# Package 'minpack.lm' 

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Title R Interface to the Levenberg-Marquardt Nonlinear Least-Squares Algorithm Found in MINPACK, Plus Support for Bounds
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Description The nls.lm function provides an R interface to lmder and lmdif from the MINPACK library, for solving nonlinear least-squares problems by a modification of the LevenbergMarquardt algorithm, with support for lower and upper parameter bounds. The implementation can be used via nls-like calls using the nlsLM function.
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Addresses NLS problems with the Levenberg-Marquardt algorithm

## Description

The purpose of $n l s . l m$ is to minimize the sum square of the vector returned by the function $f n$, by a modification of the Levenberg-Marquardt algorithm. The user may also provide a function jac which calculates the Jacobian.

## Usage

```
nls.lm(par, lower=NULL, upper=NULL, fn, jac = NULL,
            control = nls.lm.control(), ...)
```


## Arguments

par A list or numeric vector of starting estimates. If par is a list, then each element must be of length 1 .
lower A numeric vector of lower bounds on each parameter. If not given, the default lower bound for each parameter is set to -Inf.
upper A numeric vector of upper bounds on each parameter. If not given, the default upper bound for each parameter is set to Inf.
fn A function that returns a vector of residuals, the sum square of which is to be minimized. The first argument of $f n$ must be par.
jac A function to return the Jacobian for the fn function.
control An optional list of control settings. See nls.lm. control for the names of the settable control values and their effect.
... Further arguments to be passed to fn and jac.

## Details

Both functions fn and jac (if provided) must return numeric vectors. Length of the vector returned by fn must not be lower than the length of par. The vector returned by jac must have length equal to length (fn(par, ...)) • length(par).
The control argument is a list; see nls.lm. control for details.

## Successful completion.

The accuracy of nls. 1 m is controlled by the convergence parameters ftol, ptol, and gtol. These parameters are used in tests which make three types of comparisons between the approximation par and a solution $p a r_{0} . \mathrm{nls} .1 \mathrm{~m}$ terminates when any of the tests is satisfied. If any of the convergence parameters is less than the machine precision, then nls.lm only attempts to satisfy the test defined by the machine precision. Further progress is not usually possible.
The tests assume that fn as well as jac are reasonably well behaved. If this condition is not satisfied, then nls.lm may incorrectly indicate convergence. The validity of the answer can be checked, for example, by rerunning nls.lm with tighter tolerances.

## First convergence test.

If $|z|$ denotes the Euclidean norm of a vector $z$, then this test attempts to guarantee that

$$
|f v e c|<(1+\text { ftol }) \mid \text { fvec }_{0} \mid
$$

where $f v e c_{0}$ denotes the result of $f n$ function evaluated at par $_{0}$. If this condition is satisfied with $\mathrm{ftol} \simeq 10^{-k}$, then the final residual norm $\mid$ fvec $\mid$ has $k$ significant decimal digits and info is set to 1 (or to 3 if the second test is also satisfied). Unless high precision solutions are required, the recommended value for ftol is the square root of the machine precision.

## Second convergence test.

If $D$ is the diagonal matrix whose entries are defined by the array diag, then this test attempt to guarantee that

$$
\mid D\left(\text { par }-\operatorname{par}_{0}\right)|<\operatorname{ptol}| D \operatorname{par}_{0} \mid,
$$

If this condition is satisfied with ptol $\simeq 10^{-k}$, then the larger components of ( $D$ par ) have $k$ significant decimal digits and info is set to 2 (or to 3 if the first test is also satisfied). There is a danger that the smaller components of ( $D$ par ) may have large relative errors, but if diag is internally set, then the accuracy of the components of par is usually related to their sensitivity. Unless high precision solutions are required, the recommended value for ptol is the square root of the machine precision.

## Third convergence test.

This test is satisfied when the cosine of the angle between the result of fn evaluation fvec and any column of the Jacobian at par is at most gtol in absolute value. There is no clear relationship between this test and the accuracy of nls.lm, and furthermore, the test is equally well satisfied at other critical points, namely maximizers and saddle points. Therefore, termination caused by this test $(i n f o=4)$ should be examined carefully. The recommended value for gtol is zero.

## Unsuccessful completion.

Unsuccessful termination of nls.lm can be due to improper input parameters, arithmetic interrupts, an excessive number of function evaluations, or an excessive number of iterations.

