# Package 'momentfit'

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**Title** Methods of Moments

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Description Several classes for moment-based models are defined. The classes are defined for moment conditions derived from a single equation or a system of equations. The conditions can also be expressed as functions or formulas. Several methods are also offered to facilitate the development of different estimation techniques. The methods that are currently provided are the Generalized method of moments (Hansen 1982; <doi:10.2307/1912775>), for single equations and systems of equation, and the Generalized Empirical Likelihood (Smith 1997; <doi:10.1111/j.0013-0133.1997.174.x>, Kitamura 1997; <doi:10.1214/aos/1069362388>, Newey and Smith 2004; <doi:10.1111/j.1468-0262.2004.00482.x>, and Anatolyev 2005 <doi:10.1111/j.1468-0262.2005.00601.x>).

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'momentModel-methods.R' 'momentModel.R' 
'momentWeights-methods.R' 'gmmfit-methods.R' 
'specTest-methods.R' 'summary-methods.R' 'rModel-methods.R' 
'hypothesisTest-methods.R' 'sysMomentModel.R' 
'sysMomentModel-methods.R' 'rsysMomentModel-methods.R' 
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'gel4.R'

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alinLModel-class	4
pread-methods	4
CigarettesSW	5
coef-methods	7
confint-class	8
confint-methods	9
	10
Dresiduals-methods	12
	12
estfun-methods	14
evalDMoment-methods	14
	16
	18
evalGmm-methods	19
evalGmmObj-methods	20
evalMoment-methods	21
	22
	23
functionModel-class	24
gel4	26
gelfit-class	28
gelFit-methods	29
getImpProb-methods	30
getRestrict-methods	30
gmm4	32
gmmfit-class	35
	36
Griliches	39
	40
nypothesisTest-class	12
nypothesisTest-methods	43
kernapply-methods	46
Klein	<del>1</del> 7
LabourCR	18
ambdaAlgo	50
	51
	53
	54
	54
	56
	57
modelDims-methods	59

$model Response-methods \ \ldots \ \ldots$	
$momentModel \dots \dots$	
momentModel-class	
momentStrength-methods	
momentWeights-class	. 64
$momFct\text{-methods} \ \ldots \ \ldots$	
Mroz	
nonlinearModel-class	
plot-methods	. 69
print-methods	. 70
printRestrict-methods	. 71
quadra-methods	. 71
regModel-class	. 73
$residuals\text{-methods} \ . \ . \ . \ . \ . \ . \ . \ . \ . \ $	. 73
$rest Model-methods \ \dots $	. 74
rformulaModel-class	
rfunctionModel-class	. 78
rhoFct	. 79
rlinearModel-class	. 80
rmomentModel-class	
rnonlinearModel-class	. 82
rslinearModel-class	
rsnonlinearModel-class	
rsysModel-class	
setCoef-methods	. 86
sfunctionModel-class	
sgmmfit-class	
show-methods	
simData	
slinearModel-class	
snonlinearModel-class	
solveGel-methods	
solveGmm-methods	
specTest-class	
specTest-methods	
sSpec-class	
stsls-class	
summary-methods	. 101
summaryGel-class	
summaryGmm-class	
summarySysGmm-class	
sysModel-class	
sysMomentModel	
sysMomentWeights-class	
systemGmm-doc	
ThreeSLS-methods	
tsls-class	
tsls-methods	
1010 11101110100	

4 bread-methods

Index																12
	[-methods	 		•	 	•		 •		•						. 11
	vcovHAC-method															
	vcov-methods	 			 											. 11
	update-methods .	 			 											. 11

allNLModel-class

Class "allNLModel"

# **Description**

A union class for all nonlinear models. It includes "nonlinearModel", "formulaModel", and "functionModel".

# **Objects from the Class**

A virtual Class: No objects may be created from it.

#### Methods

```
solveGmm signature(object = "allNLModel", wObj = "momentWeights"): ...
```

# **Examples**

```
showClass("allNLModel")
```

bread-methods

~~ Methods for Function bread in Package sandwich ~~

# Description

It computes the bread in the sandwich representation of the covariance matrix of the GMM estimator.

# Usage

```
## S4 method for signature 'gmmfit'
bread(x, ...)
## S4 method for signature 'sgmmfit'
bread(x, ...)
## S4 method for signature 'tsls'
bread(x, ...)
```

CigarettesSW 5

# **Arguments**

x GMM fit object

... Arguments to pass to other methods

#### Methods

```
signature(x = "gmmfit")
signature(x = "sgmmfit")
signature(x = "tsls")
```

# **Examples**

```
data(simData)
theta <- c(beta0=1,beta1=2)
model1 <- momentModel(y~x1, ~z1+z2, data=simData)

res <- gmmFit(model1)
m <- meatGmm(res)
b <- bread(res)

## Sandwich vcov
b

## TSLS
model2 <- momentModel(y~x1, ~z1+z2, data=simData, vcov="iid")
res <- tsls(model2)
bread(res)</pre>
```

CigarettesSW

Cigarette Consumption Panel Data

## **Description**

Panel data on cigarette consumption for the 48 continental US States from 1985–1995.

# Usage

```
data("CigarettesSW")
```

# **Format**

A data frame containing 48 observations on 7 variables for 2 periods.

```
state Factor indicating state.
```

year Factor indicating year.

6 CigarettesSW

```
cpi Consumer price index.
population State population.
packs Number of packs per capita.
income State personal income (total, nominal).
tax Average state, federal and average local excise taxes for fiscal year.
price Average price during fiscal year, including sales tax.
```

taxs Average excise taxes for fiscal year, including sales tax.

#### Source

Online complements to Stock and Watson (2007). The dataset and this help file comes from the AER package.

#### References

Stock, J.H. and Watson, M.W. (2007). *Introduction to Econometrics*, 2nd ed. Boston: Addison Wesley.

Christian Kleiber and Achim Zeileis (2008). Applied Econometrics with R. New York: Springer-Verlag. ISBN 978-0-387-77316-2. URL https://CRAN.R-project.org/package=AER

```
## Stock and Watson (2007)
## data and transformations
data(CigarettesSW)
CigarettesSW$rprice <- with(CigarettesSW, price/cpi)</pre>
CigarettesSW$rincome <- with(CigarettesSW, income/population/cpi)</pre>
CigarettesSW$tdiff <- with(CigarettesSW, (taxs - tax)/cpi)</pre>
c1985 <- subset(CigarettesSW, year == "1985")</pre>
c1995 <- subset(CigarettesSW, year == "1995")</pre>
## Equation 12.15
model1 <- momentModel(log(packs)~log(rprice)+log(rincome),</pre>
                    ~log(rincome)+tdiff, data = c1995, vcov="MDS")
res1 <- gmmFit(model1)</pre>
## HC0 robust se (different from the textbook)
summary(res1, sandwich=TRUE)
## HC1 robust se (like in the textbook)
## A little harder to get, but is it really worth it
## in the case of GMM?
summary(res1, sandwich=TRUE, df.adj=TRUE)@coef
## Equation 12.16
model2<- momentModel(log(packs)~log(rprice)+log(rincome),</pre>
                   ~log(rincome)+tdiff+I(tax/cpi), data = c1995,
                   centeredVcov=FALSE, vcov="MDS")
```

coef-methods 7

```
res2<- tsls(model2)</pre>
summary(res2, sandwich=TRUE, df.adj=TRUE)
## Table 12.1
data <- data.frame(dQ=log(c1995$pack/c1985$pack),</pre>
                    dP=log(c1995$rprice/c1985$rprice),
                    dTs=c1995$tdiff-c1985$tdiff,
                    dT=c1995$tax/c1995$cpi-c1985$tax/c1985$cpi,
                    dInc=log(c1995$rincome/c1985$rincome))
model1 <- momentModel(dQ~dP+dInc, ~dInc+dTs, vcov="MDS", data=data)</pre>
model2 <- momentModel(dQ~dP+dInc, ~dInc+dT, vcov="MDS", data=data)</pre>
model3 <- momentModel(dQ~dP+dInc, ~dInc+dTs+dT, vcov="MDS", data=data)</pre>
res1 <- tsls(model1)</pre>
summary(res1, TRUE, TRUE)
res2 <- tsls(model2)</pre>
summary(res2, TRUE, TRUE)
res3 <- tsls(model3)</pre>
summary(res3, TRUE, TRUE)
```

coef-methods

~~ Methods for Function coef in Package stats ~~

#### **Description**

It extract the coefficient estimates of some moment-based models.

#### Methods

```
signature(object = "gemfit")
signature(object = "gelfit")
signature(object = "sgmmfit")
signature(object = "momentModel")
signature(object = "rlinearModel") It gives the unrestricted representation of a restricted model.
    See examples.
signature(object = "rslinearModel") It gives the unrestricted representation of a restricted model.
signature(object = "rsnonlinearModel") It gives the unrestricted representation of a restricted model.
signature(object = "rfunctionModel") It gives the unrestricted representation of a restricted model. See examples.
signature(object = "rformulaModel") It gives the unrestricted representation of a restricted model. See examples.
```

model. See examples.
signature(object = "rnonlinearModel") It gives the unrestricted representation of a restricted

signature(object = "rnonlinearModel") It gives the unrestricted representation of a restricted nonlinear model.

8 confint-class

#### **Examples**

```
data(simData)
model1 <- momentModel(y~x1+x2+x3+z1, ~x1+x2+z1+z2+z3+z4, data=simData)
res1 <- gmmFit(model1)
coef(res1)

### Restricted models
rmodel1 <- restModel(model1, R=c("x1=1", "x2=2*x3"))
res2 <- gmmFit(rmodel1)
res2
coef(rmodel1, coef(res2))</pre>
```

confint-class

Class "confint"

# Description

A class to store a confidence interval result.

# **Objects from the Class**

Objects can be created by calls of the form new("confint", ...). It is generated by the "confint" method (see confint-methods).

#### **Slots**

```
interval: Object of class "matrix" ~~
type: Object of class "character" ~~
level: Object of class "numeric" ~~
theta: Object of class "numeric" ~~
```

### Methods

```
print signature(x = "confint"): ...
show signature(object = "confint"): ...
```

```
showClass("confint")
```

confint-methods 9

confint-methods

~~ Methods for Function confint in Package stats ~~

#### **Description**

Method to contruct confidence intervals for objects of class "gmmfit" and "gelfit".

#### Usage

```
## S4 method for signature 'gmmfit'
confint(object, parm, level = 0.95, vcov=NULL,
                    area=FALSE, npoints=50, ...)
## S4 method for signature 'gelfit'
confint(object, parm, level = 0.95, lambda = FALSE,
                    type = c("Wald", "invLR", "invLM", "invJ"),
                    fact = 3, corr = NULL, vcov=NULL,
                    area = FALSE, npoints = 20, cores=4, ...)
## S4 method for signature 'numeric'
confint(object, parm, level = 0.95, gelType="EL",
                    type = c("Wald", "invLR", "invLM", "invJ"),
                    fact = 3, vcov="iid")
## S4 method for signature 'data.frame'
confint(object, parm, level = 0.95, gelType="EL",
                    type = c("Wald", "invLR", "invLM", "invJ"),
                    fact = 3, vcov="iid", npoints=10,
                    cores=4)
## S4 method for signature 'matrix'
confint(object, parm, level = 0.95, gelType="EL",
                    type = c("Wald", "invLR", "invLM", "invJ"),
                    fact = 3, vcov="iid", npoints=10,
                    cores=4)
## S4 method for signature 'ANY'
confint(object, parm, level = 0.95, ...)
```

# **Arguments**

object	Object of class "gmmfit", "gelfit", "numeric" or "data.frame".
parm	Vector of integers or characters for selecting the elements for which the intervals should be computed.
level	The confidence level.
lambda	Should be compute intervals for the Lagrange multipliers?

10 ConsumptionG

type	The type of confidence intervals. The default is the Wald interval, and the others are computed by inverting the LR, LM or J specification test.
fact	For the inversion of the specification tests, uniroot searches within fact standard error of the coefficient estimates
corr	Correction to apply to the specification tests
vcov	For Wald intervals, an optional covariance matrix can be provided. For "numeric" or "data.frame", it specifies the type of observations.
cores	The number of cores for mclapply. It is set to 1 for Windows OS.
gelType	Type of GEL confidence interval.
npoints	Number of equally spaced points for the confidence region
area	If TRUE, a cnnfidence region is computed. The length of "parm" must be 2 in that case.
	Other arguments to pass to gmmFit or gelFit.

#### Methods

```
signature(object = "ANY") The method from the stats in used in that case.
signature(object = "gelfit") Method for any GEL fit class.
signature(object = "gmmfit") Method for any GMM fit class.
signature(object = "numeric") It computes the GEL confidence interval for the mean.
signature(object = "data.frame") It computes the 2D GEL confidence region for the means of two variables.
signature(object = "matrix") It converts the object into a data.frame and call its method.
```

Consumption data from Greene (2012) applications.

# **Description**

 ${\tt ConsumptionG}$ 

Quarterly macroeconomic US data from 1950 to 2000.

# Usage

```
data("ConsumptionG")
```

#### **Format**

A data frame with 204 observations on the following 14 variables.

YEAR Year

QTR Quarter

REALGDP Read GDP

REALCONS Real Consumption

Consumption G 11

```
REALINVS Real Investment
REALGOVT Real public expenditure
REALDPI ector
CPI_U CPI
M1 Money stock
TBILRATE Interest rate
UNEMP Unemployment rate
POP Population
INFL Inflation
REALINT Real interest rate.
```

#### **Source**

Greene (2012) online resources: (http://pages.stern.nyu.edu/~wgreene/Text/Edition7/tablelist8new.htm)

#### References

Green, W.H.. (2012). Econometric Analysis, 7th edition, Prentice Hall.

```
data(ConsumptionG)
## Get the data ready for Table 8.2 of Greene (2012)
Y <- ConsumptionG$REALDPI
C <- ConsumptionG$REALCONS</pre>
n <- nrow(ConsumptionG)</pre>
Y1 \leftarrow Y[-c(1,n)]; Y2 \leftarrow Y[-c(n-1,n)]; Y \leftarrow Y[-c(1:2)]
C1 \leftarrow C[-c(1,n)]; C \leftarrow C[-(1:2)]
dat <- data.frame(Y=Y,Y1=Y1,Y2=Y2,C=C,C1=C1)</pre>
## Starting at the NLS estimates (from the table)
theta0=c(alpha=468, beta=0.0971, gamma=1.24)
## Greene (2012) seems to assume iid errors (probably wrong assumption here)
model <- momentModel(C~alpha+beta*Y^gamma, ~C1+Y1+Y2, data=dat, theta0=theta0, vcov="iid")</pre>
### Scaling the parameters increase the speed of convergence
res <- gmmFit(model, control=list(parscale=c(1000,.1,1)))</pre>
### It also seems that there is a degree of freedom adjustment for the
### estimate of the variance of the error term.
summary(res, df.adj=TRUE)@coef
```

12 DWH-methods

Dresiduals-methods

~~ Methods for Function Dresiduals in Package Gmm ~~

# Description

It returns the matrix of derivatives of the residuals with respect to the coefficients.

#### Methods

```
signature(object = "linearModel")
signature(object = "nonlinearModel")
signature(object = "rsnonlinearModel")
signature(object = "sysMomentModel")
```

# **Examples**

```
data(simData)
theta <- c(beta0=1,beta1=2)
model1 <- momentModel(y~x1, ~z1+z2, data=simData)
Dresiduals(model1, theta)[1:3,]</pre>
```

DWH-methods

~~ Methods for Function DWH in Package momentfit ~~

# Description

It performs the Durbin-Wu-Hausman test on GMM fit models.

# Usage

```
## S4 method for signature 'gmmfit,missing'
DWH(object1, object2)

## S4 method for signature 'gmmfit,lm'
DWH(object1, object2,
tol=sqrt(.Machine$double.eps), v1=NULL, v2=NULL, ...)

## S4 method for signature 'gmmfit,gmmfit'
DWH(object1, object2,
tol=sqrt(.Machine$double.eps), v1=NULL, v2=NULL, ...)
```

DWH-methods 13

## **Arguments**

object1 object2	Object of class "gmmfit".  Object of class "gmmfit" or "lm". If missing, the DWH test is a two step test in which the fitted endogenous variables from the first step are added to the
	regression. In that case, the test a a test of significance of the coefficients of the fitted endogenous variables.
v1	Alternatively, we can provide a different covariance matrix for object1
v2	Alternatively, we can provide a different covariance matrix for object2
tol	Tolerance for the Moore-Penrose generalized inverse
	Argument to pass to vcov

#### Methods

```
signature(object1 = "gmmfit", object2 = "lm")
signature(object1 = "gmmfit", object2 = "gmmfit")
signature(object1 = "gmmfit", object2 = "missing")
```

#### References

Green, W.H.. (2012). Econometric Analysis, 7th edition, Prentice Hall.

```
### Exampe 8.7 of Greene (2012)
data(ConsumptionG)
Y <- ConsumptionG$REALDPI
C <- ConsumptionG$REALCONS</pre>
n <- nrow(ConsumptionG)</pre>
Y1 \leftarrow Y[-n]; Y \leftarrow Y[-1]
C1 \leftarrow C[-n]; C \leftarrow C[-1]
dat <- data.frame(Y=Y,Y1=Y1,C=C,C1=C1)</pre>
model1 <- momentModel(C~Y, ~Y, data=dat, vcov="iid")</pre>
model2 <- momentModel(C~Y, ~Y1+C1, data=dat, vcov="iid")</pre>
res1 <- tsls(model1)</pre>
res2 <- tsls(model2)</pre>
res <- lm(C^{Y})
## Exampke 8.7-2. The difference is explained by the rounding
## error in Greene. Only the first the 3 digits of the t-test are used.
DWH(res2)
## Example 8.7-1. Not quite the same.
DWH(res2, res1)
## using lm object to compare OLS and 2SLS:
```

14 evalDMoment-methods

```
## The same adjustment on the vcov must be done (it is by default in lm)
## otherwise the different in the covariance matrices is mostly caused by the
## different ways to compute them.
DWH(res2, res, df.adj=TRUE)

## To reproduce the same results as Exampke 8.7-1,
## we need to specify the variance.
## But it is not necessary as the above way is
## asymptotically equivalent
X <- model.matrix(model1)
Xhat <- qr.fitted(res2@wObj@w, X)
s2 <- sum(residuals(res)^2)/(res$df.residual)
v1 <- solve(crossprod(Xhat))*s2
v2 <- solve(crossprod(X))*s2
DWH(res2, res, v1=v1, v2=v2)</pre>
```

estfun-methods

~~ Methods for Function estfun in Package sandwich ~~

## **Description**

Estimating equations for moment models.

#### Methods

```
signature(x = "momentModel")
```

evalDMoment-methods

~~ Methods for Function evalDMoment in Package momentfit ~~

## Description

It computes the matrix of derivatives of the sample moments with respect to the coefficients.

## Usage

```
## S4 method for signature 'functionModel'
evalDMoment(object, theta, impProb=NULL,
lambda=NULL)

## S4 method for signature 'rfunctionModel'
evalDMoment(object, theta, impProb=NULL,
lambda=NULL)

## S4 method for signature 'rnonlinearModel'
```

evalDMoment-methods 15

```
evalDMoment(object, theta, impProb=NULL,
lambda=NULL)
## S4 method for signature 'formulaModel'
evalDMoment(object, theta, impProb=NULL,
lambda=NULL)
## S4 method for signature 'rformulaModel'
evalDMoment(object, theta, impProb=NULL,
lambda=NULL)
## S4 method for signature 'regModel'
evalDMoment(object, theta, impProb=NULL,
lambda=NULL)
## S4 method for signature 'sysModel'
evalDMoment(object, theta)
## S4 method for signature 'rslinearModel'
evalDMoment(object, theta)
## S4 method for signature 'rsnonlinearModel'
evalDMoment(object, theta, impProb=NULL)
```

#### **Arguments**

object An model object

theta A numerical vector of coefficients

impProb If a vector of implied probabilities is provided, the sample means are computed

using them. If not provided, the means are computed using the uniform weight

lambda A vector of Lagrange multipliers associated with the moment conditions. Its

length must therefore match the number of conditions. See details below.

#### **Details**

Without the argument lambda, the method returns a  $q \times k$  matrix, where k is the number of coefficients, and q is the number of moment conditions. That matrix is the derivative of the sample mean of the moments with respect to the coefficient.

If lambda is provided, the method returns an  $n \times k$  matrix, where n is the sample size. The ith row is  $G_i'\lambda$ , where  $G_i'$  is the derivative of the moment function evaluated at the ith observation. For now, this option is used to compute robust-to-misspecified standard errors of GEL estimators.

#### Methods

```
signature(object = "functionModel")
```

signature(object = "rfunctionModel") The theta vector must match the number of coefficients in the restricted model.

16 evalGel-methods

```
signature(object = "formulaModel")
signature(object = "rformulaModel") The theta vector must match the number of coefficients
    in the restricted model.
signature(object = "regModel")
signature(object = "sysModel")
signature(object = "rslinearModel")
```

## **Examples**

```
data(simData)
theta <- c(1,1)
model1 <- momentModel(y~x1, ~z1+z2, data=simData)</pre>
G <- evalDMoment(model1, theta)</pre>
## A nonlinearModel
g <- y~beta0+x1^beta1
h <- ~z1+z2
model2 <- momentModel(g, h, c(beta0=1, beta1=2), data=simData)</pre>
G <- evalDMoment(model2, c(beta0=1, beta1=2))</pre>
## A functionModel
fct <- function(tet, x)</pre>
    {
        m1 <- (tet[1] - x)
        m2 \leftarrow (tet[2]^2 - (x - tet[1])^2)
        m3 <- x^3 - tet[1]*(tet[1]^2 + 3*tet[2]^2)
        f <- cbind(m1, m2, m3)
        return(f)
dfct <- function(tet, x)</pre>
        jacobian <- matrix(c( 1, 2*(-tet[1]+mean(x)), -3*tet[1]^2-3*tet[2]^2,0, 2*tet[2],</pre>
   -6*tet[1]*tet[2]), nrow=3,ncol=2)
        return(jacobian)
         }
X \leftarrow rnorm(200)
model3 <- momentModel(fct, X, theta0=c(beta0=1, beta1=2), grad=dfct)</pre>
G <- evalDMoment(model3, c(beta0=1, beta1=2))</pre>
```

evalGel-methods

~~ Methods for Function evalGel in Package modelfit ~~

# Description

Method to simply evaluate a GEL model at a fixed coefficient vector. It creates a "gelfit" object using that fixed vector.

evalGel-methods 17

# Usage

# **Arguments**

model	An object of class "momentModel".
theta	A vector of coefficients at which the model is estimated
lambda	The Lagrange multiplier vector. If not provided, the optimal vector is obtained for the given theta
gelType	The type of GEL. It is either "EL", "ET", "EEL", "HD", "ETEL" or "ETHD".
rhoFct	An alternative objective function for GEL. This argument is only used if we want to fit the model with a different GEL method. see <code>rhoFct</code> .
lamSlv	An alternative solver for the Lagrange multiplier. By default, either Wu_lam, EEL_lam, REEL_lam or getLambda is used.
lControl	A list of controls for the Lagrange multiplier algorithm.
	Other arguments to pass. Not used for the moment.

