip, rmarkdown, spelling, testthat

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VignetteBuilder knitr

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Author Mark Padgham [aut, cre],

Michael D. Sumner [aut],

Kelly Hondula [rev] (Kelly reviewed the package for rOpenSci, see https://github.com/ropensci/software-review/issues/330),

Nicholas Potter [rev] (Nichola reviewed the package for rOpenSci, see https://github.com/ropensci/software-review/issues/330),

Stanislaw Adaszewski [cph] (author of include concaveman-cpp code)

Maintainer Mark Padgham <mark.padgham@email.com>

Repository CRAN

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## **Description**

Planar partition from disparate polygon inputs. Overlaps aggregate to n.

#### Usage

```
ms_aggregate_polys(p)
```

## Arguments р

input (multi-)polygons (assumed to be overlapping)

#### **Details**

Input is a single simple features polygon data frame. No attribute data is considered.

#### Value

Set of sf-format polygons with additional column, n, denoting number of overlaps contributing to each of the resultant polygons.

#### **Examples**

```
g <- sf::st_sfc(list(sf::st_point(cbind(0, 0)),</pre>
                      sf::st_point(cbind(0, 1)),
                      sf::st_point(cbind(1, 0))))
pts <- sf::st_sf(a = 1:3, geometry = g)
overlapping_polys <- sf::st_buffer(pts, 0.75)</pre>
## decompose and count space-filling from overlapping polygons
x <- ms_aggregate_polys(overlapping_polys)</pre>
plot(x)
## Not run:
library(ggplot2)
ggplot(x) + geom_sf() + facet_wrap(~n)
## End(Not run)
```

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```
library(sf)
set.seed(6)
pts <- expand.grid (x = 1:8, y = 1:10) %>% st_as_sf (coords = c("x", "y"))
xsf <- sf::st_buffer (pts, runif (nrow (pts), 0.2, 1.5))
## Not run:
out <- ms_aggregate_polys (xsf)
## End(Not run)</pre>
```

ms\_generate\_map

Generate maps for 'mapscanner' use

#### **Description**

Generate a map image for a specified area or bounding box, by downloading tiles from <a href="https://www.mapbox.com/">https://www.mapbox.com/</a>. Map is automatically saved in both .pdf and .png formats, by default in current working directory, or alternative location when mapname includes the full path.

#### Usage

```
ms_generate_map(
  bbox,
  max_tiles = 16L,
  mapname = NULL,
  bw = TRUE,
  style = "light",
  raster_brick = NULL
)
```

#### **Arguments**

bw

ppox	Either a string specifying the location, or a numeric bounding box as a single
	vector of (xmin, ymin, xmax, ymax), or a 2-by-2 matrix with columns of (min,
	max) and rows of $(x, y)$ , respectively.
may tiles	Maximum number of tiles to use to create man

max_tiles	Maxiiii	uiii iiui	mbe	1 01	mes u	use	10 0	reau	iap	,		
											0 11	

mapname	Name of map to be produced, optionally including full path. Extension will be
	ignored.

If FALSE, print maps in colour, otherwise black-and-white.	. Note that the default
style = "light" is monochrome, and that this parameter	er only has effect for

style values of "streets" or "outdoors".

style The style of the map to be generated; one of 'light', 'streets', or 'outdoors', ren-

dered in black and white. See https://docs.mapbox.com/api/maps/#styles/

for examples.

raster\_brick Instead of automatically downloading tiles within a given bbox, a pre-downloaded

raster::rasterBrick object may be submitted and used to generate the .pdf

and .png equivalents.

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#### Value

Invisibly returns a rasterBrick object from the **raster** package containing all data used to generate the map.

#### **Examples**

ms\_rectify\_map

Rectify one map to another

#### Description

Rectify two previously scanned-in pdf or png maps with RNiftyReg, and return the modifications in map\_modified as spatial objects in **sf** format.

#### Usage

```
ms_rectify_map(
   map_original,
   map_modified,
   nitems = NULL,
   non_linear = 1,
   type = "hulls",
   downsample = 10,
   concavity = 0,
   length_threshold = 10,
   quiet = FALSE
)
```

#### **Arguments**

map\_original File name of the original map without anything drawn over it (either a .pdf or

.png; extension will be ignored).

map\_modified File name of the modified version with drawings (either a .pdf or .png; exten-

sion will be ignored).

nitems Optional parameter to explicitly specify number of distinct items to be extracted from map; if possible, specifying this parameter may improve results.

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non\_linear Integer value of 0, 1, or 2 representing degree of non-linearity in modified image

- see Note.

type Currently either "points", "polygons", or "hulls", where "points" simply reduces

each distinct object to a single, central point; "polygons" identifies individual groups and returns the polygon representing the outer boundary of each; and

"hulls" constructs convex or concave polygons around each group.

downsample Factor by which to downsample type = "polygons", noting that polygons ini-

tially include every outer pixel of image, so can generally be downsampled by at least an order or magnitude (n = 10). Higher values may be used for higher-resolution images; lower values will generally only be necessary for very low

lower resolution images.

concavity For type = "hulls", a value between 0 and 1, with 0 giving convex hulls and 1

giving highly concave hulls.

length\_threshold

For type = "hulls", the minimal length of a segment to be made more convex. Low values will produce highly detailed hulls which may cause problems; if in

doubt, or if odd results appear, increase this value.

quiet If FALSE, display progress information on screen

#### Value

An **sf** object representing the drawn additions to map\_modified.

#### Note

The non-linear parameter should generally set according to how the modified maps were digitised. A value of 0 will give fastest results, and should be used for directly scanned or photocopied images. A value of 1 (the default) still presumes modified images have been linearly translated, and will apply affine transformations (rotations, contractions, dilations). This value should be used when modified images have been photographed (potentially from an oblique angle). A value of 2 should only be used when modified maps have somehow been non-linearly distorted, for example through having been crumpled or screwed up. Rectification with non-linear = 2 will likely take considerably longer than with lower values.

ms\_rotate\_map Rotate maps

#### **Description**

Display original and modified maps to determine necessary rotation

#### Usage

ms\_rotate\_map(map\_original, map\_modified, rotation = 0, apply\_rotation = FALSE)

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#### **Arguments**

map\_original File name of the original map without anything drawn over it (either a .pdf or

.png; extension will be ignored).

map\_modified File name of the modified version with drawings (either a .pdf or .png; exten-

sion will be ignored).

rotation Rotation value to be applied, generally +/- 90

apply\_rotation If FALSE, display results of rotation without actually applying it; otherwise trans-

form the specified map\_modified image according to the specified rotation.

#### Value

No return value. Function either modifies files on disk by rotating images by the specified amount (if apply\_rotation = TRUE), or displays a rotated version of map\_original (if apply\_rotation = FALSE).

#### Note

If a call to ms\_rectify\_map detects potential image rotation, that function will stop and suggest that rotation be applied using this function in order to determine the required degree of image rotation. Values for rotation can be trialled in order to determine the correct value, following which that value can be entered with apply\_rotation = TRUE in order to actually apply that rotation to the modified image.

set\_mapbox\_token
Set 'mapbox' token

#### **Description**

Set a mapbox token for use with the ms\_generate\_map function.

#### Usage

```
set_mapbox_token(token)
```

#### **Arguments**

token Personal mapbox API token, obtained from https://docs.mapbox.com/api/

#access-tokens-and-token-scopes.

#### Value

TRUE if the token was able to be set; otherwise FALSE.

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