## Improper input parameters.

info is set to 0 if length(par) $=0$, or length $(f v e c)<l e n g t h(p a r)$, or ftol $<0$, or ptol $<0$, or gtol $<0$, or maxfev $\leq 0$, or factor $\leq 0$.

## Arithmetic interrupts.

If these interrupts occur in the fn function during an early stage of the computation, they may be caused by an unacceptable choice of par by nls.lm. In this case, it may be possible to remedy the situation by rerunning nls .1 m with a smaller value of factor.

## Excessive number of function evaluations.

A reasonable value for maxfev is $100 \cdot($ length $(\mathrm{par})+1$ ). If the number of calls to fn reaches maxfev, then this indicates that the routine is converging very slowly as measured by the progress of $f v e c$ and info is set to 5 . In this case, it may be helpful to force diag to be internally set.

## Excessive number of function iterations.

The allowed number of iterations defaults to 50 , can be increased if desired.

The list returned by nls. 1 m has methods for the generic functions coef, deviance, df.residual, print, residuals, summary, confint, and vcov.

## Value

A list with components:

| par | The best set of parameters found. |
| :--- | :--- |
| hessian | A symmetric matrix giving an estimate of the Hessian at the solution found. |


| fvec | The result of the last fn evaluation; that is, the residuals. |
| :---: | :---: |
| info | info is an integer code indicating the reason for termination. |
|  | 0 Improper input parameters. |
|  | 1 Both actual and predicted relative reductions in the sum of squares are at most ftol. |
|  | 2 Relative error between two consecutive iterates is at most ptol. |
|  | 3 Conditions for info $=1$ and info $=2$ both hold. |
|  | 4 The cosine of the angle between fvec and any column of the Jacobian is at most gtol in absolute value. |
|  | 5 Number of calls to fn has reached maxfev. |
|  | 6 ftol is too small. No further reduction in the sum of squares is possible. |
|  | 7 ptol is too small. No further improvement in the approximate solution par is possible. |
|  | $\mathbf{8}$ gtol is too small. fvec is orthogonal to the columns of the Jacobian to machine precision. |
|  | 9 The number of iterations has reached maxiter. |
| message | character string indicating reason for termination |
| diag | The result list of diag. See Details. |
| niter | The number of iterations completed before termination. |
| rsstrace | The residual sum of squares at each iteration. Can be used to check the progress each iteration. |
| deviance | The sum of the squared residual vector. |

## Note

The public domain FORTRAN sources of MINPACK package by J.J. Moré, implementing the Levenberg-Marquardt algorithm were downloaded from http://netlib.org/minpack/, and left unchanged. The contents of this manual page are largely extracted from the comments of MINPACK sources.

## References

J.J. Moré, "The Levenberg-Marquardt algorithm: implementation and theory," in Lecture Notes in Mathematics 630: Numerical Analysis, G.A. Watson (Ed.), Springer-Verlag: Berlin, 1978, pp. 105-116.