# Methods

```
signature(model = "momentModel")
```

```
data(simData)
theta <- c(beta0=1,beta1=2)

## A linear model with optimal lambda
model1 <- momentModel(y~x1, ~z1+z2, data=simData)
evalGel(model1, c(1,1))

## A nonlinear model with fixed lambda
g <- y~beta0+x1^beta1
h <- ~z1+z2
model2 <- momentModel(g, h, c(beta0=1, beta1=2), data=simData)
evalGel(model2, theta=c(beta1=2, beta0=0.5), lambda=c(.1,.2,.3), gelType="ET")</pre>
```

18 evalGelObj-methods

 ${\tt evalGelObj-methods}$ 

~~ Methods for Function evalGelObj in Package Gmm ~~

# **Description**

~~ Methods to compute the GEL objective function. ~~

# Usage

# **Arguments**

object	An object of class "momentModel"
theta	The vector for coefficients.
lambda	Vector of Lagrange multiplier.
gelType	The type of GEL. It is either "EL", "ET", "EEL", "HD", "ETEL" or "ETHD".
rhoFct	An alternative objective function for GEL. This argument is only used if we want to fit the model with a different GEL method. see rhoFct.
	Arguments to pass to other methods

### Methods

```
signature(object = "momentModel", theta = "numeric", lambda = "numeric")
```

```
data(simData)
theta <- c(beta0=1,beta1=2)
model1 <- momentModel(y~x1, ~z1+z2, data=simData)
evalGelObj(model1, theta, c(.2,.3,.4), gelType="EL")</pre>
```

evalGmm-methods 19

evalGmm-methods

~~ Methods for Function evalGmm in Package modelfit ~~

#### **Description**

Method to simply evaluate a GMM model at a fixed coefficient vector. It creates a "gmmfit" object using that fixed vector.

#### Usage

```
## S4 method for signature 'momentModel'
evalGmm(model, theta, wObj=NULL, ...)
## S4 method for signature 'sysModel'
evalGmm(model, theta, wObj=NULL, ...)
```

# Arguments

model An object of class "momentModel".

theta A vector of coefficients at which the model is estimated

wObj An object of class "momentWeights". If not provided, the optimal weights based

on the specification of the model evaluated at theta will be computed.

... Other arguments to pass. Not used for the moment.

#### Methods

```
signature(model = "momentModel")
signature(model = "sysModel")
```

```
m3 <- x^3 - tet[1]*(tet[1]^2 + 3*tet[2]^2)
    f <- cbind(m1, m2, m3)
    return(f)
}
dfct <- function(tet, x)
    {
        jacobian <- matrix(c( 1, 2*(-tet[1]+mean(x)), -3*tet[1]^2-3*tet[2]^2,0, 2*tet[2],
        -6*tet[1]*tet[2]), nrow=3,ncol=2)
        return(jacobian)
    }
model3 <- momentModel(fct, simData$x3, theta0=c(beta0=1, beta1=2), grad=dfct)
evalGmm(model3, theta=c(beta1=.1, beta0=0.3))</pre>
```

evalGmmObj-methods

~~ Methods for Function evalGmmObj in Package momentfit ~~

# Description

~~ Methods to compute the GMM objective function. ~~

#### Usage

```
## S4 method for signature 'momentModel,numeric,momentWeights'
evalGmmObj(object, theta,
wObj, ...)
## S4 method for signature 'sysModel,list,sysMomentWeights'
evalGmmObj(object, theta,
wObj, ...)
```

## **Arguments**

object An object of class "momentModel", or "sysMomentModels".

theta The vector for coefficients for single equation, or a list of vector for system of equations.

wObj An object of class "momentWeights" or "sysMomentWeights".

... Arguments to pass to other methods

#### Methods

```
signature(object = "momentModel", theta = "numeric", wObj = "momentWeights")
signature(object = "sysModel", theta = "list", wObj = "sysMomentWeights")
```

evalMoment-methods 21

#### **Examples**

```
data(simData)
theta <- c(beta0=1,beta1=2)
model1 <- momentModel(y~x1, ~z1+z2, data=simData)
w <- evalWeights(model1, theta)
evalGmmObj(model1, theta, w)</pre>
```

evalMoment-methods

~~ Methods for Function evalMoment in Package momentfit ~~

# **Description**

Method to evaluate the moment matrix at a given coefficient vector.

#### Methods

```
signature(object = "functionModel")
signature(object = "formulaModel")
signature(object = "regModel")
signature(object = "sysModel")
signature(object = "rsysModel")
```

```
data(simData)
theta <- c(1,1)
model1 <- momentModel(y~x1, ~z1+z2, data=simData)</pre>
gt <- evalMoment(model1, theta)</pre>
## A nonlinearGmm
g <- y~beta0+x1^beta1
h <- ~z1+z2
model2 <- momentModel(g, h, c(beta0=1, beta1=2), data=simData)</pre>
gt <- evalMoment(model2, c(beta0=1, beta1=2))</pre>
## A functionGmm
fct <- function(tet, x)</pre>
    {
        m1 <- (tet[1] - x)
        m2 \leftarrow (tet[2]^2 - (x - tet[1])^2)
        m3 <- x^3 - tet[1]*(tet[1]^2 + 3*tet[2]^2)
        f <- cbind(m1, m2, m3)
        return(f)
dfct <- function(tet, x)</pre>
        {
```

22 evalWeights-methods

```
jacobian <- matrix(c( 1, 2*(-tet[1]+mean(x)), -3*tet[1]^2-3*tet[2]^2,0, 2*tet[2],
    -6*tet[1]*tet[2]), nrow=3,ncol=2)
        return(jacobian)
      }
X <- rnorm(200)
model3 <- momentModel(fct, X, theta0=c(beta0=1, beta1=2), grad=dfct)
gt <- evalMoment(model3, c(beta0=1, beta1=2))</pre>
```

evalWeights-methods

Methods for Function evalWeights in Package Gmm

# Description

This is a constructor for objects of class momentWeights

#### Usage

```
## S4 method for signature 'momentModel'
evalWeights(object, theta=NULL, w="optimal",
...)

## S4 method for signature 'sysModel'
evalWeights(object, theta = NULL, w="optimal",
wObj=NULL)

## S4 method for signature 'rslinearModel'
evalWeights(object, theta = NULL, w="optimal",
wObj=NULL)
```

#### **Arguments**

object	Object of class momentModel
theta	The vector of coefficients to compute the optimal weights. If NULL, theta0 for the object is used.
W	A matrix for fixed weights, one of "optimal" or "ident"
wObj	An object of class "sysMomentWeights". Providing it avoid having to recompute Z'Z.
	Arguments to pass to other methods

#### Methods

```
signature(object = "momentModel")
signature(object = "sysModel")
signature(object = "rslinearModel") System of equations with restrictions on the coefficients.
   It only affects the computation of the weights when there are cross-equation restrictions.
```

formulaModel-class 23

#### **Examples**

```
data(simData)
theta <- c(beta0=1,beta1=2)
model1 <- momentModel(y~x1, ~z1+z2, data=simData)

## Identity weights object
w0bj1 <- evalWeights(model1, w="ident")

## Identity weights object (an alternative way less efficient)
w0bj1 <- evalWeights(model1, w=diag(3))

## Optimal weights
w0bj1 <- evalWeights(model1, theta, w="optimal")</pre>
```

formulaModel-class

Class "formulaModel"

## **Description**

Class for moment-based models for which moments are expressed using formulas.

# **Objects from the Class**

Objects can be created by calls of the form new("formulaModel", ...). It is generated my momentModel.

#### **Slots**

```
modelF: Object of class "data.frame" ~~
vcov: Object of class "character" ~~
theta0: Object of class "numeric" ~~
n: Object of class "integer" ~~
q: Object of class "integer" ~~
k: Object of class "integer" ~~
parNames: Object of class "character" ~~
momNames: Object of class "character" ~~
fRHS: Object of class "list" ~~
theta0: Object of class "list" ~~
vcovOptions: Object of class "list" ~~
varNames: Object of class "logical" ~~
isEndo: Object of class "logical" ~~
```

24 functionModel-class

```
isMDE: Object of class "logical" ~~
omit: Object of class "integer" ~~
survOptions: Object of class "list" ~~
sSpec: Object of class "sSpec" ~~
smooth: Object of class "logical" ~~
```

#### **Extends**

```
Class "allNLModel", directly. Class "momentModel", directly.
```

#### Methods

```
[ signature(x = "formulaModel", i = "numeric", j = "missing"): ...
evalDMoment signature(object = "formulaModel"): ...
evalMoment signature(object = "formulaModel"): ...
gmmFit signature(model = "formulaModel"): ...
modelDims signature(object = "formulaModel"): ...
momentStrength signature(object = "formulaModel"): ...
restModel signature(object = "formulaModel"): ...
subset signature(x = "formulaModel"): ...
```

# **Examples**

```
showClass("formulaModel")
```

```
functionModel-class Class "functionModel"
```

# **Description**

Class for moment-based models for which moment conditions are defined using a function.

#### **Objects from the Class**

Objects can be created by calls of the form new("functionModel", ...). It is generated my momentModel.

functionModel-class 25

#### **Slots**

```
X: Object of class "ANY" ~~
fct: Object of class "function" ~~
dfct: Object of class "functionORNULL" ~~
vcov: Object of class "character" ~~
theta0: Object of class "numeric" ~~
n: Object of class "integer" ~~
q: Object of class "integer" ~~
k: Object of class "integer" ~~
parNames: Object of class "character" ~~
momNames: Object of class "character" ~~
vcov0ptions: Object of class "list" ~~
centeredVcov: Object of class "logical" ~~
varNames: Object of class "character" ~~
isEndo: Object of class "logical" ~~
omit: Object of class "integer" ~~
survOptions: Object of class "list" ~~
sSpec: Object of class "sSpec" ~~
smooth: Object of class "logical" ~~
```

## **Extends**

```
Class "allNLModel", directly. Class "momentModel", directly.
```

#### Methods

```
[ signature(x = "functionModel", i = "numeric", j = "missing"): ...
evalDMoment signature(object = "functionModel"): ...
evalMoment signature(object = "functionModel"): ...
modelDims signature(object = "functionModel"): ...
momentStrength signature(object = "functionModel"): ...
restModel signature(object = "functionModel"): ...
subset signature(x = "functionModel"): ...
```

```
showClass("functionModel")
```

26 gel4

gel4	GEL estimation	

# **Description**

The main functions and methods to fit any model with GEL. As opposed to gelFit, models don't need to be created. It is all done by the functions. It is meant to be more user friendly.

# Usage

```
gel4(g, x=NULL, theta0=NULL, lambda0=NULL, getVcov=FALSE,
    gelType = c("EL","ET","EEL","HD", "REEL","ETEL","ETHD"),
    vcov = c("MDS","iid","HAC"), grad=NULL,
    vcovOptions=list(), centeredVcov = TRUE,
    cstLHS=NULL, cstRHS=NULL, lamSlv=NULL,
    rhoFct=NULL, initTheta=c("gmm", "theta0"),
    data = parent.frame(),
    coefSlv=c("optim","nlminb","constrOptim"),
    smooth=FALSE,
    lControl=list(), tControl=list())
```

#### **Arguments**

g	A function of the form $g(\theta,x)$ and which returns a $n\times q$ matrix with typical element $g_i(\theta,x_t)$ for $i=1,,q$ and $t=1,,n$ . This matrix is then used to build the q sample moment conditions. It can also be a formula if the model is linear (see details below).
Х	The matrix or vector of data from which the function $g(\theta,x)$ is computed. If "g" is a formula, it is an $n \times Nh$ matrix of instruments or a formula (see details below).
theta0	A $k \times 1$ vector of starting values. It is required only when "g" is a function, a formula or a list of formulas. For these cases, they are needed to create the "momentModel" object.
lambda0	The $q \times 1$ vector of starting values for the Lagrange multipliers. By default a zero vector is used.
getVcov	Should the method computes the covariance matrices of the coefficients and Lagrange multipliers.
gelType	A character string specifying the type of GEL.
vcov	Assumption on the properties of the moment conditions.
grad	A function of the form $G(\theta,x)$ which returns a $q\times k$ matrix of derivatives of $\bar{g}(\theta)$ with respect to $\theta$ .
vcovOptions	A list of options for the covariance matrix of the moment conditions. See vcovHAC for the default values.

gel4 27

centeredVcov	Should the moment function be centered when computing its covariance matrix. Doing so may improve inference.
cstLHS	The left hand side of the constraints to impose on the coefficients. See restModel for more details.
cstRHS	The right hand side of the constraints to impose on the coefficients. See restModel for more details.
lamSlv	An alternative solver for the Lagrange multiplier. By default, either Wu_lam, EEL_lam, REEL_lam or getLambda is used. See the vignette for the required format.
rhoFct	An optional function that return $\rho(v)$ . This is for users who want a GEL model that is not built in the package. The four arguments of the function must be "gmat", the matrix of moments, "lambda", the vector of Lagrange multipliers, "derive", which specify the order of derivative to return, and k a numeric scale factor required for time series and kernel smoothed moments.
initTheta	Method to obtain the starting values for the coefficient vector. By default the GMM estimate with identity matrix is used. The second argument means that "theta0" is used instead.
data	A required data.frame, in which all variables in g and x can be found.
smooth	If TRUE, "vcov" is set to "MDS" and the moment conditions are smoothed using a kernel. See the vignette for more details.
coefSlv	Minimization solver for the coefficient vector.
lControl	A list of controls for the Lagrange multiplier algorithm.
tControl	A list of controls for the coefficient algorithm.

# Value

It returns an object of class "gelfit"

#### References

Anatolyev, S. (2005), GMM, GEL, Serial Correlation, and Asymptotic Bias. *Econometrica*, **73**, 983-1002.

Andrews DWK (1991), Heteroskedasticity and Autocorrelation Consistent Covariance Matrix Estimation. *Econometrica*, **59**, 817–858.

Kitamura, Yuichi (1997), Empirical Likelihood Methods With Weakly Dependent Processes. *The Annals of Statistics*, **25**, 2084-2102.

Kitamura, Y. and Otsu, T. and Evdokimov, K. (2013), Robustness, Infinitesimal Neighborhoods and Moment Restrictions. *Econometrica*, **81**, 1185-1201.

Newey, W.K. and Smith, R.J. (2004), Higher Order Properties of GMM and Generalized Empirical Likelihood Estimators. *Econometrica*, **72**, 219-255.

Smith, R.J. (2004), GEL Criteria for Moment Condition Models. Working paper, CEMMAP.

# See Also

gelFit, momentModel

28 gelfit-class

## **Examples**

# **Description**

A class to store fitted models obtained using a GEL method.

# **Objects from the Class**

Objects can be created by calls of the form new("gelfit", ...). It is created by gelFit.

#### **Slots**

```
theta: Object of class "numeric" ~~
convergence: Object of class "numeric" ~~
lambda: Object of class "numeric" ~~
lconvergence: Object of class "numeric" ~~
call: Object of class "callORNULL" ~~
gelType: Object of class "list" ~~
vcov: Object of class "list" ~~
model: Object of class "momentModel" ~~
restrictedLam: Object of class "integer" ~~
```

#### Methods

```
coef signature(object = "gelfit"): ...
confint signature(object = "gelfit"): ...
getImpProb signature(object = "gelfit"): ...
momFct signature(eta = "numeric", object = "gelfit"): ...
print signature(x = "gelfit"): ...
residuals signature(object = "gelfit"): ...
show signature(object = "gelfit"): ...
specTest signature(object = "gelfit", which = "missing"): ...
summary signature(object = "gelfit"): ...
update signature(object = "gelfit"): ...
vcov signature(object = "gelfit"): ...
```

```
showClass("gelfit")
```

gelFit-methods 29

gelFit-methods	~~ Methods for Function gelFit in Package momentfit ~~
----------------	--

# **Description**

Method to fit a model using GEL, from an object of class "momentModel" or its restricted counterpart.

## Usage

# **Arguments**

model	A model class object
gelType	The type of GEL. It is either "EL", "ET", "EEL", "HD", "ETEL" or "ETHD".
rhoFct	An alternative objective function for GEL. This argument is only used if we want to fit the model with a different GEL method. see ${\tt rhoFct}$ .
initTheta	Method to obtain the starting values for the coefficient vector. By default the GMM estimate with identity matrix is used. The second argument means that the theta0 of the object, if any, should be used.
theta0	An optional initial vector for $\mbox{optim}$ when the model is nonlinear. If provided, the argument "initTheta" is ignored.
lambda0	Manual starting values for the Lagrange multiplier. By default, it is a vector of zeros.
vcov	Should the method computes the covariance matrices of the coefficients and Lagrange multipliers.
	Arguments to pass to other methods (mostly the optimization algorithm)

# Methods

```
signature(model = "momentModel") The main method for all moment-based models.
signature(model = "rmomentModel") The main method for all restricted moment-based models.
```

30 getRestrict-methods

#### **Examples**

```
data(simData)

theta <- c(beta0=1,beta1=2)
model1 <- momentModel(y~x1, ~z1+z2, data=simData)

## EL estimate
res1 <- gelFit(model1)
res1

## ET estimate
res2 <- gelFit(model1, gelType="ET")
res2

## Restricted models by EL
## using the Brent method
R <- matrix(c(0,1), ncol=2)
q <- 2
rmodel1 <- restModel(model1, R, q)
gelFit(rmodel1, tControl=list(method="Brent", lower=-10, upper=10))</pre>
```

getImpProb-methods

~~ Methods for Function getImpProb in Package momenfit ~~

# **Description**

Method to evaluate the implied probabilities of GEL.

#### Methods

```
signature(object = "gelfit")
```

getRestrict-methods

~~ Methods for Function getRestrict in Package momentfit ~~

# **Description**

It computes the matrices related to linear and nonlinear contraints. Those matrices are used to perform hypothesis tests.

getRestrict-methods 31

#### **Usage**

```
## S4 method for signature 'rlinearModel'
getRestrict(object, theta)
## S4 method for signature 'rslinearModel'
getRestrict(object, theta)
## S4 method for signature 'rsnonlinearModel'
getRestrict(object, theta)
## S4 method for signature 'rnonlinearModel'
getRestrict(object, theta)
## S4 method for signature 'rformulaModel'
getRestrict(object, theta)
## S4 method for signature 'momentModel'
getRestrict(object, theta, R, rhs=NULL)
## S4 method for signature 'sysModel'
getRestrict(object, theta, R, rhs=NULL)
## S4 method for signature 'rfunctionModel'
getRestrict(object, theta)
```

# Arguments

object	Object of class included in momentModel, rmomentModel, and rsysModel.
theta	A vector of coefficients for the unrestricted model (see examples).
R	A matrix, character or list of formulas that specifies the contraints to impose on the coefficients. See restModel for more details.
rhs	The right hand side for the restriction on the coefficients. See restModel for more details. It is ignored for objects of class "nonlinearModel".

# Methods

- signature(object = "momentModel") A restricted model is created from the constraints, and the restriction matrices are returned. The methods is applied to linear and nonlinear models in a regression form.
- signature(object = "sysModel") A restricted model is created from the constraints, and the restriction matrices are returned. The methods is applied to systems of linear and nonlinear models.
- signature(object = "rlinearModel") The restriction matrices are evaluated at the coefficient vector theta of the unrestricted representation.
- signature(object = "rslinearModel") The restriction matrices are evaluated at the coefficient vector theta of the unrestricted representation.

32 gmm4

signature(object = "rsnonlinearModel") The restriction matrices are evaluated at the coefficient vector theta of the unrestricted representation.

signature(object = "rnonlinearModel") The restriction matrices are evaluated at the coefficient vector theta of the unrestricted representation.

signature(object = "rfunctionModel") The restriction matrices are evaluated at the coefficient vector theta of the unrestricted representation.

#### **Examples**

```
data(simData)
theta <- c(beta0=1,beta1=2)
## Unrestricted model
model1 \leftarrow momentModel(y\sim x1+x2+x3+z1, \sim x1+x2+z1+z2+z3+z4, data=simData)
## The restricted model
R1 <- c("x1", "2*x2+z1=2", "4+x3*5=3")
res <- gmmFit(model1)</pre>
rest <- getRestrict(model1, coef(res), R1)</pre>
## it allows to test the restriction
g <- rest$R-rest$q
v <- rest$dR%*%vcov(res)%*%t(rest$dR)</pre>
(test <- crossprod(g, solve(v, g)))</pre>
(pv <- 1-pchisq(test, length(rest$R)))</pre>
## Delta Method:
## To impose nonlinear restrictions, we need to convert
## the linear model into a nonlinear one
NLmodel <- as(model1, "nonlinearModel")</pre>
R1 <- c("theta2=2", "theta3=theta4^2")
res <- gmmFit(NLmodel)</pre>
rest <- getRestrict(NLmodel, coef(res), R1)</pre>
g <- rest$R-rest$q
v <- rest$dR%*%vcov(res)%*%t(rest$dR)</pre>
(test <- crossprod(g, solve(v, g)))</pre>
(pv <- 1-pchisq(test, length(rest$R)))</pre>
## See hypothesisTest method for an easier approach.
```

gmm4

**GMM** estimation

#### **Description**

The main functions and methods to fit any model with GMM. As opposed to gmmFit, models don't need to be created. It is all done by the functions. It is meant to be more user friendly. This document needs to changed. It is just a copy and paste from the gmm package

gmm4 33

#### Usage

```
gmm4(g, x, theta0 = NULL, grad = NULL,
     type = c("twostep", "iter", "cue", "onestep"),
     vcov = c("iid", "HAC", "MDS", "TrueFixed", "CL"),
     initW = c("ident", "tsls", "EbyE"), weights = "optimal",
     itermaxit = 50, cstLHS=NULL, cstRHS=NULL,
     vcovOptions=list(), survOptions=list(),
     itertol = 1e-07, centeredVcov = TRUE,
     data = parent.frame(), ...)
## S4 method for signature 'formula'
tsls(model, x, vcov = c("iid", "HAC", "MDS", "CL"),
         vcovOptions=list(), survOptions=list(), centeredVcov = TRUE,
         data = parent.frame())
## S4 method for signature 'list'
tsls(model, x=NULL, vcov = c("iid", "HAC", "MDS",
          "CL"), vcovOptions=list(), survOptions=list(),
          centeredVcov = TRUE, data = parent.frame())
## S4 method for signature 'list'
ThreeSLS(model, x=NULL, vcov = c("iid", "HAC", "MDS",
          "CL"), vcovOptions=list(), survOptions=list(),
          centeredVcov = TRUE, data = parent.frame())
```

# **Arguments**

model A formula or a list of formulas.

A function of the form  $g(\theta, x)$  and which returns a  $n \times q$  matrix with typical element  $g_i(\theta, x_t)$  for i = 1, ..., q and t = 1, ..., n. This matrix is then used to build the q sample moment conditions. It can also be a formula if the model is linear or nonlinear, or a list of formulas for systems of equations.

The matrix or vector of data from which the function  $g(\theta, x)$  is computed. If "g" is a formula, it is an  $n \times Nh$  matrix of instruments or a formula (see details below).

A  $k \times 1$  vector of starting values. It is required only when "g" is a function or a nonlinear equation defined by a formula, in which case, it must be a named vector

A function of the form  $G(\theta,x)$  which returns a  $q \times k$  matrix of derivatives of  $\bar{g}(\theta)$  with respect to  $\theta$ . By default, the numerical algorithm numericDeriv is used. It is of course strongly suggested to provide this function when it is possible. This gradient is used to compute the asymptotic covariance matrix of  $\hat{\theta}$  and to obtain the analytical gradient of the objective function if the method is set to "CG" or "BFGS" in optim and if "type" is not set to "cue". If "g" is a formula, the gradiant is not required (see the details below).

What GMM methods should we use? for type=="onestep", if "weights" is not a matrix, the model will be estimated with the weights equals to the identity

8...

Χ

theta0

grad

type

34 gmm4

	matrix
vcov	Assumption on the properties of the random vector x. By default, x is a weakly dependant process. The "iid" option will avoid using the HAC matrix which will accelerate the estimation if one is ready to make that assumption. The option "TrueFixed" is used only when the matrix of weights is provided and it is the optimal one. For type CL, clustered covariance matrix is computed. The options are then included in vcovOptions (see meatCL).
initW	How should be compute the initial coefficient vector in the first. It only makes a difference for linear models for which the choice is GMM with identity matrix or two-stage least quares.
weights	What weighting matrix to use? The choices are "optimal", in which case it is the inverse of the moment vovariance matrix, "ident" for the identity matrix, or a fixed matrix.
itermaxit	Maximum iterations for iterative GMM
itertol	Tolance for the stopping rule in iterative GMM
centeredVcov	Should the moment function be centered when computing its covariance matrix. Doing so may improve inference.
data	A data.frame or a matrix with column names (Optional).
cstLHS	The left hand side of the constraints to impose on the coefficients. See restModel for more details.
cstRHS	The right hand side of the constraints to impose on the coefficients. See restModel for more details.
vcovOptions	A list of options for the covariance matrix of the moment conditions. See vcovHAC for the default values.
survOptions	If needed, a list with the type of survey weights and the weights as a numeric vector, data.frame or formula. The type is either "sampling" or "fequency".
	Arguments to pass to optim when the model is nonlinear.

#### Value

It returns an object of class "gmmfit"

#### References

Zeileis A (2006), Object-oriented Computation of Sandwich Estimators. *Journal of Statistical Software*, **16**(9), 1–16. URL doi:10.18637/jss.v016.i09.

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Newey WK & West KD (1994), Automatic Lag Selection in Covariance Matrix Estimation. *Review of Economic Studies*, **61**, 631-653.

Hansen, L.P. (1982), Large Sample Properties of Generalized Method of Moments Estimators. *Econometrica*, **50**, 1029-1054,

Hansen, L.P. and Heaton, J. and Yaron, A.(1996), Finite-Sample Properties of Some Alternative GMM Estimators. *Journal of Business and Economic Statistics*, **14** 262-280.

gmmfit-class 35

#### See Also

```
gmmFit, momentModel
```

# **Examples**

```
data(simData)  res <- gmm4(y\sim x1, \sim z1+z2, \ vcov="MDS", \ type="iter", \ data=simData) \\ res
```

gmmfit-class

Class "gmmfit"

# **Description**

A class to store a fitted model obtained using GMM.

# **Objects from the Class**

Objects can be created by calls of the form new("gmmfit", ...). Generated by gmmFit.

#### **Slots**

```
theta: Object of class "numeric" ~~
convergence: Object of class "numericORNULL" ~~
convIter: Object of class "numericORNULL" ~~
call: Object of class "callORNULL" ~~
type: Object of class "character" ~~
wObj: Object of class "momentWeights" ~~
niter: Object of class "integer" ~~
efficientGmm: Object of class "logical" ~~
model: Object of class "momentModel" ~~
```

#### Methods

```
bread signature(x = "gmmfit"): ...
coef signature(object = "gmmfit"): ...

confint signature(object = "gmmfit"): ...

DWH signature(object1 = "gmmfit", object2 = "gmmfit"): ...

DWH signature(object1 = "gmmfit", object2 = "lm"): ...

DWH signature(object1 = "gmmfit", object2 = "missing"): ...

hypothesisTest signature(object.u = "gmmfit", object.r = "gmmfit"): ...

hypothesisTest signature(object.u = "gmmfit", object.r = "missing"): ...
```

36 gmmFit-methods

```
hypothesisTest signature(object.u = "missing", object.r = "gmmfit"): ...
meatGmm signature(object = "gmmfit"): ...
print signature(x = "gmmfit"): ...
residuals signature(object = "gmmfit"): ...
show signature(object = "gmmfit"): ...
specTest signature(object = "gmmfit", which = "missing"): ...
specTest signature(object = "gmmfit", which = "numeric"): ...
summary signature(object = "gmmfit"): ...
update signature(object = "gmmfit"): ...
vcov signature(object = "gmmfit"): ...
```

#### **Examples**

```
showClass("gmmfit")
```

gmmFit-methods

~~ *Methods for Function* gmmFit *in Package* **momentfit** ~~

#### **Description**

Method to fit a model using GMM, from an object of class "momentModel" or "sysModel".

#### Usage

```
## S4 method for signature 'momentModel'
gmmFit(model, type=c("twostep", "iter","cue",
              "onestep"), itertol=1e-7, initW=c("ident", "tsls"),
              weights="optimal", itermaxit=100,
              efficientWeights=FALSE, theta0=NULL, ...)
## S4 method for signature 'formulaModel'
gmmFit(model, type=c("twostep", "iter","cue",
              "onestep"), itertol=1e-7, initW=c("ident", "tsls"),
              weights="optimal", itermaxit=100,
              efficientWeights=FALSE, theta0=NULL, ...)
## S4 method for signature 'sysModel'
gmmFit(model, type=c("twostep", "iter","cue",
              "onestep"), itertol=1e-7, initW=c("ident", "tsls", "EbyE"),
              weights="optimal", itermaxit=100,
              efficientWeights=FALSE, theta0=NULL, EbyE=FALSE, ...)
## S4 method for signature 'rnonlinearModel'
gmmFit(model, type=c("twostep", "iter", "cue",
```

gmmFit-methods 37

```
"onestep"), itertol=1e-7, initW=c("ident", "tsls"),
              weights="optimal", itermaxit=100,
              efficientWeights=FALSE, theta0=NULL, ...)
## S4 method for signature 'rlinearModel'
gmmFit(model, type=c("twostep", "iter","cue",
              "onestep"), itertol=1e-7, initW=c("ident", "tsls"),
              weights="optimal", itermaxit=100,
              efficientWeights=FALSE, ...)
## S4 method for signature 'rformulaModel'
gmmFit(model, type=c("twostep", "iter", "cue",
              "onestep"), itertol=1e-7, initW=c("ident", "tsls"),
              weights="optimal", itermaxit=100,
              efficientWeights=FALSE, theta0=NULL, ...)
## S4 method for signature 'rslinearModel'
gmmFit(model, type=c("twostep", "iter","cue",
              "onestep"), itertol=1e-7, initW=c("ident", "tsls", "EbyE"),
              weights="optimal", itermaxit=100,
              efficientWeights=FALSE, theta0=NULL, EbyE=FALSE, ...)
```

### **Arguments**

model A model class object.

type What GMM methods should we use? for type=="onestep", if "weights" is not a matrix, the model will be estimated with the weights equals to the identity

matrix. For restricted

itertol Tolance for the stopping rule in iterative GMM

initW How should be compute the initial coefficient vector in the first. For single equa-

tion GMM, it only makes a difference for linear models for which the choice is GMM with identity matrix or two-stage least quares. For system of equations, "tsls", refers to equation by equation two-stage least squares. It is also possible to start at the equation by equation estimate using the same GMM type as

specified by "type".

weights What weighting matrix to use? The choices are "optimal", in which case it

is the inverse of the moment vovariance matrix, "ident" for the identity matrix, or a fixed matrix. It is also possible for weights to be an object of class

gmmWeights.

itermaxit Maximum iterations for iterative GMM

EbyE Should the system be estimated equation by equation?

efficientWeights

If weights is a matrix or a gmmWeights class object, setting efficientWeights to TRUE implies that the resulting one-step GMM is efficient. As a result, the default covariance matrix for the coefficient estimates will not be a sandwich type.

38 gmmFit-methods

An optional initial vector for optim when the model is nonlinear. By default, the theta0 argument of the model is used

Arguments to pass to other methods (mostly the optimization algorithm)

### Methods

signature(model = "momentModel") The main method for all moment-based models.

signature(model = "rnonlinearModel") It makes a difference only if the number of contraints is equal to the number of coefficients, in which case, the method evalGmm is called at the contrained vector. If not, the next method is called.

signature(model = "rformulaModel") It makes a difference only if the number of contraints is equal to the number of coefficients, in which case, the method evalGmm is called at the contrained vector. If not, the next method is called.

signature(model = "rlinearModel") It makes a difference only if the number of contraints is equal to the number of coefficients, in which case, the method evalGmm is called at the contrained vector. If not, the next method is called.

signature(model = "sysModel") Method to estimate system of equations using GMM methods.

```
data(simData)
theta <- c(beta0=1,beta1=2)
model1 <- momentModel(y~x1, ~z1+z2, data=simData)</pre>
## Efficient GMM with HAC vcov and tsls as first step.
res1 <- gmmFit(model1, init="tsls")</pre>
## GMM with identity. Two ways.
res2 <- gmmFit(model1, type="onestep")</pre>
res3 <- gmmFit(model1, weights=diag(3))</pre>
## nonlinear regression with iterative GMM.
g <- v~beta0+x1^beta1
h <- ~z1+z2
model2 <- momentModel(g, h, c(beta0=1, beta1=2), data=simData)</pre>
res4 <- gmmFit(model2, type="iter")</pre>
## GMM for with no endogenous vaiables is
## OLS with Robust standard error
library(lmtest)
model3 <- momentModel(y~x1, ~x1, data=simData, vcov="MDS")</pre>
resGmm <- gmmFit(model3)</pre>
resLm <- lm(y\sim x1, simData)
summary(resGmm)
coeftest(resLm, vcov=vcovHC(resLm, "HC0"))
summary(resGmm, df.adj=TRUE)
coeftest(resLm, vcov=vcovHC(resLm, "HC1"))
```

Griliches 39

```
### All constrained
R <- diag(2)
q <- c(1,2)
rmodel1 <- restModel(model1, R, q)
gmmFit(rmodel1)

## Only one constraint
R <- matrix(c(0,1), ncol=2)
q <- 2
rmodel1 <- restModel(model1, R, q)
gmmFit(rmodel1)</pre>
```

Griliches

Return to Education Data

## **Description**

Labour data on 758 young workers between 16 and 30 years hold. Each observation provides information on one individual at two points in time: in 1980 (variable with 80) and in the year given be the YEAR (variable without 80).

### Usage

```
data("Griliches")
```

#### Format

A data.frame with 758 observations and 20 variables.

RNS, RNS80 Dummy for residency in the southern states

MRT, MRT80 Dummy for marital status (1 if married)

SMSA, SMSA80 Dummy for residency in metropolitan areas

**MED** Mother's education in years

IQ IQ score

KWW "Knowledge of the World of Work" test score

Year The year of the first observation

AGE, AGE80 Age in years

S, S80 Completed years of schooling

EXPR, EXPR80 Experience in years

TENURE, TENURE80 Tenure im years

LW, LW80 log wage

## Source

Online complements of Fumio Hayashi (2000)

40 HealthRWM

#### References

Griliches, Z. (1976). Wages of Very Young Men. Journal of Political Economy, 84, S69-S85.

Blackburn, M. and Neumark, D. (1992). Unobserved Ability, Efficiency Wages, and Interindustry Wage Differentials. *Quarterly Journal of Economics*, **107**, 1421–1436.

Hayashi, F. (2000). *Econometrics*, New Jersey: Princeton University Press.

**HealthRWM** 

Health data from Greene (2012) applications.

## **Description**

The dataset is used in Greene (2012) and is taken from Riphahn, Wambach, Million (2003).

#### Usage

```
data("HealthRWM")
```

#### **Format**

A data frame with 27326 observations on the following 25 variables.

ID Person-identification number

female Female=1; male=0

year Calendar year of the observation

age Age in years

hsat Health satisfaction, coded 0 (low) to 10 (high)

handdum Handicapped=1; otherwise=0

handper Degree of handicap in percent (0 to 100)

hhninc Household nominal monthly net income in German marks/10,000

hhkids Children under age 16 in the household=1; otherwise=0

educ Years of schooling

married Married=1; otherwise=0

haupts Highest schooling degree is Hauptschul degree=1; otherwise=0

reals Highest schooling degree is Realschul degree=1; otherwise=0

fachhs Highest schooling degree is Polytechnical degree=1; otherwise=0

abitur Highest schooling degree is Abitur=1; otherwise=0

univ Highest schooling degree is university degree=1; otherwise=0

working Employed=1; otherwise=0

bluec Blue-collar employee=1; otherwise=0

whitec White-collar employee=1; otherwise=0

HealthRWM 41

```
self Self-employed=1; otherwise=0
beamt Civil servant=1; otherwise=0
docvis Number of doctor visits in last three months,
hospvis Number of hospital visits in last calendar year,
public Insured in public health insurance=1; otherwise=0
addon Insured by add-on insurance=1; otherwise=0
```

#### Source

On Greene (2012) online resources, and on the Journal of Applied Econometrics website (http://qed.econ.queensu.ca/jae/2003 v18.4/riphahn-wambach-million/).

#### References

Riphahn, R.T. and Wambach, A. and Million, A. (2003), *Incentive Effects in the Demand for Health Care: A Bivariate Panel Count Data Estimation*, Journal of Applied Econometrics, Vol. 18, No. 4, 387–405.

Green, W.H.. (2012). Econometric Analysis, 7th edition, Prentice Hall.

```
##### Example 13.7 of Greene (2012)
## Selecting the same data point and scaling income
##########
data(HealthRWM)
dat88 <- subset(HealthRWM, year==1988 & hhninc>0)
dat88$hhninc <- dat88$hhninc/10000
### A guess start
thet0 <- c(b0=log(mean(dat88\$hhninc)),b1=0,b2=0,b3=0)
## Table 13.2 First column
g <- hhninc~exp(b0+b1*age+b2*educ+b3*female)</pre>
res0 <- nls(g, dat88, start=thet0, control=list(maxiter=100))</pre>
summary(res0)$coef
## Table 13.2 Second column
## Trying very hard to reproduce the results,
## Who is right?
h1 <- ~age+educ+female
model1 <- momentModel(g, h1, thet0, vcov="MDS", data=dat88)</pre>
res1 <- gmmFit(model1, control=list(reltol=1e-10, abstol=1e-10))</pre>
summary(res1)@coef
## Table 13.2 third column (close enough)
## Here a sandwich vcov is required because it is not
## efficient GMM
h2 <- ~age+educ+female+hsat+married
```

42 hypothesisTest-class

```
model2 <- momentModel(g, h2, thet0, vcov="MDS", data=dat88)
res2 <- gmmFit(model2, type="onestep")
summary(res2, sandwich=TRUE)@coef

## Table 13.2 fourth column (Can't get closer than that)
res3 <- gmmFit(model2)
summary(res3)@coef

# Lets see what happens if we start on Greene solution

update(res3, theta0=c(b0=-1.61192, b1=.00092, b2=.04647, b3=-.01517))

## No...</pre>
hypothesisTest-class Class "hypothesisTest"
```

## **Description**

A class to store results form an hypothesis test.

## **Objects from the Class**

Objects can be created by calls of the form new("hypothesisTest", ...). It is created by hypothesisTest.

## **Slots**

```
test: Object of class "numeric" ~~
hypothesis: Object of class "character" ~~
dist: Object of class "character" ~~
df: Object of class "integer" ~~
pvalue: Object of class "numeric" ~~
type: Object of class "character" ~~
```

#### Methods

```
print signature(x = "hypothesisTest"): ...
show signature(object = "hypothesisTest"): ...
```

```
showClass("hypothesisTest")
```

```
hypothesisTest-methods
```

~~ Methods for Function hypothesisTest in Package momentfit ~~

#### **Description**

Performs hypothesis tests on the coefficients estimated by any GMM fit method.

## Usage

```
## S4 method for signature 'gmmfit,missing'
hypothesisTest(object.u, object.r, R,
rhs=NULL, vcov=NULL, ...)
## S4 method for signature 'sgmmfit,missing'
hypothesisTest(object.u, object.r, R,
rhs=NULL, vcov=NULL, ...)
## S4 method for signature 'gmmfit,gmmfit'
hypothesisTest(object.u, object.r,
type=c("Wald", "LR", "LM"), sameVcov=TRUE, vcov=NULL,
firstStepWeight=FALSE, wObj=NULL, ...)
## S4 method for signature 'sgmmfit, sgmmfit'
hypothesisTest(object.u, object.r,
type=c("Wald", "LR", "LM"), sameVcov=TRUE, vcov=NULL,
firstStepWeight=FALSE, wObj=NULL, ...)
## S4 method for signature 'missing,gmmfit'
hypothesisTest(object.u, object.r, wObj=NULL)
## S4 method for signature 'missing,sgmmfit'
hypothesisTest(object.u, object.r, wObj=NULL)
```

# Arguments

1	of class gmmfit obtained using a restricted "momentModel" or "sysModel".
object.r An object	
version of expresses matrix an	n object of class gmmfit, one of the model fit must be the restricted of the other. The restrictions are then tested. If R is a character type, it is the restrictions using the coefficient names. If it numeric, it must be a different the the restrictions are $R\theta=0$ for NULL rhs, or $R\theta=rhs$ otherwise. If the gmmfit must be a fitted restricted model, in which case, a LM test ned.
rhs A vector of	of right hand sides if R is numeric

type Should we perform a Wald, LR or LM test?

sameVcov For the LR test, should we use the same estimate of the covariance matrix of the

moment conditions? See details below.

vcov For the Wald test, it is possible to provide the method with the covariance matrix

of the coefficients.

wObj For the LR test, it is possible to provide the gmmWeights object. In that case, the

provided gmm weights object if used for the restricted and unrestricted models.

... Other argument to pass to specTest.

firstStepWeight

Should we use the first step weighting matrix to compute the test (By default, the optimal weighting matrix is recomputed using the final vector of coefficient estimates). See details below.

#### **Details**

The LR test is the difference between the J-tests of the restricted and unrestricted models. It is therefore  $n\bar{g}'_rW_r\bar{g}_r-n\bar{g}'_uW_u\bar{g}_u$ , where  $\bar{g}_r$  and  $\bar{g}_u$  are respectively the restricted and unrestricted sample mean of the moment conditions, and  $W_r$  and  $W_u$  their respective optimal weighting matrix. The test is therefore invalid if either of the weighting matrices does not converge to the inverse of the covariance matrix of the moment conditions. The restricted and unrestricted models must therefore be estimated by efficient GMM. This is not required for the Wald test.

Asymptotically, it makes no difference which consistent estimate of  $W_u$  or  $W_r$  is used. However, it will make a difference in finite samples.

If sameVcov=TRUE, both  $W_r$  and  $W_u$  are equal to the optimal weighting matrix from the unrestricted model if firstStepWeight=FALSE, and they are equal to the first step weighting matrix (or the last step for iteratice GMM) of the unrestricted model if it is TRUE. For CUE, the value of firstStepWeight makes no difference since the weighting matrix and coefficients are computed simultaneously. Having  $W_r = W_u$  prevents the test to be negative in small samples.

If w0bj is provided, both  $W_r$  and  $W_u$  are equal to it. Of cource, w0bj must be a consistent estimate of the optimal weighting matrix for the test to be valid.

## Methods

- signature(object.u = "gmmfit", object.r = "gmmfit") Used to test a restricted model against an unrestricted one.
- signature(object.u = "sgmmfit", object.r = "sgmmfit") Used to test a restricted model against an unrestricted one (for systems of equations).
- signature(object.u = "missing", object.r= "gmmfit") Used to test a restricted model using
  the LM test.
- signature(object.u = "missing", object.r= "sgmmfit") Used to test a restricted model using the LM test (for systems of equations).
- signature(object.u = "gmmfit", object.r = "missing") Perform a Wald test using an unrestricted model and a restriction matrix or vector.
- signature(object.u = "sgmmfit", object.r = "missing") Perform a Wald test using an unrestricted model and a restriction matrix or vector in systems of linear equations.

```
data(simData)
## Unrestricted model
model1 <- momentModel(y~x1+x2+x3, ~x2+x3+z1+z2+z3, data=simData, vcov="MDS")</pre>
res1 <- gmmFit(model1)</pre>
## Wald test
R < -c("x1=0.5", "x2=x3")
hypothesisTest(object.u=res1, R=R)
## LR tests
rmodel1 <- restModel(model1, R)</pre>
res2 <- gmmFit(rmodel1)</pre>
hypothesisTest(object.u=res1, object.r=res2, type="LR")
### LR and Wald should be the same as long as the same weighting
### matrix if used for both GMM fits, for the LR and Wald as well
# Unrestricted model and save the weights
res1 <- gmmFit(model1)</pre>
w <- res1@w0bi
# estimate models with the same weights
res2 <- gmmFit(rmodel1, weights=w)</pre>
# LR test with the same weights
hypothesisTest(res1, res2, type="LR", wObj=w)
# Wald test with vcov based on the same weights (or the bread)
hypothesisTest(object.u=res1, R=R, breadOnly=TRUE)
### Another example with real data
data(Mroz)
model <- momentModel(log(wage)~educ+exper+I(exper^2),</pre>
                   ~exper+I(exper^2)+fatheduc+motheduc, vcov="MDS",
                   data=Mroz, centeredVcov=FALSE)
R <- c("educ=0","I(exper^2)=0")</pre>
rmodel <- restModel(model, R)</pre>
res1 <- gmmFit(model)</pre>
res2 <- gmmFit(rmodel, weights=res1@wObj)</pre>
hypothesisTest(object.u=res1, object.r=res2, type="LR", w0bj=res1@w0bj)
hypothesisTest(object.u=res1, object.r=res2, type="Wald",
vcov=vcov(res1, breadOnly=TRUE))
## LM test (identical to the other two tests as well)
hypothesisTest(object.r=res2)
hypothesisTest(object.u=res1, object.r=res2, type="LM")
```

46 kernapply-methods

```
## Wald with the Delta Method:
## To impose nonlinear restrictions, we need to convert
## the linear model into a nonlinear one
NLmodel <- as(model1, "nonlinearModel")
R1 <- c("theta2=2", "theta3=theta4^2")
rNLmodel <- restModel(NLmodel, R1)
res.u <- gmmFit(NLmodel)
res.r <- gmmFit(rNLmodel)
hypothesisTest(object.u=res.u, R=R1)
## LM
hypothesisTest(object.r=res.r)
## LR
hypothesisTest(object.r=res.r, object.u=res.u, type="LR")</pre>
```

kernapply-methods

A kernel smoothing utility for "momentModel" classes

## **Description**

It either generates the optimal bandwidth and kernel weights or the smoothed moments of moment based models.

## Usage

```
## S4 method for signature 'momentModel'
kernapply(x, theta=NULL, smooth=TRUE, ...)
```

## Arguments

x	An object of class "momentModel".
theta	An optional vector of coefficients. For smooth=FALSE, it is used to obtain the optimal bandwidth. If NULL, the bandwidth is obtained using one step GMM with the identity matrix as weights. For smooth=TRUE, the coefficient is required since the function returns the smoothed moments at a given vector of coefficients.
smooth	By default, it returns the smoothed moment matrix. If FALSE, it computes the optimal bandwidth and kernel weights.
	Other arguments to pass. Currently not used

Klein 47

### Value

It return an object of class "sSpec".

#### References

Anatolyev, S. (2005), GMM, GEL, Serial Correlation, and Asymptotic Bias. *Econometrica*, **73**, 983-1002.

Kitamura, Yuichi (1997), Empirical Likelihood Methods With Weakly Dependent Processes. *The Annals of Statistics*, **25**, 2084-2102.

Smith, R.J. (2011), GEL Criteria for Moment Condition Models. *Econometric Theory*, **27**(6), 1192–1235.

## **Examples**

```
data(simData)
theta <- c(beta0=1,beta1=2)

## A linearModel
model1 <- momentModel(y~x1, ~z1+z2, data=simData,vcov="HAC",vcovOptions=list(kernel="Bartlett"))

### get the bandwidth
### Notice that the kernel name is the not the same
### That's because a Truncated kernel for smoothing
### lead to a Bartlett kernel for the HAC of the moments
### See Smith (2011)
kernapply(model1, smooth=FALSE)

### Adding the kernel option to the model
model2 <- momentModel(y~x1, ~z1+z2,
data=simData,vcov="HAC",vcovOptions=list(kernel="Bartlett"), smooth=TRUE)
kernapply(model2, theta)$smoothx[1:5,]</pre>
```

Klein

Klein (1950) macro data.

## **Description**

The data is used to reproduce examples of Greene (2012)

## Usage

```
data("Klein")
```

48 LabourCR

### **Format**

A data frame with 22 observations on the following 10 variables.

YEAR a numeric vector

C a numeric vector

P a numeric vector

WP a numeric vector

I a numeric vector

K1 a numeric vector

X a numeric vector

WG a numeric vector

G a numeric vector

T a numeric vector

### **Source**

On Greene (2012) online resources.

### References

Klein, L. (1950), *Economic Fluctuations in the United-States 1921-1941*, New York: John Wiley and Sons.

Green, W.H.. (2012). Econometric Analysis, 7th edition, Prentice Hall.

## **Examples**

data(Klein)

LabourCR

Labour data from Greene (2012) applications,

## Description

A panel data set of 565 individuals from 1976 to 1982 used by Cornwell and Rupert (1988)

## Usage

```
data("LabourCR")
```

LabourCR 49

#### **Format**

A data frame with 4165 observations on the following 12 variables.