## See Also

```
optim,nls, nls.lm.control
```


## Examples

```
###### example 1
## values over which to simulate data
x <- seq(0,5,length=100)
## model based on a list of parameters
getPred <- function(parS, xx) parS$a * exp(xx * parS$b) + parS$c
## parameter values used to simulate data
pp <- list(a=9,b=-1, c=6)
## simulated data, with noise
simDNoisy <- getPred(pp,x) + rnorm(length(x),sd=.1)
## plot data
plot(x,simDNoisy, main="data")
## residual function
residFun <- function(p, observed, xx) observed - getPred(p,xx)
## starting values for parameters
parStart <- list(a=3,b=-.001, c=1)
## perform fit
nls.out <- nls.lm(par=parStart, fn = residFun, observed = simDNoisy,
xx = x, control = nls.lm.control(nprint=1))
## plot model evaluated at final parameter estimates
lines(x,getPred(as.list(coef(nls.out)), x), col=2, lwd=2)
## summary information on parameter estimates
summary(nls.out)
###### example 2
## function to simulate data
f <- function(TT, tau, N0, a, f0) {
    expr <- expression(N0*exp(-TT/tau)*(1 + a*cos(f0*TT)))
    eval(expr)
}
## helper function for an analytical gradient
j <- function(TT, tau, N0, a, f0) {
    expr <- expression(N0*exp(-TT/tau)*(1 + a*cos(f0*TT)))
    c(eval(D(expr, "tau")), eval(D(expr, "N0" )),
        eval(D(expr, "a" )), eval(D(expr, "f0" )))
}
## values over which to simulate data
TT <- seq(0, 8, length=501)
```

```
## parameter values underlying simulated data
p <- c(tau = 2.2, N0 = 1000, a = 0.25, f0 = 8)
## get data
Ndet <- do.call("f", c(list(TT = TT), as.list(p)))
## with noise
N <- Ndet + rnorm(length(Ndet), mean=Ndet, sd=.01*max(Ndet))
## plot the data to fit
par(mfrow=c(2,1), mar = c(3,5,2,1))
plot(TT, N, bg = "black", cex = 0.5, main="data")
## define a residual function
fcn <- function(p, TT, N, fcall, jcall)
    (N - do.call("fcall", c(list(TT = TT), as.list(p))))
## define analytical expression for the gradient
fcn.jac <- function(p, TT, N, fcall, jcall)
    -do.call("jcall", c(list(TT = TT), as.list(p)))
## starting values
guess <- c(tau = 2.2, N0 = 1500, a = 0.25, f0 = 10)
## to use an analytical expression for the gradient found in fcn.jac
## uncomment jac = fcn.jac
out <- nls.lm(par = guess, fn = fcn, jac = fcn.jac,
    fcall = f, jcall = j,
    TT = TT, N = N, control = nls.lm.control(nprint=1))
## get the fitted values
N1 <- do.call("f", c(list(TT = TT), out$par))
## add a blue line representing the fitting values to the plot of data
lines(TT, N1, col="blue", lwd=2)
## add a plot of the log residual sum of squares as it is made to
## decrease each iteration; note that the RSS at the starting parameter
## values is also stored
plot(1:(out$niter+1), log(out$rsstrace), type="b",
main="log residual sum of squares vs. iteration number",
xlab="iteration", ylab="log residual sum of squares", pch=21,bg=2)
## get information regarding standard errors
summary (out)
```


## Description

Allow the user to set some characteristics Levenberg-Marquardt nonlinear least squares algorithm implemented in nls.lm.

## Usage

nls.lm.control(ftol = sqrt(.Machine\$double.eps),
ptol $=\operatorname{sqrt}($. Machine\$double.eps), gtol $=0$, diag $=1 i s t(), ~ e p s f c n=0$, factor $=100$, maxfev $=$ integer (), maxiter $=50$, nprint $=0$ )

## Arguments

\(\left.$$
\begin{array}{ll}\text { ftol } & \begin{array}{l}\text { non-negative numeric. Termination occurs when both the actual and predicted } \\
\text { relative reductions in the sum of squares are at most ftol. Therefore, ftol } \\
\text { measures the relative error desired in the sum of squares. }\end{array}
$$ <br>
ptol <br>
non-negative numeric. Termination occurs when the relative error between two <br>
consecutive iterates is at most ptol. Therefore, ptol measures the relative error <br>
desired in the approximate solution. <br>
non-negative numeric. Termination occurs when the cosine of the angle between <br>
result of fn evaluation fvec and any column of the Jacobian is at most gtol in <br>
absolute value. Therefore, gtol measures the orthogonality desired between the <br>

function vector and the columns of the Jacobian.\end{array}\right\}\)| a list or numeric vector containing positive entries that serve as multiplicative |
| :--- |
| scale factors for the parameters. Length of diag should be equal to that of par. |
| If not, user-provided diag is ignored and diag is internally set. |
| (used if jac is not provided) is a numeric used in determining a suitable step |
| for the forward-difference approximation. This approximation assumes that the |
| relative errors in the functions are of the order of epsfcn. If epsfcn is less than |
| the machine precision, it is assumed that the relative errors in the functions are |
| of the order of the machine precision. |

## Value

A list with exactly nine components:
ftol
ptol
gtol
diag
epsfon
factor
maxfev
nprint
with meanings as explained under 'Arguments'.

## References

J.J. Moré, "The Levenberg-Marquardt algorithm: implementation and theory," in Lecture Notes in Mathematics 630: Numerical Analysis, G.A. Watson (Ed.), Springer-Verlag: Berlin, 1978, pp. 105-116.

## See Also

nls.lm

## Examples

nls.lm.control(maxiter = 4)
nlsLM Standard 'nls' framework that uses 'nls.lm' for fitting

## Description

nlsLM is a modified version of $n l s$ that uses nls. 1 m for fitting. Since an object of class 'nls' is returned, all generic functions such as anova, coef, confint, deviance, df.residual, fitted, formula, logLik, predict, print, profile, residuals, summary, update, vcov and weights are applicable.