EXP Year of full time experience.

WKS Weeks worked.

OCC 1 if blue-collar occupation, 0 otherwise.

IND 1 if works in a manufacture industry, 0 otherwise.

SOUTH 1 if resides in the south, 0 otherwise.

SMSA 1 if resides in an SMSA, 0 otherwise.

MS 1 if married, 0 otherwise.

FEM 1 if the individual is a female and 0 otherwise.

UNION 1 if wage is set by a union contract and 0 otherwise.

ED Years of education.

BLK 1 if the individual is black and 0 otherwise.

LWAGE Log wage.

#### **Source**

Greene (2012) online resources: (http://pages.stern.nyu.edu/~wgreene/Text/Edition7/tablelist8new.htm)

## References

Green, W.H.. (2012). Econometric Analysis, 7th edition, Prentice Hall.

Cornwell, C. and Rupert, P. (1988), *Efficient Estimation with Panel Data: An Empirical Comparision of Instrumental Variable Estimators*, Journal of Applied Econometrics, No.3, 149–155.

50 lambdaAlgo

## **Description**

The algorithms finds the vector or Lagrange multipliers that maximizes the GEL objective function for a given vector of coefficient  $\theta$ .

## Usage

# Arguments

gmat	The $n \times q$ matrix of moments
lambda0	The $q \times 1$ vector of starting values for the Lagrange multipliers.
tol	A tolerance level for the stopping rule in the Wu algorithm
maxiter	The maximum number of iteration in the Wu algorithm
gelType	A character string specifying the type of GEL. The available types are "EL", "ET", "EEL", "HD" and "REEL". For the latter, the algorithm restricts the implied probabilities to be non negative.
rhoFct	An optional function that return $\rho(v)$ . This is for users who want a GEL model that is not built in the package. The four arguments of the function must be "gmat", the matrix of moments, "lambda", the vector of Lagrange multipliers, "derive", which specify the order of derivative to return, and k a numeric scale factor required for time series and kernel smoothed moments.
k	A numeric scaling factor that is required when "gmat" is a matrix of time series which require smoothing. The value depends on the kernel and is automatically set when the "gelModels" is created.
method	This is the method for optim.
algo	Which algorithm should be used to maximize the GEL objective function. If set to "Wu", which is only for "EL", the Wu (2005) algorithm is used.
control	A list of control to pass to either optim or nlminb.
restrictedLam	A vector of integers indicating which "lambda" are restricted to be equal to $0$ .

linearModel-class 51

#### **Details**

The ETXX\_lam is used for ETEL and ETHD. In general, it computes lambda using ET, and returns the value of the objective function determined by the gelType.

#### Value

It returns the vector  $\rho(gmat\lambda)$  when derive=0,  $\rho'(gmat\lambda)$  when derive=1 and  $\rho''(gmat\lambda)$  when derive=2.

#### References

Anatolyev, S. (2005), GMM, GEL, Serial Correlation, and Asymptotic Bias. *Econometrica*, 73, 983-1002.

Kitamura, Yuichi (1997), Empirical Likelihood Methods With Weakly Dependent Processes. *The Annals of Statistics*, **25**, 2084-2102.

Kitamura, Y. and Otsu, T. and Evdokimov, K. (2013), Robustness, Infinitesimal Neighborhoods and Moment Restrictions. *Econometrica*, **81**, 1185-1201.

Newey, W.K. and Smith, R.J. (2004), Higher Order Properties of GMM and Generalized Empirical Likelihood Estimators. *Econometrica*, **72**, 219-255.

Smith, R.J. (2011), GEL Criteria for Moment Condition Models. *Econometric Theory*, **27**(6), 1192–1235.

Wu, C. (2005), Algorithms and R codes for the pseudo empirical likelihood method in survey sampling. *Survey Methodology*, **31**(2), page 239.

linearModel-class

Class "linearModel"

### **Description**

Class for moment-based models for which moment conditions are linear and expressed by a formula.

## **Objects from the Class**

Objects can be created by calls of the form new("linearModel", ...). It is generated my momentModel.

### **Slots**

```
modelF: Object of class "data.frame" ~~
instF: Object of class "data.frame" ~~
vcov: Object of class "character" ~~
n: Object of class "integer" ~~
q: Object of class "integer" ~~
k: Object of class "integer" ~~
```

52 linearModel-class

```
parNames: Object of class "character" ~~
momNames: Object of class "character" ~~
vcovOptions: Object of class "list" ~~
centeredVcov: Object of class "logical" ~~
varNames: Object of class "character" ~~
isEndo: Object of class "logical" ~~
omit: Object of class "integer" ~~
survOptions: Object of class "list" ~~
sSpec: Object of class "sSpec" ~~
smooth: Object of class "logical" ~~
```

### **Extends**

Class "regModel", directly. Class "momentModel", directly.

#### Methods

```
Dresiduals signature(object = "linearModel"): ...
merge signature(x = "linearModel", y = "linearModel"): ...
merge signature(x = "slinearModel", y = "linearModel"): ...
model.matrix signature(object = "linearModel"): ...
modelDims signature(object = "linearModel"): ...
modelResponse signature(object = "linearModel"): ...
momentStrength signature(object = "linearModel"): ...
residuals signature(object = "linearModel"): ...
restModel signature(object = "linearModel"): ...
solveGmm signature(object = "linearModel"): ...
tsls signature(model = "linearModel"): ...
```

```
showClass("linearModel")
```

ManufactCost 53

ManufactCost

Manufacturing Costs data from Bernt and Wood (1975)

## **Description**

The data is used to reproduce examples of Greene (2012)

## Usage

```
data("ManufactCost")
```

### **Format**

A data frame with 25 observations on the following 10 variables.

Year a numeric vector

Cost a numeric vector

K a numeric vector

L a numeric vector

E a numeric vector

M a numeric vector

Pk a numeric vector

Pl a numeric vector

Pe a numeric vector

Pm a numeric vector

## **Source**

On Greene (2012) online resources.

### References

Berndt, E. and Wood, D. (1975), *Technology, Prices, and the Derived Demand for Energy*, Review of Economics and Statistics, Vol. 57, 376–384.

Green, W.H.. (2012). Econometric Analysis, 7th edition, Prentice Hall.

```
data(ManufactCost)
```

54 meatGmm-methods

mconfint-class

Class "mconfint"

## Description

A class to store confidence region.

### **Objects from the Class**

Objects can be created by calls of the form new("mconfint", ...). It is created by the "confint" method with the option area=TRUE (see confint-methods).

## **Slots**

```
areaPoints: Object of class "matrix" ~~
type: Object of class "character" ~~
level: Object of class "numeric" ~~
theta: Object of class "numeric" ~~
```

### Methods

```
plot signature(x = "mconfint"): ...
print signature(x = "mconfint"): ...
show signature(object = "mconfint"): ...
```

## **Examples**

```
showClass("mconfint")
```

meatGmm-methods

~~ Methods for Function meatGmm in Package momentfit ~~

## **Description**

It computes the meat in the sandwich representation of the covariance matrix of the GMM estimator.

## Usage

```
## S4 method for signature 'gmmfit'
meatGmm(object, robust=FALSE)

## S4 method for signature 'sgmmfit'
meatGmm(object, robust=FALSE)

## S4 method for signature 'tsls'
meatGmm(object, robust=FALSE)
```

meatGmm-methods 55

## Arguments

object GMM fit object

robust If TRUE, the meat is robust to the failure of the assumption that the weighting

matrix is the inverse of the covariance matrix of the moment conditions. (see

details)

#### **Details**

If robust=FALSE, then the meat is  $G'V^{-1}G$ , where G and V are respectively the sample mean of the derivatives and the covariance matrix of the moment conditions. If it is TRUE, the meat is G'WVWG, where W is the weighting matrix.

For tsls objects, the function makes use of the QR representation of the weighting matrix. It is simply possible to get the meat in a more stable way. In that case,  $W=(\sigma^2 Z'Z/n)^{-1}$ . If robust is FALSE, V is assumed to be  $\sigma^2 Z'Z/n$  which is the inverse of the bread. Therefore, a sandwich covariance matrix with robust=FALSE will result in a non-sandwich matrix.

For sgmmfit, the covariance is for the vectorized coefficient vector of all equations.

#### Methods

```
signature(object = "gmmfit") General GMM fit.
signature(object = "tsls") For model estimated by two-stage least squares.
signature(object = "sgmmfit") For system of equations.
```

```
data(simData)
theta <- c(beta0=1,beta1=2)
model1 <- momentModel(y~x1, ~z1+z2, data=simData)</pre>
res <- gmmFit(model1)</pre>
meatGmm(res)
## It is a slightly different because the weighting matrix
## is computed using the first step estimate and the covariance
## matrix of the moment conditions is based on the final estimate.
## They should, however, be asymptotically equivalent.
meatGmm(res, robust=TRUE)
## TSLS
res2 <- tsls(model1)</pre>
## Robust meat
meatGmm(res2, TRUE)
## It makes no difference is the model is assumed iid
model2 <- momentModel(y~x1, ~z1+z2, data=simData, vcov="iid")</pre>
res2 <- tsls(model2)</pre>
meatGmm(res2, FALSE)
```

56 merge-methods

```
meatGmm(res2, TRUE)
```

merge-methods

~~ Methods for Function merge in Package base ~~

## Description

It allows to merge momentModel classes into system objects.

#### Usage

```
## S4 method for signature 'linearModel,linearModel'
merge(x, y, ...)

## S4 method for signature 'nonlinearModel,nonlinearModel'
merge(x, y, ...)

## S4 method for signature 'slinearModel,linearModel'
merge(x, y, ...)

## S4 method for signature 'snonlinearModel,nonlinearModel'
merge(x, y, ...)
```

### **Arguments**

x An object on which the other objects are merged to.

y An object to be merged to x.

... Other objects of the same class as y to be merged to x.

## Methods

```
signature(x = "linearModel", y = "linearModel") Merging linear models into a system of
    equations.
```

- signature(x = "nonlinearModel", y = "nonlinearModel") Merging nonlinear models into a
   system of equations.
- signature(x = "slinearModel", y = "linearModel") Adding linear equations to a system of linear equations.
- signature(x = "snonlinearModel", y = "nonlinearModel") Adding nonlinear equations to a
  system of nonlinear equations.

model.matrix-methods 57

### **Examples**

```
data(simData)
g1 \leftarrow y1^x1+x4; h1 \leftarrow z1+z2+z3+z4+x4
g2 \leftarrow y2^x1+x2+x3; h2 \leftarrow z1+z2+z3+z4+x3
g3 \leftarrow y3^2x2+x3+x4; h3 \leftarrow z2+z3+z4+x3+x4
## Linear models
m1 <- momentModel(g1, h1, data=simData)</pre>
m2 <- momentModel(g2, h2, data=simData)</pre>
m3 <- momentModel(g3, h3, data=simData)</pre>
(sys1 <- merge(m1, m2))
## add an equation to the model
(sys2 <- merge(sys1, m3))
## want to get back the first?
sys2[1:2]
## Nonlinear (not really, just written as nonlinear)
nlg <- list(y1~theta0+theta1*x1+theta2*x4,</pre>
             y2~alpha0+alpha1*x1+alpha2*x2+alpha3*x3,
             y3~beta0+beta1*x2+beta2*x3+beta3*x4)
theta0 <- list(c(theta0=1,theta1=2,theta2=3),</pre>
               c(alpha0=1,alpha1=2,alpha2=3, alpha3=4),
               c(beta0=1,beta1=2,beta2=3,beta3=4))
nm1 <- momentModel(nlg[[1]], h1, theta0[[1]], data=simData)</pre>
nm2 <- momentModel(nlg[[2]], h2, theta0[[2]], data=simData)</pre>
nm3 <- momentModel(nlg[[3]], h3, theta0[[3]], data=simData)</pre>
merge(nm1, nm2, nm3)
```

model.matrix-methods ~~ Methods for Function model.matrix in Package stats ~~

## **Description**

Model matrix form momentModel. It returns the matrix of regressors or the instruments. In restricted models, it returns the reduced matrix of regressors.

## Usage

```
## S4 method for signature 'linearModel'
```

58 model.matrix-methods

```
model.matrix(object,
type=c("regressors","instruments"))
## S4 method for signature 'rlinearModel'
model.matrix(object,
type=c("regressors","instruments"))
## S4 method for signature 'nonlinearModel'
model.matrix(object,
type=c("regressors","instruments"))
## S4 method for signature 'slinearModel'
model.matrix(object,
type=c("regressors","instruments"))
## S4 method for signature 'rslinearModel'
model.matrix(object,
type=c("regressors","instruments"))
## S4 method for signature 'rsnonlinearModel'
model.matrix(object,
type=c("regressors","instruments"))
## S4 method for signature 'snonlinearModel'
model.matrix(object,
type=c("regressors","instruments"))
```

## **Arguments**

object Object of class linearModel, rlinearModel or any system of equations class.

type Should the function returns the matrix of instruments or the matrix of regressors.

For nonlinearModel classes, type='regressors' will produce an error message,

because there is no such model matrix in this case, at least not for now.

#### Methods

```
signature(object = "linearModel") Linear models with not restrictions.
signature(object = "nonlinearModel") Nonlinear models with not restrictions.
signature(object = "rlinearModel") linear models with restrictions.
signature(object = "slinearModel") System of linear equations with no restrictions.
signature(object = "rslinearModel") System of linear equations with restrictions.
signature(object = "rsnonlinearModel") System of nonlinear equations with no restrictions.
signature(object = "snonlinearModel") System of nonlinear equations with no restrictions.
```

```
data(simData)
## Unrestricted model
model1 <- momentModel(y~x1+x2+x3, ~x2+x3+z1+z2, data=simData)
model.matrix(model1)[1:3,]
## Restrictions change the response
R <- c("x2=2","x3+x1=3")</pre>
```

modelDims-methods 59

```
rmodel1 <- restModel(model1, R)
rmodel1
model.matrix(rmodel1)[1:3,]</pre>
```

modelDims-methods

Methods for Function modelDims

## **Description**

It extracts important information from the model. It is mostly used by other methods when a modelModel has been modified. An example is when restrictions have been imposed on coefficients.

### Methods

```
signature(object = "rlinearModel")
signature(object = "rnonlinearModel")
signature(object = "rfunctionModel")
signature(object = "linearModel")
signature(object = "nonlinearModel")
signature(object = "functionModel")
signature(object = "formulaModel")
signature(object = "rformulaModel")
signature(object = "rslinearModel")
signature(object = "rslinearModel")
signature(object = "rsnonlinearModel")
signature(object = "snonlinearModel")
signature(object = "sfunctionModel")
```

```
data(simData)
model1 <- momentModel(y~x1+x2, ~x2+z1+z2, data=simData)
modelDims(model1)
## Unrestricted model
rmodel1 <- restModel(model1, R=c("x1+x2=4"))
modelDims(rmodel1)</pre>
```

60 momentModel

modelResponse-methods ~~ Methods for Function modelResponse in Package momentfit ~~

## **Description**

Return the response vector in models with and without restrictions

#### Methods

```
signature(object = "linearModel") For linear models without restrictions on the coefficients.
signature(object = "slinearModel") For system of linear models without restrictions on the coefficients.
signature(object = "rslinearModel") For system of linear models with restrictions on the coefficients.
signature(object = "rlinearModel") For linear models with restrictions on the coefficients.
```

## **Examples**

```
data(simData)
## Unrestricted model
model1 <- momentModel(y~x1+x2+x3, ~x2+x3+z1+z2, data=simData)
y <- modelResponse(model1)

## Restrictions change the response
R <- c("x2=2","x3=3")
rmodel1 <- restModel(model1, R)
rmodel1
restY <- modelResponse(rmodel1)</pre>
```

momentModel

Constructor for "momentModel" classes

### **Description**

It builds an object class "momentModel", which is a union class for "linearModel", "nonlinearModel", "formulaModel" and "functionModel" classes. These are classes for moment based models. This is the first step before running any estimation algorithm.

# Usage

momentModel 61

#### **Arguments**

A function of the form  $g(\theta, x)$  and which returns a  $n \times q$  matrix with typical g element  $g_i(\theta, x_t)$  for i = 1, ..., q and t = 1, ..., n. This matrix is then used to build the q sample moment conditions. It can also be a formula if the model is linear (see detailsbelow). The matrix or vector of data from which the function  $q(\theta, x)$  is computed. If Х "g" is a formula, it is an  $n \times Nh$  matrix of instruments or a formula (see details below). theta0 A  $k \times 1$  vector of starting values. It is required only when "g" is a function because only then a numerical algorithm is used to minimize the objective function. If the dimension of  $\theta$  is one, see the argument "optfct". A function of the form  $G(\theta, x)$  which returns a  $q \times k$  matrix of derivatives of  $\bar{g}(\theta)$ grad with respect to  $\theta$ . By default, the numerical algorithm numericDeriv is used. It is of course strongly suggested to provide this function when it is possible. This gradient is used to compute the asymptotic covariance matrix of  $\theta$  and to obtain the analytical gradient of the objective function if the method is set to "CG" or "BFGS" in optim and if "type" is not set to "cue". If "g" is a formula, the gradiant is not required (see the details below). vcov Assumption on the properties of the moment conditions. By default, they are weakly dependant processes. For MDS, we assume that the conditions are martingale difference sequences, which implies they are serially uncorrelated, but may be heteroscedastic. There is a difference between iid and MDS only when g is a formula. In that case, residuals are assumed homoscedastic as well as serially uncorrelated. For type CL, clustered covariance matrix is computed. The options are then included in vcovOptions (see meatCL). vcovOptions A list of options for the covariance matrix of the moment conditions. See vcovHAC for the default values. Should the moment function be centered when computing its covariance matrix. centeredVcov Doing so may improve inference. data A data.frame or a matrix with column names (Optional). na.action Action to take for missing values. If missing values are present and the option is set to "na.pass", the model won't be estimable. survOptions If needed, a list with the type of survey weights and the weights as a numeric vector, data.frame or formula. The type is either "sampling" or "fequency".

#### Value

'momentModel' returns an object of one of the subclasses of "momentModel".

#### References

smooth

Andrews DWK (1991), Heteroskedasticity and Autocorrelation Consistent Covariance Matrix Estimation. *Econometrica*, **59**, 817–858.

If TRUE, the moment function is smoothed using a kernel method.

62 momentModel-class

Newey WK & West KD (1987), A Simple, Positive Semi-Definite, Heteroskedasticity and Auto-correlation Consistent Covariance Matrix. *Econometrica*, **55**, 703–708.

Newey WK & West KD (1994), Automatic Lag Selection in Covariance Matrix Estimation. *Review of Economic Studies*, **61**, 631-653.

## Examples

```
data(simData)
theta <- c(beta0=1,beta1=2)
## A linearModel
model1 <- momentModel(y~x1, ~z1+z2, data=simData)</pre>
## A nonlinearModel
g <- y~beta0+x1^beta1
h <- ~z1+z2
model2 <- momentModel(g, h, c(beta0=1, beta1=2), data=simData)</pre>
## A functionModel
fct <- function(tet, x)</pre>
    {
        m1 <- (tet[1] - x)
        m2 \leftarrow (tet[2]^2 - (x - tet[1])^2)
        m3 <- x^3 - tet[1]*(tet[1]^2 + 3*tet[2]^2)
        f <- cbind(m1, m2, m3)
        return(f)
dfct <- function(tet, x)</pre>
       jacobian <- matrix(c(1, 2*(-tet[1]+mean(x)), -3*tet[1]^2-3*tet[2]^2,0, 2*tet[2],
   -6*tet[1]*tet[2]), nrow=3,ncol=2)
        return(jacobian)
model3 <- momentModel(fct, simData$x3, theta0=c(beta0=1, beta1=2), grad=dfct)</pre>
```

momentModel-class

Class "momentModel"

## Description

A union class for all moment based models. It is created by momentModel.

## **Objects from the Class**

A virtual Class: No objects may be created from it.

### Methods

```
[ signature(x = "momentModel", i = "missing", j = "missing"): ...
coef signature(object = "momentModel"): ...
evalGel signature(model = "momentModel"): ...
evalGelObj signature(object = "momentModel", theta = "numeric", lambda = "numeric"):
evalGmm signature(model = "momentModel"): ...
evalGmmObj signature(object = "momentModel", theta = "numeric", wObj = "momentWeights"):
evalWeights signature(object = "momentModel"): ...
gelFit signature(model = "momentModel"): ...
getRestrict signature(object = "momentModel"): ...
gmmFit signature(model = "momentModel"): ...
kernapply signature(x = "momentModel"): ...
print signature(x = "momentModel"): ...
show signature(object = "momentModel"): ...
solveGel signature(object = "momentModel"): ...
update signature(object = "momentModel"): ...
vcov signature(object = "momentModel"): ...
vcovHAC signature(x = "momentModel"): ...
```

# **Examples**

```
showClass("momentModel")
```

momentStrength-methods

~~ Methods for Function momentStrength in Package momentfit ~~

## **Description**

It produces measures of the strength of the moment conditons.

## Usage

```
## S4 method for signature 'linearModel'
momentStrength(object, theta,
vcovType=c("OLS","HC","HAC","CL"))
```

#### **Arguments**

object An object of class "linearModel"

theta Coefficient vector at which the strength must be measured. It does not impact

the measure for objects of class linear Model.

vcovType Type of covariance matrix used to compute the F-test of the first-stage regres-

sion. For HC, the function vcovHC is used with "HC1", and vcovHAC is used with the default setup is "HAC" is chosen. In summary for gmmfit objects, it is adjusted to the type of covariance that is set in the object. For type CL, clustered covariance matrix is computed. The options are the one included in the vcovOptions slot of the object (see meatCL). The object must have be defined

with clusters for that to work. See momentModel.

#### Methods

signature(object = "functionModel") Not implemented yet. In that case, we want some measure of the rank of the matrix of derivatives.

signature(object = "formulaModel") Not implemented yet. In that case, we want some measure of the rank of the matrix of derivatives.

signature(object = "linearModel") It returns the F-test of the first stage regression. It is a measure of the strength of the instruments.

```
signature(object = "rlinearModel") Returns nothing for now.
signature(object = "nonlinearModel") Not implemented yet.
```

### **Examples**

```
data(simData)

theta <- c(beta0=1,beta1=2)
model1 <- momentModel(y~x1, ~z1+z2, data=simData)
momentStrength(model1)</pre>
```

momentWeights-class

Class "momentWeights"

## Description

A class to store the weighting matrix of a set of moment conditions.

## **Objects from the Class**

Objects can be created by calls of the form new("momentWeights", ...). It is created my evalWeights.

#### **Slots**

```
w: Object of class "ANY" ~~
type: Object of class "character" ~~
wSpec: Object of class "list" ~~
```

momFct-methods 65

#### Methods

```
[ signature(x = "momentWeights", i = "missing", j = "missing"): ...
[ signature(x = "momentWeights", i = "numeric", j = "missing"): ...
evalGmmObj signature(object = "momentModel", theta = "numeric", wObj = "momentWeights"): ...
print signature(x = "momentWeights"): ...
quadra signature(w = "momentWeights", x = "matrixORnumeric", y = "matrixORnumeric"): ...
quadra signature(w = "momentWeights", x = "matrixORnumeric", y = "missing"): ...
quadra signature(w = "momentWeights", x = "missing", y = "missing"): ...
show signature(object = "momentWeights"): ...
solveGmm signature(object = "allNLModel", wObj = "momentWeights"): ...
solveGmm signature(object = "linearModel", wObj = "momentWeights"): ...
```

#### **Examples**

```
showClass("momentWeights")
```

momFct-methods

Methods for Function momFct in Package momentfit

## **Description**

The methods computes the moment matrix. It is use to create special moment functions

## Usage

```
## S4 method for signature 'numeric,gelfit'
momFct(eta, object)
```

### **Arguments**

eta A vector that includes the coefficient and the Lagrange multipliers object An object of class "gmmfit"

## Methods

```
signature(eta = "numeric", object = "gelfit")
```

66 Mroz

Mroz

Labour data on married women

## **Description**

The dataset was used by Mroz (1987) and in examples in Wooldridge (2016)

## Usage

```
data("Mroz")
```

### **Format**

```
A data frame with 753 observations on the following 22 variables.
```

```
inlf =1 if in lab frce, 1975
hours hours worked, 1975
kidslt6 number of kids < 6 years
kidsge6 number of kids 6-18
age woman's age in years
educ years of schooling
wage Estimated wage from earnings and hours
repwage reported wage at interview in 1976
hushrs hours worked by husband, 1975
husage husband's age
huseduc husband's years of schooling
huswage husband's hourly wage, 1975
famine family income, 1975
mtr federal marginal tax rate facing woman
motheduc mother's years of schooling
fatheduc father's years of schooling
unem unemployment rate in county of residence
city =1 if live in SMSA
exper actual labor market experience
nwifeinc (faminc - wage * hours)/1000
```

#### Source

From Wooldridge (2016) online resources.

nonlinearModel-class 67

#### References

Mroz, T.A. (1987), The Sensitivity of an Empirical Model of Married Women's Hours of Work to Economic and Statistical Assumptions, Econometrica, 55, 657–678. 387–405.

Wooldridge, J.M. (2016). Introductory Econometrics, A Modern Approach, 6th edition, Cengage Learning.

### **Examples**

```
## Example 15.1 of Wooldridge (2016)
data(Mroz)
Mroz <- subset(Mroz, hours>0)
## I guess IID is assumed (That's how we get the same s.e.)
## By default a sandwich vcov is computed because it is
## a just-identified model.
res4 <- gmm4(log(wage)~educ, ~fatheduc, vcov="iid", data=Mroz)</pre>
summary(res4)
## If we adjust the variance of the residuals, however,
## we are a little off (very little)
summary(res4, df.adj=TRUE)
## Example 15.5 of Wooldridge (2016)
## Need to adjust for degrees of freedom in order
## to get the same s.e.
## The first stage F-test is very different though
## Cannot get the same even if do it manually
## with the linearHypothesis from the car package
model <- momentModel(log(wage)~educ+exper+I(exper^2),</pre>
~exper+I(exper^2)+fatheduc+motheduc, vcov="iid", data=Mroz)
res <- tsls(model)</pre>
summary(res, df.adj=TRUE)
```

nonlinearModel-class Class "nonlinearModel"

# Description

Class for moment-based models for which moment conditions are orthogonality conditions between instruments and the residuals from a nonlinear regression.

#### **Objects from the Class**

Objects can be created by calls of the form new("nonlinearModel", ...). It is generated my momentModel.

68 nonlinearModel-class

#### **Slots**

```
modelF: Object of class "data.frame" ~~
instF: Object of class "data.frame" ~~
vcov: Object of class "character" ~~
theta0: Object of class "numeric" ~~
n: Object of class "integer" ~~
q: Object of class "integer" ~~
k: Object of class "integer" ~~
parNames: Object of class "character" ~~
momNames: Object of class "character" ~~
fRHS: Object of class "expression" ~~
fLHS: Object of class "expressionORNULL" ~~
vcov0ptions: Object of class "list" ~~
centeredVcov: Object of class "logical" ~~
varNames: Object of class "character" ~~
isEndo: Object of class "logical" ~~
omit: Object of class "integer" ~~
survOptions: Object of class "list" ~~
sSpec: Object of class "sSpec" ~~
smooth: Object of class "logical" ~~
```

## **Extends**

```
Class "regModel", directly. Class "allNLModel", directly. Class "momentModel", directly.
```

## Methods

```
Dresiduals signature(object = "nonlinearModel"): ...
merge signature(x = "nonlinearModel", y = "nonlinearModel"): ...
merge signature(x = "snonlinearModel", y = "nonlinearModel"): ...
model.matrix signature(object = "nonlinearModel"): ...
modelDims signature(object = "nonlinearModel"): ...
momentStrength signature(object = "nonlinearModel"): ...
residuals signature(object = "nonlinearModel"): ...
restModel signature(object = "nonlinearModel"): ...
```

```
showClass("nonlinearModel")
```

plot-methods 69

plot-methods ~~ Methods for Function plot from package <b>graphics</b> ~~	~
---	---

## **Description**

It plots the confidence region.

# Usage

# Arguments

An object to plot
On used for "ANY".
Optional title
Optional label for the x-axis.
Optional label for the y-axis.
Type of points (see points).
Background color for points.
The color for the points. If col is used, it is passed to polygon
Optional range for the x-axis.
Optional range for the y-axis.
If TRUE, the region is added to an existing plot.
Should we add the point estimate to the confidence region? This option is only used when add is FALSE.
Arguments to pass to polygon

## Methods

```
signature(object = "ANY") It uses the plot from package graphics
signature(object = "mconfint") Plot the 2D confidence region.
```

70 print-methods

print-methods

Methods for Function print in Package base

## **Description**

Print method for all "momentModel", "gmmfit", "summaryGmm" "hypothesisTest" and "specTest" objects.

### Methods

```
signature(x = "ANY")
signature(x = "momentModel")
signature(x = "sSpec")
signature(x = "confint")
signature(x = "mconfint")
signature(x = "sysModel")
signature(x = "sysMomentWeights")
signature(x = "gmmfit")
signature(x = "gelfit")
signature(x = "sgmmfit")
signature(x = "summaryGmm")
signature(x = "summaryGel")
signature(x = "summarySysGmm")
signature(x = "specTest")
signature(x = "rlinearModel")
signature(x = "rformulaModel")
signature(x = "rslinearModel")
signature(x = "rsnonlinearModel")
signature(x = "rnonlinearModel")
signature(x = "rfunctionModel")
signature(x = "hypothesisTest")
signature(x = "momentWeights")
```

printRestrict-methods 71

```
printRestrict-methods ~~ Methods for Function printRestrict in Package momentfit ~~
```

## **Description**

It prints the detailed restrictions imposed on "momentModel" classes.

#### Methods

```
signature(object = "rgelModels")
signature(object = "rlinearModel")
signature(object = "rnonlinearModel")
signature(object = "rfunctionModel")
signature(object = "rformulaModel")
signature(object = "rslinearModel")
signature(object = "rsnonlinearModel")
```

## **Examples**

```
data(simData)
theta <- c(beta0=1,beta1=2)

## Unrestricted model
model1 <- momentModel(y~x1+x2+x3+z1, ~x1+x2+z1+z2+z3+z4, data=simData)

## restricted model
R <- matrix(c(1,1,0,0,0,0,0,2,0,0,0,0,1,-1),3,5, byrow=TRUE)
q <- c(0,1,3)
rmodel1 <- restModel(model1, R, q)
printRestrict(rmodel1)</pre>
```

quadra-methods

~~ Methods for Function quadra in Package momentfit ~~

## **Description**

~~ Computes the quadratic form, where the center matrix is a class momentWeights object ~~

72 quadra-methods

## Usage

```
## S4 method for signature 'momentWeights,missing,missing'
quadra(w, x, y)

## S4 method for signature 'momentWeights,matrixORnumeric,missing'
quadra(w, x, y)

## S4 method for signature 'momentWeights,matrixORnumeric,matrixORnumeric'
quadra(w, x,
y)

## S4 method for signature 'sysMomentWeights,matrixORnumeric,matrixORnumeric'
quadra(w, x,
y)

## S4 method for signature 'sysMomentWeights,matrixORnumeric,missing'
quadra(w, x, y)

## S4 method for signature 'sysMomentWeights,missing,missing'
quadra(w, x, y)
```

## **Arguments**

w An object of class "momentWeights"
 x A matrix or numeric vector
 y A matrix or numeric vector

## Methods

```
signature(w = "momentWeights", x = "matrixORnumeric", y = "matrixORnumeric") It computes x'Wy, where W is the weighting matrix. signature(w = "momentWeights", x = "matrixORnumeric", y = "missing") It computes x'Wx, where W is the weighting matrix. signature(w = "momentWeights", x = "missing", y = "missing") It computes W, where W is the weighting matrix. When W is the inverse of the covariance matrix of the moment conditions, it is saved as either a QR decompisition, a Cholesky decomposition or a covariance
```

matrix into the momentWeights object. The quadra method with no y and x is therefore a way

## **Examples**

```
data(simData)
theta <- c(beta0=1,beta1=2)
model1 <- momentModel(y~x1, ~z1+z2, data=simData)</pre>
```

to invert it. The same applies to system of equations

regModel-class 73

```
gbar <- evalMoment(model1, theta)
gbar <- colMeans(gbar)

### Onjective function of GMM with identity matrix
wObj <- evalWeights(model1, w="ident")
quadra(wObj, gbar)

### Onjective function of GMM with efficient weights
wObj <- evalWeights(model1, theta)
quadra(wObj, gbar)</pre>
```

regModel-class

Class "regModel"

### **Description**

A union class for "linearModel" and "nonlinearModel" classes.

## **Objects from the Class**

A virtual Class: No objects may be created from it.

## Methods

```
[ signature(x = "regModel", i = "numeric", j = "missing"): ...
evalDMoment signature(object = "regModel"): ...
evalMoment signature(object = "regModel"): ...
subset signature(x = "regModel"): ...
```

### **Examples**

```
showClass("regModel")
```

residuals-methods

~~ Methods for Function residuals in Package stats ~~

## **Description**

It computes the residual for a given coefficient vector, when the model is a linear of nonlinear regression with instruments. The method can be called on a momentModel class for a given coefficient theta or on a gmmfit object.

74 restModel-methods

### Methods

```
signature(object = "rsysModel")
signature(object = "linearModel")
signature(object = "nonlinearModel")
signature(object = "gmmfit")
signature(object = "gelfit")
signature(object = "sgmmfit")
signature(object = "sysModel")
```

## **Examples**

```
x <- rchisq(200,5)
z1 <- rnorm(200)
z2 <- .2*x+rnorm(200)
y <- x+rnorm(200)
dat <- data.frame(y=y,z1=z1,x=x,z2=z2)
theta <- c(beta0=1,beta1=2)
model1 <- momentModel(y~x, ~z1+z2, data=dat)
## residuals for a given theta
e <- residuals(model1, theta)
## residuals of the fit
res <- gmmFit(model1)
e <- residuals(res)</pre>
```

restModel-methods

~~ Methods for Function restModel in Package momentfit ~~

### **Description**

It converts momentModel objects into its restricted counterpart.

### Usage

```
## S4 method for signature 'linearModel'
restModel(object, R, rhs=NULL)

## S4 method for signature 'slinearModel'
restModel(object, R, rhs=NULL)

## S4 method for signature 'snonlinearModel'
restModel(object, R, rhs=NULL)
```

restModel-methods 75

```
## S4 method for signature 'nonlinearModel'
restModel(object, R, rhs=NULL)

## S4 method for signature 'formulaModel'
restModel(object, R, rhs=NULL)

## S4 method for signature 'functionModel'
restModel(object, R, rhs=NULL)
```

### **Arguments**

object An object of class "momentModel" or "sysModel".

R Either a matrix or a vector of characters for linear models and a list of formulas

for nonlinear models

rhs The right hand side of the linear restrictions. It is ignored for nonlinear models.

#### Methods

```
signature(object = "linearModel") Method for object of class linearModel.
signature(object = "linearGel") Method for all classes related to linearGel.
signature(object = "slinearModel") Method for object of class slinearModel.
signature(object = "snonlinearModel") Method for object of class snonlinearModel.
signature(object = "nonlinearModel") Method for object of class nonlinearModel.
signature(object = "nonlinearGel") Method for object of class nonlinearGel.
signature(object = "functionModel") Method for object of class functionModel.
signature(object = "functionGel") Method for object of class formulaModel.
signature(object = "formulaModel") Method for object of class formulaModel.
signature(object = "formulaGel") Method for object of class formulaGel.
```

```
data(simData)
theta <- c(beta0=1,beta1=2)

## Unrestricted model
model1 <- momentModel(y~x1+x2+x3+z1, ~x1+x2+z1+z2+z3+z4, data=simData)

## Using matrix R
R <- matrix(c(1,1,0,0,0,0,0,2,0,0,0,0,1,-1),3,5, byrow=TRUE)
q <- c(0,1,3)

rmodel1 <- restModel(model1, R, q)
rmodel1

## Using character
## Many ways to write the constraints</pre>
```

76 rformulaModel-class

```
R1 <- c("x1", "2*x2+z1=2", "4+x3*5=3")
rmodel1 <- restModel(model1, R1)</pre>
rmodel1
## Works with interaction and identity function I()
model1 \leftarrow momentModel(y^x1*x2+exp(x3)+I(z1^2), x1+x2+z1+z2+z3+z4, data=simData)
R1 <- c("x1", "exp(x3)+2*x1:x2", "I(z1^2)=3")
rmodel1 <- restModel(model1, R1)</pre>
rmodel1
## nonlinear constraints on a linear model
## we need to convert the linear model into a nonlinear one
model \leftarrow momentModel(y\sim x1+x2+x3+z1, \sim x1+x2+z1+z2+z3+z4, data=simData)
NLmodel <- as(model, "nonlinearModel")
## To avoid having unconventional parameter names, which happens
## when I() is used or with interaction, the X's and coefficients are
## renamed
NLmodel@parNames
## Restriction can be a list of formula or vector of characters
## For the latter, it will be converted into a list of formulas
R1 \leftarrow c("theta2=2", "theta3=theta4^2")
rmod1 <- restModel(NLmodel, R1)</pre>
res1 <- gmmFit(rmod1)</pre>
res1
## recover the orignial form
coef(rmod1, coef(res1))
## with formulas
R2 \leftarrow list(theta2^2, theta3^1/theta4)
rmod2 <- restModel(NLmodel, R2)</pre>
res2 <- gmmFit(rmod2)</pre>
res2
coef(rmod2, coef(res2))
## The same can be done with function based models
```

rformulaModel-class

Class "rformulaModel"

### **Description**

A class for restricted moment-based models for which moment conditions are expressed using a list of formulas.

rformulaModel-class 77

### **Objects from the Class**

Objects can be created by calls of the form new("rformulaModel", ...). It is created by restModel-methods.

#### **Slots**

```
R: Object of class "list" ~~
cstSpec: Object of class "list" ~~
modelF: Object of class "data.frame" ~~
vcov: Object of class "character" ~~
theta0: Object of class "numeric" ~~
n: Object of class "integer" ~~
q: Object of class "integer" ~~
k: Object of class "integer" ~~
parNames: Object of class "character" ~~
momNames: Object of class "character" ~~
fRHS: Object of class "list" ~~
fLHS: Object of class "list" ~~
vcov0ptions: Object of class "list" ~~
centeredVcov: Object of class "logical" ~~
varNames: Object of class "character" ~~
isEndo: Object of class "logical" ~~
isMDE: Object of class "logical" ~~
omit: Object of class "integer" ~~
survOptions: Object of class "list" ~~
sSpec: Object of class "sSpec" ~~
smooth: Object of class "logical" ~~
```

### **Extends**

```
Class "formulaModel", directly. Class "rmomentModel", directly. Class "allNLModel", by class "formulaModel", distance 2. Class "momentModel", by class "formulaModel", distance 2.
```

#### Methods

```
coef signature(object = "rformulaModel"): ...
evalDMoment signature(object = "rformulaModel"): ...
getRestrict signature(object = "rformulaModel"): ...
gmmFit signature(model = "rformulaModel"): ...
modelDims signature(object = "rformulaModel"): ...
print signature(x = "rformulaModel"): ...
printRestrict signature(object = "rformulaModel"): ...
```

78 rfunctionModel-class

### **Examples**

```
showClass("rformulaModel")

rfunctionModel-class Class "rfunctionModel"
```

## **Description**

A restricted moment-based model for which moment conditions are defined by a function.

### **Objects from the Class**

Objects can be created by calls of the form new("rfunctionModel", ...). It is created by restModel-methods.

#### **Slots**

```
R: Object of class "list" ~~
cstSpec: Object of class "list" ~~
X: Object of class "ANY" ~~
fct: Object of class "function" ~~
dfct: Object of class "functionORNULL" ~~
vcov: Object of class "character" ~~
theta0: Object of class "numeric" ~~
n: Object of class "integer" ~~
q: Object of class "integer" ~~
k: Object of class "integer" ~~
parNames: Object of class "character" ~~
momNames: Object of class "character" ~~
vcov0ptions: Object of class "list" ~~
centeredVcov: Object of class "logical" ~~
varNames: Object of class "character" ~~
isEndo: Object of class "logical" ~~
omit: Object of class "integer" ~~
survOptions: Object of class "list" ~~
sSpec: Object of class "sSpec" ~~
smooth: Object of class "logical" ~~
```

#### **Extends**

```
Class "functionModel", directly. Class "rmomentModel", directly. Class "allNLModel", by class "functionModel", distance 2. Class "momentModel", by class "functionModel", distance 2.
```

rhoFct 79

### Methods

```
[ signature(x = "rfunctionModel", i = "numeric", j = "missing"): ...
coef signature(object = "rfunctionModel"): ...
evalDMoment signature(object = "rfunctionModel"): ...
getRestrict signature(object = "rfunctionModel"): ...
modelDims signature(object = "rfunctionModel"): ...
print signature(x = "rfunctionModel"): ...
printRestrict signature(object = "rfunctionModel"): ...
```

## **Examples**

```
showClass("rfunctionModel")
```

rhoFct

GEL objective functions

## Description

Functions that returns the GEL function  $\rho(g(\theta, x)'\lambda)$  and its derivatives.

## Usage

```
rhoET(gmat, lambda, derive = 0, k = 1)
rhoETEL(gmat, lambda, derive = 0, k = 1)
rhoEL(gmat, lambda, derive = 0, k = 1)
rhoEEL(gmat, lambda, derive = 0, k = 1)
rhoREEL(gmat, lambda, derive = 0, k = 1)
rhoHD(gmat, lambda, derive = 0, k = 1)
rhoETHD(gmat, lambda, derive = 0, k = 1)
```

## Arguments

gmat	The $n \times q$ matrix of moments
lambda	The $q \times 1$ vector of Lagrange multipliers.
derive	An integer which indicates which derivative to return
k	A numeric scaling factor that is required when "gmat" is a matrix of time series which require smoothing. The value depends on the kernel and is automatically set when the "gelModels" is created.

80 rlinearModel-class

#### Value

It returns the vector  $\rho(gmat\lambda)$  when derive=0,  $\rho'(gmat\lambda)$  when derive=1 and  $\rho''(gmat\lambda)$  when derive=2.

#### References

Anatolyev, S. (2005), GMM, GEL, Serial Correlation, and Asymptotic Bias. *Econometrica*, 73, 983-1002.

Kitamura, Yuichi (1997), Empirical Likelihood Methods With Weakly Dependent Processes. *The Annals of Statistics*, **25**, 2084-2102.

Kitamura, Y. and Otsu, T. and Evdokimov, K. (2013), Robustness, Infinitesimal Neighborhoods and Moment Restrictions. *Econometrica*, **81**, 1185-1201.

Newey, W.K. and Smith, R.J. (2004), Higher Order Properties of GMM and Generalized Empirical Likelihood Estimators. *Econometrica*, **72**, 219-255.

Smith, R.J. (2011), GEL Criteria for Moment Condition Models. *Econometric Theory*, **27**(6), 1192–1235.

rlinearModel-class

Class "rlinearModel"

### **Description**

A class for restricted moment-based models for which moment conditions are orthogonality conditions between instruments and the residuals from a linear regression.

#### **Objects from the Class**

Objects can be created by calls of the form new("rlinearModel", ...). It is created by restModel-methods.

## **Slots**

```
cstLHS: Object of class "matrix" ~~
cstRHS: Object of class "numeric" ~~
cstSpec: Object of class "list" ~~
modelF: Object of class "data.frame" ~~
instF: Object of class "data.frame" ~~
vcov: Object of class "character" ~~
n: Object of class "integer" ~~
q: Object of class "integer" ~~
k: Object of class "integer" ~~
parNames: Object of class "character" ~~
momNames: Object of class "character" ~~
```

rmomentModel-class 81

```
vcovOptions: Object of class "list" ~~
centeredVcov: Object of class "logical" ~~
varNames: Object of class "character" ~~
isEndo: Object of class "logical" ~~
omit: Object of class "integer" ~~
survOptions: Object of class "list" ~~
sSpec: Object of class "sSpec" ~~
smooth: Object of class "logical" ~~
```

#### **Extends**

```
Class "linearModel", directly. Class "rmomentModel", directly. Class "regModel", by class "linearModel", distance 2. Class "momentModel", by class "linearModel", distance 2.
```

#### Methods

```
coef signature(object = "rlinearModel"): ...
getRestrict signature(object = "rlinearModel"): ...
gmmFit signature(model = "rlinearModel"): ...
model.matrix signature(object = "rlinearModel"): ...
modelDims signature(object = "rlinearModel"): ...
modelResponse signature(object = "rlinearModel"): ...
momentStrength signature(object = "rlinearModel"): ...
print signature(x = "rlinearModel"): ...
printRestrict signature(object = "rlinearModel"): ...
```

### **Examples**

```
showClass("rlinearModel")
```

rmomentModel-class

Class "rmomentModel"

## Description

A union class for all restricted moment-based models.

### **Objects from the Class**

A virtual Class: No objects may be created from it.

### Methods

```
gelFit signature(model = "rmomentModel"): ...
```

82 rnonlinearModel-class

### **Examples**

```
showClass("rmomentModel")
```

rnonlinearModel-class Class "rnonlinearModel"

## Description

A class for restricted moment-based models for which moment conditions are orthogonality conditions between instruments and the residuals from a nonlinear regression.

### **Objects from the Class**

Objects can be created by calls of the form new("rnonlinearModel", ...). It is created by restModel-methods.

### Slots

```
R: Object of class "list" ~~
cstSpec: Object of class "list" ~~
modelF: Object of class "data.frame" ~~
instF: Object of class "data.frame" ~~
vcov: Object of class "character" ~~
theta0: Object of class "numeric" ~~
n: Object of class "integer" ~~
q: Object of class "integer" ~~
k: Object of class "integer" ~~
parNames: Object of class "character" ~~
momNames: Object of class "character" ~~
fRHS: Object of class "expression" ~~
fLHS: Object of class "expressionORNULL" ~~
vcovOptions: Object of class "list" ~~
centeredVcov: Object of class "logical" ~~
varNames: Object of class "character" ~~
isEndo: Object of class "logical" ~~
omit: Object of class "integer" ~~
survOptions: Object of class "list" ~~
sSpec: Object of class "sSpec" ~~
smooth: Object of class "logical" ~~
```

rslinearModel-class 83

#### **Extends**

```
Class "nonlinearModel", directly. Class "rmomentModel", directly. Class "regModel", by class "nonlinearModel", distance 2. Class "allNLModel", by class "nonlinearModel", distance 2. Class "momentModel", by class "nonlinearModel", distance 2.
```

#### Methods

```
coef signature(object = "rnonlinearModel"): ...
evalDMoment signature(object = "rnonlinearModel"): ...
getRestrict signature(object = "rnonlinearModel"): ...
gmmFit signature(model = "rnonlinearModel"): ...
modelDims signature(object = "rnonlinearModel"): ...
print signature(x = "rnonlinearModel"): ...
printRestrict signature(object = "rnonlinearModel"): ...
```

### **Examples**

```
showClass("rnonlinearModel")
```

```
rslinearModel-class Class "rslinearModel"
```

## Description

A class for restricted system of linear equations.

### **Objects from the Class**

Objects can be created by calls of the form new("rslinearModel", ...). It is created by restModel-methods.