## Usage

```
nlsLM(formula, data = parent.frame(), start, jac = NULL,
    algorithm = "LM", control = nls.lm.control(),
    lower = NULL, upper = NULL, trace = FALSE, subset,
    weights, na.action, model = FALSE, ...)
```


## Arguments

| formula | a nonlinear model formula including variables and parameters. Will be coerced <br> to a formula if necessary. <br> an optional data frame in which to evaluate the variables informula and weights. <br> Can also be a list or an environment, but not a matrix. |
| :--- | :--- |
| data | a named list or named numeric vector of starting estimates. |
| start | A function to return the Jacobian. |
| jac | only method "LM" (Levenberg-Marquardt) is implemented. |
| algorithm | an optional list of control settings. See nls. Im. control for the names of the <br> settable control values and their effect. |
| control | A numeric vector of lower bounds on each parameter. If not given, the default <br> lower bound for each parameter is set to -Inf. |
| upper | A numeric vector of upper bounds on each parameter. If not given, the default <br> upper bound for each parameter is set to Inf. |
| trace | logical value indicating if a trace of the iteration progress should be printed. <br> Default is FALSE. If TRUE, the residual (weighted) sum-of-squares and the pa- <br> rameter values are printed at the conclusion of each iteration. |
| subset | an optional vector specifying a subset of observations to be used in the fitting <br> process. <br> an optional numeric vector of (fixed) weights. When present, the objective func- <br> tion is weighted least squares. See the wfct function for options for easy speci- |
| fication of weighting schemes. |  |

## Details

The standard nl s function was modified in several ways to incorporate the Levenberg-Marquardt type nls.lm fitting algorithm. The formula is transformed into a function that returns a vector of (weighted) residuals whose sum square is minimized by nls.lm. The optimized parameters are then transferred to nlsModel in order to obtain an object of class 'nlsModel'. The internal C function C_nls_iter and nls_port_fit were removed to avoid subsequent "Gauss-Newton", "port" or
 to make all generic functions work on the output.

## Value

A list of

| data | the expression that was passed to nls as the data argument. The actual data <br> values are present in the environment of the m component. <br> the matched call. |
| :--- | :--- |
| call | a list with convergence information. <br> convInfo <br> control |
| the control list used, see the control argument. |  |
| na.action | the "na.action" attribute (if any) of the model frame. |
| dataClasses | the "dataClasses" attribute (if any) of the "terms" attribute of the model <br> frame. |
| model | if model = TRUE, the model frame. |
| weights | if weights is supplied, the weights. |

## Author(s)

Andrej-Nikolai Spiess and Katharine M. Mullen

## References

Bates, D. M. and Watts, D. G. (1988) Nonlinear Regression Analysis and Its Applications, Wiley
Bates, D. M. and Chambers, J. M. (1992) Nonlinear models. Chapter 10 of Statistical Models in S eds J. M. Chambers and T. J. Hastie, Wadsworth \& Brooks/Cole.
J.J. More, "The Levenberg-Marquardt algorithm: implementation and theory," in Lecture Notes in Mathematics 630: Numerical Analysis, G.A. Watson (Ed.), Springer-Verlag: Berlin, 1978, pp. 105-116.