### **Slots**

```
cstLHS: Object of class "matrix" ~~
cstRHS: Object of class "numeric" ~~
cstSpec: Object of class "list" ~~
modelT: Object of class "list" ~~
instT: Object of class "list" ~~
data: Object of class "data.frame" ~~
vcov: Object of class "character" ~~
n: Object of class "integer" ~~
q: Object of class "integer" ~~
k: Object of class "integer" ~~
```

84 rslinearModel-class

```
parNames: Object of class "list" ~~

momNames: Object of class "list" ~~

eqnNames: Object of class "character" ~~

vcovOptions: Object of class "list" ~~

centeredVcov: Object of class "logical" ~~

sameMom: Object of class "logical" ~~

SUR: Object of class "logical" ~~

varNames: Object of class "list" ~~

isEndo: Object of class "list" ~~

omit: Object of class "integer" ~~

survOptions: Object of class "list" ~~

sSpec: Object of class "sSpec" ~~

smooth: Object of class "logical" ~~
```

## **Extends**

Class "slinearModel", directly. Class "rsysModel", directly. Class "sysModel", by class "slinearModel", distance 2.

#### Methods

```
[ signature(x = "rslinearModel", i = "numeric", j = "missing"): ...
coef signature(object = "rslinearModel"): ...
evalDMoment signature(object = "rslinearModel"): ...
evalMoment signature(object = "rslinearModel"): ...
evalWeights signature(object = "rslinearModel"): ...
getRestrict signature(object = "rslinearModel"): ...
gmmFit signature(model = "rslinearModel"): ...
model.matrix signature(object = "rslinearModel"): ...
modelDims signature(object = "rslinearModel"): ...
modelResponse signature(object = "rslinearModel"): ...
print signature(x = "rslinearModel"): ...
printRestrict signature(object = "rslinearModel"): ...
residuals signature(object = "rslinearModel"): ...
ThreeSLS signature(model = "rslinearModel"): ...
```

```
showClass("rslinearModel")
```

rsnonlinearModel-class 85

```
rsnonlinearModel-class
```

Class "rsnonlinearModel"

### **Description**

A class for restricted systems of nonlinear equations.

## **Objects from the Class**

Objects can be created by calls of the form new("rsnonlinearModel", ...). It is created by restModel-methods.

#### Slots

```
R: Object of class "list" ~~
cstSpec: Object of class "list" ~~
data: Object of class "data.frame" ~~
instT: Object of class "list" ~~
vcov: Object of class "character" ~~
theta0: Object of class "list" ~~
n: Object of class "integer" ~~
q: Object of class "integer" ~~
k: Object of class "integer" ~~
parNames: Object of class "list" ~~
momNames: Object of class "list" ~~
fRHS: Object of class "list" ~~
fLHS: Object of class "list" ~~
eqnNames: Object of class "character" ~~
vcov0ptions: Object of class "list" ~~
centeredVcov: Object of class "logical" ~~
sameMom: Object of class "logical" ~~
SUR: Object of class "logical" ~~
varNames: Object of class "list" ~~
isEndo: Object of class "list" ~~
omit: Object of class "integer" ~~
survOptions: Object of class "list" ~~
sSpec: Object of class "sSpec" ~~
smooth: Object of class "logical" ~~
```

86 setCoef-methods

### **Extends**

```
Class "snonlinearModel", directly. Class "rsysModel", directly. Class "sysModel", by class "snonlinearModel", distance 2.
```

#### Methods

No methods defined with class "rsnonlinearModel" in the signature.

## **Examples**

```
showClass("rsnonlinearModel")
```

rsysModel-class

Class "rsysModel"

## **Description**

A union class for all systems of equations. (see link{systemGmm})

## **Objects from the Class**

A virtual Class: No objects may be created from it.

### Methods

No methods defined with class "rsysModel" in the signature.

## **Examples**

```
showClass("rsysModel")
```

setCoef-methods

Methods for Function setCoef in Package momentfit ~~

### **Description**

The method validates the coefficient theta and returns a coefficient object in a format that satisfies the moment model.

# Usage

```
## S4 method for signature 'momentModel'
setCoef(model, theta)
## S4 method for signature 'sysModel'
setCoef(model, theta)
```

setCoef-methods 87

#### **Arguments**

model A moment model object.

theta A coefficient object. The type depends on the model object. See the examples

below.

### Methods

signature(object = "momentModel") Methods for all single equation models including the re-

signature(object = "sysModel") Methods for all system of equations models including the restricted ones.

```
### A few system of equation models:
data(simData)
h \leftarrow list(~z1+z2+z3,~x3+z1+z2+z3+z4,~x3+x4+z1+z2+z3)
nlg <- list(Supply=y1~theta0+theta1*x1+theta2*z2,</pre>
            Demand1=y2~alpha0+alpha1*x1+alpha2*x2+alpha3*x3,
            Demand2=y3~beta0+beta1*x3+beta2*x4+beta3*z1)
g \leftarrow list(Supply=y1\sim x1+z2, Demand1=y2\sim x1+x2+x3, Demand2=y3\sim x3+x4+z1)
theta0 <- list(c(theta0=1,theta1=2,theta2=3),</pre>
                c(alpha0=1,alpha1=2,alpha2=3, alpha3=4),
                c(beta0=1,beta1=2,beta2=3,beta3=4))
nlin <- sysMomentModel(nlg, h, theta0, data=simData)</pre>
lin <- sysMomentModel(g, h, data=simData)</pre>
### from numeric vector to the proper format with names:
setCoef(nlin, 1:11)
### reorder the equation and name the coefficients
setCoef(nlin, list(Demand1=1:4, Supply=1:3, Demand2=1:4))
### reorder the coefficint to match the order in the model
tet <- do.call("c", theta0)</pre>
set.seed(112233)
setCoef(nlin, tet[sample(11)])
### It validates length and names and provide source of errors
## Not run:
setCoef(nlin, list(Demand1=1:4, Supply=1:2, Demand2=1:4))
names(tet)[4] <- "gamma3"</pre>
setCoef(nlin, tet)
setCoef(nlin, list(Demand1=1:4, Supply=1:3, Demand4=1:4))
## End(Not run)
### a single equation model
single <- momentModel(nlg[[1]], h[[1]], theta0[[1]], data=simData)</pre>
setCoef(single, c(theta1=4, theta0=6, theta2=8))
setCoef(single, 1:3)
```

88 sfunctionModel-class

```
sfunctionModel-class Class "sfunctionModel"
```

### **Description**

A class for systems of nonlinear equations.

## **Objects from the Class**

Objects can be created by calls of the form new("sfunctionModel", ...). It is created by momentModel.

#### **Slots**

```
X: Object of class "ANY" ~~
fct: Object of class "list" ~~
dfct: Object of class "list" ~~
vcov: Object of class "character" ~~
theta0: Object of class "list" ~~
n: Object of class "integer" ~~
q: Object of class "integer" ~~
k: Object of class "integer" ~~
parNames: Object of class "list" ~~
momNames: Object of class "list" ~~
egnNames: Object of class "character" ~~
vcovOptions: Object of class "list" ~~
centeredVcov: Object of class "logical" ~~
sameMom: Object of class "logical" ~~
SUR: Object of class "logical" ~~
varNames: Object of class "list" ~~
omit: Object of class "integer" ~~
survOptions: Object of class "list" ~~
sSpec: Object of class "sSpec" ~~
smooth: Object of class "logical" ~~
```

## Extends

```
Class "sysModel", directly.
```

```
\verb|showClass("sfunctionModel")|\\
```

sgmmfit-class 89

sgmmfit-class

Class "sgmmfit"

## **Description**

Class to store fitted system of equations obtained using the GMM method.

## **Objects from the Class**

Objects can be created by calls of the form new("sgmmfit", ...). It is created by gmmFit.

#### **Slots**

```
theta: Object of class "list" ~~
convergence: Object of class "numericORNULL" ~~
convIter: Object of class "numericORNULL" ~~
call: Object of class "callORNULL" ~~
type: Object of class "character" ~~
wObj: Object of class "sysMomentWeights" ~~
niter: Object of class "integer" ~~
efficientGmm: Object of class "logical" ~~
model: Object of class "sysModel" ~~
```

#### Methods

```
bread signature(x = "sgmmfit"): ...

coef signature(object = "sgmmfit"): ...

hypothesisTest signature(object.u = "missing", object.r = "sgmmfit"): ...

hypothesisTest signature(object.u = "sgmmfit", object.r = "missing"): ...

hypothesisTest signature(object.u = "sgmmfit", object.r = "sgmmfit"): ...

meatGmm signature(object = "sgmmfit"): ...

print signature(x = "sgmmfit"): ...

residuals signature(object = "sgmmfit"): ...

show signature(object = "sgmmfit"): ...

specTest signature(object = "sgmmfit"): ...

summary signature(object = "sgmmfit"): ...

vcov signature(object = "sgmmfit"): ...
```

```
showClass("sgmmfit")
```

90 simData

show-methods

~~ Methods for Function show in Package methods ~~

## **Description**

Display method for all objects.

## Methods

```
signature(object = "ANY")
signature(object = "confint")
signature(object = "mconfint")
signature(object = "sSpec")
signature(object = "momentModel")
signature(object = "sysModel")
signature(object = "gmmfit")
signature(object = "gelfit")
signature(object = "sgmmfit")
signature(object = "specTest")
signature(object = "summarySysGmm")
signature(object = "summaryGmm")
signature(object = "summaryGel")
signature(object = "hypothesisTest")
signature(object = "momentWeights")
signature(object = "sysMomentWeights")
```

simData

Simulated data.

## **Description**

This dataset is used in several documentation files to illustrate the different functionality of the package.

## Usage

```
data("simData")
```

simData 91

## **Format**

A data frame with 50 observations on the following 12 variables. See the examples for the method used to generate them.

```
y a numeric vector
y1 a numeric vector
y3 a numeric vector
y2 a numeric vector
z1 a numeric vector
x1 a numeric vector
z2 a numeric vector
x2 a numeric vector
x3 a numeric vector
x4 a numeric vector
z4 a numeric vector
z5 a numeric vector
```

```
# Here is how the data was simulated
 set.seed(1122)
 n <- 50
x1 <- rchisq(n,5)
 x2 <- rchisq(n,5)
 x3 <- rnorm(n)
 x4 <- rnorm(n)
 z1 <- .2*x1+rnorm(n)
 z2 <- .2*x2+rnorm(n)
 z3 <- rnorm(n)</pre>
 z4 <- rnorm(n)
 z5 <- rnorm(n)</pre>
 y \leftarrow y1 \leftarrow x1+rnorm(n)
 y2 \leftarrow 2*x1+rnorm(n)
 y3 <- 0.5*x2+rnorm(n)
 simData <- \ data.frame(y=y, \ y1=y1,y3=y3,y2=y2, \ z1=z1,x1=x1,z2=z2,x2=x2,z3=z3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,
                                                                                                                   x4=x4,z4=z4,z5=z5)
```

92 slinearModel-class

```
slinearModel-class Class "slinearModel"
```

## **Description**

A class for systems of linear equations.

## **Objects from the Class**

Objects can be created by calls of the form new("slinearModel", ...). It is created by momentModel.

### **Slots**

```
modelT: Object of class "list" ~~
instT: Object of class "list" ~~
data: Object of class "data.frame" ~~
vcov: Object of class "character" ~~
n: Object of class "integer" ~~
q: Object of class "integer" ~~
k: Object of class "integer" ~~
parNames: Object of class "list" ~~
momNames: Object of class "list" ~~
eqnNames: Object of class "character" ~~
vcov0ptions: Object of class "list" ~~
centeredVcov: Object of class "logical" ~~
sameMom: Object of class "logical" ~~
SUR: Object of class "logical" ~~
varNames: Object of class "list" ~~
isEndo: Object of class "list" ~~
omit: Object of class "integer" ~~
survOptions: Object of class "list" ~~
sSpec: Object of class "sSpec" ~~
smooth: Object of class "logical" ~~
```

#### **Extends**

```
Class "sysModel", directly.
```

snonlinearModel-class 93

### Methods

```
[ signature(x = "slinearModel", i = "numeric", j = "missing"): ...
merge signature(x = "slinearModel", y = "linearModel"): ...
model.matrix signature(object = "slinearModel"): ...
modelDims signature(object = "slinearModel"): ...
modelResponse signature(object = "slinearModel"): ...
restModel signature(object = "slinearModel"): ...
solveGmm signature(object = "slinearModel"): ...
ThreeSLS signature(model = "slinearModel"): ...
tsls signature(model = "slinearModel"): ...
```

### **Examples**

```
showClass("slinearModel")
```

```
snonlinearModel-class Class "snonlinearModel"
```

## **Description**

A class for systems of nonlinear equations.

### **Objects from the Class**

Objects can be created by calls of the form new("snonlinearModel", ...). It is created by momentModel.

#### Slots

```
data: Object of class "data.frame" ~~

instT: Object of class "list" ~~

vcov: Object of class "character" ~~

theta0: Object of class "list" ~~

n: Object of class "integer" ~~

q: Object of class "integer" ~~

k: Object of class "integer" ~~

parNames: Object of class "list" ~~

fRHS: Object of class "list" ~~

fLHS: Object of class "list" ~~

eqnNames: Object of class "character" ~~
```

94 solveGel-methods

```
vcovOptions: Object of class "list" ~~
    centeredVcov: Object of class "logical" ~~
    sameMom: Object of class "logical" ~~
    SUR: Object of class "logical" ~~
    varNames: Object of class "list" ~~
    isEndo: Object of class "list" ~~
    omit: Object of class "integer" ~~
    survOptions: Object of class "list" ~~
    sSpec: Object of class "sSpec" ~~
    smooth: Object of class "logical" ~~
Extends
    Class "sysModel", directly.
Methods
   [ signature(x = "snonlinearModel", i = "numeric", j = "missing"): ...
    merge signature(x = "snonlinearModel", y = "nonlinearModel"): ...
    model.matrix signature(object = "snonlinearModel"): ...
    modelDims signature(object = "snonlinearModel"): ...
    solveGmm signature(object = "snonlinearModel", wObj = "sysMomentWeights"): ...
Examples
    showClass("snonlinearModel")
```

### **Description**

solveGel-methods

It fits a moment-based model using GEL methods.

## Usage

~~ Methods for Function solveGel in Package momentfit ~~

solveGel-methods 95

### **Arguments**

object	An object of class "gelModels"
gelType	The type of GEL. It is either "EL", "ET", "EEL", "HD", "ETEL" or "ETHD".
theta0	The vector of coefficients for the starting values used in minimization algorithm. If NULL, the starting values in the object is used. For linear models, it must be provided because "linearGel" objects do not have a theta0 slot.
lambda0	The $q \times 1$ vector of starting values for the Lagrange multipliers. By default a zero vector is used.
lamSlv	An alternative solver for the Lagrange multiplier. By default, either Wu_lam, EEL_lam, REEL_lam or getLambda is used.
coefSlv	Minimization solver for the coefficient vector.
rhoFct	An alternative objective function for GEL. This argument is only used if we want to fit the model with a different GEL method. see rhoFct.
lControl	A list of controls for the Lagrange multiplier algorithm.
tControl	A list of controls for the coefficient algorithm.

### Value

A list with the following:

theta The vector of solution

lambda The vector of Lagrange multiplier

1 convergence code for the Lagrange multiplier. 0 means normal convergence.

convergence code for the coefficients. 0 means normal convergence. For higher

numbers, see optim, constrOptim or nlminb

## Methods

signature(object = "momentModel") The method applies to all GEL classes.

96 solveGmm-methods

solveGmm-methods

~~ Methods for Function solveGmm in Package momentfit ~~

## **Description**

The main function to get the GMM solution for a given weighting matrix.

## Usage

```
## S4 method for signature 'linearModel, momentWeights'
solveGmm(object, wObj, theta0=NULL,
...)
## S4 method for signature 'allNLModel,momentWeights'
solveGmm(object, wObj, theta0=NULL,
algo=c("optim","nlminb"), ...)
## S4 method for signature 'rnonlinearModel,momentWeights'
solveGmm(object, wObj, theta0=NULL,
...)
## S4 method for signature 'slinearModel, sysMomentWeights'
solveGmm(object, wObj, theta0=NULL)
## S4 method for signature 'rslinearModel,sysMomentWeights'
solveGmm(object, wObj, theta0=NULL)
## S4 method for signature 'snonlinearModel,sysMomentWeights'
solveGmm(object, wObj,
theta0=NULL, ...)
## S4 method for signature 'sfunctionModel,sysMomentWeights'
solveGmm(object, wObj,
theta0=NULL, ...)
```

## **Arguments**

object	A moment-based model
theta0	The vector of coefficients for the starting values used in optim. If NULL, the starting values in the object if used. For system of equations, it is a list of vectors.
wObj	An object of class "momentWeights" or "sysMomentWeights".
algo	The numerical algorithm to minimize the objective function.
	Arguments to pass to optim.

specTest-class 97

#### Value

A list with the following:

theta The vector of solution

convergence convergence code. 0 means normal convergence. For higher numbers, see optim

#### Methods

signature(object = "allNLMoment", wObj = "momentWeights") Method to solve either nonlinear regressions or models in which moments are computed with a function. The objective is minimized using optim.

signature(object = "rnonlinearModel", w0bj = "momentWeights") Method to solve restricted nonlinear models. It computes the analytical solution.

signature(object = "linearModel", wObj = "momentWeights") Method to solve linear models. It computes the analytical solution.

signature(object = "slinearModel", wObj = "sysMomentWeights") Method to solve system
 of linear models. It computes the analytical solution.

signature(object = "rslinearModel", wObj = "sysMomentWeights") Method to solve system of linear models in which restrictions have been imposed on the coefficients. It computes the analytical solution.

signature(object = "slinearModel", wObj = "sysMomentWeights") Method to solve system of nonlinear models. The solution is obtained with optim using the analytical derivatives.

## **Examples**

```
data(simData)
theta <- c(beta0=1,beta1=2)
model1 <- momentModel(y~x1, ~z1+z2, data=simData)

## A manual two-step GMM
w0 <- evalWeights(model1, w="ident")
theta0 <- solveGmm(model1, w0)$theta
w <- evalWeights(model1, theta0)
theta1 <- solveGmm(model1, w)$theta</pre>
```

specTest-class

Class "specTest"

## **Description**

A class to store results from a specification test.

## **Objects from the Class**

Objects can be created by calls of the form new("specTest", ...). It is created my specTest-methods.

98 specTest-methods

### **Slots**

```
test: Object of class "matrix" ~~
testname: Object of class "character" ~~
```

#### Methods

```
print signature(x = "specTest"): ...
show signature(object = "specTest"): ...
```

### **Examples**

```
showClass("specTest")
```

specTest-methods

~~ Methods for Function specTest in Package momentfit ~~

## **Description**

It computes tests of specification for GMM fit.

## Usage

## **Arguments**

object GMM or GEL fit object

which Which sub-moment conditions to test.

df.adj Should we adjust the covariance matrix of the moment conditions for degrees of freedom. If TRUE the covariance matrix is multiplied by n/(n-k), where n is

the sample size and k is the number of coefficients. For heteroscedastic robust covariance matrix, adjusting is equivalent to computing HC1 while not adjusting

is HC0.

sSpec-class 99

w0bj An object of class gmmWeights. If NULL (the recommended value), the optimal

weights is computed at the fitted coefficient estimates. It is used by hypothesisTest if one wants the LR statistics to be computed using the same weights for the re-

stricted and unrestricted model.

type For GEL, three specification tests are available

#### Methods

```
signature(object = "gmmfit", which="missing")
signature(object = "sgmmfit", which="missing")
signature(object = "gmmfit", which="numeric")
```

### References

Eichenbaum, M. and Hansen L. and Singleton, K. (1985). A time Series Analysis of Representative Agent Models of Consumption and Leisure Choise under Uncertainty. *Quarterly Journal of Economics*, **103**, 51–78.

Hayashi, F. (2000). *Econometrics*, New Jersey: Princeton University Press.

## **Examples**

```
data(simData)
model1 <- momentModel(y~x1, ~z1+z2, data=simData)

res <- gmmFit(model1)
specTest(res)

## Hayashi Example 3.3 (there is not result in the book but
## that's how we would do it for YEAR=1967
data(Griliches)
dat <- subset(Griliches, YEAR==67)
model <- momentModel(LW~S+EXPR+IQ, ~S+EXPR+AGE+MED, data=dat, vcov="MDS")
res <- gmmFit(model)
## testing the orthogonality conditions of S
specTest(res, 2)</pre>
```

sSpec-class

Class "sSpec"

### **Description**

A class to store the specifications of the kernel used to smooth moment conditions.

## **Objects from the Class**

Objects can be created by calls of the form new("sSpec", ...). It is created by kernapply-methods.

100 stsls-class

## **Slots**

```
k: Object of class "numeric" ~~
kernel: Object of class "character" ~~
bw: Object of class "numeric" ~~
w: Object of class "tskernel" ~~
bwMet: Object of class "character" ~~
```

#### Methods

```
print signature(x = "sSpec"): ...
show signature(object = "sSpec"): ...
```

## **Examples**

```
showClass("sSpec")
```

stsls-class

Class "stsls"

## **Description**

A class to store a fitted system of equations obtained using the two-stage least squares method.

## **Objects from the Class**

Objects can be created by calls of the form new("stsls", ...). It is created my tsls-methods.

#### **Slots**

```
theta: Object of class "list" ~~
convergence: Object of class "numericORNULL" ~~
convIter: Object of class "numericORNULL" ~~
call: Object of class "callORNULL" ~~
type: Object of class "character" ~~
wObj: Object of class "sysMomentWeights" ~~
niter: Object of class "integer" ~~
efficientGmm: Object of class "logical" ~~
model: Object of class "sysModel" ~~
```

## **Extends**

```
Class "sgmmfit", directly.
```

summary-methods 101

### Methods

No methods defined with class "stsls" in the signature.

### **Examples**

```
showClass("stsls")
```

summary-methods

~~ Methods for Function summary in Package base ~~

## Description

Compute several results from a moment based model fit.

# Usage

```
## $4 method for signature 'gmmfit'
summary(object, ...)
## $4 method for signature 'gelfit'
summary(object, ...)
## $4 method for signature 'sgmmfit'
summary(object, ...)
```

### Arguments

object A fit object from the package (GMM and GEL are the only methods for now)
... Other arguments to pass to vcov-methods

### Methods

```
signature(object = "gmmfit")
signature(object = "gmmfit")
signature(object = "sgmmfit")
```

```
data(simData)
theta <- c(beta0=1,beta1=2)
model1 <- momentModel(y~x1, ~z1+z2, data=simData)

res <- gmmFit(model1)
summary(res)

## Fixed and True Weights matrix
## Consider the moment of a normal distribution:</pre>
```

102 summaryGel-class

```
## Using the first three non centered moments
g <- function(theta, x)</pre>
mu <- theta[1]</pre>
sig2 <- theta[2]</pre>
m1 <- x-mu
m2 \leftarrow x^2-mu^2-sig^2
m3 <- x^3-mu^3-3*mu*sig2
cbind(m1,m2,m3)
dg \leftarrow function(theta, x)
mu <- theta[1]</pre>
sig2 <- theta[2]</pre>
G \leftarrow matrix(c(-1,-2*mu,-3*mu^2-3*sig2, 0, -1, -3*mu),3,2)
x <- simData$x3
model <- momentModel(g, x, c(mu=.1, sig2=1.5), vcov="iid")</pre>
res1 <- gmmFit(model)</pre>
summary(res1)
## Same results (that's because the moment vcov is centered by default)
W \leftarrow solve(var(cbind(x,x^2,x^3)))
res2 <- gmmFit(model, weights=W)</pre>
res2
## If is therefore more efficient in this case to do the following:
summary(res2, breadOnly=TRUE)
```

summaryGel-class

Class "summaryGel"

## **Description**

Class to store the summary of a model fitted by GEL.

### **Objects from the Class**

Objects can be created by calls of the form new("summaryGel", ...). It is created by link{summary-methods}.

### **Slots**

```
coef: Object of class "matrix" ~~
specTest: Object of class "specTest" ~~
model: Object of class "momentModel" ~~
lambda: Object of class "matrix" ~~
```

summaryGmm-class 103

```
convergence: Object of class "numeric" ~~
  lconvergence: Object of class "numeric" ~~
  impProb: Object of class "list" ~~
  gelType: Object of class "list" ~~
  restrictedLam: Object of class "integer" ~~

Methods
  print signature(x = "summaryGel"): ...
  show signature(object = "summaryGel"): ...

Examples
  showClass("summaryGel")

summaryGmm-class

Class "summaryGmm"
```

## Description

A class to store the summary of a model fitted by GMM.

### **Objects from the Class**

Objects can be created by calls of the form new("summaryGmm", ...). It is created by link{summary-methods}.

### **Slots**

```
coef: Object of class "matrix" ~~

specTest: Object of class "specTest" ~~

strength: Object of class "list" ~~

model: Object of class "momentModel" ~~

sandwich: Object of class "logical" ~~

type: Object of class "character" ~~

convergence: Object of class "numericORNULL" ~~

convIter: Object of class "numericORNULL" ~~

wSpec: Object of class "list" ~~

niter: Object of class "integer" ~~

df.adj: Object of class "logical" ~~

breadOnly: Object of class "logical" ~~
```

### Methods

```
print signature(x = "summaryGmm"): ...
show signature(object = "summaryGmm"): ...
```

### **Examples**

```
showClass("summaryGmm")
```

summarySysGmm-class

Class "summarySysGmm"

### **Description**

A class to store the summary of a system of equations fitted by GMM.

### **Objects from the Class**

Objects can be created by calls of the form new("summarySysGmm", ...). It is created by summary-methods.

### **Slots**

```
coef: Object of class "list" ~~

specTest: Object of class "specTest" ~~

strength: Object of class "list" ~~

model: Object of class "sysModel" ~~

sandwich: Object of class "logical" ~~

type: Object of class "character" ~~

convergence: Object of class "numericORNULL" ~~

convIter: Object of class "numericORNULL" ~~

wSpec: Object of class "list" ~~

niter: Object of class "integer" ~~

df.adj: Object of class "logical" ~~

breadOnly: Object of class "logical" ~~
```

### Methods

```
print signature(x = "summarySysGmm"): ...
show signature(object = "summarySysGmm"): ...
```

```
showClass("summarySysGmm")
```

sysModel-class 105

sysModel-class Class "sysModel"

## **Description**

A union class for all systems of equations.

# **Objects from the Class**

A virtual Class: No objects may be created from it.

#### Methods

```
[ signature(x = "sysModel", i = "missing", j = "list"): ...
[ signature(x = "sysModel", i = "missing", j = "missing"): ...
[ signature(x = "sysModel", i = "numeric", j = "list"): ...

Dresiduals signature(object = "sysModel"): ...
evalDMoment signature(object = "sysModel"): ...
evalGmmObj signature(object = "sysModel"): ...
evalMoment signature(object = "sysModel"): ...
evalWeights signature(object = "sysModel"): ...
getRestrict signature(object = "sysModel"): ...
getRestrict signature(model = "sysModel"): ...
print signature(x = "sysModel"): ...
print signature(object = "sysModel"): ...
show signature(object = "sysModel"): ...
show signature(object = "sysModel"): ...
vcov signature(object = "sysModel"): ...
vcov signature(object = "sysModel"): ...
```

```
showClass("sysModel")
```

106 sysMomentModel

sysMomentModel Constructor for "sysMomentModel" classes	
---	--

## Description

It builds the object of either class "slinearModel" or "snonlinearModel", which are system of equations based on moment conditions.

# Usage

## Arguments

<b>8</b>	
g	A list of linear or nonlinear regression formulas for each equation in the system.
h	A list of linear formulas for the instruments in each equation in the system.
theta0	A list of vectors of starting values. It is required only when the equations are nonlinear, in which case, it must be a list of named vector, with the names corresponding to the coefficient names in the regression formulas.
grad	A list of functions that returns the derivative of the moment functions. Only used if g is a list of functions.
VCOV	Assumption on the properties of the moment conditions. By default, they are weakly dependant processes. For MDS, we assume that the conditions are martingale difference sequences, which implies they are serially uncorrelated, but may be heteroscedastic. There is a difference between iid and MDS only when g is a formula. In that case, residuals are assumed homoscedastic as well as serially uncorrelated. For type CL, clustered covariance matrix is computed. The options are then included in vcovOptions (see meatCL).
vcovOptions	A list of options for the covariance matrix of the moment conditions. See vcovHAC for the default values.
centeredVcov	Should the moment function be centered when computing its covariance matrix. Doing so may improve inference.
data	A data.frame or a matrix with column names (Optional).
na.action	Action to take for missing values. If missing values are present and the option is set to "na.pass", the model won't be estimable.
survOptions	If needed, a list with the type of survey weights and the weights as a numeric vector, data.frame or formula. The type is either "sampling" or "fequency".

## Value

<sup>&#</sup>x27;sysMomentModel' returns an object of one of the subclasses of "sysMomentModel".

sysMomentModel 107

### References

Hayashi, F. (2000). Econometrics, New Jersey: Princeton University Press.

Andrews DWK (1991), Heteroskedasticity and Autocorrelation Consistent Covariance Matrix Estimation. *Econometrica*, **59**, 817–858.

Newey WK & West KD (1987), A Simple, Positive Semi-Definite, Heteroskedasticity and Auto-correlation Consistent Covariance Matrix. *Econometrica*, **55**, 703–708.

Newey WK & West KD (1994), Automatic Lag Selection in Covariance Matrix Estimation. *Review of Economic Studies*, **61**, 631-653.

```
set.seed(1122)
x1 < - rchisq(50,5)
x2 < - rchisq(50,5)
x3 <- rnorm(50)
x4 <- rnorm(50)
z1 <- .2*x1+rnorm(50)
z2 <- .2*x2+rnorm(50)
z3 <- rnorm(50)
z4 <- rnorm(50)
z5 <- rnorm(50)
y1 <- x1 + rnorm(50)
y2 <- 2*x1+rnorm(50)
y3 <- 0.5*x2+rnorm(50)
dat <- data.frame(y1=y1,y3=y3,y2=y2, z1=z1,x1=x1,z2=z2,x2=x2,z3=z3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=x3,x3=
                                                              x4=x4, z4=z4, z5=z5)
g1 < y1^x1+x4; h1 < z1+z2+z3+z4+x4
g2 \leftarrow y2^x1+x2+x3; h2 \leftarrow z1+z2+z3+z4+x3
g3 \leftarrow y3^2x2+x3+x4; h3 \leftarrow z2+z3+z4+x3+x4
g <- list(g1,g2,g3)
h \leftarrow list(h1,h2,h3)
 smodel <- sysMomentModel(g, h, data=dat)</pre>
 ## not really nonlinear
nlg <- list(y1~theta0+theta1*x1+theta2*x4,</pre>
                                         y2~alpha0+alpha1*x1+alpha2*x2+alpha3*x3,
                                         y3~beta0+beta1*x2+beta2*x3+beta3*x4)
 theta0 <- list(c(theta0=1,theta1=2,theta2=3),</pre>
                                                c(alpha0=1,alpha1=2,alpha2=3, alpha3=4),
                                                c(beta0=1,beta1=2,beta2=3,beta3=4))
snmodel <- sysMomentModel(nlg, h, theta0, data=dat)</pre>
```

```
{\it Sys} {\it MomentWeights-class} \\ {\it Class~"} {\it sys} {\it MomentWeights"}
```

### Description

A class to store the weighting matrix of the moment conditions from a system of equations.

## **Objects from the Class**

Objects can be created by calls of the form new("sysMomentWeights", ...). It is created by the evalWeights method.

### **Slots**

```
w: Object of class "ANY" ~~

type: Object of class "character" ~~

wSpec: Object of class "list" ~~

Sigma: Object of class "ANY" ~~

momNames: Object of class "list" ~~

eqnNames: Object of class "character" ~~

sameMom: Object of class "logical" ~~
```

### Methods

```
[ signature(x = "sysMomentWeights", i = "missing", j = "list"): ...
[ signature(x = "sysMomentWeights", i = "numeric", j = "list"): ...
[ signature(x = "sysMomentWeights", i = "numeric", j = "missing"): ...
evalGmmObj signature(object = "sysModel", theta = "list", wObj = "sysMomentWeights"): ...
print signature(x = "sysMomentWeights"): ...
quadra signature(w = "sysMomentWeights", x = "matrixORnumeric", y = "matrixORnumeric"): ...
quadra signature(w = "sysMomentWeights", x = "matrixORnumeric", y = "missing"): ...
quadra signature(w = "sysMomentWeights", x = "missing", y = "missing"): ...
show signature(object = "sysMomentWeights"): ...
solveGmm signature(object = "rslinearModel", wObj = "sysMomentWeights"): ...
solveGmm signature(object = "snonlinearModel", wObj = "sysMomentWeights"): ...
solveGmm signature(object = "snonlinearModel", wObj = "sysMomentWeights"): ...
```

```
showClass("sysMomentWeights")
```

systemGmm-doc 109

systemGmm-doc

A guide to estimating systems of equations

# **Description**

This document is meant to describe how to create system of equations objects, estimating them and peforming hypothesis tests.

#### **Details**

Instread of repeating the same example for each method, we are going through all methods and classes for systems of equations.

```
data(simData)
## first, we create an sysGmm object
g1 \leftarrow y1^x1+x4; h1 \leftarrow x4+z1+z2+z3+z4
g2 \leftarrow y2^x1+x2+x3; h2 \leftarrow x3+z1+z2+z3+z4
g3 \leftarrow y3^2x2+x3+x4; h3 \leftarrow x3+x4+z1+z2+z3+z4
g <- list(g1,g2,g3)
h <- list(h1,h2,h3)
smodel <- sysMomentModel(g, h, data=simData, vcov="MDS")</pre>
## The show or print method
smodel
## The ']' method
smodel[1:2]
smodel[1] ## becomes a one equation model
## equation by equation 2SLS
tsls(smodel)
## or manually
lapply(1:3, function(i) coef(tsls(smodel[i])))
## Fitting the model by two-step GMM
res <- gmmFit(smodel)</pre>
## testing Overidentifying restrictions
specTest(res)
## All info using the summary method
## which includes equation by equation measures of
## the instrument stengths
summary(res)
### When the error id iid (homoscedastic), we have a
```

110 ThreeSLS-methods

```
### FIVE estimator with 2SLS as the first step
smodel <- sysMomentModel(g, h, data=simData, vcov="iid")</pre>
gmmFit(smodel)
### When the error is iid (homoscedastic),
### all instruments are the same, and the first step is 2SLS,
### we have 3SLS
smodel <- sysMomentModel(g, ~x4+z1+z2+z3+z4, data=simData, vcov="iid")</pre>
gmmFit(smodel, initW='tsls')
### When the error is iid (homoscedastic),
### the instruments are the same and are the union of all regressors,
### we have SUR
smodel <- sysMomentModel(g, NULL, data=simData, vcov="iid")</pre>
gmmFit(smodel, initW='tsls')
## unrestricted
smodel <- sysMomentModel(g, h, data=simData, vcov="MDS")</pre>
res <- gmmFit(smodel)</pre>
## no cross-equation restrictions
R1 <- list(c("x1=-12*x4"), character(), c("x2=0.8", "x4=0.3"))
rm1 <- restModel(smodel, R1)</pre>
(res1 <- gmmFit(rm1))</pre>
## Cross equation restrictions
R2<- c("Eqn1.x1=1", "Eqn2.x1=Eqn3.x2")
rm2 <- restModel(smodel, R2)</pre>
(es2 <- gmmFit(rm2))## no longer expressed as a system</pre>
## testing the restriction
hypothesisTest(res, res1, type="LR")
hypothesisTest(res, res1, type="LM")
hypothesisTest(res, res1, type="Wald")
```

ThreeSLS-methods

~~ Methods for Function ThreeSLS in Package momentfit ~~

## **Description**

Method to estimate system of equations by Three-Stage least squares (3SLS) or, as a special case, by Seemingly Unrelatd Regressions (SUR).

## Usage

```
## S4 method for signature 'slinearModel'
```

111 tsls-class

```
ThreeSLS(model, coefOnly=FALSE, qrZ=NULL,
Sigma=NULL)
## S4 method for signature 'rslinearModel'
ThreeSLS(model, coefOnly=FALSE, qrZ=NULL,
Sigma=NULL)
```

## **Arguments**

mode1 An object of class "slinearModel" in which instruments are the same in each equation and the error terms are homoscedastic. coefOnly Should the method return the only the coefficients or create an object of class "sgmmfit". The qr decomposition of the common instruments. It is mostly used by gmmFit qrZ to avoid recomputing it in iterative GMM or CUE. It should not be used directly unless the user knows what he is doing. Sigma The covariance matrix of the residuals. If not provided, it is computed using the

residuals of the equation by equation two-stage least squares. It should not be

used directly unless the user knows what he is doing.

#### Methods

signature(model = "slinearModel") The method is specifically for system of linear models with the same instruments and homoscedastic errors. It becomes SUR as a special case when the instruments are the union of all regressors.

signature(model = "rslinearModel") This method is for restricted models that does not impose cross-equation restrictions. With such restrictions 3SLS is not possible as we can no longer write the model as a system of equations.

## **Description**

Class that contains a fitted model using two-stage least squares

## **Objects from the Class**

Objects can be created by calls of the form new("tsls", ...). It is created my the

#### Slots

```
theta: Object of class "numeric" ~~
convergence: Object of class "numericORNULL" ~~
convIter: Object of class "numericORNULL" ~~
call: Object of class "callORNULL" ~~
```

112 tsls-methods

```
type: Object of class "character" ~~
wObj: Object of class "momentWeights" ~~
niter: Object of class "integer" ~~
efficientGmm: Object of class "logical" ~~
model: Object of class "momentModel" ~~
```

## **Extends**

```
Class "gmmfit", directly.
```

# **Examples**

```
showClass("tsls")
```

tsls-methods

~~ Methods for Function tsls in Package momentfit ~~

# Description

It estimates a linear model using two-stage least squares.

# Usage

```
## S4 method for signature 'linearModel'
tsls(model)
## S4 method for signature 'slinearModel'
tsls(model)
```

# **Arguments**

mode1

An object of class linearModel or slinearModel.

#### Methods

update-methods 113

## **Examples**

update-methods

~~ Methods for Function update in Package stats ~~

## **Description**

The method is used to refit a model with either a different method or with modifications to the momentModel.

#### Usage

```
## S4 method for signature 'gmmfit'
update(object, ..., evaluate=TRUE)

## S4 method for signature 'momentModel'
update(object, ...)

## S4 method for signature 'gelfit'
update(object, newModel=NULL, ...,
evaluate=TRUE)

## S4 method for signature 'list'
update(object, ...)
```

## **Arguments**

object An object produced by "gelFit", "gmmFit" or a model. It can also be a list, in which case, it is used to change elements of a list.

.. Arguments to modify the model or the GMM method

114 vcov-methods

newModel When provided, the new model is estimated using the same specification. For

example, it is particularly useful to estimate the restricted model using the same

optim specification as the unrestricted model.

evaluate The modified call argument is only evaluated when evaluate is TRUE

#### Methods

```
signature(object = "ANY") That just calls "update" from the "stats" package.
signature(object = "gmmfit")
signature(object = "momentModel")
signature(object = "list")
```

# **Examples**

```
x <- rchisq(200,5)
z1 <- rnorm(200)
z2 <- .2*x+rnorm(200)
y <- x+rnorm(200)
dat <- data.frame(y=y,z1=z1,x=x,z2=z2)
theta <- c(beta0=1,beta1=2)
model1 <- momentModel(y~x, ~z1+z2, data=dat)

(res <- gmmFit(model1))

## lets change to iterative
update(res, type="iter")

## Let change the HAC specification in the model1 object
## to MDS
update(res, vcov="MDS")</pre>
```

vcov-methods

~~ Methods for Function vcov in Package stats ~~

## **Description**

Computes the covariance matrix of the coefficient estimated by GMM or GEL.

# Usage

```
## S4 method for signature 'gmmfit'
vcov(object, sandwich=NULL, df.adj=FALSE,
breadOnly=FALSE, modelVcov=NULL)
## S4 method for signature 'sgmmfit'
vcov(object, sandwich=NULL, df.adj=FALSE,
```

vcov-methods 115

#### **Arguments**

object A fitted model or a model, For fitted models, it computes the covariance matrix

of the estimators. For models, it computes the covariance matrix of the moment

conditions, in which case, the coefficient vector must be provided.

theta Coefficient vector to compute the covariance matrix of the moment conditions.

sandwich Should we compute the sandwich covariance matrix. This is only necessary if

the weighting matrix is not the optimal one, or if we think it is a bad estimate of it. If NULL, it will be set to "TRUE" for One-Step GMM, which includes

just-identified GMM like IV, and "FALSE" otherwise.

df.adj Should we adjust for degrees of freedom. If TRUE the covariance matrix is multi-

plied by n/(n-k), where n is the sample size and k is the number of coefficients. For heteroscedastic robust covariance matrix, adjusting is equivalent to comput-

ing HC1 while not adjusting is HC0.

breadOnly If TRUE, the covariance matrix is set to the bread (see details below).

modelVcov Should be one of "iid", "MDS" or "HAC". It is meant to change the way the

variance of the moments is computed. If it is set to a different specification

included in the model, sandwich is set to TRUE.

withImpProb Should we compute the moments with the implied probabilities

tol Any diagonal less than "tol" is set to tol

robToMiss Should we compute a covariance matrix that is robust to misspecification?

#### **Details**

If sandwich=FALSE, then it returns  $(G'V^{-1}G)^{-1}/n$ , where G and V are respectively the matrix of average derivatives and the covariance matrix of the moment conditions. If it is TRUE, it returns  $(G'WG)^{-1}G'WVWG(G'WG)^{-1}/n$ , where W is the weighting matrix used to obtain the vector of estimates.

If breadOnly=TRUE, it returns  $(G'WG)^{-1}/n$ , where the value of W depends on the type of GMM. For two-step GMM, it is the first step weighting matrix, for one-step GMM, it is either the identity matrix or the fixed weighting matrix that was provided when gmmFit was called, for iterative GMM,

116 vcov-methods

it is the weighting matrix used in the last step. For CUE, the result is identical to sandwich=FALSE and beadOnly=FALSE, because the weighting and coefficient estimates are obtained simultaneously, which makes W identical to V.

breadOnly=TRUE should therefore be used with caution because it will produce valid standard errors only if the weighting matrix converges to the inverse of the covariance matrix of the moment conditions.

For "tsls" objects, sandwich is TRUE by default. If we assume that the error term is iid, then setting it to FALSE to result in the usual  $\sigma^2(\hat{X}'\hat{X})^{-1}$  covariance matrix. If FALSE, it returns a robust covariance matrix determined by the value of vcov in the momentModel.

#### Methods

```
signature(object = "gmmfit") For any model estimated by any GMM methods.
signature(object = "gelfit") For any model estimated by any GMM methods.
signature(object = "sgmmfit") For any system of equations estimated by any GMM methods.
```

```
data(simData)
theta <- c(beta0=1,beta1=2)
model1 <- momentModel(y~x1, ~z1+z2, data=simData)</pre>
## optimal matrix
res <- gmmFit(model1)</pre>
vcov(res)
## not the optimal matrix
res <- gmmFit(model1, weights=diag(3))</pre>
vcov(res, TRUE)
## Model with heteroscedasticity
## MDS is for models with no autocorrelation.
## No restrictions are imposed on the structure of the
## variance of the moment conditions
model2 <- momentModel(y~x1, ~z1+z2, data=simData, vcov="MDS")</pre>
res <- tsls(model2)</pre>
## HC0 type of robust variance
vcov(res, sandwich=TRUE)
## HC1 type of robust variance
vcov(res, sandwich=TRUE, df.adj=TRUE)
## Fixed and True Weights matrix
## Consider the moment of a normal distribution:
## Using the first three non centered moments
g <- function(theta, x)</pre>
mu <- theta[1]</pre>
sig2 <- theta[2]
```

vcovHAC-methods 117

```
m1 <- x-mu
m2 <- x^2-mu^2-sig2
m3 <- x^3-mu^3-3*mu*sig2
cbind(m1,m2,m3)
dg <- function(theta, x)</pre>
mu <- theta[1]</pre>
sig2 <- theta[2]</pre>
G \leftarrow matrix(c(-1, -2*mu, -3*mu^2-3*sig2, 0, -1, -3*mu), 3, 2)
x <- simData$x3
model <- momentModel(g, x, c(mu=.1, sig2=1.5), vcov="iid")</pre>
res1 <- gmmFit(model)</pre>
summary(res1)
## Same results (that's because the moment vcov is centered by default)
W \leftarrow solve(var(cbind(x,x^2,x^3)))
res2 <- gmmFit(model, weights=W)</pre>
res2
## If is therefore more efficient in this case to do the following:
## the option breadOnly of summary() is passed to vcov()
summary(res2, breadOnly=TRUE)
```

vcovHAC-methods

~~ Methods for Function vcovHAC in Package sandwich ~~

# **Description**

Methods to compute the HAC covariance matrix of the moment matrix ~~

## Methods

```
signature(x = "momentModel")
```

```
data(simData)
theta <- c(beta0=1,beta1=2)
model1 <- momentModel(y~x1, ~z1+z2, data=simData)

# a warning is given if the model is not set as being HAC
vcovHAC(model1, theta)

model1 <- momentModel(y~x1, ~z1+z2, data=simData, vcov="HAC",vcovOptions=list(kernel="B"))
vcovHAC(model1, theta)</pre>
```

118 [-methods

[-methods

Subsetting methods

## **Description**

Different subsetting methods for S4 class objects of the package. The subset method returns an new object with observations selected by the second argument. See example.

#### Methods

- signature(x = "momentWeights", i = "integer", j = "missing") It creates a partition from the weighting matrix.
- signature(x = "momentWeights", i = "missing", j = "missing") It generates the whole weighting matrix.
- signature(x = "sysMomentWeights", i = "missing", j = "list") It creates a partition from the weighting matrix. j has no effect here. It creates a partition from the weighting matrix in a systemof equations. i selects the equation and the list j the moments in each equation. Missing i means all equations.
- signature(x = "sysMomentWeights", i = "numeric", j = "missing") It creates a partition from the weighting matrix. j has no effect here. It creates a partition from the weighting matrix in a systemof equations. i selects the equation and the list j the moments in each equation. Missing j means all moments.
- $signature (\texttt{x = "sysMomentWeights"}, \texttt{i = "missing"}, \texttt{j = "missing"}) \ \ No \ effect. \ It \ returns \ \texttt{x}.$
- signature(x = "snonlinearModel", i = "numeric", j="missing") It generates a system of equations with a subset of equations selected by i. If the number of remaining equations is one, it returns an object of class "nonlinearGmm".
- signature(x = "slinearModel", i = "numeric", j="missing") It generates a system of equations with a subset of equations selected by i. If the number of remaining equations is one, it returns an object of class "linearModel".
- signature(x = "rslinearModel", i = "numeric", j="missing") It is only use to select one equation when no cross-equation restrictions are imposed. Only one equation can be selected.
- signature(x = "rsnonlinearModel", i = "numeric", j="missing") It is only use to select one equation when no cross-equation restrictions are imposed. Only one equation can be selected.
- signature(x = "sysMomentModel", i = "numeric", j="list") It generates a system of equations with a subset of equations selected by i and a subset of moment conditions selected by j. If the number of remaining equations is one, it returns an object of class "linearGmm".
- signature(x = "sysMomentModel", i = "missing", j="missing") No effect. It returns x.
- signature(x = "momentModel", i = "missing", j = "missing") Returns the model without any change.
- signature(x = "functionModel", i = "numeric", j = "missing") It generates the same model
   with a subset of the moment conditions.
- signature(x = "formulaModel", i = "numeric", j = "missing") It generates the same model
   with a subset of the moment conditions.
- signature(x = "rfuncionModel", i = "numeric", j = "missing") It generates the same model with a subset of the moment conditions. j has no effect here.