## See Also

nls.lm, nls, nls.lm. control, optim

## Examples

```
### Examples from 'nls' doc ###
DNase1 <- subset(DNase, Run == 1)
## using a selfStart model
fm1DNase1 <- nlsLM(density ~ SSlogis(log(conc), Asym, xmid, scal), DNase1)
## using logistic formula
fm2DNase1 <- nlsLM(density ~ Asym/(1 + exp((xmid - log(conc))/scal)),
    data = DNase1,
    start = list(Asym = 3, xmid = 0, scal = 1))
## all generics are applicable
coef(fm1DNase1)
confint(fm1DNase1)
deviance(fm1DNase1)
df.residual(fm1DNase1)
fitted(fm1DNase1)
formula(fm1DNase1)
logLik(fm1DNase1)
predict(fm1DNase1)
```

```
print(fm1DNase1)
profile(fm1DNase1)
residuals(fm1DNase1)
summary(fm1DNase1)
update(fm1DNase1)
vcov(fm1DNase1)
weights(fm1DNase1)
## weighted nonlinear regression using
## inverse squared variance of the response
## gives same results as original 'nls' function
Treated <- Puromycin[Puromycin$state == "treated", ]
var.Treated <- tapply(Treated$rate, Treated$conc, var)
var.Treated <- rep(var.Treated, each = 2)
Pur.wt1 <- nls(rate ~ (Vm * conc)/(K + conc), data = Treated,
    start = list(Vm = 200, K = 0.1), weights = 1/var.Treated^2)
Pur.wt2 <- nlsLM(rate ~ (Vm * conc)/(K + conc), data = Treated,
                start = list(Vm = 200, K = 0.1), weights = 1/var.Treated^2)
all.equal(coef(Pur.wt1), coef(Pur.wt2))
## 'nlsLM' can fit zero-noise data
## in contrast to 'nls'
x <- 1:10
y<- 2*x + 3
## Not run:
nls(y ~ a + b * x, start = list(a = 0.12345, b = 0.54321))
## End(Not run)
nlsLM(y ~ a + b * x, start = list(a = 0.12345, b = 0.54321))
### Examples from 'nls.lm' doc
## values over which to simulate data
x <- seq(0,5, length = 100)
## model based on a list of parameters
getPred <- function(parS, xx) parS$a * exp(xx * parS$b) + parS$c
## parameter values used to simulate data
pp <- list(a = 9,b = -1, c = 6)
## simulated data with noise
simDNoisy <- getPred(pp, x) + rnorm(length(x), sd = .1)
## make model
mod <- nlsLM(simDNoisy ~ a * exp(b * x) + c,
    start = c(a = 3, b = -0.001, c = 1),
    trace = TRUE)
## plot data
plot(x, simDNoisy, main = "data")
## plot fitted values
lines(x, fitted(mod), col = 2, lwd = 2)
## create declining cosine
## with noise
TT <- seq(0, 8, length = 501)
tau <- 2.2
N0 <- 1000
```

```
a <- 0.25
f0 <- 8
Ndet <- N0 * exp(-TT/tau) * (1 + a * cos(f0 * TT))
N <- Ndet + rnorm(length(Ndet), mean = Ndet, sd = .01 * max(Ndet))
## make model
mod <- nlsLM(N ~ N0 * exp(-TT/tau) * (1 + a * cos(f0 * TT)),
    start = c(tau = 2.2, N0 = 1500, a = 0.25, f0 = 10),
    trace = TRUE)
## plot data
plot(TT, N, main = "data")
## plot fitted values
lines(TT, fitted(mod), col = 2, lwd = 2)
```

wfct
Weighting function that can be supplied to the weights argument of
nlsLM or nls

## Description

wfct can be supplied to the weights argument of $n l s L M$ or $n l s$, and facilitates specification of weighting schemes.

## Usage

wfct(expr)

## Arguments

expr An expression specifying the weighting scheme as described in the Details section below.

## Details

The weighting function can take 5 different variable definitions and combinations thereof:

- the name of the predictor (independent) variable
- the name of the response (dependent) variable
- error: if replicates $y_{i j}$ exist, the error $\sigma\left(y_{i j}\right)$
- fitted: the fitted values $\hat{y}_{i}$ of the model
- resid: the residuals $y_{i}-\hat{y}_{i}$ of the model

For the last two, the model is fit unweighted, fitted values and residuals are extracted and the model is refit by the defined weights.

## Value

The results of evaluation of expr in a new environment, yielding the vector of weights to be applied.

## Author(s)

Andrej-Nikolai Spiess

## See Also

nlsLM, nls

## Examples

```
### Examples from 'nls' doc ###
## note that 'nlsLM' below may be replaced with calls to 'nls'
Treated <- Puromycin[Puromycin$state == "treated", ]
## Weighting by inverse of response 1/y_i:
nlsLM(rate ~ Vm * conc/(K + conc), data = Treated,
start = c(Vm = 200, K = 0.05), weights = wfct(1/rate))
## Weighting by square root of predictor \sqrt{x_i}:
nlsLM(rate ~ Vm * conc/(K + conc), data = Treated,
start = c(Vm = 200, K = 0.05), weights = wfct(sqrt(conc)))
## Weighting by inverse square of fitted values 1/\hat{y_i}^2:
nlsLM(rate ~ Vm * conc/(K + conc), data = Treated,
start = c(Vm = 200, K = 0.05), weights = wfct(1/fitted^2))
## Weighting by inverse variance 1/\sigma{y_i}^2:
nlsLM(rate ~ Vm * conc/(K + conc), data = Treated,
start = c(Vm = 200, K = 0.05), weights = wfct(1/error^2))
```


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