[-methods 119

```
data(simData)
model1 <- momentModel(y~x1+x2, ~x2+x3+z1+z2+z3, data=simData, vcov="MDS")
w <- evalWeights(model1, theta=1:3)
w[]
w[1:3]
## A model with a subset of the instruments
model1[1:4]
## Selecting the observations:
subset(model1, simData[["x1"]]<3)
subset(model1, 1:25)</pre>
```

# **Index**

* 3SLS	rnonlinearModel-class, 82
systemGmm-doc, 109	rslinearModel-class,83
* Confidence Intervals	rsnonlinearModel-class, 85
confint-methods, 9	rsysModel-class, 86
* FIVE	sfunctionModel-class, 88
systemGmm-doc, 109	sgmmfit-class, 89
* GEL	slinearModel-class,92
gel4, 26	snonlinearModel-class, 93
* GMM	specTest-class, 97
gmm4, 32	sSpec-class, 99
systemGmm-doc, 109	stsls-class, 100
* Instruments	summaryGel-class, 102
gel4, 26	summaryGmm-class, 103
gmm4, 32	summarySysGmm-class, 104
* Moment	sysModel-class, 105
gel4, 26	sysMomentWeights-class, 108
gmm4, 32	tsls-class, 111
* SUR	* datasets
systemGmm-doc, 109	CigarettesSW, 5
* System of Equations	ConsumptionG, 10
systemGmm-doc, 109	Griliches, 39
* classes	HealthRWM, 40
allNLModel-class, 4	Klein, 47
confint-class, 8	LabourCR, 48
formulaModel-class, 23	ManufactCost, 53
functionModel-class, 24	Mroz, 66
gelfit-class, 28	simData, 90
gmmfit-class, 35	* methods
hypothesisTest-class, 42	[-methods, 118
linearModel-class, 51	bread-methods, 4
mconfint-class, 54	coef-methods, 7
momentModel-class, 62	confint-methods, 9
momentWeights-class, 64	Dresiduals-methods, 12
nonlinearModel-class, 67	DWH-methods, 12
regModel-class,73	estfun-methods, 14
rformulaModel-class,76	evalDMoment-methods, 14
rfunctionModel-class, 78	evalGel-methods, 16
rlinearModel-class, 80	evalGelObj-methods, 18
rmomentModel-class, 81	evalGmm-methods, 19

evalGmmObj-methods, 20	([-methods), 118
evalMoment-methods, 21	[,rslinearModel,numeric,missing-method
evalWeights-methods, 22	([-methods), 118
gelFit-methods, 29	[,rsnonlinearModel,numeric,missing-method
getRestrict-methods, 30	([-methods), 118
gmmFit-methods, 36	[,sfunctionModel,numeric,missing-method
hypothesisTest-methods, 43	([-methods), 118
meatGmm-methods, 54	[,slinearModel,numeric,missing-method
merge-methods, 56	([-methods), 118
model.matrix-methods, 57	[,snonlinearModel,numeric,missing-method
modelDims-methods, 59	([-methods), 118
modelResponse-methods, 60	[,sysModel,missing,list-method
momentStrength-methods, 63	([-methods), 118
momFct-methods, 65	[,sysModel,missing,missing-method
plot-methods, 69	([-methods), 118
print-methods, 70	[,sysModel,numeric,list-method
printRestrict-methods, 71	([-methods), 118
quadra-methods, 71	[,sysMomentWeights,missing,list-method
residuals-methods, 73	([-methods), 118
restModel-methods, 74	[,sysMomentWeights,numeric,list-method
setCoef-methods, 86	([-methods), 118
show-methods, 90	[,sysMomentWeights,numeric,missing-method
solveGel-methods, 94	([-methods), 118
solveGmm-methods, 96	[-methods, 118
specTest-methods, 98	
summary-methods, 101	allNLModel, 24, 25, 68, 77, 78, 83
ThreeSLS-methods, 110	allNLModel-class, 4
tsls-methods, 112	
update-methods, 113	bread (bread-methods), 4
vcov-methods, 114	bread, gmmfit-method (bread-methods), 4
vcovHAC-methods, 117	bread, sgmmfit-method (bread-methods), 4
* misspecified	bread, tsls-method (bread-methods), 4
momFct-methods, 65	bread-methods, 4
* probabilities	Cinconstate CW 5
getImpProb-methods, 30	CigarettesSW, 5
•	coef, gelfit-method (coef-methods), 7
[,formulaModel,numeric,missing-method	coef, gmmfit-method (coef-methods), 7
([-methods), 118	<pre>coef, momentModel-method (coef-methods),</pre>
[,functionModel,numeric,missing-method ([-methods), 118	7
	coef,rformulaModel-method
[,momentModel,missing,missing-method	(coef-methods), 7
([-methods), 118	coef, rfunctionModel-method
[,momentWeights,missing,missing-method	(coef-methods), 7
([-methods), 118	coef, rlinearModel-method
[,momentWeights,numeric,missing-method	(coef-methods), 7
([-methods), 118	coef, rnonlinearModel-method
[,regModel,numeric,missing-method	(coef-methods), 7
([-methods), 118	coef, rslinearModel-method
[,rfunctionModel,numeric,missing-method	(coef-methods), 7

coef,rsnonlinearModel-method	evalDMoment,regModel-method
(coef-methods), 7	(evalDMoment-methods), 14
<pre>coef,sgmmfit-method(coef-methods),7</pre>	evalDMoment,rformulaModel-method
coef-methods, 7	(evalDMoment-methods), 14
confint, ANY-method (confint-methods), 9	evalDMoment,rfunctionModel-method
confint,data.frame-method	(evalDMoment-methods), 14
(confint-methods), 9	evalDMoment,rnonlinearModel-method
confint,gelfit-method	(evalDMoment-methods), 14
(confint-methods), 9	evalDMoment,rslinearModel-method
confint,gmmfit-method	(evalDMoment-methods), 14
(confint-methods), 9	evalDMoment,rsnonlinearModel-method
confint, matrix-method	(evalDMoment-methods), 14
(confint-methods), 9	evalDMoment, sysModel-method
confint, numeric-method	(evalDMoment-methods), 14
(confint-methods), 9	evalDMoment-methods, 14
confint-class, 8	evalGel (evalGel-methods), 16
confint-methods, 9	evalGel, momentModel-method
constrOptim, 95	(evalGel-methods), 16
ConsumptionG, 10	evalGel-methods, 16
	evalGelObj (evalGelObj-methods), 18
Dresiduals (Dresiduals-methods), 12	evalGelObj,momentModel,numeric,numeric-method
Dresiduals, linearModel-method	(evalGelObj-methods), 18
(Dresiduals-methods), 12	evalGelObj-methods, 18
Dresiduals, nonlinearModel-method	evalGmm, 38
(Dresiduals-methods), 12	evalGmm (evalGmm-methods), 19
Dresiduals, rsnonlinearModel-method	evalGmm, momentModel-method
(Dresiduals-methods), 12	(evalGmm-methods), 19
Dresiduals, sysModel-method	evalGmm, sysModel-method
(Dresiduals-methods), 12	(evalGmm-methods), 19
Dresiduals-methods, 12	
DWH (DWH-methods), 12	evalGmm-methods, 19
DWH,gmmfit,gmmfit-method(DWH-methods),	evalGmmObj (evalGmmObj-methods), 20
12	evalGmmObj,momentModel,numeric,momentWeights-method
DWH,gmmfit,lm-method(DWH-methods), 12	(evalGmmObj-methods), 20
DWH,gmmfit,missing-method	evalGmmObj,sysModel,list,sysMomentWeights-method
(DWH-methods), 12	(evalGmmObj-methods), 20
DWH-methods, 12	evalGmmObj-methods, 20
	evalMoment (evalMoment-methods), 21
EEL_1am, 17, 27, 95	evalMoment, formulaModel-method
EEL_lam (lambdaAlgo), 50	(evalMoment-methods), 21
estfun,momentModel-method	evalMoment, functionModel-method
(estfun-methods), 14	(evalMoment-methods), 21
estfun-methods, 14	evalMoment,regModel-method
ETXX_lam (lambdaAlgo), 50	(evalMoment-methods), 21
evalDMoment (evalDMoment-methods), 14	evalMoment,rsysModel-method
evalDMoment,formulaModel-method	(evalMoment-methods), 21
(evalDMoment-methods), 14	evalMoment,sysModel-method
evalDMoment,functionModel-method	(evalMoment-methods), 21
(evalDMoment-methods), 14	evalMoment-methods, 21

evalWeights, 64, 108	gmmFit, 10, 32, 35, 89, 111, 115
evalWeights (evalWeights-methods), 22	gmmFit (gmmFit-methods), 36
evalWeights, momentModel-method	gmmfit, 112
(evalWeights-methods), 22	gmmFit,formulaModel-method
evalWeights,rslinearModel-method	(gmmFit-methods), 36
(evalWeights-methods), 22	gmmFit, momentModel-method
evalWeights, sysModel-method	(gmmFit-methods), 36
(evalWeights-methods), 22	gmmFit,rformulaModel-method
evalWeights-methods, 22	(gmmFit-methods), 36
	gmmFit,rlinearModel-method
formulaModel, 77	(gmmFit-methods), 36
formulaModel-class, 23	gmmFit,rnonlinearModel-method
functionModel, 78	(gmmFit-methods), 36
functionModel-class, 24	gmmFit,rslinearModel-method
	(gmmFit-methods), 36
gel4, 26	gmmFit,sysModel-method
gelFit, 10, 26-28	(gmmFit-methods), 36
gelFit (gelFit-methods), 29	gmmfit-class, 35
gelFit,momentModel-method	gmmFit-methods, 36
(gelFit-methods), 29	Griliches, 39
gelFit,rmomentModel-method	0. 111000, 07
(gelFit-methods), 29	HealthRWM, 40
gelfit-class, 28	hypothesisTest, 42, 99
gelFit-methods, 29	hypothesisTest
<pre>getImpProb (getImpProb-methods), 30</pre>	(hypothesisTest-methods), 43
<pre>getImpProb,gelfit-method</pre>	hypothesisTest,gmmfit,gmmfit-method
(getImpProb-methods), 30	(hypothesisTest-methods), 43
getImpProb-methods, 30	hypothesisTest,gmmfit,missing-method
getLambda, <i>17</i> , <i>27</i> , <i>95</i>	(hypothesisTest-methods), 43
getLambda(lambdaAlgo), 50	hypothesisTest, missing, gmmfit-method
getRestrict (getRestrict-methods), 30	(hypothesisTest-methods), 43
getRestrict,momentModel-method	hypothesisTest, missing, sgmmfit-method
(getRestrict-methods), 30	(hypothesisTest-methods), 43
getRestrict,rformulaModel-method	hypothesisTest,sgmmfit,missing-method
(getRestrict-methods), 30	(hypothesisTest-methods), 43
getRestrict,rfunctionModel-method	hypothesisTest,sgmmfit,sgmmfit-method
(getRestrict-methods), 30	(hypothesisTest-methods), 43
getRestrict,rlinearModel-method	hypothesisTest-class, 42
(getRestrict-methods), 30	hypothesisTest-methods, 43
getRestrict,rnonlinearModel-method	
(getRestrict-methods), 30	kernapply (kernapply-methods), 46
getRestrict,rslinearModel-method	kernapply,momentModel-method
(getRestrict-methods), 30	(kernapply-methods), 46
getRestrict,rsnonlinearModel-method	kernapply-methods, 46
(getRestrict-methods), 30	Klein, 47
getRestrict,sysModel-method	
(getRestrict-methods), 30	LabourCR, 48
getRestrict-methods, 30	lambdaAlgo, 50
gmm4, 32	linearModel, 81

linearModel-class, 51	modelDims,nonlinearModel-method
	(modelDims-methods), 59
ManufactCost, 53	modelDims,rformulaModel-method
mclapply, 10	(modelDims-methods), 59
mconfint-class, 54	modelDims,rfunctionModel-method
meatCL, 34, 61, 64, 106	(modelDims-methods), 59
meatGmm (meatGmm-methods), 54	modelDims,rlinearModel-method
meatGmm, gmmfit-method	(modelDims-methods), 59
(meatGmm-methods), 54	modelDims,rnonlinearModel-method
meatGmm, sgmmfit-method	(modelDims-methods), 59
(meatGmm-methods), 54	modelDims,rslinearModel-method
meatGmm, tsls-method (meatGmm-methods),	(modelDims-methods), 59
54	modelDims,rsnonlinearModel-method
meatGmm-methods, 54	(modelDims-methods), 59
merge (merge-methods), 56	modelDims,sfunctionModel-method
	(modelDims-methods), 59
merge, ANY, ANY-method (merge-methods), 56	modelDims,slinearModel-method
merge,linearModel,linearModel-method	(modelDims-methods), 59
(merge-methods), 56	modelDims,snonlinearModel-method
merge,nonlinearModel,nonlinearModel-method	(modelDims-methods), 59
(merge-methods), 56	modelDims,sysMomentModel-method
merge, slinearModel, linearModel-method	
(merge-methods), 56	(modelDims-methods), 59 modelDims-methods, 59
merge, snonlinear Model, nonlinear Model-method	*
(merge-methods), 56	<pre>modelResponse (modelResponse-methods),</pre>
merge-methods, 56	60
<pre>model.matrix (model.matrix-methods), 57</pre>	modelResponse,linearModel-method
model.matrix,linearModel-method	(modelResponse-methods), 60
<pre>(model.matrix-methods), 57</pre>	modelResponse,rlinearModel-method
model.matrix,nonlinearModel-method	(modelResponse-methods), 60
<pre>(model.matrix-methods), 57</pre>	modelResponse,rslinearModel-method
model.matrix,rlinearModel-method	(modelResponse-methods), 60
(model.matrix-methods), 57	modelResponse,slinearModel-method
model.matrix,rslinearModel-method	(modelResponse-methods), 60
<pre>(model.matrix-methods), 57</pre>	modelResponse-methods, 60
<pre>model.matrix,rsnonlinearModel-method</pre>	momentModel, 23–25, 27, 35, 51, 52, 60, 62,
<pre>(model.matrix-methods), 57</pre>	64, 67, 68, 77, 78, 81, 83, 88, 92, 93
<pre>model.matrix,slinearModel-method</pre>	momentModel-class, 62
(model.matrix-methods), 57	momentStrength
<pre>model.matrix,snonlinearModel-method</pre>	(momentStrength-methods), 63
(model.matrix-methods), 57	momentStrength,formulaModel-method
model.matrix-methods, 57	(momentStrength-methods), 63
modelDims (modelDims-methods), 59	momentStrength, functionModel-method
modelDims,formulaModel-method	(momentStrength-methods), 63
(modelDims-methods), 59	momentStrength,linearModel-method
modelDims, functionModel-method	(momentStrength-methods), 63
(modelDims-methods), 59	momentStrength, nonlinearModel-method
modelDims,linearModel-method	(momentStrength-methods), 63
(modelDims-methods), 59	momentStrength,rlinearModel-method
(moderorms methods), 33	momento di englii, i i i i i edi fibuet i ile di ibu

(momentStrength-methods), 63	print,sSpec-method(print-methods),70
momentStrength-methods, 63	<pre>print,summaryGel-method</pre>
momentWeights, 72	(print-methods), 70
momentWeights (momentWeights-class), 64	<pre>print,summaryGmm-method</pre>
momentWeights-class, 64	(print-methods), 70
momFct (momFct-methods), 65	<pre>print,summarySysGmm-method</pre>
momFct, numeric, gelfit-method	(print-methods), 70
(momFct-methods), 65	<pre>print,sysModel-method(print-methods),</pre>
momFct-methods, 65	70
Mroz, 66	<pre>print,sysMomentWeights-method</pre>
	(print-methods), 70
nlminb, <i>50</i> , <i>95</i>	print-methods, 70
nonlinearModel, 83	<pre>printRestrict (printRestrict-methods),</pre>
nonlinearModel-class, 67	71
	printRestrict,rformulaModel-method
optim, 29, 33, 34, 38, 50, 61, 95–97	(printRestrict-methods), 71
	printRestrict,rfunctionModel-method
plot, ANY-method (plot-methods), 69	(printRestrict-methods), 71
plot, mconfint-method (plot-methods), 69	printRestrict,rlinearModel-method
plot-methods, 69	(printRestrict-methods), 71
points, 69	printRestrict,rnonlinearModel-method
polygon, 69	(printRestrict-methods), 71
<pre>print, ANY-method (print-methods), 70</pre>	printRestrict,rslinearModel-method
<pre>print, confint-method (print-methods), 70</pre>	(printRestrict-methods), 71
<pre>print,gelfit-method(print-methods), 70</pre>	printRestrict,rsnonlinearModel-method
<pre>print,gmmfit-method(print-methods),70</pre>	(printRestrict-methods), 71
<pre>print,hypothesisTest-method</pre>	printRestrict-methods, 71
(print-methods), 70	pi Trickesti Tet illetrious, 71
<pre>print,mconfint-method(print-methods),</pre>	quadra (quadra-methods), 71
70	quadra, momentWeights, matrixORnumeric, matrixORnumeric-metho
<pre>print,momentModel-method</pre>	(quadra-methods), 71
(print-methods), 70	quadra, momentWeights, matrixORnumeric, missing-method
print, momentWeights-method	(quadra-methods), 71
(print-methods), 70	quadra, momentWeights, missing, missing-method
print,rformulaModel-method	(quadra-methods), 71
(print-methods), 70	quadra,sysMomentWeights,matrixORnumeric,matrixORnumeric-me
print,rfunctionModel-method	(quadra-methods), 71
(print-methods), 70	quadra, sysMomentWeights, matrixORnumeric, missing-method
print,rlinearModel-method	(quadra-methods), 71
(print-methods), 70	quadra, sysMomentWeights, missing, missing-method
print, rnonlinear Model-method	(quadra-methods), 71
(print-methods), 70	quadra-methods, 71
print,rslinearModel-method	quadi a ilicatious, 71
(print-methods), 70	REEL_lam, 17, 27, 95
print,rsnonlinearModel-method	REEL_lam(lambdaAlgo), 50
(print-methods), 70	regModel, 52, 68, 81, 83
print, sgmmfit-method (print-methods), 70	regModel-class, 73
print, specTest-method (print-methods),	residuals, ANY-method
70	(residuals-methods), 73

residuals,gelfit-method	setCoef (setCoef-methods), 86
(residuals-methods), 73	setCoef,momentModel-method
residuals,gmmfit-method	(setCoef-methods), 86
(residuals-methods), 73	setCoef,sysModel-method
residuals, linearModel-method	(setCoef-methods), 86
(residuals-methods), 73	setCoef-methods, 86
residuals, nonlinearModel-method	sfunctionModel-class, 88
(residuals-methods), 73	sgmmfit, <i>100</i>
residuals, rsysModel-method	sgmmfit-class, 89
(residuals-methods), 73	show, ANY-method (show-methods), 90
residuals,sgmmfit-method	show, confint-method (show-methods), 90
(residuals-methods), 73	show, gelfit-method (show-methods), 90
residuals, sysModel-method	show, gmmfit-method (show-methods), 90
(residuals-methods), 73	show, hypothesisTest-method
residuals-methods, 73	(show-methods), 90
restModel, 27, 31, 34	show, mconfint-method (show-methods), 90
restModel (restModel-methods), 74	show, momentModel-method (show-methods),
restModel,formulaModel-method	90
(restModel-methods), 74	show, momentWeights-method
restModel,functionModel-method	(show-methods), 90
(restModel-methods), 74	show, sgmmfit-method (show-methods), 90
restModel,linearModel-method	show, specTest-method (show-methods), 90
(restModel-methods), 74	show, sSpec-method (show-methods), 90
restModel,nonlinearModel-method	show, summaryGel-method (show-methods),
(restModel-methods), 74	90
restModel,slinearModel-method	show, summaryGmm-method (show-methods),
(restModel-methods), 74	90
restModel,snonlinearModel-method	show,summarySysGmm-method
(restModel-methods), 74	(show-methods), 90
restModel-methods, 74	show, sysModel-method (show-methods), 90
rformulaModel-class, 76	show,sysMomentWeights-method
rfunctionModel-class, 78	(show-methods), 90
rhoEEL (rhoFct), 79	show-methods, 90
rhoEL (rhoFct), 79	${\sf simData}, 90$
rhoET (rhoFct), 79	slinearModel, 84
rhoETEL (rhoFct), 79	slinearModel-class, 92
rhoETHD (rhoFct), 79	snonlinearModel, 86
rhoFct, 17, 18, 29, 79, 95	snonlinearModel-class, 93
rhoHD (rhoFct), 79	solveGel(solveGel-methods), 94
rhoREEL (rhoFct), 79	solveGel, momentModel-method
rlinearModel-class, 80	(solveGel-methods), 94
rmomentModel, 77, 78, 81, 83	solveGel-methods, 94
<pre>rmomentModel-class, 81</pre>	solveGmm (solveGmm-methods), 96
rnonlinearModel-class, 82	solveGmm,allNLModel,momentWeights-method
rslinearModel-class, 83	(solveGmm-methods), 96
rsnonlinearModel-class, 85	<pre>solveGmm,linearModel,momentWeights-method</pre>
rsysModel, <i>84</i> , <i>86</i>	(solveGmm-methods), 96
rsysModel-class, 86	solveGmm,rnonlinearModel,momentWeights-method

(solveGmm-methods), 96	ThreeSLS (ThreeSLS-methods), 110
<pre>solveGmm,rslinearModel,sysMomentWeights-met</pre>	hodhreeSLS,list-method(gmm4),32
(solveGmm-methods), 96	ThreeSLS,rslinearModel-method
<pre>solveGmm,sfunctionModel,sysMomentWeights-me</pre>	thod (ThreeSLS-methods), 110
(solveGmm-methods), 96	ThreeSLS,slinearModel-method
<pre>solveGmm,slinearModel,sysMomentWeights-methor</pre>	od (ThreeSLS-methods), 110
(solveGmm-methods), 96	ThreeSLS-methods, 110
<pre>solveGmm,snonlinearModel,sysMomentWeights-me</pre>	ethods), 112
(solveGmm-methods), 96	tsls, formula-method(gmm4), 32
solveGmm-methods, 96	tsls,linearModel-method(tsls-methods),
specTest, 44	112
<pre>specTest (specTest-methods), 98</pre>	tsls, list-method (gmm4), 32
<pre>specTest,gelfit,missing-method</pre>	tsls,slinearModel-method
(specTest-methods), 98	(tsls-methods), 112
specTest,gmmfit,missing-method	tsls-class, 111
(specTest-methods), 98	tsls-methods, 112
specTest,gmmfit,numeric-method	
(specTest-methods), 98	uniroot, 10
specTest,sgmmfit,missing-method	update, ANY-method (update-methods), 113
(specTest-methods), 98	update,gelfit-method(update-methods),
specTest-class, 97	113
specTest-methods, 98	<pre>update,gmmfit-method(update-methods),</pre>
sSpec-class, 99	113
stsls-class, 100	update, list-method (update-methods), 113
subset ([-methods), 118	update,momentModel-method
<pre>subset, formulaModel-method([-methods),</pre>	(update-methods), 113
118	update-methods, 113
subset, functionModel-method	vcov, <i>13</i>
([-methods), 118	vcov, gelfit-method (vcov-methods), 114
<pre>subset,regModel-method([-methods), 118</pre>	vcov, gmmfit-method (vcov-methods), 114
<pre>subset, sysModel-method ([-methods), 118</pre>	vcov, momentModel-method (vcov-methods),
summary (summary-methods), 101	114
summary,gelfit-method	vcov,sgmmfit-method(vcov-methods), 114
(summary-methods), 101	vcov, sysModel-method (vcov-methods), 114
summary,gmmfit-method	vcov,tsls-method (vcov-methods), 114
(summary-methods), 101	vcov-methods, 114
summary,sgmmfit-method	vcovHAC, 26, 34, 61, 64, 106
(summary-methods), 101	vcovHAC, momentModel-method
summary-methods, 101	(vcovHAC-methods), 117
summaryGel-class, 102	vcovHAC-methods, 117
summaryGmm-class, 103	vcovHC, <i>64</i>
summarySysGmm-class, 104	,
sysModel, 84, 86, 88, 92, 94	Wu_lam, <i>17</i> , <i>27</i> , <i>95</i>
sysModel-class, 105	Wu_lam(lambdaAlgo), 50
sysMomentModel, 106	
sysMomentWeights-class, 108	
systemGmm (systemGmm-doc), 109	
systemGmm-doc, 109	